

Derivatives of Modular Forms of Negative Weight

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Dedicated to John Coates

Let $G = \mathrm{Sp}(2n, \mathbb{R})$, and let Γ be a discrete subgroup. Let $\chi : \Gamma \rightarrow \mathbb{C}$ be a function such that when $Z \in \mathcal{H}_n$, the Siegel space of genus n , the multiplier system

$$(1) \quad j_k(\gamma, Z) = \chi(\gamma) \det(CZ + D)^{-k}, \quad \gamma = \begin{pmatrix} A & B \\ C & D \end{pmatrix} \in \Gamma$$

satisfies the cocycle condition

$$(2) \quad j_k(\gamma\gamma', Z) = j_k(\gamma, \gamma'Z) j_k(\gamma', Z).$$

It is important for us to allow $k \in \frac{1}{2}\mathbb{Z}$. If k is half-integral, then $\det(CZ + D)^{-k}$ involves the choice of a branch of square root, but this is unimportant since a different choice of branch can be compensated for in the choice of the function χ .

Let $M_k(\Gamma, \chi)$ be the space of *meromorphic* functions f on \mathcal{H}_n such that

$$(3) \quad f(Z) = j_k(\gamma, Z) f(\gamma Z).$$

Let $Z = (Z_{ij}) \in \mathcal{H}_n$, and let ∂_{ij} be the differential operator defined by

$$\partial_{ij} = \left(\frac{1 + \delta_{ij}}{2} \right) \frac{\partial}{\partial Z_{ij}}.$$

(Note that Z_{ij} and Z_{ji} are the same variable.) Let

$$\mathbb{D}_n = \det(\partial_{ij}).$$

Conjecture 1. *Let $r \geq 0$ be an integer. If $f \in M_{-r+\frac{n-1}{2}}(\Gamma, \chi)$, then the derivative $\mathbb{D}_n^{r+1} f \in M_{r+2+\frac{n-1}{2}}(\Gamma, \chi)$.*

If $n = 1$, Conjecture 1 can be proved as follows. Let $\mathcal{H} = \mathcal{H}_n$ be the usual upper half plane. Let S be a finite set of points in $\Gamma \backslash \mathcal{H}$, where a modular form is allowed to have poles. Let \mathcal{H}_S be the set of all $z \in \mathcal{H}$ such that the image of z in $\Gamma \backslash \mathcal{H}$ is not in S . Define

$$\mathbb{D} = \frac{d}{dz}, \quad \partial_k = \frac{1}{2\pi i} \left(\mathbb{D} - \frac{ik}{2y} \right)$$

In the notation of the next section, $\partial_k = -\frac{1}{4\pi} \mathcal{R}_k$. The operator ∂_k does not preserve holomorphicity but preserves the space $\mathcal{M}_k^S(\Gamma, \chi)$ of smooth functions $f : \mathcal{H}_S \rightarrow \mathbb{C}$ such that

$$(4) \quad f(z) = j_k(\gamma, z) f\left(\frac{az+b}{cz+d}\right), \quad z \in \mathcal{H}_S, \quad g = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in G.$$

one proves by induction the identity of Bol [1]:

$$\partial_k^h = \partial_{k+2h-2} \circ \dots \circ \partial_{k+2} \circ \partial_k = \left(-\frac{1}{4\pi y}\right)^h \sum_{j=0}^h \binom{h}{j} \frac{\Gamma(h+k)}{\Gamma(j+k)} (2iy\mathbb{D})^j.$$

It is understood that the term is zero if $j+k$ is a nonpositive integer but $h+k$ is not, since then $\Gamma(j+k)^{-1} = 0$ but $\Gamma(h+k)$ has no pole. In particular, there is only one nonzero term in

$$\partial_{-r}^{r+1} = \left(-\frac{1}{4\pi y}\right)^{r+1} \sum_{j=0}^{r+1} \binom{r+1}{j} \frac{\Gamma(1)}{\Gamma(j-r)} (2iy\mathbb{D})^j = \left(\frac{1}{2\pi i} \mathbb{D}\right)^{r+1}.$$

As a consequence \mathbb{D}^{r+1} maps holomorphic functions in $\mathcal{M}_{-r}^S(\Gamma)$ into $\mathcal{M}_{r+2}^S(\Gamma)$, and if such a function is meromorphic on \mathcal{H} , so of course is $\mathbb{D}^{r+1} f$.

The purpose of this paper is to reveal some underlying representation theory behind Conjecture 1 and to prove it when $n \leq 2$. When $n = 1$, the alternative proof that we will give below in Theorem 1 is different from the one just given using the inductive formula or the result of Bol [1], and reveals an underlying reason why the statement is true. We will see that given a form of negative (integral) weight for $\mathrm{SL}(2, \mathbb{R})$, we may construct an ‘‘automorphic representation’’ by transferring it to the group and considering the (\mathfrak{g}, K) -module that it generates. This representation is reducible but indecomposable, and it has a representation of the holomorphic discrete

series as an irreducible quotient. The interesting feature is that it has two “holomorphic vectors” corresponding to f and $f^{(r+1)}$.

We will formulate the purely representation-theoretic Conjecture 2 which implies Conjecture 1, and prove it when $n = 2$. When $n = 2$, the modular form must be of half-integral weight, and so the representations we consider will be not of $\mathrm{Sp}(2n, \mathbb{R})$, but of the metaplectic group.

If n is even, Choie and Kim [4] used another very different method to prove a similar result, using the Fourier-Jacobi expansion and Bol’s identity. This approach requires that the group be of a particular type; for example it could not work if Γ is cocompact.

This work was partially supported by NSF Grant DMS-0354662 and KOSEF Grant R01-2003-00011596-0. We would like to thank the referee for a careful reading.

1. THE CASE $n = 1$

To clarify the ideas we start with the case $n = 1$. It will be noted that when n is even, Conjecture 1 involves modular forms of half-integral weight $r + \frac{n-1}{2}$. Since in this case n is odd, this does not apply here and there is no need to introduce the metaplectic group. We will suppress the character χ , and also consider only modular forms which are holomorphic in \mathcal{H} . (If the weight is negative, such a function must have poles at the cusps of Γ .)

Let $G = \mathrm{SL}(2, \mathbb{R})$, and let Γ be a discrete subgroup. Let $\mathcal{M}_k(\Gamma)$ be the space of smooth functions satisfying (3). They are *not* assumed to be holomorphic. The subspace of holomorphic functions will be denoted $M_k(\Gamma)$. We allow k to be negative. Denote by $\mathcal{C}_k(\Gamma \backslash \mathcal{H})$ the space of smooth functions $f : \mathcal{H} \rightarrow \mathbb{C}$ such that

$$f(z) = \chi(\gamma) \left(\frac{c\bar{z} + d}{|cz + d|} \right)^k f\left(\frac{az + b}{cz + d} \right), \quad z \in \mathcal{H}, \quad \gamma = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \Gamma.$$

Finally, let $\mathcal{C}_k(\Gamma \backslash G)$ be the space of smooth functions $f : G \rightarrow \mathbb{C}$ such that $f(\gamma g) = f(g)$ for $\gamma \in \Gamma$ and $f(g\kappa_\theta) = e^{ik\theta} f(g)$, where

$$\kappa_\theta = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}.$$

We have isomorphisms

$$\mathcal{M}_k(\Gamma) \xrightarrow{y^{k/2}} \mathcal{C}_k(\Gamma \backslash \mathcal{H}) \xrightarrow{\sigma_k} \mathcal{C}_k(\Gamma \backslash G)$$

where $y^{k/2}$ is just multiplication by $y^{k/2}$ and σ_k is defined by

$$\sigma_k(f)(g) = (f|_k g)(i),$$

where

$$\left(f|_k \begin{pmatrix} a & b \\ c & d \end{pmatrix} \right) (z) = \left(\frac{c\bar{z} + d}{|cz + d|} \right)^k f \left(\frac{az + b}{cz + d} \right), \quad z \in \mathcal{H}, \quad g = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in G.$$

We have *Maass operators* (Maass [11]) on $\mathcal{C}_k(\Gamma \backslash \mathcal{H})$ defined by

$$\begin{aligned} R_k &= iy \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} + \frac{k}{2} = (z - \bar{z}) \frac{\partial}{\partial z} + \frac{k}{2}, \\ L_k &= -iy \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} - \frac{k}{2} = (z - \bar{z}) \frac{\partial}{\partial \bar{z}} - \frac{k}{2}, \end{aligned}$$

with

$$\frac{\partial}{\partial z} = \frac{1}{2} \left(\frac{\partial}{\partial x} - i \frac{\partial}{\partial y} \right), \quad \frac{\partial}{\partial \bar{z}} = \frac{1}{2} \left(\frac{\partial}{\partial x} + i \frac{\partial}{\partial y} \right), \quad z = x + iy \in \mathcal{H}.$$

Let \mathfrak{g} be the Lie algebra of G , identified with the Lie algebra of 2×2 real matrices of trace zero. It acts on smooth functions as follows. If $X \in \mathfrak{g}$ and $f : G \rightarrow \mathbb{C}$ is smooth then

$$(Xf)(g) = \frac{d}{dt} f(g e^{itX})|_{t=0}.$$

This action is extended to the complexification $\mathfrak{g}_{\mathbb{C}}$ and to the universal enveloping algebra $U(\mathfrak{g}_{\mathbb{C}})$. Let

$$(5) \quad R = \frac{1}{2} \begin{pmatrix} 1 & i \\ i & -1 \end{pmatrix}, \quad L = \frac{1}{2} \begin{pmatrix} 1 & -i \\ -i & -1 \end{pmatrix}, \quad H = -i \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \in \mathfrak{g}_{\mathbb{C}}.$$

We have, in $\mathfrak{g}_{\mathbb{C}}$, the commutation relations

$$[H, R] = 2R, \quad [H, L] = 2L, \quad [R, L] = H.$$

Let

$$-4\Delta = H^2 + 2RL + 2LR.$$

This is the Casimir element, in the center of $U(\mathfrak{g}_{\mathbb{C}})$. Then $\mathcal{C}_k(\Gamma \backslash G)$ is just the subspace of $C^\infty(\Gamma \backslash G)$ consisting H -eigenfunctions f with $Hf = kf$. Since $[R, L] = H$ we have

$$(6) \quad -4\Delta = H^2 + 2H + 4LR = H^2 - 2H + 4RL.$$

We define operators R_k , L_k and Δ_k on $\mathcal{C}_k(\Gamma \backslash G)$, and operators \mathcal{R}_k , \mathcal{L}_k and Δ_k on $\mathcal{C}_k(\Gamma \backslash \mathcal{H})$ by asking that the following diagrams be commutative:

$$\begin{array}{ccccc}
 \mathcal{M}_k(\Gamma) & \xrightarrow{y^{k/2}} & \mathcal{C}_k(\Gamma \backslash \mathcal{H}) & \xrightarrow{\sigma_k} & \mathcal{C}_k(\Gamma \backslash G) \\
 \mathcal{R}_k \downarrow & & R_k \downarrow & & R \downarrow \\
 \mathcal{M}_{k+2}(\Gamma) & \xrightarrow{y^{(k+2)/2}} & \mathcal{C}_{k+2}(\Gamma \backslash \mathcal{H}) & \xrightarrow{\sigma_{k+2}} & \mathcal{C}_{k+2}(\Gamma \backslash G) \\
 \mathcal{M}_k(\Gamma) & \xrightarrow{y^{k/2}} & \mathcal{C}_k(\Gamma \backslash \mathcal{H}) & \xrightarrow{\sigma_k} & \mathcal{C}_k(\Gamma \backslash G) \\
 \mathcal{L}_k \downarrow & & L_k \downarrow & & L \downarrow \\
 \mathcal{M}_{k-2}(\Gamma) & \xrightarrow{y^{(k-2)/2}} & \mathcal{C}_{k-2}(\Gamma \backslash \mathcal{H}) & \xrightarrow{\sigma_{k-2}} & \mathcal{C}_{k-2}(\Gamma \backslash G) \\
 \mathcal{M}_k(\Gamma) & \xrightarrow{y^{k/2}} & \mathcal{C}_k(\Gamma \backslash \mathcal{H}) & \xrightarrow{\sigma_k} & \mathcal{C}_k(\Gamma \backslash G) \\
 \Delta_k \downarrow & & \Delta_k \downarrow & & \Delta \downarrow \\
 \mathcal{M}_k(\Gamma) & \xrightarrow{y^{k/2}} & \mathcal{C}_k(\Gamma \backslash \mathcal{H}) & \xrightarrow{\sigma_k} & \mathcal{C}_k(\Gamma \backslash G)
 \end{array}$$

We have, in particular

$$L_k = -2iy \frac{\partial}{\partial \bar{z}} - \frac{k}{2}, \quad R_k = 2iy \frac{\partial}{\partial z} + \frac{k}{2},$$

so

$$(7) \quad \mathcal{R}_k = y^{-(k+2)/2} R_k y^{k/2} = 2i \frac{\partial}{\partial z} + \frac{k}{y},$$

$$\mathcal{L}_k = y^{-(k-2)/2} L_k y^{k/2} = 2iy^2 \frac{\partial}{\partial \bar{z}}.$$

Thus, by the Cauchy-Riemann equations, $f \in \mathcal{M}_k(\Gamma)$ is holomorphic if and only if $\mathcal{L}_k f = 0$, that is

$$(8) \quad M_k(\Gamma) = \ker(\mathcal{L}_k).$$

Finally, we note that Δ and R commute in $U(\mathfrak{g}_{\mathbb{C}})$.

Lemma 1. *If $f \in M_k(\Gamma)$ then $\Delta_k f = \lambda f$, where $\lambda = \frac{k}{2}(1 - \frac{k}{2})$.*

Proof Let $F = \sigma_k(y^{k/2} f) \in \mathcal{C}_k(\Gamma \backslash G)$. It is enough to show that $\Delta F = \lambda F$. We have $HF = kF$ while $LF = 0$. Thus using the second expression in (6)

$$-4\Delta F = (H^2 - 2H + 4RL) = (k^2 - 2k)F,$$

and the statement follows. \square

Theorem 1. *Let $r \geq 0$ and let $f \in M_{-r}(\Gamma)$. Then the $r + 1$ -st derivative $f^{(r+1)} \in M_{r+2}(\Gamma)$.*

This is Conjecture 1 when $n = 1$. It was already proved in the introduction by another method.

Proof It is clear *a priori* from (7) that $f_{r+2} = \mathcal{R}_r \circ \dots \circ \mathcal{R}_{-r+2} \circ \mathcal{R}_{-r}(f)$ is a linear combination of terms of the form $y^{-(r+1-i)} f^{(i)}$ where $0 \leq i \leq r + 1$, and the coefficient of $f^{(r+1)}$ is $(2i)^{r+1}$. If we can show that this function is holomorphic, it will follow that $y^{-(r+1-i)} f^{(i)}$ with $i > 0$ have zero coefficient, hence

$$(2i)^{r+1} f^{(r+1)} = f_{r+2} \in \mathcal{M}_{r+2}(\Gamma \backslash \mathcal{H}).$$

The statement will therefore follow. We will prove this by computations in $U(\mathfrak{g}_{\mathbb{C}})$, so it will be useful to transfer the function to the group. Let $F = \sigma_{-r}(y^{-r/2} f) \in \mathcal{C}_{-r}(\Gamma \backslash G)$. By Lemma 1 we have $\Delta F = -\frac{r}{2}(1 + \frac{r}{2})F$. Since Δ commutes with R , we have

$$\Delta F_r = -\frac{r}{2} \left(1 + \frac{r}{2}\right) F_r, \quad F_r = R^r F.$$

Also $HF_r = rF_r$ since $F_r \in \mathcal{C}_r(\Gamma \backslash G)$. Now using the first expression in (6) this means that

$$r(r+2)F_r = -4\Delta F_r = (H^2 + 2H + 4LR)F_r = (r^2 + 2r)F_r + 4LRF_r.$$

It follows that $LR^{r+1}F = LRF_r = 0$. Transferring this back to a statement about f , we see that

$$\mathcal{L}_{r+2}(\mathcal{R}_r \circ \dots \circ \mathcal{R}_{-r+2} \circ \mathcal{R}_{-r}(f)) = 0,$$

so f_{r+2} is holomorphic, as required. \square

We now reinterpret this proof in terms of representations of $G = \mathrm{SL}_2(\mathbb{R})$. We will exhibit an indecomposable representation ρ_r of G (actually a (\mathfrak{g}, K) -module) which contains two ‘‘holomorphic vectors,’’ one of weight $-r$ and one of weight $r + 2$, corresponding to f and $f^{(r+1)}$. Then we will show how, given a modular form of weight $-r$, one may construct a (\mathfrak{g}, K) -submodule of $C^\infty(\Gamma \backslash G)$ isomorphic to ρ_r .

Let $K = \mathrm{SO}(2)$, and let (π, V) be a (\mathfrak{g}, K) -module. This means that we have compatible representations $\pi : K \rightarrow \mathrm{End}(V)$ and $d\pi : \mathfrak{g} \rightarrow \mathrm{End}(V)$. The compatibility amounts to the following condition. If $k \in \mathbb{Z}$ let

$$V(k) = \{v \in V \mid \pi(\kappa_\theta)v = e^{ik\theta}\}, \quad \kappa_\theta = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}.$$

It is assumed that V is the algebraic direct sum of the $V(k)$, and that each $V(k)$ is finite-dimensional; and the compatibility of the representations π and $d\pi$ amounts to the assumption that

$$(9) \quad d\pi \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} v = ikv, \quad v \in V(k).$$

We assume that V is indecomposable, though not necessarily irreducible, and that each $V(k)$ is at most one-dimensional. The indecomposability implies that $\pi(-I)$ must operate by a scalar $(-1)^\varepsilon$. Thus $V(k) = 0$ unless $k \equiv \varepsilon$ modulo 2.

Let

$$\hat{H} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \quad \hat{R} = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \quad \hat{L} = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \in \mathfrak{g}.$$

Then H , R and L defined by (5) are obtained by applying $\text{Ad}(c^{-1})$ to \hat{H} , \hat{R} and \hat{L} , where

$$c = \frac{1}{\sqrt{2i}} \begin{pmatrix} 1 & -i \\ 1 & i \end{pmatrix}, \quad c^{-1} = \frac{1}{\sqrt{2i}} \begin{pmatrix} i & i \\ -1 & 1 \end{pmatrix}$$

denotes the Cayley transform (in $\text{SL}(2, \mathbb{C})$). We may interpret (9) as the condition that $V(k)$ is the k -eigenspace of H . With this in mind, the commutation conditions $[H, R] = 2R$ and $[H, L] = -2L$ imply that $L(V(k)) \subseteq V(k-2)$ and $R(V(k)) \subseteq V(k+2)$. Also let Δ be the Casimir element of $U(\mathfrak{g})$, defined by

$$(10) \quad -4\Delta = \hat{H}^2 + 2\hat{R}\hat{L} + 2\hat{L}\hat{R} = H^2 + 2RL + 2LR.$$

The center of $U(\mathfrak{g})$ is $\mathbb{C}[\Delta]$. It is easy to see that the center of $U(\mathfrak{g})$ must act by scalars on indecomposable admissible (\mathfrak{g}, K) -modules; this is a version of Schur's Lemma. So Δ acts by a scalar value λ on V .

We call $v \in V(k)$ a *holomorphic vector* if $v \neq 0$ and $\pi(L)v = 0$. If V is irreducible, then V can have at most one holomorphic vector. The irreducible (\mathfrak{g}, K) -modules of $\text{SL}(2, \mathbb{R})$ that have holomorphic vectors are the finite-dimensional representations, the holomorphic discrete series and the holomorphic weight one "limit of discrete series."

Let us recall how the discrete series representations are embedded in the principal series. Let s be a complex number, and let $\varepsilon = 0$ or 1. Let $\chi_{s,\varepsilon}$ denote the character

$$\chi_{s,\varepsilon} \begin{pmatrix} y^{1/2} & xy^{-1/2} \\ & y^{-1/2} \end{pmatrix} = \text{sgn}(y)^\varepsilon |y|^s.$$

Let $\text{Ind}(\chi_{s,\varepsilon})$ denote the (\mathfrak{g}, K) -module obtained by non-normalized induction. Thus $V(k)$ is zero unless $k \equiv \varepsilon$ modulo 2, in which case it is one-dimensional, and spanned by $v_k = v_{k,s,\varepsilon}$, where

$$v_{k,s,\varepsilon} \left(\begin{pmatrix} y^{1/2} & xy^{-1/2} \\ & y^{-1/2} \end{pmatrix} \kappa_\theta \right) = \text{sgn}(y)^\varepsilon |y|^s e^{ik\theta}.$$

Proposition 1. *We have*

$$d\pi(L)v_k = \frac{1}{2}(2s - k)v_{k-2}, \quad d\pi(R)v_k = \frac{1}{2}(2s + k)v_{k+2}.$$

Proof It follows from the fact that $[H, L] = -2L$ and $[H, R] = 2R$, and from the fact that v_k spans the k -eigenspace $V(k)$ of H that $Lv_k \in V(k-2)$ and $Rv_k \in V(k+2)$. Thus it is sufficient to compute the values of Lv_k and Rv_k at the identity. We first show

$$d\pi(\hat{H})v_k(I) = 2s, \quad d\pi(\hat{R})v_k(I) = 0, \quad d\pi(\hat{L})v_k(I) = -ik.$$

Indeed,

$$d\pi(\hat{H})v_k(I) = \frac{d}{dt}\pi(\exp(t\hat{H}))v_k(I)|_{t=0} = \frac{d}{dt}v_k \begin{pmatrix} e^t & \\ & e^{-t} \end{pmatrix} |_{t=0} = \frac{d}{dt}e^{2ts}|_{t=0} = 2s,$$

$$d\pi(\hat{R})v_k(I) = \frac{d}{dt}\pi(\exp(t\hat{R}))v_k(I)|_{t=0} = \frac{d}{dt}v_k \begin{pmatrix} 1 & t \\ & 1 \end{pmatrix} |_{t=0} = \frac{d}{dt}1|_{t=0} = 0$$

and since $\hat{R} - \hat{L} = iH$, $d\pi(\hat{L})v_k(I) = -d\pi(\hat{R} - \hat{L})v_k = -id\pi(H)v_k(I) = -ik$.
Now

$$d\pi(R)v_k(1) = \frac{1}{2}d\pi \left(\hat{H} + i\hat{R} + i\hat{L} \right) v_k(1) = \frac{1}{2}(2s + k),$$

$$d\pi(L)v_k(1) = \frac{1}{2}d\pi \left(\hat{H} - i\hat{R} - i\hat{L} \right) v_k(1) = \frac{1}{2}(2s - k).$$

□

Proposition 2. *The eigenvalue of Δ on $\text{Ind}_{s,\varepsilon}$ is $s(1 - s)$.*

Proof It follows easily from (10) and Proposition 1 that Δ , applied to any v_k multiplies it by this constant. □

The principal series representation $\text{Ind}(\chi_{s,\varepsilon})$ is reducible if $s = \frac{r}{2}$ where r is an integer congruent to ε modulo 2. There are two cases, depending on

whether r is positive or negative. If $r > 0$, then $Lv_r = 0$ and $Rv_{-r} = 0$. This means that V has two invariant subspaces

$$D_r^+ = \bigoplus_{\substack{k \geq r \\ k \equiv \varepsilon \pmod{2}}} V(k), \quad D_r^- = \bigoplus_{\substack{k \leq -r \\ k \equiv \varepsilon \pmod{2}}} V(k).$$

These are closed under H , R and L and so they are (\mathfrak{g}, K) -submodules. The quotient

$$\text{Ind}(\chi_{r/2, \varepsilon}) / (D_r^+ \oplus D_r^-)$$

is finite dimensional – in fact, its dimension is $r - 2$, and it is spanned by the images of the $V(k)$ with $2 - r \leq k \leq r - 2$. The space D_r^+ has a holomorphic vector v_r , and this is a representation of the holomorphic discrete series provided $r \geq 2$. (If $r = 1$ it is a “limit of discrete series.”)

If r is negative and $\varepsilon \equiv r \pmod{2}$, then $\text{Ind}(\chi_{r/2, \varepsilon})$ is again reducible. However it has the same composition factors as $\text{Ind}(\chi_{(2-r)/2, \varepsilon})$, namely the two discrete series and the $r - 2$ -dimensional representation. There is an important distinction: D_r^+ and D_r^- appear as quotients rather than subrepresentations of $\text{Ind}(\chi_{(2-r)/2, \varepsilon})$.

Now we may construct an indecomposable representation with two holomorphic vectors. Let $r > 0$, and let $\varepsilon = 0$ or 1 be congruent to r modulo 2 . Consider the quotient

$$\rho_r = \text{Ind}(\chi_{(r+2)/2, \varepsilon}) / D_{r+2}^-.$$

Let u_k denote the image of v_k in this representation. Then u_{-r} and u_{r+2} are both holomorphic vectors. The space on which it acts is

$$V_\rho = \bigoplus_{\substack{k \geq -r \\ k \equiv r \pmod{2}}} V_\rho(k), \quad V_\rho(k) = \mathbb{C}u_k.$$

The Lie algebra acts by the rules

$$\begin{aligned} d\rho(L)u_k &= \begin{cases} \frac{1}{2}(r+2-k)v_{k-2} & \text{if } k \geq -r \\ 0 & \text{if } k = -r \end{cases} \\ d\rho(R)u_k &= \frac{1}{2}(r+2+k)v_{k+2} \\ d\rho(H)u_k &= ku_k \end{aligned}$$

The eigenvalue of Δ is $-\frac{r}{2} \left(1 + \frac{r}{2}\right)$.

Proposition 3. *Let $r > 0$ and let $f \in M_{-r}(\Gamma)$. Then $\sigma_{-r}(y^{-r/2}f) \in C^\infty(G)$ generates a (\mathfrak{g}, K) -module isomorphic to ρ_{r+2} .*

Proof Define $f_{-r} = \sigma_{-r}(y^{-r/2}f)$ and, recursively, for $k \geq -r$, $k \equiv r \pmod{2}$

$$f_{k+2} = \frac{2}{r+k+2} Rf_k.$$

It may be easily checked that $\rho_k \mapsto f_k$ is an isomorphism of V_ρ onto the span of the f_k , with $k \geq -r$, $k \equiv r \pmod{2}$. \square

2. MAASS OPERATORS FOR $\mathrm{Sp}(2n)$

In this section we review Maass operators for the symplectic group, and their origin in the Lie algebra. See Maass [13], [11] and [12] and Harris [8].

Let $G = \mathrm{Sp}(2n, \mathbb{R})$, $G_{\mathbb{C}} = \mathrm{Sp}(2n, \mathbb{C})$, and let \mathfrak{g} , $\mathfrak{g}_{\mathbb{C}}$ be their Lie algebras. The *Cayley transform* $c \in \mathrm{Sp}(2n, \mathbb{C})$ is defined by

$$c = \frac{1}{\sqrt{2i}} \begin{pmatrix} I_n & -iI_n \\ I_n & iI_n \end{pmatrix}, \quad c^{-1} = \frac{1}{\sqrt{2i}} \begin{pmatrix} iI_n & iI_n \\ -I_n & I_n \end{pmatrix}.$$

The map

$$A + iB \mapsto \begin{pmatrix} A & B \\ -B & A \end{pmatrix}$$

embeds $U(n)$ into $\mathrm{Sp}(2n, \mathbb{R})$, and is easily checked to be a homomorphism. Let K be the image of this map. We have

$$cKc^{-1} = \left\{ \begin{pmatrix} A + iB & \\ & A - iB \end{pmatrix} \mid A + iB \in U(n) \right\}.$$

Thus $\mathrm{Ad}(c)$ is the differential of an inner automorphism of $\mathrm{Sp}(2n, \mathbb{C})$ that takes K into the Levi factor MU of the parabolic subgroup

$$P = MU, \quad M \cong \mathrm{GL}(n, \mathbb{C}) = \left\{ \begin{pmatrix} g & \\ & {}^t g^{-1} \end{pmatrix} \mid g \in \mathrm{GL}(n, \mathbb{C}) \right\},$$

$$U = \left\{ \begin{pmatrix} I & X \\ & I \end{pmatrix} \mid X = {}^t X \right\}.$$

If $X \in \mathrm{Mat}_n(\mathbb{C})$ we will denote

$$\hat{H}_X = \begin{pmatrix} X & \\ & -{}^t X \end{pmatrix} \in \mathfrak{g}_{\mathbb{C}}, \quad H_X = \mathrm{Ad}(c^{-1})\hat{H}_X,$$

and if X is symmetric, we will also denote

$$\hat{R}_X = \begin{pmatrix} 0 & X \\ 0 & 0 \end{pmatrix}, \quad \hat{L}_X = \begin{pmatrix} 0 & 0 \\ X & 0 \end{pmatrix},$$

$$R_X = \mathrm{Ad}(c^{-1})\hat{R}_X, \quad L_X = \mathrm{Ad}(c^{-1})\hat{L}_X.$$

We recall that the irreducible representations of $U(n)$ are parametrized by decreasing sequences of integers

$$\lambda = (\lambda_1, \lambda_2, \dots, \lambda_n), \quad \lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_n.$$

In this parametrization, the representation π_λ corresponding to λ has highest weight vector λ , which we identify with the rational character

$$\begin{pmatrix} t_1 & & \\ & \ddots & \\ & & t_n \end{pmatrix} \mapsto \prod_{i=1}^n t_i^{\lambda_i}$$

of the diagonal torus. In particular if $\lambda = (k, \dots, k)$ then π_λ is the one dimensional representation with character \det^k . If the λ_i are nonnegative we describe λ as a *partition* (of length $\leq n$) and if furthermore the λ_i are even we describe λ as *even*.

We are interested in representations of the metaplectic group, that is, the double cover of $\mathrm{Sp}(2n, \mathbb{R})$. This is the unique nontrivial central extension:

$$1 \longrightarrow \mu_2 \longrightarrow \widetilde{\mathrm{Sp}}(2n, \mathbb{R}) \longrightarrow \mathrm{Sp}(2n, \mathbb{R}) \longrightarrow 1,$$

where μ_2 is a group of order two.

Let \tilde{K} be the preimage of $K = U(n)$ in $\widetilde{\mathrm{Sp}}(2n, \mathbb{R})$. As we will now explain, the irreducible representations of \tilde{K} may be parametrized by decreasing sequences

$$\lambda = (\lambda_1, \lambda_2, \dots, \lambda_n), \quad \lambda_i \in \frac{1}{2}\mathbb{Z}, \quad \lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_n, \quad \lambda_i \equiv \lambda_j \pmod{\mathbb{Z}}.$$

The fundamental group $\pi_1(K) \cong \mathbb{Z}$, and so K has a unique nontrivial double cover, which is easily described. Indeed, we may identify \tilde{K} with the group $\{(g, t) \mid g \in U(n), t \in \mathbb{C}^\times, t^2 = \det(g)\}$. We naturally denote the character $(g, t) \mapsto t$ of \tilde{K} by $\det^{1/2}$. Now if π is an irreducible representation of \tilde{K} which factors through K , then we denote it as π_λ , where λ is the highest weight vector of the corresponding representation of K , identified with an integer sequence. Otherwise, it is of the form $\pi_\mu \otimes \det^{1/2}$, where μ is an integer sequence, in which case we denote the representation π_λ with

$$\lambda = \left(\mu_1 + \frac{1}{2}, \dots, \mu_n + \frac{1}{2} \right).$$

The Lie algebra of \tilde{K} is the same as the Lie algebra of $K = U(n)$, and is generated by $-iH_X$ where $X \in \mathrm{Mat}_n(\mathbb{C})$ is skew-Hermitian, and $H_X = \mathrm{Ad}(c^{-1})\hat{H}_X$.

Let (π, V) be a $(\mathfrak{g}, \tilde{K})$ -module. If $0 \neq v \in V$ we call v a *semispherical vector* if $\mathbb{C}v$ is stable under K . In this case $\pi(g)v = \det(g)^k v$ when $g \in \tilde{K}$ for some $k \in \frac{1}{2}\mathbb{Z}$, and we call k the *weight* of v . We call v a *holomorphic vector* if it is semispherical, and if $\pi(L_X)v = 0$ for all symmetric X .

The R_X , where $X \in \text{Mat}_n(\mathbb{C})$ are symmetric are an abelian complex Lie subalgebra \mathfrak{R} of $\mathfrak{g}_{\mathbb{C}}$. We may therefore identify the universal enveloping algebra $U(\mathfrak{R})$ and the symmetric algebra $S(\mathfrak{R})$.

Proposition 4. *Let v be a holomorphic vector of weight k in V . Then $S(\mathfrak{R})v$ is an invariant subspace. If π_λ is a representation of \tilde{K} that occurs in the decomposition of $S(\mathfrak{R})v$ over \tilde{K} , then $(\lambda_1 - k, \dots, \lambda_n - k)$ is an even partition. The representation of \tilde{K} on $S(\mathfrak{R})v$ is multiplicity-free.*

Compare Harris [8], Proposition 3.1.

Proof We note that in the adjoint representation $U(n)$ stabilizes

$$\mathcal{R} = \{R_X \mid X \text{ symmetric}\},$$

and the action of $U(n)$ is equivalent to the action on symmetric matrices by

$$(11) \quad U(n) \ni g \longmapsto gX^t g.$$

That is, if $g = A + Bi$ then

$$(12) \quad \text{Ad} \begin{pmatrix} A & B \\ -B & A \end{pmatrix} R_X = R_{gX^t g}.$$

From this it follows that $S(\mathfrak{R})v$ is invariant under \tilde{K} .

To check that it is invariant under $U(\mathfrak{g}_{\mathbb{C}})$, we will show that $U(\mathfrak{g}_{\mathbb{C}})v = S(\mathfrak{R})v$. We note that every element of $U(\mathfrak{g}_{\mathbb{C}})$ can be written as a linear combination of elements of the form

$$R_{X_1} \cdots R_{X_p} H_{Y_1} \cdots H_{Y_q} L_{Z_1} \cdots L_{Z_s}.$$

Unless $s = 0$, such an element kills v . If $s = 0$, then $H_{Y_1} \cdots H_{Y_q} v$ is a constant multiple of v , and so $R_{X_1} \cdots R_{X_p} H_{Y_1} \cdots H_{Y_q} L_{Z_1} \cdots L_{Z_s} v \in S(\mathfrak{R})v$, as required.

We have checked that $S(\mathfrak{R})v$ is a $(\mathfrak{g}, \tilde{K})$ -submodule of V . It is clear from (12) that the action of \tilde{K} is by a quotient of $\det^k \otimes S(\mathfrak{R})$. Now we claim that the action (11) is equivalent to the symmetric square action of $U(n)$ on $\text{Sym}_2(\mathbb{C}^n)$. Indeed, an equivalence is given by

$$v_1 \vee v_2 \longmapsto v_1^t v_2 + v_2^t v_1$$

where v_1 and v_2 are column vectors, so the right-hand side is a square matrix in \mathcal{R} .

The decomposition of $S(\mathcal{R})$ is well-known and essentially due to Littlewood [10]. See Bump [2] Theorem 46.1 or Goodman and Wallach [5] for a proof that

$$(13) \quad S(\mathcal{R}) \cong \bigoplus_{\lambda \text{ an even partition}} \pi_\lambda.$$

Since $S(\mathfrak{A}) \cong \det^k \otimes S(\mathcal{R})$ as \tilde{K} -modules, the statement follows. □

The one-dimensional representations of $U(n)$ that occur in (13) are those of the form $\lambda = (2l, \dots, 2l)$. Thus weights of the semispherical vectors that occur in $S(\mathfrak{A})v$ are a subset of

$$\{(2l + k, \dots, 2l + k) \mid 0 \leq l \in \mathbb{Z}\}.$$

If π is infinite-dimensional these will all occur; for example, this is the case when $S(\mathfrak{A})v$ is a representation of the holomorphic discrete series. However nothing in our assumptions preclude V and hence $S(\mathfrak{A})v$ from being finite-dimensional.

The *Maass operators* which we now introduce shift between these semi-spherical vectors. If $1 \leq i, j \leq n$, let E_{ij} be the square matrix with a 1 in the i, j position and zeros elsewhere, and let $X_{ij} = E_{ij} + E_{ji}$. Let

$$M_+ = \det(R_{X_{ij}}) \in S(\mathfrak{A}).$$

Remark 1. *The notation $\det(R_{X_{ij}})$ is potentially ambiguous. We do not mean the determinant of the matrix $R_{X_{ij}}$. Rather we mean that we regard $R_{X_{ij}}$ as an element of the commutative ring \mathcal{R} , and we form the determinant of the matrix whose i, j entry is $R_{X_{ij}}$.*

For example if $n = 2$, we will denote

$$\hat{R}_1 = \hat{R} \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \quad \hat{R}_2 = \hat{R} \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}, \quad \hat{R}_3 = \hat{R} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad R_i = \text{Ad}(c^{-1})\hat{R}_i.$$

Then $R_{X_{11}} = 2R_1$, $R_{X_{12}} = R_{X_{21}} = R_3$ and $R_{X_{22}} = 2R_2$ so $M_+ = 4R_1R_2 - R_3^2$.

Lemma 2. *Let $g \in \text{GL}(n, \mathbb{C})$, acting on \mathcal{R} and hence on $S(\mathcal{R})$ by $g : X \mapsto gX^t g$. Let \mathcal{M}_+ be the element $\det(R_{ij})$ of $S(\mathcal{R})$. Then \mathcal{M}_+ is multiplied by $\det(g)^2$ in this action.*

Proof If $X \in \mathcal{R}$ let $p_X : \mathcal{R} \rightarrow \mathbb{C}$ be defined by $p_X(Y) = \frac{1}{2} \operatorname{tr}(XY)$. The map $X \mapsto p_X$ extends to an isomorphism α of $S(\mathcal{R})$ onto the ring $P(\mathcal{R})$ of polynomial functions on \mathcal{R} . We let $U(n)$ act on $P(\mathcal{R})$ by $gf(X) = f({}^t g X g)$. Then the map $X \mapsto p_X$ is equivariant. We note that $\alpha(X_{ij})$ is the i, j coordinate function on \mathcal{R} , so $\alpha(\mathcal{M}_+)$ is the determinant map $\mathcal{R} \rightarrow \mathbb{C}$. The statement is now clear. \square

Proposition 5. *Let w be a semispherical vector of weight l in a $(\mathfrak{g}, \tilde{K})$ -module V . If $M_+ w \neq 0$ then $M_+ w$ is semispherical of weight $l + 2$.*

Proof Since H_X with $X \in \operatorname{Mat}_n(\mathbb{C})$ span the complexified Lie algebra of \tilde{K} , the assumption that w be a semispherical vector of weight l amounts to the fact that $H_X w = l \operatorname{tr}(X) w$ for $H \in \operatorname{Mat}_n(\mathbb{C})$. Now

$$H_X M_+ w = [H_X, M_+] w + M_+ H_X w = [H_X, M_+] w + l \operatorname{tr}(X) M_+ w,$$

so the assertion reduces to showing that $[H_X, M_+] = 2 \operatorname{tr}(X) M_+$ in $U(\mathfrak{g}_{\mathbb{C}})$. This is a Lie algebra version of the assertion that $\operatorname{Ad}(g) M_+ = \det(g)^2 M_+$ when $g \in U(n)$. If $g = A + iB$ with A and B real, identified as usual with the symplectic matrix $\begin{pmatrix} A & B \\ -B & A \end{pmatrix}$, then $\operatorname{Ad}(g)$ acts by (12). Thus the statement follows from Lemma 2. \square

Thus if v is a holomorphic vector, M_+ shifts one-dimensional spaces of semispherical vectors in $S(\mathfrak{A})v$, starting with v itself, successively into each other. Similarly $M_- = \det(L_{X_{ij}})$ shifts a semispherical vector of weight l to a semispherical vector of weight $l - 2$.

Conjecture 2. *Let $r \geq 0$ be an integer. If v is a holomorphic vector of weight $-r + \frac{n-1}{2}$ in a $(\mathfrak{g}, \tilde{K})$ -module of $\widetilde{\operatorname{Sp}}(2n, \mathbb{R})$, then $M_+^{r+1} v$ is a holomorphic vector of weight $r + 2 + \frac{n-1}{2}$.*

3. MODULAR FORMS

Theorem 2. *Conjecture 2 implies Conjecture 1.*

Proof Let S be an analytic subset of $\Gamma \backslash \mathcal{H}_n$ of codimension one where the modular form f will be allowed to be polar. Let \mathcal{H}_n^S be the preimage of $\mathcal{H}_n - S$ in \mathcal{H}_n , which is an open set, and let G^S be the preimage of \mathcal{H}_n^S under the map $g \mapsto g(iI_n) = (Ai + B)(Ci + D)^{-1}$, $g = \begin{pmatrix} A & B \\ C & D \end{pmatrix} \in G$. If

$f \in C^\infty(\mathcal{H}_n^S)$ denote

$$(f|_k g)(Z) = j_k(g, Z) f(gZ),$$

where j_k is as in the introduction.

We assume first that k is integral, and discuss the modification needed when k is half-integral afterwards. Let $\mathcal{M}_k^S(\Gamma, \chi)$ be the space of smooth functions on \mathcal{H}_n^S satisfying (3). They are *not* assumed to be holomorphic. The subspace of holomorphic functions will be denoted $M_k^S(\Gamma, \chi)$. Denote by $\mathcal{C}_k(\Gamma \backslash \mathcal{H}_n^S, \chi)$ the space of smooth functions $f : \mathcal{H}_n^S \rightarrow \mathbb{C}$ such that

$$f(Z) = \chi(\gamma) \left(\frac{\det(C\bar{Z} + D)}{|\det(CZ + D)|} \right)^k f(\gamma Z), \quad Z \in \mathcal{H}_n^S, \quad \gamma = \begin{pmatrix} A & B \\ C & D \end{pmatrix} \in \Gamma.$$

Also, let $\mathcal{C}_k(\Gamma \backslash G^S, \chi)$ be the space of smooth functions $f : G^S \rightarrow \mathbb{C}$ such that $f(g) = \chi(\gamma) f(\gamma g)$ for $\gamma \in \Gamma$ and

$$f \left(g \begin{pmatrix} A & B \\ -B & A \end{pmatrix} \right) = \det(\kappa)^k f(g), \quad \kappa = A + Bi \in U(n).$$

If k is half-integral, we modify these definitions as follows. The condition (1) implicitly assumes a choice of square root. We ask that a choice of square root be made in the function

$$(g, Z) \mapsto J_k(g, Z) = \det(CZ + D)^{-k}, \quad g = \begin{pmatrix} A & B \\ C & D \end{pmatrix} \in \mathrm{Sp}(2n, \mathbb{R})$$

which is continuous as a function of Z . (It is not possible to make it continuous of g .) Then

$$\sigma(g_1, g_2) = \frac{J_k(g_1 g_2, Z)}{J_k(g_1, g_2 Z) J_k(g_2, Z)} \in \{\pm 1\}$$

is constant as a function of Z , and satisfies the cocycle relation

$$\sigma(g_1, g_2 g_3) \sigma(g_2, g_3) = \sigma(g_1 g_2, g_3) \sigma(g_1, g_2).$$

Hence this is a 2-cocycle in $H^2(G, \{\pm 1\})$ determining a double cover $\tilde{G} = \widetilde{\mathrm{Sp}}(2n, \mathbb{R})$. It is the same group considered in Section 2. Elements of \tilde{G} are pairs (g, ε) with $g \in G$ and $\varepsilon = \pm 1$, and the multiplication is given by

$$(g_1, \varepsilon_1)(g_2, \varepsilon_2) = (g_1 g_2, \sigma(g_1, g_2) \varepsilon_1 \varepsilon_2).$$

The cocycle relation (2) means that

$$\tilde{\chi}(\gamma, \varepsilon) = \chi(\gamma) \varepsilon$$

is a character of the preimage $\tilde{\Gamma}$ of Γ in \tilde{G} .

Now let \tilde{G}^S be the preimage of G^S in \tilde{G} . Whether k is integral or half-integral we have maps

$$(14) \quad \mathcal{M}_k^S(\Gamma, \chi) \xrightarrow{\det(Y)^{k/2}} \mathcal{C}_k^S(\Gamma \backslash \mathcal{H}_n, \chi) \xrightarrow{\sigma_k} \mathcal{C}_k^S(\tilde{\Gamma} \backslash \tilde{G}^S, \chi).$$

The first map is multiplication by $\det(Y)^{k/2}$, where $Y = \text{im}(Z)$. The second map σ_k is defined by

$$\sigma_k(f)(\tilde{g}) = (f|_k \tilde{g})(i),$$

where if

$$\tilde{g} = \left(\begin{pmatrix} A & B \\ C & D \end{pmatrix}, \varepsilon \right)$$

we define

$$(f|_k \tilde{g})(z) = \varepsilon \frac{\overline{J_k(g, Z)}}{|J_k(g, Z)|} f\left(\frac{AZ + B}{CZ + D}\right).$$

As in the introduction, we can use the exact sequence (14) to transfer the actions of \mathfrak{g} and \tilde{K} to actions on $\mathcal{M}_k^S(\Gamma, \chi)$. Particularly if X is symmetric we have a commutative diagram

$$\begin{array}{ccccc} \mathcal{M}_k(\Gamma, \chi) & \xrightarrow{\det(Y)^{k/2}} & \mathcal{C}_k^S(\Gamma \backslash \mathcal{H}_n, \chi) & \xrightarrow{\sigma_k} & \mathcal{C}_k^S(\tilde{\Gamma} \backslash \tilde{G}, \chi) \\ \mathcal{L}_{k,X} \downarrow & & \mathcal{L}_{k,X} \downarrow & & \mathcal{L}_X \downarrow \\ \mathcal{M}_{k-2}(\Gamma, \chi) & \xrightarrow{\det(Y)^{(k-2)/2}} & \mathcal{C}_{k-2}^S(\Gamma \backslash \mathcal{H}_n, \chi) & \xrightarrow{\sigma_k} & \mathcal{C}_{k-2}^S(\tilde{\Gamma} \backslash \tilde{G}, \chi) \end{array}$$

where the operator $\mathcal{L}_{k,X}$ is determined by the commutativity of the diagram. The operators $\mathcal{L}_{k,X}$ are made explicit in Harris [8], Section 2.3.1, and they are linear combinations of $\partial/\partial \bar{Z}_{ij}$ where Z_{ij} are the matrix coefficients of Z . Thus as in [8], $\mathcal{L}_{k,X}f = 0$ for all X if and only if f is holomorphic. Thus f is holomorphic if and only if its image in $\mathcal{C}_k^S(\tilde{\Gamma} \backslash \tilde{G}, \chi)$ is a holomorphic vector v in the $(\mathfrak{g}, \tilde{K})$ -module it generates.

Similarly there are operators $\mathcal{R}_{k,X}$ determined by the commutativity of

$$\begin{array}{ccccc} \mathcal{M}_k(\Gamma, \chi) & \xrightarrow{\det(Y)^{k/2}} & \mathcal{C}_k^S(\Gamma \backslash \mathcal{H}_n, \chi) & \xrightarrow{\sigma_k} & \mathcal{C}_k^S(\tilde{\Gamma} \backslash \tilde{G}, \chi) \\ \mathcal{R}_{k,X} \downarrow & & \mathcal{R}_{k,X} \downarrow & & \mathcal{R}_X \downarrow \\ \mathcal{M}_{k+2}(\Gamma, \chi) & \xrightarrow{\det(Y)^{(k+2)/2}} & \mathcal{C}_{k+2}^S(\Gamma \backslash \mathcal{H}_n, \chi) & \xrightarrow{\sigma_k} & \mathcal{C}_{k+2}^S(\tilde{\Gamma} \backslash \tilde{G}, \chi) \end{array}$$

these too are made explicitly in Harris [8], Section 1.5.1. If $X_{ij} = E_{ij} + E_{ji}$, where E_{ij} is the elementary matrix with 1 in the i, j position and zeros

elsewhere, then

$$R_{k,X_{ij}} = (\det Y)^{\frac{n+1-k}{2}} \frac{\partial}{\partial Z_{ij}} (\det Y)^{\frac{k-n+1}{2}}.$$

and

$$\mathcal{R}_{k,X_{ij}} = (\det Y)^{\frac{n-1}{2}-k} \frac{\partial}{\partial Z_{ij}} (\det Y)^{-\frac{n-1}{2}+k},$$

It is clear that applying

$$\mathbb{M}_k = \det(\mathcal{R}_{k,X_{ij}})$$

to f gives a linear combination of terms, one of which is $2^n \mathbb{D}_n^{r+1} f$, and the others are combinations of products of lower order derivatives of f times various minors of Y . The only way this can be holomorphic is if all these other terms cancel. However the image of $\mathbb{M}_k f$ in $C_{r+2+\frac{n-1}{2}}^S(\tilde{\Gamma} \backslash \tilde{G}, \chi)$ is precisely $M_+^{r+1} v$, which by Conjecture 2 is a holomorphic vector. Hence the nonholomorphic terms of $\mathbb{M}_k f$ must cancel, and $2^n \mathbb{D}_n^{r+1} f = \mathbb{M}_k f$. We have excluded the set S from these considerations but this is no problem since $\mathbb{D}_n^{r+1} f$ is a derivative of a meromorphic function, hence meromorphic. \square

4. COMPUTATIONS IN $\mathrm{Sp}(4, \mathbb{R})$

Since $\mathrm{Sp}(4, \mathbb{R})$ has real rank equal to its complex rank, the ring of invariant differential operators on G may be identified with the ring of invariant differential operators on its homogeneous space \mathcal{H}_2 , or with the center \mathcal{Z} of its universal enveloping algebra. Let $\mathfrak{g} = \mathfrak{sp}(4, \mathbb{R})$ and if $X \in \mathrm{Mat}_2(\mathbb{C})$ let

$$\hat{H}_X = \begin{pmatrix} X & \\ & -{}^t X \end{pmatrix} \in \mathfrak{g}_{\mathbb{C}} = \mathfrak{sp}(4, \mathbb{C}).$$

If X is symmetric, let

$$\hat{R}_X = \begin{pmatrix} 0 & X \\ 0 & 0 \end{pmatrix}, \quad \hat{L}_X = \begin{pmatrix} 0 & 0 \\ X & 0 \end{pmatrix}.$$

Let

$$\begin{aligned} \hat{H}_0 &= \hat{H} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, & \hat{H}_1 &= \hat{H} \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, & \hat{H}_2 &= \hat{H} \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, & \hat{H}_3 &= \hat{H} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \\ \hat{R}_1 &= \hat{R} \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, & \hat{R}_2 &= \hat{R} \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}, & \hat{R}_3 &= \hat{R} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \\ \hat{L}_1 &= \hat{L} \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, & \hat{L}_2 &= \hat{L} \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}, & \hat{L}_3 &= \hat{L} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}. \end{aligned}$$

We also use the same notation without the “hats” for the corresponding Lie group elements obtained by applying $\text{Ad}(c^{-1})$. Thus

$$H_i = \text{Ad}(c^{-1})\hat{H}_i, \quad R_i = \text{Ad}(c^{-1})\hat{R}_i, \quad L_i = \text{Ad}(c^{-1})\hat{L}_i.$$

Note that $H_i \in \mathbb{C} \otimes \text{Lie}(K)$.

Let $S(\mathfrak{g}_{\mathbb{C}})$ and $U(\mathfrak{g}_{\mathbb{C}})$ denote the symmetric algebra and universal enveloping algebra, respectively, of $\mathfrak{g}_{\mathbb{C}}$. Let $\lambda : S(\mathfrak{g}_{\mathbb{C}}) \rightarrow U(\mathfrak{g}_{\mathbb{C}})$ denote the symmetrization map, defined by

$$\lambda(X_1 \cdots X_d) = \frac{1}{d!} \sum_{w \in S_d} X_{\sigma(1)} \cdots X_{\sigma(d)}.$$

It is *not* a ring homomorphism.

Proposition 6. *The center \mathcal{Z} of $U(\mathfrak{g}_{\mathbb{C}})$ is a polynomial ring with two generators, of degrees 2 and 4, respectively. They are $\mathfrak{D}_2 = \lambda(D_2)$ and $\mathfrak{D}_4 = \lambda(D_4)$, where D_2 and D_4 are the following $\text{ad}(\mathfrak{g})$ -invariant elements of $S(\mathfrak{g}_{\mathbb{C}})$. Of degree 2:*

$$D_2 = H_0^2 + 4H_1H_2 + H_3^2 + 8L_1R_1 + 8L_2R_2 + 4L_3R_3,$$

and of degree 4:

$$\begin{aligned} D_4 = & 4H_0^2H_1H_2 + H_0^2H_3^2 + 16H_1H_2L_1R_1 + 8H_0H_3L_1R_1 - 16H_2^2L_2R_1 \\ & + 8H_0H_2L_3R_1 - 8H_2H_3L_3R_1 + 16L_1^2R_1^2 - 16H_1^2L_1R_2 \\ & + 16H_1H_2L_2R_2 - 8H_0H_3L_2R_2 + 8H_0H_1L_3R_2 \\ & + 8H_1H_3L_3R_2 - 32L_1L_2R_1R_2 + 16L_3^2R_1R_2 + 16L_2^2R_2^2 \\ & + 8H_0H_1L_1R_3 - 8H_1H_3L_1R_3 + 8H_0H_2L_2R_3 + 8H_2H_3L_2R_3 \\ & + 4H_3^2L_3R_3 + 16L_1L_3R_1R_3 + 16L_2L_3R_2R_3 + 16L_1L_2R_3^2 \end{aligned}$$

Proof According to a well-known theorem of Harish-Chandra (essentially Lemma 36 of [6], or see Helgason [9]), if $\mathfrak{g}_{\mathbb{C}}$ is a complex semisimple Lie algebra of rank r , the center \mathcal{Z} of $U(\mathfrak{g}_{\mathbb{C}})$ is isomorphic to the ring of invariants of the Weyl group W , which is a polynomial ring in r variables by a theorem of Chevalley [3]. The degrees d_1, \dots, d_r can be computed by a theorem of Solomon [14], which says that if e_p is the p -th elementary symmetric polynomial ($p \leq r$) and if $m_p = d_p - 1$ then $e_p(d_1, \dots, d_r)$ is the number of Weyl group elements whose fixed points have codimension p in the action of W on \mathbb{R}^r . If $\mathfrak{g}_{\mathbb{C}} = \mathfrak{sp}(4, \mathbb{C})$ this means that $m_1 + m_2 = 4$ while $m_1m_2 = 3$, so $m_1 = 1$ and $m_2 = 3$. Thus d_1 and d_2 are 2 and 4, as stated.

If $X \in \mathfrak{g}$ then $\text{ad}(X) : \mathfrak{g}_{\mathbb{C}} \rightarrow \mathfrak{g}_{\mathbb{C}}$ extends to a derivation of $S(\mathfrak{g}_{\mathbb{C}})$, given by

$$\text{ad}(X)(Y_1 \cdots Y_r) = \sum_{i=0}^r Y_1 \cdots Y_{i-1} (\text{ad}(X)Y_i) Y_{i+1} \cdots Y_r.$$

Applying λ and making use of the fact that $\text{ad}(X)Y = XY - YX$ in $U(\mathfrak{g})$ gives

$$\frac{1}{r!} \sum_{\sigma \in S_r} \sum_{i=0}^r Y_{\sigma(1)} \cdots Y_{\sigma(i-1)} (XY_{\sigma(i)} - Y_{\sigma(i)}X) Y_{\sigma(i+1)} \cdots Y_{\sigma(r)},$$

so after cancellation

$$(15) \quad \lambda(\text{ad}(X)(Y_1 \cdots Y_r)) = X\lambda(Y_1 \cdots Y_r) - \lambda(Y_1 \cdots Y_r)X.$$

Let $S(\mathfrak{g}_{\mathbb{C}})^{\text{ad}(\mathfrak{g})} = \{\alpha \in S(\mathfrak{g}_{\mathbb{C}}) \mid \text{ad}(X)\alpha = 0 \text{ for all } X \in \mathfrak{g}\}$ be the space of $\text{ad}(\mathfrak{g})$ -invariants. Then (15) shows that λ takes $S(\mathfrak{g}_{\mathbb{C}})^{\text{ad}(\mathfrak{g})}$ into \mathcal{Z} .

Elements of $S(\mathfrak{g}_{\mathbb{C}})^{\text{ad}(\mathfrak{g})}$ can be computed using a computer algebra package such as Mathematica. There is little point in reproducing these computations here, but let us offer a word as to how they were done. One starts with a general polynomial F of given degree in a set of generators, which one can represent as functions of an independent variable \mathfrak{t} . The polynomial F may be taken to be homogeneous. Thus for $\mathfrak{sp}(4)$, there will be 10 variables, and 55 terms for a homogeneous polynomial of degree 2 or 715 for a homogeneous polynomial of degree 4. Let Y be another element of the Lie algebra. Denoting the variables as $X_1[\mathfrak{t}], X_2[\mathfrak{t}], \dots$ one may then differentiate the polynomial $F[X_1[\mathfrak{t}], X_2[\mathfrak{t}], \dots]$ with respect to \mathfrak{t} , then wherever a derivative $X_i'[\mathfrak{t}]$ occurs, substitute the value of $[Y, X_i]$. This gives the value of $\text{ad}(Y)$ applied to F . Setting this to zero gives a set of linear equations in the coefficients, and solving these gives the ad invariants. In the case at hand, one arrives at the two generators listed above. Clearly $\lambda(D_2)^2$ and $\lambda(D_4)$ are linearly independent since $\lambda(D_4)$ does not involve the monomial H_0^4 , and since we know \mathcal{Z} is a polynomial ring in two variables, with generators in these degrees, they must be generators. \square

Remark 2. *We made use of the fact that $S(\mathfrak{g}_{\mathbb{C}})^{\text{ad}} \subseteq \mathcal{Z}$. It was shown by Harish-Chandra [7], Corollary at the bottom of p. 192 that $\lambda : S(\mathfrak{g}_{\mathbb{C}})^{\text{ad}} \rightarrow \mathcal{Z}$ is a linear isomorphism, though we do not need the surjectivity of this map. (See Helgason [9], Theorem 4.3 on p. 270.) It is of course not a ring homomorphism.*

Let \mathcal{J} be the left ideal generated by H_1, H_2, H_3, L_1, L_2 and L_3 .

Theorem 3. *We have*

$$\mathfrak{D}_2 \equiv H_0^2 - 6H_0, \quad \mathfrak{D}_4 \equiv -2H_0^2 + 12H_0 \quad \text{mod } \mathcal{J}.$$

In particular $2\mathfrak{D}_2 + \mathfrak{D}_4 \in \mathcal{J}$.

Proof The computation proceeds by examining each term in D_i , applying λ to it, and writing it as a polynomial in H_0 modulo \mathcal{J} . We omit the details, which can be most easily checked using a computer. \square

Corollary 1. *If v is a holomorphic vector of weight k , then $\pi(\mathfrak{D}_2)$ and $\pi(\mathfrak{D}_4)$ act as scalars on $S(\mathfrak{R})v$, with eigenvalues $4(k^2 - 3k)$ and $-8(k^2 - 3k)$, respectively.*

Proof This is because $\pi(H_0)v = 2kv$, while \mathcal{J} annihilates v . \square

Now let r be a positive integer, and let $\alpha = r^2 + 2r - \frac{5}{4}$. Thus α is the value of $k^2 - 3k$ when $k = -r + \frac{1}{2}$. The equation

$$k^2 - 3k = \alpha$$

has two roots $k = r_1$ and $k = r_2$ such that $r_1 + r_2 = 3$. Since one root $r_1 = -r + \frac{1}{2}$, the other root is $r + \frac{5}{2}$. Thus if v is a holomorphic vector of weight $-r + \frac{1}{2}$ and we apply M_+ to this vector $r + 1$ times, we expect to obtain another holomorphic vector.

Theorem 4. *Conjecture 2 is true if $n = 2$.*

Proof Let v be a holomorphic vector of weight $-r + \frac{1}{2}$ in a $(\mathfrak{g}, \tilde{K})$ -module V , and let $w = M_+^{r+1}v$. We will show that w is holomorphic.

The first step is to show that $M_-w = 0$. Let \mathcal{J} be the left ideal generated by H_1, H_2 and H_3 and L_1, L_2, L_3 . Apply \mathfrak{D}_2 and \mathfrak{D}_4 to v . Since \mathcal{J} annihilates v and H_0 has eigenvalue $1 - 2r$, by Theorem 3 we have $\mathfrak{D}_2v = \delta v$ and $\mathfrak{D}_4v = -2\delta v$ where

$$\delta = (1 - 2r)^2 - 6(1 - 2r) = 4r^2 + 8r - 5.$$

Now since \mathfrak{D}_2 and \mathfrak{D}_4 commute with $\mathfrak{g}_{\mathbb{C}}$, they have the same eigenvalues applied to any vector in the space.

Let $u = M_+^r v$, and let \mathcal{J} be the left ideal generated by H_1, H_2 and H_3 . Since u is semispherical, it is annihilated by \mathcal{J} . A computer calculation shows that if $M_+ = 4R_1R_2 - R_3^3$ and $M_- = 4L_1L_2 - L_3^2$ then

$$\begin{aligned} 16M_-M_+ + 4\mathfrak{D}_4 - \mathfrak{D}_2^2 + 8H_0\mathfrak{D}_2 + 2H_0^2\mathfrak{D}_2 &\equiv \\ H_0^4 + 8H_0^3 + 4H_0^2 - 48H_0 \text{ mod } \mathcal{J}. \end{aligned}$$

Thus both sides have the same effect on u . Since $M_-M_+u = M_-w$, and since $H_0u = hu$, with $h = 2r + 1$, we have

$$16M_-w - 8\delta w - \delta^2 w + 8h\delta w + 2h^2\delta w = (h^4 + 8h^3 + 4h^2 - 48h)w.$$

But

$$-8\delta - \delta^2 + 8h\delta + 2h^2\delta = h^4 + 8h^3 + 4h^2 - 48h.$$

(Both equal $16r^2 + 96r^3 + 136r^2 - 24r - 35$.) Therefore $M_-w = 0$.

Now suppose that w is not holomorphic. We have

$$\begin{aligned} [H_1, L_1] &= -L_3, & [H_1, L_2] &= 0, & [H_1, L_3] &= -2L_2, \\ [H_2, L_1] &= 0, & [H_2, L_2] &= -L_3, & [H_2, L_3] &= -2L_1, \\ [H_3, L_1] &= -2L_1, & [H_3, L_2] &= 2L_2, & [H_3, L_3] &= 0. \end{aligned}$$

Since $H_iw = 0$ with $i = 1, 2, 3$ this implies that

$$\begin{aligned} H_1L_1w &= -L_3w, & H_1L_2w &= 0, & H_1L_3w &= -2L_2w, \\ H_2L_1w &= 0, & H_2L_2w &= -L_3w, & H_2L_3w &= -2L_1w, \\ H_3L_1w &= -2L_1w, & H_3L_2w &= 2L_2w, & H_3L_3w &= 0. \end{aligned}$$

Also

$$H_0L_1w = (2r+3)L_1w, \quad H_0L_2w = (2r+3)L_2w, \quad H_0L_3w = (2r+3)L_3w.$$

Similarly using $H_iu = 0$ with $i = 1, 2, 3$ we can compute

$$\begin{aligned} H_1R_1u &= 0, & H_1R_2u &= R_3u, & H_1R_3u &= 2R_1u, \\ H_2R_1u &= R_3u, & H_2R_2u &= 0, & H_2R_3u &= 2R_2u, \\ H_3R_1u &= 2R_1u, & H_3R_2u &= -2R_2u, & H_3R_3u &= 0, \end{aligned}$$

and we also have

$$H_0R_1w = (2r+3)R_1w, \quad H_0R_2w = (2r+3)R_2w, \quad H_0R_3w = (2r+3)R_3w.$$

We recall that the H_i span the complexified Lie algebra $\mathfrak{k}_{\mathbb{C}}$ of \tilde{K} , the double cover of $SU(2)$. Since we are assuming that L_iu are not all zero, we see that both L_iu and R_iu span isomorphic \tilde{K} -modules. By Proposition 4 the space $S(\mathfrak{R})v$ is multiplicity-free over \tilde{K} , so these two sets of vectors span the same three-dimensional vector space. Moreover,

$$L_1w \mapsto R_2u, \quad L_2w \mapsto R_1u, \quad L_3w \mapsto -R_3u$$

is an isomorphism with respect to $\mathfrak{k}_{\mathbb{C}}$, so by Schur's Lemma, this map is a constant multiple of the identity map. Thus there is a nonzero constant c such that $cL_1w = R_2u$, $cL_2w = R_1u$ and $cL_3w = -R_3u$. This means that

$$2L_1R_1u + 2L_2R_2u + L_3R_3u = 2L_1L_2w + 2L_2L_1w - L_3^2w = M_-w = 0.$$

We can write

$$\mathfrak{D}_2 = H_0^2 + 2H_1H_2 + 2H_2H_1 + H_3^2 + 6H_0 + 8L_1R_1 + 8L_2R_2 + 4L_3R_3.$$

We apply this to u , recalling that \mathfrak{D}_2 acts by the scalar $4r^2 + 8r - 5$ on the entire space. We obtain

$$(4r^2 + 8r - 5)u = (H_0^2 + 2H_1H_2 + 2H_2H_1 + H_3^2 + 6H_0)u.$$

Since $H_0u = (2r + 1)u$ while $H_iu = 0$ when $i = 1, 2, 3$, this means that

$$(4r^2 + 8r - 5)u = ((2r + 1)^2 + 6(2r + 1))u = (4r^2 + 16r + 7)u$$

Simplifying gives $8r + 12 = 0$. This is a contradiction since $r \geq 0$. This proves the holomorphicity of w . \square

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