NON-UNITARY SET-THEORETICAL SOLUTIONS TO THE QUANTUM YANG-BAXTER EQUATION

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ABSTRACT. We develop a theory of non-unitary set-theoretical solutions to the Quantum Yang-Baxter equation. Our results generalize those obtained by Etingof, Schedler and the author in [ESS]. We remark that some of our constructions are similar to constructions obtained by Lu, Yan, and Zhu in [LYZ].

1. Introduction

In this paper we study set-theoretical solutions to the Quantum Yang-Baxter equation, i.e. permutations $R: X \times X \to X \times X$ with X being a non-empty set such that

$$R^{12}R^{13}R^{23} = R^{23}R^{13}R^{12}$$
 in $Aut(X \times X \times X)$.

In the above R^{12} , R^{13} , $R^{23} \in \operatorname{Aut}(X \times X \times X)$ stand for R acting in 1,2; 1,3; and 2,3 components of $X \times X \times X$ correspondingly. The idea to consider set-theoretical solutions first appeared in [Dr]. Later on, Etingof, Schedler and the author [ESS] studied set-theoretical solutions to the Quantum Yang-Baxter equation which satisfied additional properties of unitarity and nondegeneracy (crossing symmetry). In particular, [ESS] contained the classification of nondegenerate unitary set-theoretical solutions to QYBE in group theoretical terms as well as numerous classes of examples of such solutions. Subsequently, Lu, Yan and Zhu in [LYZ] showed that many of the constructions from [ESS] hold in a more general case of nondegenerate but not necessarily unitary set-theoretical solutions to QYBE.

Following [ESS] and [LYZ], we develop a theory of nondegenerate settheoretical solutions to QYBE. Particularly, we show that the unitarity condition that was used in [ESS] for group theoretical characterization of unitary nondegenerate set-theoretical solutions to QYBE can be dropped. We give a group theoretical characterization of general set-theoretical nondegenerate solutions to QYBE in Theorem 2.7. We also introduce injective solutions, study their properties, and show that there is a combinatorial criterion (Theorem 2.9) describing the class of injective nondegenerate solutions to QYBE. Injectivity property, which is a generalization of involutivity, is important for studying affine solutions. In particular the classification of unitary affine solutions given in [ESS] can be generalized to include injective solutions.

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It was shown in [ESS] that the structure group of a nondegenerate unitary set-theoretical solution to QYBE on a set with N elements always has an abelian subgroup of finite index and of rank N. We compute (Theorem 2.10) the rank of a finite index abelian subgroup of the structure group for an arbitrary nondegenerate finite solution and show that this rank never exceeds N, with the equality taking place only in the unitary case.

In the second part of the paper we discuss the applications of the developed theory to examples. In particular, we classify affine solutions on an abelian group. It is proved that injective affine solutions are obtained from the representations of the algebra generated by invertible elements p, q, and z are subject to pq = qp and $z^2 - z(p+q) + pq = 0$.

2. Structure groups

2.1. Construction of the structure groups. Let X be a nonempty set and $S: X \times X \to X \times X$ a bijective map. We call a pair (X, S) a braided set if the following braiding condition holds in $X \times X \times X$:

(2.1) $S_1 S_2 S_1 = S_2 S_1 S_2 \,,$

where $S_1 = S \times id$, $S_2 = id \times S$.

Remark. Consider the map $R : X \times X \to X \times X$ given by $R = \sigma S$, where $\sigma(x, y) = (y, x)$ for $x, y \in X$. Then (X, S) is a braided set if and only if R satisfies the Quantum Yang-Baxter equation.

It is useful to associate with a braided set (X, S) two groups G_X and A_X .

Definition 1. Define the group G_X as the group generated by the elements of X subject to the relations $xy = y_1x_1$ if $S(x, y) = (y_1, x_1)$, where $x, y \in X$. We call G_X the structure group of the braided set (X, S).

Definition 2. Define the group A_X as the group generated by elements of X subject to relations $x_1 \bullet y = y_2 \bullet x_1$, where $x, y \in X$ and $x_1, y_2 \in X$ are defined out of relations $S(x, y) = (y_1, x_1)$, $S(y_1, x_1) = (x_2, y_2)$. We call A_X the derived structure group of the braided set (X, S).

We introduce the maps $g: X \times X \to X$ and $f: X \times X \to X$ as components of S, i.e. for $x, y \in X$,

$$S(x, y) = (g_x(y), f_y(x)).$$

Definition 3. (i) We call a set (X, S) nondegenerate if $g_x(y)$ is a bijective function of y for fixed x and $f_y(x)$ is a bijective function of x for fixed y. (ii) We call a set (X, S) involutive if $S^2 = id_{X^2}$. A braided set which is involutive will be called symmetric.

In particular, for a symmetric set (X, S) we see that the group A_X is the free abelian group generated by elements of X. Note that the properties of involutivity and nondegeneracy are equivalent to corresponding properties of unitarity and crossing symmetry for the map $R = \sigma S$ [ESS].

Recall that the braid group B_n for $n \ge 2$ is generated by elements b_i , $1 \le i \le n-1$, with defining relations

$$b_i b_j = b_j b_i, \ |i - j| > 1, \ b_i b_{i+1} b_i = b_{i+1} b_i b_{i+1},$$

and recall that the symmetric group S_n is the quotient of B_n by the relations $b_i^2 = 1$. The following obvious proposition explains our terminology. Let $S_n^{ii+1} : X^n \to X^n$ be defined as $S_n^{ii+1} = id_{X^{i-1}} \times S \times id_{X^{n-i-1}}$.

Theorem 2.1 ([ESS]). (i) The assignment $b_i \to S_n^{ii+1}$ extends to an action of B_n on X^n $(n \ge 3)$ if and only if (X, S) is a braided set. (ii) The assignment $b_i \to S_n^{ii+1}$ extends to an action of S_n on X^n $(n \ge 3)$ if

(ii) The assignment $b_i \to S_n^{n+1}$ extends to an action of S_n on X^n $(n \ge 3)$ if and only if (X, S) is a symmetric set.

Definition 4. The action of Theorem 2.1 is called the twisted action of B_n (or S_n) given by S.

The following result shows how a nondegenerate braided set (X, S) gives rise to two actions of the structure group G_X on the set X.

Theorem 2.2. ([ESS]) Suppose that (X, S) is nondegenerate. Then (X, S) is a braided set if and only if the following conditions are simultaneously satisfied:

- (i) the assignment $x \to f_x$ is a right action of G_X on X;
- (ii) the assignment $x \to g_x$ is a left action of G_X on X;
- (iii) the linking relation

$$f_{g_{f_y(z)}(z)}(g_x(y)) = g_{f_{g_y(z)}(x)}(f_z(y))$$

holds.

Proof. Conditions (i)-(iii) are exactly the three components of the braid relation (2.1).

In light of the above proposition it makes sense to introduce the notations $x \circ y = g_x(y)$ and $y * x = f_y^{-1}(x)$ for $x, y \in X$. Then if (X, S) is a nondegenerate braided set, we can extend * and \circ to left actions of G_X on X. We will denote the actions of an element $g \in G_X$ on an element $x \in X$ by $g \circ x$ and g * x correspondingly.

From now on we always assume (X, S) to be a nondegenerate braided set. Sometimes we refer to nondegenerate braided sets as to "solutions", meaning that S is a solution to braid equation (2.1).

Define $\phi: X \times X \to X$ by

(2.2)
$$\phi(y,x) = x^{-1} * ((y * x) \circ y),$$

and $S': X \times X \to X \times X$ as $S'(x, y) = (\phi(y, x), x)$.

Theorem 2.3. (i) $\phi(y, z)$ is G_X -invariant w.r.t. *-action, i.e. for $g \in G_X$, $g * \phi(y, z) = \phi(g * y, g * z)$.

(ii) (X, S') is a nondegenerate braided set. We call this set the derived braided set or the derived solution.

(iii) The structure group of the derived solution is the derived structure group.

(iv) For each integer $n \geq 2$ there exists a bijection $J_n : X^n \to X^n$ such that $J_n S_n^{ii+1} J_n^{-1} = (S')_n^{ii+1}$, where S_n^{ii+1} is the same as in Theorem 2.1. In this way, twisted actions of B_n given by S and S' are conjugate.

We remark that the statement (iv) of Theorem 2.3 was proved in [ESS] (cf. Prop. 1.7) for unitary solutions and in [LYZ] (cf. Th. 3) for injective solutions that are defined in Section 2.3.

Proof. It is easy to see that (iv) implies (ii). Statement (iii) follows from definitions of structure group, derived structure group and ϕ . Let us show that (i) implies (iv). Define J_n inductively as $J_1 = id_X$, $J_n = Q_n(J_{n-1} \times id_X)$, where $Q_n : X^n \to X^n$ is defined as $Q_n(x_1, ..., x_n) = (x_n^{-1} * x_1, ..., x_n^{-1} * x_{n-1}, x_n)$. We prove formula $J_n S_n^{ii+1} J_n^{-1} = (S')_n^{ii+1}$ by induction on n. For n = 2 (induction base) the relation follows directly from definition of ϕ . Suppose the relation holds for n = k, let us prove it holds for n = k+1. Since $J_{k+1} = Q_{k+1}(J_k \times id_X)$ and Q_{k+1} commutes with $(S')_{k+1}^{ii+1}$ for i < k (by (i)) the relation is true for i < k. So, it remains to prove it for i = k when it becomes identical to the relation of the induction base.

Now we have to show that (i) is true. It is enough to check that for every $t, y, z \in X$, $t^{-1} * \phi(y, z) = \phi(t^{-1} * y, t^{-1} * z)$ or, equivalently by (2.2):

$$\begin{array}{ll} (2.3) \quad t^{-1}*(z^{-1}*((y*z)\circ y))=\\ & (t^{-1}*z)^{-1}*(((t^{-1}*y)*(t^{-1}*z))\circ(t^{-1}*y)). \end{array}$$

The linking relation of Theorem 2.2 states that for $x, y, t \in X$

(2.4)
$$((y^{-1} * x) \circ t)^{-1} * (x \circ y) = ((y \circ t)^{-1} * x) \circ (t^{-1} * y)$$

holds. If we substitute x = y * z in relation (2.4) we can rewrite its right hand side as follows:

$$((y \circ t)^{-1} * (y * z)) \circ (t^{-1} * y) = ((y \circ t)^{-1} * (yt * (t^{-1} * z))) \circ (t^{-1} * y)$$

where the product yt is the product of elements y, t in group G_X , thus $yt = (y \circ t)(t^{-1} * y)$ and

$$((y \circ t)^{-1} * (yt * (t^{-1} * z))) \circ (t^{-1} * y) = ((t^{-1} * y) * (t^{-1} * z)) \circ (t^{-1} * y).$$

In this way, relation (2.4) is equivalent to relation (2.5) below:

(2.5)
$$(z \circ t)^{-1} * ((y * z) \circ y) = ((t^{-1} * y) * (t^{-1} * z)) \circ (t^{-1} * y).$$

Substituting, (2.5) into the right side of (2.3) we get

 $(t^{-1}*z)^{-1}*(((t^{-1}*y)*(t^{-1}*z))\circ(t^{-1}*y)) = ((t^{-1}*z)^{-1}(z\circ t)^{-1})*((y*z)\circ y).$ Using the relation $t^{-1}z^{-1} = (t^{-1}*z)^{-1}(z\circ t)^{-1}$ in group G_X we verify that invariance relation (2.3) is true. The theorem is proved.

Note that by construction we have two natural maps $\psi_G : X \to G_X$ and $\psi_A : X \to A_X$ that are not necessarily embeddings (see Examples below). Theorem 2.4 shows that the latter map is G_X -invariant with respect to a suitable G_X -module structure on A_X . Define the group Permut(X) as the group of all permutations of the set X. Then both * and \circ define homomorphisms from G_X to Permut(X). Denote by $\operatorname{Aut}_X(A_X)$ the group of automorphisms of A_X that map the generating set $\psi_A(X)$ onto itself.

Theorem 2.4. For a nondegenerate braided set (X, S) the group homomorphism $*: G_X \to \text{Permut}(X)$ can be uniquely lifted to the homomorphism $\hat{*}: G_X \to \text{Aut}_X(A_X)$ such that for any $g \in G_X$, $x \in X \ \psi_A(g * x) = g \hat{*} \psi_A(x)$.

Proof. It is clear that the map $*: G_X \to \text{Permut}(X)$ can be uniquely extended to the homomorphism from the group G_X to the group of automorphisms of the free group generated by X. So, it is enough to show that such an extension respects the generating relations in group A_X . This immediately follows from statements (i), (iii) of Theorem 2.3.

Example [Dr]. Let X be a union of conjugacy classes in a group G, i.e. $gXg^{-1} = X$ for any $g \in G$. Define $S : X \times X \to X \times X$ as $S(x, y) = (xyx^{-1}, x)$ for $x, y \in X$. It is easy to see that (X, S) is a braided nondegenerate set. It was called the conjugate solution in [LYZ]. Clearly, this solution coincides with its own derived solution - therefore $G_X = A_X$. The action of G_X on A_X is easily seen to be trivial, i.e. $g \hat{*} h = h$ for any $g \in G_X$, $h \in A_X$. The embedding $i : X \to G$ can be extended to a homomorphism $I : G_X \to G$ that maps elements of $\psi_G(X)$ onto X, thus the map $\psi_G : X \to G_X$ is injective. So (X, S) is an injective solution (cf. Definition 8).

2.2. Bijective 1-cocycle. Recall that we started with a nondegenerate braided set (X, S) and constructed two groups G_X , A_X and the action $\hat{*}$ of G_X on A_X . In the future we drop $\hat{~}$ in $\hat{*}$ and denote the action of $g \in G_X$ on $h \in A_X$ from Theorem 2.4 simply by g * h. Theorem 2.5 is the main step towards classification of nondegenerate braided sets in group theoretical terms.

Definition 5. Suppose a group G acts on a group A by automorphisms meaning that there is a homomorphism from G to Aut(A). Denote the product of elements g_1, g_2 in G by g_1g_2 and the product of elements a_1, a_2 in A by $a_1 \bullet a_2$. We call a map $\pi: G \to A$ a 1-cocycle if for any $g_1, g_2 \in G$

(2.6) $\pi(g_1g_2) = (g_2^{-1} * \pi(g_1)) \bullet \pi(g_2)$

where * stands for the action of G on A.

Theorem 2.5. (cf. [LYZ], Th. 2 and [ESS], Prop. 2.5) For a nondegenerate braided set (X, S) there exists a unique bijective 1-cocycle $\pi : G_X \to A_X$ such that $\pi \psi_G = \psi_A$ on X.

Remark. In [LYZ] the authors introduced on G_X another group structure. It follows from our and their results that G_X with the new group structure is isomorphic to A_X via $\pi: G_X \to A_X$.

Proof. Construction of the 1-cocycle.

Let us construct the 1-cocycle $\pi : G_X \to A_X$. Consider the semidirect product $G_X \ltimes A_X$. The group $G_X \ltimes A_X$ consists of pairs $(g, h), g \in G_X, h \in A_X$ with the group operation given by the formula

$$(g,h)(g',h') = (gg',((g')^{-1}*h) \bullet h').$$

Define the map $s: X \to G_X \ltimes A_X$ via the formula $s(x) = (\psi_G(x), \psi_A(x))$ for any $x \in X$. We claim that there exists a group homomorphism $\bar{s}: G_X \to G_X \ltimes A_X$ such that $\bar{s}\psi_G = s$. Indeed, since $\psi_G(X)$ generates the whole G_X to show that \bar{s} exists it is necessary and sufficient to check that s respects the relations in G_X , i.e. that for $x, y \in X$ s(x)s(y) is equal to $s(x \circ y)s(y^{-1} * x)$ in group $G_X \ltimes A_X$. When we formally multiply terms out, the above condition transforms into the relation

$$(xy, (y^{-1} * x) \bullet y) = ((x \circ y)(y^{-1} * x), ((y^{-1} * x)^{-1} * (x \circ y)) \bullet (y^{-1} * x)),$$

which coincides componentwise with the defining relations in groups G_X , A_X . Let us define the projection $p: G_X \ltimes A_X \to A_X$ by the formula p(g,h) = h. Introduce $\pi: G_X \to A_X$ as $\pi = p\bar{s}$. Clearly, π is a 1-cocycle. The tricky part is to show that π is bijective.

Proof that π is bijective.

Lemma 1. (i) For $x_1, x_2 \in X, g \in G_X$ if $\psi_G(x_1) = \psi_G(x_2)$ then $\psi_G(g * x_1) = \psi_G(g * x_2)$ and $\psi_G(g \circ x_1) = \psi_G(g \circ x_2)$.

(ii) For $x \in X$ $\psi_G((x*x) \circ x) = \psi_G(x*x)$ and $\psi_G((x^{-1} \circ x)^{-1}*x) = \psi_G(x^{-1} \circ x)$. (iii) For $x \in X$ $\psi_G(x) = \psi_G((x*x)^{-1} \circ (x*x)) = \psi_G((x^{-1} \circ x) * (x^{-1} \circ x))$.

To prove the lemma we notice that $S(x * x, x) = ((x * x) \circ x, x)$ therefore $\psi_G((x * x) \circ x)\psi_G(x) = \psi_G(x * x)\psi_G(x)$ and $\psi_G((x * x) \circ x) = \psi_G(x * x)$. Similarly $S(x, x^{-1} \circ x) = (x, (x^{-1} \circ x)^{-1} * x)$ implies that $\psi_G((x^{-1} \circ x)^{-1} * x) = \psi_G(x^{-1} \circ x)$. So statement (ii) of the lemma is proved. It is clear that statement (iii) follows from (i) and (ii) thus it remains to prove (i).

Let us show that $\psi_G(x_1) = \psi_G(x_2)$ implies that $\psi_G(g * x_1) = \psi_G(g * x_2)$. For a fixed $z \in X$ it is enough to reason that $\psi_G(x_1) = \psi_G(x_2)$ if and only if $\psi_G(z^{-1} * x_1) = \psi_G(z^{-1} * x_2)$. Since $S(x_1, z) = (x_1 \circ z, z^{-1} * x_1)$ and $S(x_2, z) = (x_2 \circ z, z^{-1} * x_2)$ we see that

(2.7)
$$\psi_G(x_1)\psi_G(z) = \psi_G(x_1 \circ z)\psi_G(z^{-1} * x_1)$$

and

(2.8)
$$\psi_G(x_2)\psi_G(z) = \psi_G(x_2 \circ z)\psi_G(z^{-1} * x_2)$$

Suppose $\psi_G(x_1) = \psi_G(x_2)$ then since * is an action of G_X on X we immediately see that $\psi_G(x_1 \circ z) = \psi_G(x_2 \circ z)$ therefore equations (2.7)-(2.8) imply that $\psi_G(z^{-1} * x_1) = \psi_G(z^{-1} * x_2)$. Conversely, assume that $\psi_G(z^{-1} * x_1) = \psi_G(z^{-1} * x_2)$. Our task is to prove that $\psi_G(x_1) = \psi_G(x_2)$. We use the statement (iv) of Theorem 2.3 in the following form: $S = J_2^{-1}S'J_2$, where $J_2(x,y) = (y^{-1} * x,y)$. We notice that $S'J_2(x_1,z) = (\phi(z,z^{-1} * x_1),z^{-1} * x_1)$ and $S'J_2(x_2,z) = (\phi(z,z^{-1} * x_2),z^{-1} * x_2)$. Since $\phi(z,z^{-1} * x_1)$ is the action

of $\psi_A(z^{-1} * x_1) \in A_X$ on $z \in X$ and $\psi_A = \pi \psi_G$ we see that $\phi(z, z^{-1} * x_1) = \phi(z, z^{-1} * x_2)$. In this way, first components of $S(x_1, z) = J_2^{-1}S'J_2(x_1, z)$ and $S(x_2, z) = J_2^{-1}S'J_2(x_2, z)$ coincide, i.e. $x_1 \circ z = x_2 \circ z$. So the equations (2.7)-(2.8) imply that $\psi_G(x_1) = \psi_G(x_2)$. In a similar fashion one can show that $\psi_G(x_1) = \psi_G(x_2)$ if and only if $\psi_G(z \circ x_1) = \psi_G(z \circ x_2)$. The lemma is proved.

We aim to construct the map $h: A_X \to G_X$ inverse to π . At first we define hon F_X - the free group generated by X and then show that it descends to A_X . We note that G_X acts on F_X via $f \to g * f$ for $f \in F_X$, $g \in G_X$ - the action induced from *-action of G_X on X. For $x \in X \subset F_X$ define

$$h(x) = \psi_G(x), \ h(x^{-1}) = (\psi_G(x^{-1} \circ x))^{-1}.$$

Notice that $x^{-1} \circ x$ is the same as $\psi_G(x)^{-1} \circ x$. For an element $f = x_1 \bullet \ldots \bullet x_k \in F_X$ of length k define inductively $h(x_1 \bullet \ldots \bullet x_k) = h(h(x_2 \bullet \ldots \bullet x_k) * x_1)h(x_2 \bullet \ldots \bullet x_k)$, where for each $i, x_i \in X \subset F_X$ or $x_i^{-1} \in X \subset F_X$. In the above $f = x_1 \bullet \ldots \bullet x_k$ was the minimum decomposition of $f \in F_X$ and k, the length of f, is the number of elements in such a decomposition. The only element of length 0 in F_X is identity e and we put $h(e) = 1 \in G_X$. We claim that for $a, b \in F_X$

(2.9)
$$h(a \bullet b) = h(h(b) * a)h(b)$$

Indeed, we can verify (2.9) by induction on the length of a. Suppose we know that (2.9) holds for for all elements a of length k and want to check that $h(a \bullet y \bullet b) = h(h(b) * (a \bullet y))h(b)$ for $y \in X \subset F_X$ or $y^{-1} \in X \subset F_X$. We simplify $h(h(b) * (a \bullet y))h(b)$ as follows:

$$\begin{aligned} h(h(b)*(a \bullet y))h(b) &= h((h(b)*a) \bullet (h(b)*y))h(b) \\ &= h(h(h(b)*y)*(h(b)*a))h(h(b)*y)h(b). \end{aligned}$$

On the other hand, we know that

$$\begin{aligned} h(a \bullet y \bullet b) &= h(h(y \bullet b) * a)h(y \bullet b) = h(h(h(b) * y)h(b) * a)h(h(b) * y)h(b) \\ &= h(h(h(b) * y) * (h(b) * a))h(h(b) * y)h(b). \end{aligned}$$

We see that $h(a \bullet y \bullet b) = h(h(b) * (a \bullet y))h(b)$. In this way, we just need to check the induction base, namely that $h(y \bullet b) = h(h(b) * y)h(b)$. There are two cases to consider:

- 1. $Length(y \bullet b) = 1 + Length(b)$.
- 2. $Length(y \bullet b) = Length(b) 1$, i.e. $b = y^{-1} \bullet b'$ and Length(b) = Length(b') + 1.

In the first case the formula $h(y \bullet b) = h(h(b) * y)h(b)$ follows from definition of h. In the second case without loss of generality assume that $y \in X$. Then,

$$\begin{aligned} h(b) &= h(y^{-1} \bullet b') = h((h(b') * y)^{-1})h(b') \text{ and letting } h(b') * y = z \text{ we get} \\ h(h(b) * y)h(b) &= h(h((h(b') * y)^{-1})h(b') * y)h((h(b') * y)^{-1})h(b') \\ &= h(h(z^{-1}) * z))h(z^{-1})h(b') = \psi_G(\psi_G(z^{-1} \circ z)^{-1} * z)\psi_G(z^{-1} \circ z)^{-1}h(b') \\ &= (\text{by Lemma}) \ \psi_G((z^{-1} \circ z)\psi_G(z^{-1} \circ z)^{-1}h(b') = h(b') = h(y \bullet b). \end{aligned}$$

Now we are going to check that h descends to A_X . Recall that A_X is given by generators - elements of X and relations $(z^{-1} * ((y * z) \circ y)) \bullet z = z \bullet y$ for each $y, z \in X$. We see that

(2.10)
$$h((z^{-1} * ((y * z) \circ y)) \bullet z) = \psi_G((y * z) \circ y)h(z) = h(z \bullet y).$$

If we define $p(y, z) = (z^{-1} * ((y * z) \circ y)) \bullet z \in F_X$ and $q(y, z) = z \bullet y \in F_X$ then for any $g \in G_X$, $h(g * (p(y, z)^{-1} \bullet q(y, z))) = h(g * (q(y, z)^{-1} \bullet p(y, z))) = 1$.

Indeed, we checked in the proof of Theorem 2.4 that the defining relations of group A_X are G_X -invariant with respect to * action, i.e. g*p(y,z) = p(g*y,g*z) and g*q(y,z) = q(g*y,g*z). Formula (2.10) states that h(p(y,z)) = h(q(y,z)), therefore

$$h(p(y,z)^{-1} \bullet q(y,z)) = h(h(q(y,z)) * p(y,z)^{-1})h(q(y,z))$$

= $h(h(p(y,z)) * p(y,z)^{-1})h(p(y,z)) = h(p(y,z)^{-1} \bullet p(y,z)) = 1.$

Thus $h(g * (p(y, z)^{-1} \bullet q(y, z))) = h(p(g * y, g * z)^{-1} \bullet q(g * y, g * z)) = 1$. Similarly, $h(g * (q(y, z)^{-1} \bullet p(y, z))) = 1$.

In order to check that $h: F_X \to G_X$ descends to the map $h: A_X \to G_X$ it is enough to check that for any $a, b \in F_X$, $y, z \in X$ $h(a \bullet p(y, z)^{-1} \bullet q(y, z) \bullet b) =$ $h(a \bullet q^{-1}(y, z) \bullet p(y, z) \bullet b) = h(a \bullet b)$ holds. By formula (2.9)

$$\begin{split} h(a \bullet p^{-1}(y, z) \bullet q(y, z) \bullet b) &= \\ h(h(p(y, z)^{-1} \bullet q(y, z) \bullet b) * a) \ h(p(y, z)^{-1} \bullet q(y, z) \bullet b), \end{split}$$

so it is enough to show that $h(p^{-1}(y,z) \bullet q(y,z) \bullet b) = h(b)$. But $h(p^{-1}(y,z) \bullet q(y,z) \bullet b) = h(h(b) * (p^{-1}(y,z) \bullet q(y,z)))h(b) = h(b)$ holds. Similar reasoning allows to check that $h(a \bullet q^{-1}(y,z) \bullet p(y,z) \bullet b) = h(a \bullet b)$. In this way we constructed the map $h: A_X \to G_X$ such that

1.
$$h(a \bullet b) = h(h(b) * a)h(b),$$

2. $h\psi_A = \psi_G.$

Condition 1 above implies that both $\pi h : A_X \to A_X$ and $h\pi : G_X \to G_X$ are group homomorphisms while Condition 2 implies that these homomorphisms are identities if restricted to corresponding generating sets $\psi_A(X)$, $\psi_G(X)$, thus $\pi h = id_{A_X}$, $h\pi = id_{G_X}$. Theorem 2.5 is proved.

It turns out then that the groups G_X and A_X both have abelian subgroups of finite index when X is finite. Namely, define $\Gamma = \{g \in G_X | g * x = x, g \circ x = x \text{ for all } x \in X\}$. In other words, Γ is the intersection of the kernels of left and right actions from Theorem 2.2. Theorem 2.6. (cf. Section 2.5 in [ESS] and Prop. 6 in [LYZ])

(i) $\pi(\Gamma)$ is a normal G_X -invariant (w.r.t. to *-action) subgroup lying in the center of A_X . Γ is a normal abelian subgroup in G_X , and $\pi : \Gamma \to \pi(\Gamma)$ is an isomorphism.

(ii) The 1-cocycle $\pi : G_X \to A_X$ can be factored out through Γ giving rise to the bijective 1-cocycle $\bar{\pi} : G_X/\Gamma \to A_X/\pi(\Gamma)$.

(iii) If X is finite then both G_X/Γ and $A_X/\pi(\Gamma)$ are finite groups.

Proof. (i) Let us show that $\pi(\Gamma)$ is G_X -invariant and central subgroup in A_X . From the defining relations in G_X we see that $\psi_G(x \circ y) = \psi_G(x)\psi_G(y)\psi_G(y^{-1}*x)^{-1}$ for all $x, y \in X$. In fact, one can easily check that the above formula can be generalized for $x \in G_X$, $y \in X$.

Lemma 2. For $g \in G_X, y \in X$,

$$\psi_G(g \circ y) = g\psi_G(y)\pi^{-1}(\psi_G(y)^{-1} * \pi(g))^{-1}$$

Proof of Lemma 2. Let us show that if the statement of the Lemma holds for some $g \in G_X$ then it holds for g^{-1} . We need to check that

(2.11)
$$g^{-1}\psi_G(g \circ y)\pi^{-1}(\psi_G(g \circ y)^{-1} * \pi(g^{-1}))^{-1} = y.$$

Notice that $\pi(g^{-1}) = (g * \pi(g))^{-1}$ therefore

$$\psi_G(g \circ y)^{-1} * \pi(g^{-1}) = ((\psi_G(g \circ y)^{-1}g) * \pi(g))^{-1}.$$

Since the statement of the Lemma holds for g, we have

$$\pi^{-1}((\psi_G(g \circ y)^{-1}g) * \pi(g))^{-1} = \pi^{-1}((\pi^{-1}(\psi_G(y)^{-1} * \pi(g))\psi_G(y)^{-1}) * \pi(g))^{-1}$$

= $\pi^{-1}(\pi^{-1}(\psi_G(y)^{-1} * \pi(g)) * (\psi_G(y)^{-1} * \pi(g)))^{-1}$
= $\pi^{-1}(\psi_G(y)^{-1} * \pi(g)).$

This implies the validity of equation (2.11). Similar, a simple computation shows that if the statement of the lemma is true for $g = g_1$ and $g = g_2$ then it is true for $g = g_1g_2$. In this way since by definition of G_X the lemma is true for $g \in \psi_G(X)$ we have proved the lemma.

In particular, for $g \in \Gamma$, $y \in \psi_G(X)$ one has $y = gy(\pi^{-1}(y^{-1} * \pi(g)))^{-1}$. Thus,

(2.12)
$$y^{-1}gy = \pi^{-1}(y^{-1} * \pi(g)).$$

The condition (2.12) implies that $\pi\Gamma$ belongs to the center of A_X . Indeed, applying π to relation $y^{-1}g = \pi^{-1}(y^{-1} * \pi(g))y^{-1}$ we get that $\pi(y^{-1})$ commutes with $\pi(g)$. Moreover, for $g \in \Gamma, h \in G_X$ 1-cocycle condition implies that

(2.13)
$$\pi^{-1}(\pi(h) \bullet \pi(g)) = hg$$

So, in particular the product of elements in $\pi(\Gamma)$ is in $\pi(\Gamma)$ and π restricted to Γ becomes an isomorphism between Γ and $\pi(\Gamma)$.

(ii) The relation (2.13) shows that π can be lifted to $\bar{\pi}: G_X/\Gamma \to A_X/\pi(\Gamma)$.

(iii) The kernels of each of the actions $*, \circ$ are of finite indexes since the corresponding quotients are isomorphic to subgroups in Permut(X). So, the intersection of kernels, i.e. subgroup Γ has finite index as well.

Definition 6. We call a 7-tuple

 $(G, A, X, \rho_{GA}, \rho_{GAX}, \overline{\pi}, \overline{\psi_A})$

a bijective cocycle 7-tuple if G, A are groups, $\rho_{GA}: G \to \operatorname{Aut}(A)$ is an action of G on A, $\rho_{GAX}: G \ltimes A \to \operatorname{Permut}(X)$ is an action of $G \ltimes A$ on X, $\overline{\pi}: G \to A$ is a bijective 1-cocycle, $\overline{\psi_A}: X \to A$ is $G \ltimes A$ -equivariant, where $G \ltimes A$ acts on A by conjugation.

Note that the action of $G \ltimes A$ gives rise to two actions $\rho_{GX} : G \to \operatorname{Permut}(X)$ and $\rho_{AX} : A \to \operatorname{Permut}(X)$. Starting with a bijective cocycle 7-tuple, let $* : X \times X \to X$ and $\phi : X \times X \to X$ be defined as $y * x = \rho_{GX}(\overline{\psi_G}(y))(x)$ and $\phi(x, y) = \rho_{AX}(\overline{\psi_A}(y))(x)$, where $\overline{\psi_G} = \overline{\pi}^{-1}\overline{\psi_A}$. Define $S : X \times X \to X \times X$ and $S' : X \times X \to X \times X$ via $S(x, y) = (x \circ y, y^{-1} * x)$ and $S'(x, y) = (\phi(y, x), x)$, where $x \circ y$ is defined in such a way that $\phi(y, x) = x^{-1} * ((y * x) \circ y)$ holds.

Lemma 3. (i) For an arbitrary bijective cocycle 7-tuple, (X, S) constructed above is a braided nondegenerate set.

(ii)(X, S') is a derived nondegenerate braided set corresponding to (X, S).

Proof. It is obvious from the definition of a bijective cocycle 7-tuple that (X, S') is a braided nondegenerate set. We introduced $x \circ y$ in such a way that (X, S') becomes a derived solution corresponding to (X, S) as long as we are able to show that (X, S) is braided nondegenerate itself. Since ϕ is *G*-invariant the argument identical to the one made in the proof of Theorem 2.3 mitigates that for each integer $n \geq 2$ there exists a bijection $J_n : X^n \to X^n$ such that $J_n S_n^{ii+1} J_n^{-1} = (S')_n^{ii+1}$. This implies that *S* is bijective and satisfies the braid relation (2.1).

It remains to prove that (X, S) is nondegenerate, i.e. that $x \circ y$ depends bijectively on $y \in X$ for a fixed $x \in X$. For that purpose we show that we can define $g \circ y \in X$ for $y \in X$, $g \in G$ such that for any $x, y \in X$, $g, h \in G$ $x \circ y = \overline{\psi_G}(x) \circ y$ and $(gh) \circ y = g \circ (h \circ y)$, i.e. \circ is an action of G on X.

Let a group homorphism $P: G \to G \ltimes A$ be defined by the formula $P(g) = (g, \overline{\pi}(g))$ for $g \in G$. Then the map $\rho_{GX}^* = \rho_{GAX}P$ is an action of G on X. For $g \in G, y \in X$ define

$$g \circ y = \rho_{GX}^*(\bar{\pi}^{-1}(\rho_{GA}(\overline{\psi_G}(y)^{-1})(\bar{\pi}(g))))(y).$$

We want to check $(gh) \circ y = g \circ (h \circ y)$. For notational convience let $\rho_{GA}(\overline{\psi_G}(y)^{-1})(\overline{\pi}(g)) = \overline{\psi_G}(y)^{-1} * \overline{\pi}(g)$, i.e. by * we will mean both actions ρ_{GA} and ρ_{GX} . Then due to the fact that P is a homomorphism it is enough to verify that

$$\bar{\pi}^{-1}(\overline{\psi_G}(h \circ y)^{-1} * \bar{\pi}(g)) = \bar{\pi}^{-1}(\overline{\psi_G}(y)^{-1} * \bar{\pi}(gh))(\bar{\pi}^{-1}(\overline{\psi_G}(y)^{-1} * \bar{\pi}(h))^{-1}.$$

Since
$$\bar{\pi}(gh) = (h^{-1} * \bar{\pi}(g))\bar{\pi}(h),$$

 $\bar{\pi}^{-1}(\overline{\psi_G}(y)^{-1} * \bar{\pi}(gh)) = \bar{\pi}^{-1}((\overline{\psi_G}(y)^{-1}h^{-1} * \bar{\pi}(g))(\overline{\psi_G}(y)^{-1} * \bar{\pi}(h)))$
 $= \bar{\pi}^{-1}(\bar{\pi}^{-1}(\overline{\psi_G}(y)^{-1} * \bar{\pi}(h))\overline{\psi_G}(y)^{-1}h^{-1} * \bar{\pi}(g))\bar{\pi}^{-1}(\overline{\psi_G}(y)^{-1} * \bar{\pi}(h)).$

In this way, if we check that

(2.14)
$$\bar{\pi}^{-1}(\overline{\psi_G}(y)^{-1} * \bar{\pi}(h))\overline{\psi_G}(y)^{-1}h^{-1} = \overline{\psi_G}(h \circ y)^{-1}$$

we conclude that $g \circ (h \circ y) = (gh) \circ y$. Let us rewrite (2.14) as (cf. Lemma 2) $\overline{\psi_G}(h \circ y)\overline{\pi}^{-1}(\overline{\psi_G}(y)^{-1} * \overline{\pi}(h)) = h\overline{\psi_G}(y)$ and apply $\overline{\pi}$ to it. We get that (2.14) is equivalent to

$$\overline{\psi_A}(\overline{\pi}^{-1}(\overline{\psi_G}(y)^{-1} * \overline{\pi}(h))^{-1} * (h \circ y))(\overline{\psi_G}(y)^{-1} * \overline{\pi}(h)) = (\overline{\psi_G}(y)^{-1} * \overline{\pi}(h))(\overline{\psi_A}(y)).$$

The last equality follows from A equivariance of $\overline{\psi_A}$ since $\overline{\pi}^{-1}(\overline{\psi_G}(y)^{-1} * \overline{\pi}(h))(\overline{\psi_A}(y))$.

The last equality follows from A-equivariance of ψ_A since $\bar{\pi}^{-1}(\psi_G(y)^{-1}*\bar{\pi}(h))^{-1}*$ $(h \circ y) = \rho_{AX}(\overline{\psi_G}(y)^{-1}*\bar{\pi}(h))(y)$ by definition of $h \circ y$. The lemma is proved. \Box

One can combine two actions of G on $X - \rho_{GX}$ and ρ_{GX}^* into the action $\rho = \rho_{GX} \times \rho_{GX}^* : G \to \operatorname{Permut}(X) \times \operatorname{Permut}(X)$ of G on X^2 .

Definition 7. We call a bijective cocycle 7-tuple $(G, A, X, \rho_{GA}, \rho_{GAX}, \overline{\pi}, \overline{\psi_A})$ faithful if $\overline{\psi_G}(X) = \overline{\pi}^{-1} \overline{\psi_A}(X)$ generates G and the action $\rho : G \to \text{Permut}(X) \times \text{Permut}(X)$ is faithful.

The following theorem is a characterization of finite braided nondegenerate sets in group theoretical terms. We notice that this result is a generalization of Proposition 2.11 in [ESS].

Theorem 2.7. The construction of Lemma 3 establishes a 1-1 correspondence between nondegenerate braided sets (X, S) and faithful bijective cocycle 7-tuples.

Proof. Having a nondegenerate braided set (X, S) it is straightforward to construct the faithful bijective cocycle 7-tuple. Indeed, following the notations of Theorem 2.6 we put $G = G_X/\Gamma$, $A = A_X/\pi(\Gamma)$ then G acts faithfully on X^2 and we have a faithful cocycle 7-tuple. Conversely, if we have a faithful 7-tuple we can construct a nondegenerate braided set by Lemma 3. Let G_X be the structure group of so constructed nondegenerate braided set. It follows from (2.14) that there is a group homomorphism $Q: G_X \to G$ such that $Q\psi_G = \overline{\psi_G}$. Since $\overline{\psi_G}(X)$ generates G, Q is surjective, and since G acts faithfully on X^2 , $Ker(Q) = \Gamma$, i.e. G_X/Γ is isomorphic to G.

2.3. Injective solutions. In this section we talk about most tractable braided nondegenerate sets - injective solutions.

Definition 8. We call a braided nondegenerate set (X, S) an injective solution if the map $\psi_G : X \to G_X$ is injective.

In [LYZ] the authors noticed that in the absence of involutivity the natural map $\psi_G : X \to G_X$ is not obviously injective which creates difficulties in characterization of solutions. It turned out that injectivity may indeed fail (see examples below). This motivates Definition 8. **Lemma 4.** A nondegenerate braided set (X, S) is injective if and only if its derived solution (X, S') is injective.

Proof. The statement of Theorem 2.5 implies that injectivity of the map $\psi_A : X \to A_X$ is equivalent to injectivity of $\psi_G : X \to G_X$. Since A_X is the structure group of the derived solution Lemma 4 is proved.

The importance of injective solutions is in the fact that their properties and group-theoretical characterization are very similar to that of involutive solutions [ESS].

Theorem 2.8. (i) Let a group G act on a group A by $\rho_{GA} : G \to \operatorname{Aut}(A)$ such that the bijective map $\pi : G \to A$ is a 1-cocycle. Then any $G \ltimes A$ -invariant subset $X \subset A$ has a natural structure of a nondegenerate braided injective set given by

(2.15)
$$S(x,y) = (\pi(\pi^{-1}(x)\pi^{-1}(y)(\pi^{-1}(\rho(\pi^{-1}(y)^{-1})(x)))^{-1}), \rho(\pi^{-1}(y)^{-1})(x)),$$

for $x, y \in X$.

(ii) Any nondegenerate braided injective set can be obtained by the method just described.

Proof. To prove (i) we can use Lemma 3. Indeed, we have the following bijective cocycle 7-tuple: $G, A, X, \bar{\pi} = \pi, \rho_{GA}$ as given; ρ_{GAX} is induced from the adjoint action of $G \ltimes A$ on its subgroup $A, \overline{\psi_A} = id_X$. It is straightforward to check (cf. (2.14)) that the map S constructed in Lemma 3 coincides with the map S given by formula (2.15). So it remains to prove that the set (X, S) is injective. Let G_X be its structure group. Arguing as in the proof of Theorem 2.7 we see that there is a group homomorphism $Q: G_X \to G$ such that $\pi Q\psi_G = id_X$. This implies that ψ_G is injective.

Conversely, if (X, S) is an injective nondegenerate braided set then $X = \psi_A(X)$ is a G_X -invariant (w.r.t. * - action) subset in A_X . Note that this subset is automatically $G_X \ltimes A_X$ -invariant. Recall that S is given by the formula $S(x,y) = (x \circ y, y^{-1} * x)$ for $x, y \in X$ according to notations after Theorem 2.2. Let us make sure that the construction of Theorem 2.8 yields the same map S we already have. Indeed, for $x, y \in \psi_A(X) = X, \pi^{-1}(y)^{-1} * x = \psi_G(y)^{-1} * x = y^{-1} * x$ and $\pi(\pi^{-1}(x)\pi^{-1}(y)(\pi^{-1}(\pi^{-1}(y)^{-1} * x))^{-1}) = \pi(\psi_G(x)\psi_G(y)\psi_G(y^{-1} * x)^{-1}) = \pi(\psi_G(x \circ y)) = \psi_A(x \circ y) = x \circ y$. The theorem is proved.

Lemma 4 implies that injectivity of a given solution is determined by the properties of the function $\phi : X \times X \to X$. In particular, for a symmetric set $(X, S), \phi(y, x) = y$ and A_X is the free abelian group generated by X. Hence, symmetric sets are injective. We don't know any easy way to check that a given function $\phi(y, x)$ corresponds to an injective solution. While an injectivity criterion is provided by Theorem 2.9, we give two simple necessary conditions below that are in many cases sufficient to check that a given solution is not injective.

Lemma 5. If (X, S) is an injective braided set then

(a)
$$\phi(x, x) = x$$
 for all $x \in X$,

(b) a pair $(y, x) \in X \times X$ satisfies $\phi(y, x) = y$ if and only if $\phi(x, y) = x$.

Proof. Suppose (X, S) is injective. The group A_X is generated by the elements of X subject to relations $\phi(y, x) \bullet y = y \bullet x$ for $x, y \in X$. Consequently $\psi_A(\phi(x, x)) \bullet \psi_A(x) = \psi_A(x) \bullet \psi_A(x)$ and $\psi_A(\phi(x, x)) = \psi_A(x)$ in A_X . Since $\psi_A : X \to A_X$ is injective $\phi(x, x) = x$ on X. Now, assume that $\phi(y, x) = y$. Then $\psi_A(y) \bullet \psi_A(x) = \psi_A(x) \bullet \psi_A(y)$. On the other hand, $\psi_A(\phi(x, y)) \bullet \psi_A(y) =$ $\psi_A(y) \bullet \psi_A(x)$, therefore $\psi_A(\phi(x, y)) = \psi_A(x)$ and $\phi(x, y) = x$. The lemma is proved.

Example. Let $c, b \in \text{Permut}(X)$. Define $S: X \times X \to X \times X$ by the formula S(x, y) = (by, cx). It is easy to see that (X, S) is a nondegenerate braided set if bc = cb. We claim that this solution is injective if and only if $cb = id_X$. Indeed, suppose the solution is injective, then by Lemma 5 $\phi(x, x) = x$, i.e. $x^{-1} * ((x * x) \circ x) = cbx = x$. Therefore $cb = id_X$. Conversely, if $cb = id_X$ then (X, S) is symmetric and hence injective.

We remark that with each nondegenerate braided set we associated two actions of the group G_X (*, \circ) and an action of A_X (via $\phi(x, y)$, which is a \circ action of the derived solution) on X. In particular, the latter action allows us to construct a finite group $A_X^0 \subset \text{Permut}(X)$, as the image of A_X under that action, and a surjective homomorphism $p: A_X \to A_X^0$. Define M_X - a module over A_X^0 generated by $v_x, x \in X$ subject to relations

$$p(y)^{-1}v_x + v_y = p(x)^{-1}v_{\phi(y,x)} + v_x.$$

By construction we have a natural map $\psi_M : X \to M_X$ given by $x \to v_x$. It turns out that injectivity of ψ_M is equivalent to injectivity of ψ_G .

Theorem 2.9. (i) There exists a unique 1-cocycle $\theta : A_X \to M_X$ such that $\theta \psi_A = \psi_M$, where A_X acts on M_X via p.

(ii) θ is injective on $\psi_A(X)$.

Proof. Statement (i) is clear from definitions of A_X and M_X . Let us show that (ii) holds. Let $Ker(p) = \Gamma_A$, i.e. $A_X^0 = A_X/\Gamma_A$. Let $x_1, x_2 \in \psi_A(X), x_1 \neq x_2$. We want to show that $\theta(x_1) \neq \theta(x_2)$ in M_X . Fix a character $\xi : \Gamma_A \to \mathbb{C}^*$. Define a vector space

$$V_{\xi} = \{ f : A_X \to \mathbb{C} | f(a \bullet \gamma) = f(a)\xi(\gamma), \ \gamma \in \Gamma_A \}.$$

 V_{ξ} clearly has an A_X -module structure defined as $(bf)(a) = f(b^{-1} \bullet a)$, where $f \in V_{\xi}$, $b, a \in A_X$. Choose a lifting $g : A^0_X \to A_X$ (as a set only). Then V_{ξ} is identified with $Fun(A^0_X, \mathbb{C})$, the space of functions on A^0_X via $f \to f|_{g(A^0_X)}$. This space has a basis $\delta_a, a \in A^0_X$ such that $\delta_a(b) = 0$ if $a \neq b$ and $\delta_a(a) = 1$. Let us define $\varepsilon : \psi_A(X) \to Fun(A^0_X, \mathbb{C})$ by the formula $x\delta_a = \delta_{p(x) \bullet a}\varepsilon(x)(a)$ for $x \in \psi_A(X), a \in A^0_X$. We can always choose ξ and g such that $\varepsilon(x_1) \neq \varepsilon(x_2)$. Indeed, if $p(x_1) = p(x_2)$ it suffices to choose ξ such that $\xi(x_1 \bullet x_2^{-1}) \neq 1$ for any

lifting g. If $p(x_1) \neq p(x_2)$ then for any character $\xi \neq 1$ there is a lifting g such that $\varepsilon(x_1) \neq \varepsilon(x_2)$. Moreover, since $x \bullet y = \phi(y, x) \bullet x$ for $x, y \in \psi_A(X)$ and

$$xy\delta_a = x\delta_{p(y)\bullet a}\varepsilon(y)(a) = \delta_{p(x)\bullet p(y)\bullet a}\varepsilon(x)(p(y)\bullet a)\varepsilon(y)(a),$$

we get that

$$\varepsilon(x)(p(y) \bullet a)\varepsilon(y)(a) = \varepsilon(\phi(y, x))(p(x) \bullet a)\varepsilon(x)(a)$$

In this way, we have the equality $(p(y)^{-1}\varepsilon(x))\varepsilon(y) = (p(x)^{-1}\varepsilon(\phi(y,x)))\varepsilon(x)$ in $Fun(A_X^0, \mathbb{C})$. Hence we can construct an A_X^0 -homomorphism from M_X to $Fun(A_X^0, \mathbb{C})$ given by $v_z \to \varepsilon(\psi_A(z)), z \in X$. But $\varepsilon(x_1) \neq \varepsilon(x_2)$ thus $\theta(x_1) \neq \theta(x_2)$.

Corollary 1. The map $\psi_M : X \to M_X$ is injective if and only if (X, S) is an injective solution.

2.4. Rank of the structure group. In this section we show how to compute the rank of the structure group G_X for a finite nondegenerate braided set (X, S).

Definition 9. (i) The rank of a group G having an abelian subgroup of finite index Γ is defined as the rank of Γ .

(ii) We define the rank of a finite nondegenerate braided set (X, S) to be the rank of its structure group G_X .

Clearly the above definition doesn't depend on the choice of Γ , for any two abelian subgroups of finite index Γ_1 , Γ_2 have the same rank that is equal to the rank of their intersection, which has finite index in each of them.

Lemma 6. The rank of a solution (X, S) is equal to the rank of the derived solution (X, S').

Proof. According to statement (i) of Theorem 2.6 abelian subgroups Γ and $\pi(\Gamma)$ of finite indexes in G_X and A_X are isomorphic, thus G_X and A_X have the same rank. The lemma is proved.

We aim to compute the rank of A_X . Note that defining relations in group A_X can be rewritten as

(2.16)
$$\phi(y,x) = x \bullet y \bullet x^{-1}.$$

Note that since $S(x, y) = (\phi(y, x), x)$ gives rise to a nondegenerate braided set, $\phi(x)$ can be extended to the action of A_X on X. Introduce an equivalence relation \sim on X such that the orbits of the above action become equivalence classes. Namely, consider the minimum equivalence relation \sim such that $y \sim \phi(y, x)$ for $x, y \in X$.

Theorem 2.10. The rank of group A_X is equal to the number of equivalence classes with respect to equivalence relation \sim on X.

The proof relies on the following lemma. Let H_1 , H_2 , H_3 be three groups, such that there is an exact sequence

$$1 \to H_1 \to H_2 \to H_3 \to 1,$$

and H_1 is central in H_2 .

Lemma 7 ([CR]). There exists an exact sequence (The Hochschild - Serre sequence) (2.17) for any abelian group B, where $H^2(H_3, B)$ stands for the second cohomology group of H_3 with coefficients in B.

$$(2.17) \qquad 1 \to Hom(H_3, B) \to Hom(H_2, B) \to Hom(H_1, B) \to H^2(H_3, B).$$

Proof of Theorem 2.10. Let us use the sequence 2.17 in the following situation: $H_2 = A_X, H_1 \subset \pi(\Gamma) \subset A_X$ is the free abelian group of rank r of finite index in $\pi(\Gamma), H_3 = H_2/H_1$ - a finite group, $B = \mathbb{C}^*$. Notice that $\pi(\Gamma)$ is central in A_X therefore H_1 is central in H_2 . Then, since both $Hom(H_3, B)$ and $H^2(H_3, B)$ are finite groups and $Hom(H_1, B) = (\mathbb{C}^*)^r$, the dimension of $Hom(H_2, B) =$ $Hom(A_X, \mathbb{C}^*)$ is equal to r, the rank of A_X . On the other hand, it is clear from formula (2.16) that $Hom(A_X, \mathbb{C}^*) = (\mathbb{C}^*)^k$, where k is the number of equivalence classes in X. The theorem is proved.

Corollary 1. The rank of any solution (X, S) is less or equal than n, the number of elements in X, with the equality taking place if and only if (X, S) is symmetric.

Proof. It is clear that if rank of A_X is equal to n then equivalence relation \sim on X is trivial, $\phi(y, x) = y$ and the map $\psi_A : X \to A_X$ is injective. This immediately implies that the pair (X, S) is symmetric.

Example. Consider a permutation solution S(x,y) = (bx,cy), $b, c \in \text{Permut}(X)$, bc = cb. It is easy to check that $\phi(y,x) = bcy$, hence $y \sim (bc)^m y$ for any integer m. The rank of the permutation solution is equal to the number of equivalence classes with respect to this relation, which, in turn, is equal to the number of independent cyclic permutations in canonical decomposition of bc (counting cyclic permutations of length 1).

3. Linear and affine solutions

3.1. Linear braided sets. In this section we will look for nondegenerate braided sets of the following form: X is an abelian group, and S is an affine linear transformation of $X \times X$. Such braided sets will be called *affine solutions*. Considering affine solutions was motivated by the results in [ESS].

We will start with considering a special case, when S is an automorphism of $X \times X$. In this case, an affine solution will be called *a linear solution*. For a linear solution, S has the form

(3.1)
$$S(x,y) = (ax + by, cx + dy), a, b, c, d \in End(X).$$

It is easy to check that for S of the form (3.1) the nondegeneracy is equivalent to invertibility of both b and c while braid relation is equivalent to the equations [Hi]

(3.2) $a(1-a) = bac, \quad d(1-d) = cdb,$

(3.3)
$$ab = ba(1-d), \quad ca = (1-d)ac, \quad dc = cd(1-a),$$

(3.4) $bd = (1-a)db, \quad cb - bc = ada - dad.$

Lemma 8. Braided nondegenerate linear sets (X, S) are in 1-1 correspondence with the quadruples $(a, b, d, s) \in End(X)^4$ such that:

- (i) 1-a, 1-d, b, 1+s are invertible,
- (ii) s commutes with a, b, d and sa = sd = 0,

(iii) $bdb^{-1} = (1-a)d$, $b^{-1}ab = a(1-d)$. The 1-1 correspondence is given via the formula

(3.5)
$$bc = (1 - d + ad)(1 - a) + s.$$

Proof. Suppose (a, b, c, d) solves (3.2)-(3.4). Note that the first of equations (3.4) implies that $bdb^{-1} = (1 - a)d$, therefore $b(1 - d)b^{-1} = 1 - d + ad$. Moreover, if we multiply the first equation of (3.3) by b^{-1} on the right we get that $a = bab^{-1}b(1 - d)b^{-1}$ thus relations (3.6) hold. Similarly from equations two and three of (3.3) we obtain relations (3.7).

(3.6)
$$bab^{-1}(1-d+ad) = a, \ bdb^{-1} = (1-a)d,$$

(3.7)
$$cac^{-1} = (1-d)a, \ cdc^{-1}(1-a+da) = d.$$

Above formulas show how to conjugate the elements of subalgebra generated by a and d by elements b, c and their products. We define s from the relation (3.5). Notice that sa = sd = 0. Indeed, multiplying (3.5) by a on the right and using first of relations (3.2) and second of relations (3.3) we get that

$$sa = bca - (1 - d + ad)(1 - a)a = b(1 - d)ac - (1 - d + ad)bac.$$

Since according to (3.6) $b(1-d)b^{-1} = 1 - d + ad$ we see that b(1-d)ac - (1 - d + ad)bac = 0. Similarly as = 0. The last of equations (3.4) imply that

(3.8)
$$cb = (1 - a + da)(1 - d) + s.$$

Multiplying the relation (3.8) just obtained by d we get that sd = ds = 0. Now we have everything to show that 1 - a, 1 + s and 1 - d are invertible. Indeed, b, c are invertible because of nondegeneracy of (X, S). Since

$$bc = (1 - d + s + ad)(1 - a) = (1 - a)(1 - d + s + da),$$

$$bc = (1 - d + ad)(1 - a + s) = (1 - a + s)(1 - d + ad),$$

and

$$cb = (1 - a + s + da)(1 - d) = (1 - d)(1 - a + s + ad),$$

we conclude that 1-a, 1-a+s and 1-d have right and left inverses and hence invertible. But 1-a+s = (1-a)(1+s), thus 1+s is invertible. Let us show that s commutes with c. We conjugate relation (3.5) by c and use relations (3.7) to conclude that

(3.9)
$$cb = (1 - a + da)(1 - d) + csc^{-1}.$$

Comparing (3.8) to (3.9) we get that $s = csc^{-1}$, i.e. s commutes with c. Now, relation (3.5) implies that s commutes with b as well. In this way, starting from (a, b, c, d), a solution to (3.2)-(3.4) we constructed a quadruple (a, b, d, s) satisfying conditions of the lemma. Conversely, let us assume we start with (a, b, d, s). Define c from the formula (3.5). Since $1 - d + ad = b(1 - d)b^{-1}$ is invertible, c is invertible as well. It is straightforward to check that so defined (a, b, c, d) satisfy the braid relations (3.2)-(3.4), and that $S : X \times X \to X \times X$ is bijective. The lemma is proved.

3.2. Injective linear solutions. It turns out that injective linear solutions are easy to characterize.

Theorem 3.1. A linear nondegenerate braided set of the form (3.1) is injective iff bc = (1 - d + ad)(1 - a) or, in the language of Lemma 8, s = 0.

Proof. Assume that (X, S) is injective. Then, by Lemma 5 $\phi(x, x) = x$ on X. In the linear case it is easy to compute $\phi(y, z)$ explicitly:

$$\phi(y,z) = c((y*z) \circ y) + dz = c(a(y*z) + by) + dz = cac^{-1}(z - dy) + cby + dz.$$

According to relation (3.8), cb = (1 - a + da)(1 - d) + s. Plugging it into formula for $\phi(y, z)$ and using (3.7) we conclude that

$$\phi(y,z) = (1 - (1 - d)(1 - a))z + ((1 - d)(1 - a) + s)y.$$

Condition $\phi(x, x) = x$ immediately implies that s = 0.

Conversely, assume that s = bc - (1 - d + ad)(1 - a) = 0. Let us show that $\psi_A : X \to A_X$ is injective. The group A_X is generated by elements of X subject to relations

(3.10)
$$\phi(y,z) \bullet z = z \bullet y, \text{ where } y, z \in X \text{ and } \phi(y,z) = z^{-1} * ((y * z) \circ y).$$

Denoting K = (1 - d)(1 - a) we see that the group A_X is given by relations $((1 - K)z + Ky) \bullet z = z \bullet y$. By Lemma 8, K is invertible. Let us now define the action of A_X on X. We let the elements of generating set $\psi_A(X)$ act with K on X and then extend this action to arbitrary elements of A_X . Consider a semidirect product $A_X \ltimes X$ with respect to this action, and define an embedding $J : X \to A_X \ltimes X$ given by the formula $J(x) = (\psi_A(x), x)$. We notice that J((1 - K)z + Ky)J(z) = J(z)J(y) in $A_X \ltimes X$. Indeed,

$$J((1-K)z + Ky)J(z) = (\psi_A((1-K)z + Ky), (1-K)z + Ky)(\psi_A(z), z)$$

= $(\psi_A((1-K)z + Ky) \bullet \psi_A(z), K^{-1}((1-K)z + Ky) + z)$
= $(\psi_A(z) \bullet \psi_A(y), K^{-1}z + y) = J(z)J(y).$

So, J can be extended to a homomorphism $\hat{J} : A_X \to A_X \ltimes X$ such that $Pr\hat{J}\psi_A = id$, where $Pr : A_X \ltimes X \to X$ stands for the projection to the second component. Therefore, the map $\psi_A : X \to A_X$ is injective. The theorem is proved.

Corollary 1. (i) Let (X, S) be a nondegenerate braided linear set of the form (3.1). Then the pair (X, \hat{S}) with $\hat{S} : X \times X \to X \times X$ given by $\hat{S}(x,y) = (ax + by, cx + (d - s)y)$, where s is defined in 3.5, is an injective solution.

(ii) Suppose (X, S) is an injective linear solution and $s : X \to X$ satisfies sa = as = 0, sb = bs, $sd = ds = -s^2$, sc = cs. Then, (X, \check{S}) with $\check{S} : X \times X \to X \times X$ given by $\check{S}(x, y) = (ax + by, cx + (d + s)y)$ is a nondegenerate braided set that corresponds under the correspondence of Lemma 8 to the quadruple (a, b, d, s).

Proof. (i) It is easy to check (X, \hat{S}) is a braided nondegenerate set by directly checking relations (3.2) - (3.4). Since *s* commutes with everything and sa = sd = 0 the above task is pretty simple. Also, it is obvious that bc = (1 - (d - s) + a(d - s))(1 - a), thus by Theorem 3.1 (X, \hat{S}) is injective. Proof of (ii) is similar to (i) and is left to the reader.

Examples. 1. Consider the linear solution S(x, y) = (cy, bx) with c, b being linear automorphisms of X subject to cb = bc. We see that s=bc-1, therefore (X, \hat{S}) with $\hat{S}(x, y) = (cy, bx + (1 - bc)y)$ is an injective solution. We obtain the same solution by a different method in Example 2 at the end of this section.

2. It was shown in [ESS] that symmetric nondegenerate linear solutions of the form 3.1 are given as the solutions to the following equations: $bab^{-1} = \frac{a}{a+1}$, $c = b^{-1}(1-a^2)$, $d = \frac{a}{a-1}$ with b, c being invertible. In particular a large class of solutions of this kind considered corresponded to nilpotent a, i.e. there was n such that $a^n = 0$. Define $s = ma^{n-1}$, m being any integer. It is easy to see that so defined s satisfies conditions of Corollary 1 (ii) hence $S''(x, y) = (ax + by, cx + (d + ma^{n-1})y)$ is a nondegenerate braided set, which is not symmetric and not injective unless $ma^{n-1} = 0$.

Theorem 3.2. Linear braided nondegenerate injective sets (X, S) on an abelian group X are in 1-1 correspondence with triples (a, b, d) of endomorphisms of X such that b, 1-a, 1-d are invertible and $bdb^{-1} = (1-a)d, b^{-1}ab = a(1-d)$.

Proof. Straightforward application of Lemma 8 and Theorem 3.1.

Corollary 1. Linear braided nondegenerate injective sets (X, S) on an abelian group X are in 1-1 correspondence with triples (p, q, z) of automorphisms of X such that pq = qp and $z^2 - z(p+q) + pq = 0$.

The statement of Corollary 1 follows from Theorem 3.2 via change of variables $p = b^{-1}$, $q = (1 - a)(1 - d)b^{-1}$, $z = (1 - a)b^{-1}$.

Examples. 1. If (X, S) is unitary then (1 - a)(1 - d) = 1 and therefore p = q. In this way, nondegenerate unitary linear braided sets are characterized as

representations of algebra generated by invertible p, z subject to $z^2 - 2zp + p^2 = 0$.

2. Put z = p, then q can be anything as long as it is invertible and pq = qp. Correspondingly, a = 0, $b = p^{-1}$, $1 - d = p^{-1}q$, c = q. The map S is defined in the following way: $S(x, y) = (p^{-1}y, qx + (1 - p^{-1}q)y)$. Similarly if we let z = q we obtain the solution given by the formula: $S(x, y) = (py + (1 - q^{-1}p)x, q^{-1}x)$.

3. Let ϵ_1 and ϵ_2 be two nilpotent operators on X of order two, i.e. $\epsilon_1^2 = \epsilon_2^2 = 0$. Then we let $p = 1 + \epsilon_1$, $q = 1 - \epsilon_1$, $z = 1 + \epsilon_2$. It is easy to check that so defined p and q commute and that $z^2 - z(p+q) + pq = 0$. We recover a, b, c, d from ϵ_1 and ϵ_2 via the formulas $b = 1 - \epsilon_1$, $a = \epsilon_1 - \epsilon_2 + \epsilon_2 \epsilon_1$, $d = 1 - (1 + \epsilon_1)(1 - \epsilon_2)(1 - 2\epsilon_1)$, $c = (1 + \epsilon_1)(1 - \epsilon_2)(1 - \epsilon_1)(1 + \epsilon_2)(1 - \epsilon_1)$. In particular, if $\epsilon_1 \epsilon_2 = \epsilon_2 \epsilon_1$ the corresponding linear solution has the form:

$$S(x,y) = \left((\epsilon_1 - \epsilon_2 + \epsilon_2\epsilon_1)x + (1 - \epsilon_1)y, (1 - \epsilon_1)x + (\epsilon_1 + \epsilon_2 - \epsilon_2\epsilon_1)y\right)$$

4. Suppose X is a n-dimensional vector space and p, q are invertible operators on it having 2n distinct eigenvalues. Let $(v_1...v_n)$ be the basis of X in which both p and q are diagonalized, i.e. $pv_i = p_iv_i$, $qv_i = q_iv_i$. Then $zv_i = z_iv_i$, where for each i either $z_i = p_i$ or $z_i = q_i$. Indeed, $0 = (z^2 - z(p+q) + pq)v_i = (z - p_i)(z - q_i)v_i$. The vector subspace of X generated by applying z to v_i (iis fixed) is annihilated by $(z - p_i)(z - q_i)$ therefore it has a basis of p_i and q_i eigenvectors of z. Therefore, it has to be one dimensional, i.e. $zv_i = p_iv_i$ or $zv_i = q_iv_i$. It is also easy to see that z given by diagonal matrix in $(v_1...v_n)$ basis with p_i or q_i entries on the i-th place does satisfy $z^2 - z(p+q) + pq = 0$ on X.

3.3. Affine solutions. In this section we talk about general affine solutions on an abelian group X.

Definition 10. The solution (braided, nondegenerate) (X, S) of the form (3.11) is called affine.

 $(3.11) \quad S(x,y) = (ax + by + z, cx + dy + t), \quad a, b, c, d \in End(X), t, z \in X.$

Lemma 9. The pair (X, S) of the form (3.11) is a solution if and only if (3.2)-(3.4) and (3.12) hold. Therefore, any affine solution gives rise to a linear solution (X, S^*) with $S^*(x, y) = (ax + by, cx + dy)$.

 $(3.12) \quad cdz + dt = 0, \ az + bat = 0, \ (c + d - ad - 1)z + (da + 1 - a - b)t = 0.$

Proof. Straightforward.

Definition 11. We call (X, S^*) from Lemma 9 the linear part of an affine solution (X, S). Conversely, we call (X, S) an affine solution associated with (X, S^*) .

Theorem 3.3. (i) Let (X, S^*) be a linear braided nondegenerate set, $S^*(x, y) = (ax + by, cx + dy)$. Then, (X, S) given by (3.11) is an affine solution associated with (X, S^*) if and only if $t = -c(1-a)^{-1}z + k$ and ak = dk = 0, (b-1)k = sz, where s is defined in (3.5).

(ii) An affine solution (X, S) is injective if and only if its linear part is injective and k = 0 in the above characterization. In this way, injective affine solutions associated with a given injective linear solution (X, S^*) are in 1-1 correspondence with elements $z \in X$, t being given by $t = -c(1-a)^{-1}z$.

Proof. Let us proof part (i). Note that since $cdz + dt = d(c(1-a)^{-1}z + t)$ and $az+bat=a(z + (1-a)c^{-1}t)$ by equations (3.2)-(3.3) we can rewrite two of the relations (3.12) as

$$d(c(1-a)^{-1}z+t) = 0, \ a(z+(1-a)c^{-1}t) = 0.$$

Therefore, if we define k from the relation

(3.13)
$$t = -c(1-a)^{-1}z + k,$$

we see using (3.2) that ak = dk = 0. Now, (3.7) implies $c(1-a)^{-1}c^{-1} = (1-a+da)^{-1}$ thus we can transform (3.13) into (1-a+da)t = -cz+(1-a+da)k = -cz+k. In this way, we rewrite last of the relations (3.12) as

$$(3.14) (d - ad - 1)z - bt + k = 0$$

If we substitute t from (3.13) into (3.14) and use (3.5) we get that (b-1)k = sz. Part (i) is proved. In order to prove part (ii) we compute the function $\phi : X \times X \to X$. Define by ϕ^* the corresponding function ϕ of the linear part (X, S^*) . Then, it is easy to check that $\phi(y, x) = \phi^*(y, x) + k$. Now, assume that (X, S) is injective. Then by Lemma 5 $\phi(x, x) = x$, hence $\phi^*(x, x) = x$ and k = 0. As we saw in the proof of Theorem 3.1 $\phi^*(x, x) = x$ implies that s = 0 and thus (X, S^*) is injective. Conversely, if (X, S^*) is injective and k = 0 then $\phi(y, x) = \phi^*(y, x)$ and hence the derived solution of (X, S) coincides with the derived solution of (X, S^*) and hence is injective. Theorem is proved.

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