#### ON CLASSIFICATION OF DYNAMICAL r-MATRICES

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ABSTRACT. Using the gauge transformations of the Classical Dynamical Yang-Baxter Equation introduced by P. Etingof and A. Varchenko in [EV], we reduce the classification of dynamical r-matrices r on a commutative subalgebra  $\mathfrak g$  of a Lie algebra  $\mathfrak g$  to a purely algebraic problem, under some assumption on the symmetric part of r. We then describe, for a simple complex Lie algebra  $\mathfrak g$ , all non skew-symmetric dynamical r-matrices on a commutative subalgebra  $\mathfrak l \subset \mathfrak g$  which contains a regular semisimple element. This interpolates results of P. Etingof and A. Varchenko ([EV], when  $\mathfrak l$  is a Cartan subalgebra) and results of A. Belavin and V. Drinfeld for constant r-matrices ([BD]). This classification is similar, and in some sense simpler than the Belavin-Drinfeld classification.

#### 1. The classical Yang-Baxter equation

Let  $\mathfrak{g}$  be a Lie algebra. The CYBE is the following algebraic equation for an element  $r \in \mathfrak{g} \otimes \mathfrak{g}$ :

(1) 
$$[r^{12}, r^{13}] + [r^{12}, r^{23}] + [r^{13}, r^{23}] = 0.$$

Solutions of this equation are called r-matrices. In the theory of quantum groups, one is mainly interested in r-matrices satisfying

$$(2) r + r^{21} \in (S^2 \mathfrak{g})^{\mathfrak{g}}.$$

See [CP] for the links with the theory of quantum groups, and [Che] for links with Conformal Field Theory and the Wess-Zumino-Witten model on  $\mathbb{P}^1$ . The geometric interpretation of the CYBE was given by Drinfeld in terms of Poisson-Lie groups ([Dr1]).

## 2. The Belavin-Drinfeld classification

**Notations.** Let  $\mathfrak{g}$  be a simple complex Lie algebra with a nondegenerate invariant form  $(\,,\,)$ ,  $\mathfrak{h} \subset \mathfrak{g}$  a Cartan subalgebra and  $\Delta$  the root system. For  $\alpha \in \Delta$ , let  $\mathfrak{g}_{\alpha}$  denote the root subspace associated to  $\alpha$ . Let W be the Weyl group and  $s_{\alpha}$ ,  $\alpha \in \Delta$  the reflection with respect to  $\alpha^{\perp}$ . Finally, let  $\Omega \in S^2\mathfrak{g}$  and  $\Omega_{\mathfrak{h}} \in S^2\mathfrak{h}$  be the inverse elements to the form  $(\,,\,)$ . Notice that  $(S^2\mathfrak{g})^{\mathfrak{g}} = \mathbb{C}\Omega$ .

For any polarization  $\mathfrak{g} = \mathfrak{n}_- \oplus \mathfrak{h} \oplus \mathfrak{n}_+$ , we denote by  $\Pi$  or  $\Pi(\mathfrak{n}_+)$  the corresponding set of simple positive roots, by  $\Delta_+$  the set of positive roots and by  $\mathfrak{b}_{\pm} = \mathfrak{n}_{\pm} \oplus \mathfrak{h}$  the Borel subalgebras. For  $\Gamma \subset \Pi$ , set  $\langle \Gamma \rangle = \mathbb{Z}\Gamma \cap \Delta$ , and let  $\mathfrak{g}_{\Gamma}$  be the subalgebra generated by  $\mathfrak{g}_{\alpha}$ ,  $\alpha \in \langle \Gamma \rangle$ . We will write  $\mathfrak{g}_{\Gamma} = \mathfrak{n}_+(\Gamma) \oplus \mathfrak{h}(\Gamma) \oplus \mathfrak{n}_-(\Gamma)$ 

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for the induced polarization and  $W(\Gamma)$  for the subgroup of W generated by  $s_{\alpha}$ ,  $\alpha \in \Gamma$ . Let us fix a polarization of  $\mathfrak{g}$ .

**Definition.** A Belavin-Drinfeld triple is a triple  $(\Gamma_1, \Gamma_2, \tau)$  where  $\Gamma_1, \Gamma_2 \subset \Pi$  and  $\tau : \Gamma_1 \xrightarrow{\sim} \Gamma_2$  is a norm-preserving bijection satisfying the following "nilpotency" condition:

"For any  $\gamma_1 \in \Gamma_1$ , there exists n > 0 such that  $\tau^n(\gamma_1) \in \Gamma_2 \backslash \Gamma_1$ ".

Let  $(\Gamma_1, \Gamma_2, \tau)$  be a Belavin-Drinfeld triple. For each choice of Chevalley generators  $(e_{\alpha}, f_{\alpha}, h_{\alpha})_{\alpha \in \Gamma_i}$ , i = 1, 2, the isomorphism  $\tau$  induces a Lie algebra isomorphism  $\mathfrak{g}_{\Gamma_1} \stackrel{\sim}{\to} \mathfrak{g}_{\Gamma_2}$  (by  $e_{\alpha} \mapsto e_{\tau(\alpha)}$ ,  $f_{\alpha} \mapsto f_{\tau(\alpha)}$ ,  $h_{\alpha} \mapsto h_{\tau(\alpha)}$ ). Define a partial order on  $\Delta_+$  by setting  $\alpha < \beta$  if there exists n > 0 such that  $\tau^n(\alpha) = \beta$  (in particular,  $\alpha \in \Gamma_1$  and  $\beta \in \Gamma_2$ ).

**Definition.** A basis  $(x_{\alpha})_{\alpha \in \Delta}$  of  $\mathfrak{n}_+ \oplus \mathfrak{n}_-$  is called *admissible* if  $(x_{\alpha}, x_{-\alpha}) = 1$  and  $\tau(x_{\alpha}) = x_{\tau(\alpha)}$  for  $\alpha \in \langle \Gamma_1 \rangle$ .

**Theorem 1 (Belavin-Drinfeld).** Let  $\mathfrak{g}$  be a simple complex Lie algebra. 1. Let  $(\Gamma_1, \Gamma_2, \tau)$  be a Belavin-Drinfeld triple,  $(x_\alpha)$  an admissible basis, and let  $r_0 \in \mathfrak{h} \otimes \mathfrak{h}$  be such that

$$(3) r_0 + r_0^{21} = \Omega_{\mathfrak{h}},$$

(4) 
$$(\tau(\alpha) \otimes 1)r + (1 \otimes \alpha)r = 0 for \alpha \in \Gamma_1.$$

Then

(5) 
$$r = r_0 + \sum_{\alpha \in \Delta_+} x_{-\alpha} \otimes x_{\alpha} + \sum_{\alpha, \beta \in \Delta_+, \alpha < \beta} x_{-\alpha} \wedge x_{\beta}$$

is an r-matrix satisfying  $r + r^{21} = \Omega$ .

2. Any r-matrix satisfying  $r + r^{21} = \Omega$  is of the above type for a suitable polarization of  $\mathfrak{g}$ .

This theorem is proved in [BD]. For instance, the standard r-matrix for a fixed polarization  $r = \frac{\Omega_{\mathfrak{h}}}{2} + \sum_{\alpha \in \Delta_{+}} x_{-\alpha} \otimes x_{\alpha}$  corresponds to  $\Gamma_{1} = \Gamma_{2} = \emptyset$ .

Remark. Skew-symmetric r-matrices admit a well known interpretation in terms of nondegenerate 2-cocycles on Lie subalgebras of  $\mathfrak{g}$  ([Dr1]), but their classification is unavailable since it requires a classification of Lie subalgebras in  $\mathfrak{g}$ .

### 3. The dynamical Yang-Baxter equation

Let  $\mathfrak g$  be a Lie algebra over  $\mathbb C$  and  $\mathfrak l\subset \mathfrak g$  a subalgebra. An element  $x\in \mathfrak g\otimes \mathfrak g$  will be called  $\mathfrak l$ -invariant if

$$[k \otimes 1 + 1 \otimes k, x] = 0 \qquad (\forall k \in \mathfrak{l}).$$

For  $x \in \mathfrak{g}^{\otimes 3}$ , we let  $\mathrm{Alt}(x) = x^{123} + x^{231} + x^{312}$ . Let  $D \subset \mathfrak{l}^*$  be any open region. The CDYBE is the following differential equation for a holomorphic  $\mathfrak{l}$ -invariant function  $r: D \to \mathfrak{g} \otimes \mathfrak{g}$ :

(7) 
$$\operatorname{Alt}(dr) + [r^{12}, r^{13}] + [r^{12}, r^{23}] + [r^{13}, r^{23}] = 0,$$

where the differential of r is considered as a holomorphic function

$$dr: D \to \mathfrak{g} \otimes \mathfrak{g} \otimes \mathfrak{g}, \qquad \lambda \mapsto \sum_{i} x_{i} \otimes \frac{\partial r^{23}}{\partial x_{i}}(\lambda), \qquad (\lambda \in \mathfrak{l}^{*}),$$

for any basis  $(x_i)$  of  $\mathfrak{l}$ . In this case,

$$Alt(dr) = \sum_{i} x_{i}^{(1)} \frac{\partial r^{23}}{\partial x_{i}} + \sum_{i} x_{i}^{(2)} \frac{\partial r^{31}}{\partial x_{i}} + \sum_{i} x_{i}^{(3)} \frac{\partial r^{12}}{\partial x_{i}}.$$

The solutions to this equation are called *dynamical* r-matrices. Dynamical r-matrices which are relevant to the theory of quantum groups are those satisfying the following condition, analogous to (2):

(8) Generalized unitarity: 
$$r(\lambda) + r^{21}(\lambda) \in (S^2\mathfrak{g})^{\mathfrak{g}}$$
.

Remark. The CDYBE was first written down by G. Felder and C. Wiezcerkowski in connection with the Wess-Zumino-Witten model on elliptic curves ([FW]). The relation with elliptic quantum groups is explained in [Fe]. A geometric interpretation of the CDYBE analogous to the theory of Poisson-Lie groups for the CYBE is given in [EV].

#### 4. Gauge transformations

We recall some results from [EV]. We suppose here that  $\mathfrak{l}$  is commutative and we let D be the formal polydisc centered at the origin. Let G be a complex Lie group such that  $\text{Lie}(G) = \mathfrak{g}$ , and let L be the connected subgroup of G such that  $\text{Lie}(L) = \mathfrak{l}$ . Let  $G^L$  be the centralizer of L in G and  $\mathfrak{g}^{\mathfrak{l}}$  its Lie algebra. We will denote by  $(\mathfrak{g} \otimes \mathfrak{g})^{\mathfrak{l}}$  the space of all  $\mathfrak{l}$ -invariant elements in  $\mathfrak{g} \otimes \mathfrak{g}$ .

Let  $g: D \to G^L$  be any holomorphic function; the 1-form  $\eta = g^{-1}dg$  gives rise to a function  $\overline{\eta}: D \to \mathfrak{l} \otimes \mathfrak{g}^{\mathfrak{l}}$ . If  $r: D \to (\mathfrak{g} \otimes \mathfrak{g})^{\mathfrak{l}}$  is an  $\mathfrak{l}$ -invariant function satisfying (8), we set

$$r^g = (g \otimes g)(r - \overline{\eta} + \overline{\eta}^{21})(g^{-1} \otimes g^{-1}).$$

**Proposition 1.** The function r is a dynamical r-matrix if and only if the function  $r^g$  is.

Thus the group  $\operatorname{Map}(D, G^L)$  is a gauge transformation group for the CDYBE. Notice that this group is not commutative if  $G^L$  isn't.

**Theorem 2.** Let  $\rho, r: D \to \mathfrak{g}^{\otimes 2}$  be two dynamical r-matrices satisfying (8) such that  $r(0) = \rho(0)$ . There exists  $g \in \operatorname{Map}(D, G^L)$  such that  $\rho = r^g$ .

This shows that the space of dynamical r-matrices is, up to gauge equivalence, finite dimensional. Proofs of the above results can be found in [EV].

We will now prove a converse of Theorem 2 which reduces the CDYBE to a purely algebraic equation under some assumption on the symmetric part  $\frac{\Omega}{2}$  of r: let  $\Omega \in (S^2\mathfrak{g})^{\mathfrak{g}}$ , let  $\mathfrak{g}_{\Omega}$  be the ideal in  $\mathfrak{g}$  generated by the components of  $\Omega$  and denote by  $\mathfrak{g}_{\Omega} = \bigoplus_{\lambda} \mathfrak{g}_{\Omega}(\lambda)$  the generalized weight space decomposition of  $\mathfrak{g}_{\Omega}$  with respect to the adjoint action of  $\mathfrak{l}$ . The condition we will need is the following:

(\*) 
$$\mathfrak{g}^{\mathfrak{l}}$$
 acts semisimply on  $\mathfrak{g}_{\Omega}(0)$ .

Suppose that (\*) is fulfilled and let  $z(\mathfrak{g}^{\mathfrak{l}})$  denote the center of  $\mathfrak{g}^{\mathfrak{l}}$ . Then we have a decomposition  $\mathfrak{g}_{\Omega}(0) = z_{0}(\mathfrak{g}^{\mathfrak{l}}) \oplus V$  where  $z_{0}(\mathfrak{g}^{\mathfrak{l}}) = z(\mathfrak{g}^{\mathfrak{l}}) \cap \mathfrak{g}_{\Omega}(0)$  and V is the sum of all non-trivial irreducible  $\mathfrak{g}^{\mathfrak{l}}$ -modules in  $\mathfrak{g}_{\Omega}(0)$ . It is clear that  $\mathfrak{l} \cap V = \{0\}$ . We will say that a complement  $\mathfrak{l}'$  of  $\mathfrak{l}$  in  $\mathfrak{g}$  is admissible if  $V \subset \mathfrak{l}'$ , and write  $\pi : \mathfrak{g} \to \mathfrak{l}$  for the projection along  $\mathfrak{l}'$ . Notice that by  $\mathfrak{g}^{\mathfrak{l}}$ -invariance of  $\Omega$ ,

(9) 
$$\Omega \in S^2 z_0(\mathfrak{g}^{\mathfrak{l}}) \oplus S^2 V \oplus \bigoplus_{\lambda \neq 0} \mathfrak{g}_{\Omega}(\lambda) \otimes \mathfrak{g}_{\Omega}(-\lambda).$$

We will denote by  $CYB: \mathfrak{g}^{\otimes 2} \to \mathfrak{g}^{\otimes 3}$  the map:

$$r \mapsto [r^{12}, r^{13}] + [r^{12}, r^{23}] + [r^{13}, r^{23}].$$

It is more convenient to work with the skew-symmetric part of r. If  $r(\lambda) + r^{21}(\lambda) = \Omega \in (S^2(\mathfrak{g}))^{\mathfrak{g}}$ , we set  $s(\lambda) = r(\lambda) - \frac{\Omega}{2}$ . It is easy to see that the CDYBE for r is equivalent to the following equation for s:

(10) 
$$\operatorname{Alt}(ds) + CYB(s) + \frac{1}{4}CYB(\Omega) = 0.$$

Recall that as  $\Omega$  is symmetric and invariant,  $CYB(\Omega) = [\Omega_{13}, \Omega_{23}].$ 

**Theorem 3.** Let G be a complex Lie group and  $L \subset G$  a connected commutative subgroup. Let  $\mathfrak{g}, \mathfrak{l}, \mathfrak{g}^{\mathfrak{l}}$  denote the Lie algebras of G, L and  $G^{L}$ . Let  $\Omega \in (S^{2}\mathfrak{g})^{\mathfrak{g}}$ . Then

- 1. Let  $\mathfrak{l}'$  be any complement of  $\mathfrak{l}$  in  $\mathfrak{g}$ . Any dynamical r-matrix  $r(\lambda)$  on  $\mathfrak{l}$  such that  $r(\lambda) + r^{21}(\lambda) = \Omega$  is gauge equivalent to a dynamical r-matrix  $\tilde{r}(\lambda)$  such that  $\tilde{r}(0) \in \frac{\Omega}{2} + (\Lambda^2(\mathfrak{l}'))^{\mathfrak{l}}$ .
- 2. Suppose that condition (\*) is true and let l' be any admissible complement of l in  $\mathfrak{g}$ . Let  $r_0 \in \frac{\Omega}{2} + (\Lambda^2(l'))^l$  satisfy

(11) 
$$CYB(r_0) \in Alt(\mathfrak{l} \otimes \mathfrak{g} \otimes \mathfrak{g}),$$

such that  $s_0 = r_0 - \frac{\Omega}{2}$  is a regular point of the algebraic manifold

$$M_{\Omega} = \{ s \in (\Lambda^{2}(\mathfrak{l}'))^{\mathfrak{l}} \mid CYB(s + \frac{\Omega}{2}) \in Alt(\mathfrak{l} \otimes \mathfrak{g} \otimes \mathfrak{g}) \}.$$

Then there exists a dynamical r-matrix  $r(\lambda): D \to \frac{\Omega}{2} + (\Lambda^2(\mathfrak{l}'))^{\mathfrak{l}}$  such that  $r(0) = r_0$ .

The condition (\*) is satisfied in the following two interesting special cases: when  $\Omega = 0$  (triangular case) or when  $\mathfrak{g}^{\mathfrak{l}}$  acts semisimply on  $\mathfrak{g}$  (for instance, G is reductive and L is contained in a maximal torus of G or more generally, if  $G^{L}$  is reductive).

The proof of this theorem will occupy the rest of this section. Let us first prove part 1:

**Lemma 1.** Any dynamical r-matrix such that  $r(\lambda) + r^{21}(\lambda) = \Omega$  is gauge-equivalent to a dynamical r-matrix  $\tilde{r}(\lambda)$  such that  $\tilde{r}(0) \in \frac{\Omega}{2} + (\Lambda^2(\mathfrak{l}')^{\mathfrak{l}})$ .

Proof. Let  $\overline{\eta} \in \mathfrak{l} \otimes \mathfrak{g}^{\mathfrak{l}}$  be such that  $r(0) - \overline{\eta} + \overline{\eta}^{21} \in \frac{\Omega}{2} + \Lambda^{2}(\mathfrak{l}')$ . There exists a function  $g: D \to G^{L}$  such that  $g^{-1}dg(0) = \eta$  (see [EV], Lemma 1.3). It is easy to see that  $\tilde{r} = r^{g}$  satisfies the desired conditions.

Let us now prove part 2. We will interpret the CDYBE (10) as a consistent system of differential equations defined on  $M_{\Omega}$ .

For  $s \in M_{\Omega}$ , (10) is equivalent to

$$(\pi \otimes 1 \otimes 1) \operatorname{Alt}(ds) = -(\pi \otimes 1 \otimes 1)(CYB(s) + \frac{1}{4}CYB(\Omega)).$$

This reduces to

(12) 
$$ds = -(\pi \otimes 1 \otimes 1)([s^{12}, s^{13}] + \frac{1}{4}CYB(\Omega)),$$

or, in coordinates  $(x_i)$ , where  $(x_i)$  is a basis of  $\mathfrak{l}$ ,

$$\frac{\partial s}{\partial x_i} = -(x_i \otimes 1 \otimes 1)([s^{12}, s^{13}] + \frac{1}{4}CYB(\Omega)).$$

**Lemma 2.** The system (12) is consistent.

*Proof.* Set  $X: M_{\Omega} \to \mathfrak{l} \otimes \mathfrak{g} \otimes \mathfrak{g}$ ,  $s \mapsto (\pi \otimes 1 \otimes 1)([s^{12}, s^{13}] + \frac{1}{4}CYB(\Omega))$ . By definition, the curvature of (12) is given by

$$\sum_{i,j} x_i \otimes x_j \otimes \left(\frac{\partial^2 s}{\partial x_i \partial x_j} - \frac{\partial^2 s}{\partial x_j \partial x_i}\right)$$

$$= (\pi \otimes \pi \otimes 1 \otimes 1) \left(\left\{\left[s^{23}, \left[s^{12}, s^{14}\right]\right] + \left[s^{23}, \frac{1}{4}CYB(\Omega)^{124}\right]\right.\right.$$

$$+ \left[\left[s^{12}, s^{13}\right], s^{24}\right] + \left[\frac{1}{4}CYB(\Omega)^{123}, s^{24}\right]\right\}$$

$$- \left\{\left[s^{13}, \left[s^{21}, s^{24}\right]\right] + \left[s^{13}, \frac{1}{4}CYB(\Omega)^{214}\right]\right.$$

$$+ \left[\left[s^{21}, s^{23}\right], s^{14}\right] + \left[\frac{1}{4}CYB(\Omega)^{213}, s^{14}\right]\right\}$$

$$= (\pi \otimes \pi \otimes 1 \otimes 1) \left(\left\{\left[s^{23}, \left[s^{12}, s^{14}\right]\right]\right.\right.$$

$$+ \left[\left[s^{12}, s^{13}\right], s^{24}\right] - \left[s^{13}, \left[s^{21}, s^{24}\right]\right] - \left[\left[s^{21}, s^{23}\right], s^{14}\right]\right\}$$

$$+ \frac{1}{4} \left\{\left[s^{13} + s^{23}, CYB(\Omega)^{124}\right] - \left[s^{14} + s^{24}, CYB(\Omega)^{123}\right]\right\}\right).$$

By the Jacobi identity,

$$[s^{23}, [s^{12}, s^{14}]] = [[s^{21}, s^{23}], s^{14}], \qquad [[s^{12}, s^{13}], s^{24}] = [s^{13}, [s^{21}, s^{24}]].$$

By  $\mathfrak{g}$ -invariance of  $CYB(\Omega)$ , we have

$$[s^{13} + s^{23}, CYB(\Omega)^{124}] = [s^{34}, CYB(\Omega)^{124}],$$
  
$$[s^{14} + s^{24}, CYB(\Omega)^{123}] = -[s^{34}, CYB(\Omega)^{123}].$$

Overall, we have the following expression for the curvature of (12):

$$\frac{1}{4}(\pi\otimes\pi\otimes 1\otimes 1)([CYB(\Omega)^{123}+CYB(\Omega)^{124},s^{34}]=\frac{1}{4}[(\pi\otimes\pi\otimes 1)CYB(\Omega),s]$$

But (9) and the fact that  $\mathfrak{l}'$  is admissible imply that  $(\pi \otimes \pi \otimes 1)CYB(\Omega) = 0$ . Thus, (12) is consistent.

**Lemma 3.** The system (12) is defined on  $M_{\Omega}$ , i.e the vector fields defined by (12) are tangent to  $M_{\Omega}$ .

Proof. Let  $x^* \in \mathfrak{l}^* \stackrel{\pi^*}{\hookrightarrow} \mathfrak{g}^*$ , and set  $h = (x^* \otimes 1 \otimes 1)([s^{12}, s^{13}] + \frac{1}{4}CYB(\Omega))$ . Since  $s \in \Lambda^2(\mathfrak{l}')$  we have  $(x^* \otimes 1 \otimes 1)[s^{12}, s^{13}] \in \Lambda^2(\mathfrak{l}')$ . Moreover, the admissibility of  $\mathfrak{l}'$  and (9) together imply that  $(x^* \otimes 1 \otimes 1)(CYB(\Omega)) \in (\Lambda^2\mathfrak{l}')^{\mathfrak{l}}$  since  $[\mathfrak{l} \otimes 1, S^2z_0(\mathfrak{g}^{\mathfrak{l}})] = 0$ . Thus  $h \in \Lambda^2\mathfrak{l}'$ .

To conclude the proof of Lemma 3 and Theorem 3, we now show that

(13) 
$$[s^{12}, h^{13}] + [s^{12}, h^{23}] + [s^{13}, h^{23}] + [h^{12}, s^{13}] + [h^{12}, s^{23}] + [h^{13}, s^{23}] \in Alt(\mathfrak{l} \otimes \mathfrak{g} \otimes \mathfrak{g}).$$

To make the presentation more clear, we will use the pictorial technique to represent expressions and make computations: we associate to each morphism from a n-tensor to a m-tensor a diagram in the following way: the operation of taking the commutator is represented by

Applying a linear form  $x^*$  will be denoted by

$$\mathbf{a} \longrightarrow \mathbf{x}^* \quad \mathbf{x}^* \quad \mathbf{x}$$

Finally, we will represent s and  $\frac{\Omega}{2}$ , which can be thought of as maps from a 0-tensor to a 2-tensor, by

$$=$$
  $\frac{\Omega}{2}$   $=$ 

For instance,

**Lemma 4.** We have  $x^{*(3)}[CYB(s+\frac{\Omega}{2})^{123}, s^{34}] \in Alt(\mathfrak{l} \otimes \mathfrak{g} \otimes \mathfrak{g})$  or, in pictures  $(modulo\ Alt(\mathfrak{l} \otimes \mathfrak{g} \otimes \mathfrak{g}))$ 

$$x^*$$
 +  $x^*$  +  $x^*$  = 0

*Proof.* Recall that  $CYB(s+\frac{\Omega}{2}) \in Alt(\mathfrak{l} \otimes \mathfrak{g} \otimes \mathfrak{g})$ . Thus the only part of the above expression which can lie outside of  $Alt(\mathfrak{l} \otimes \mathfrak{g} \otimes \mathfrak{g})$  is obtained from the  $\mathfrak{g} \otimes \mathfrak{g} \otimes \mathfrak{l}$ -part of CYB(s). But if  $y \in \mathfrak{l}$ ,

$$(x^* \otimes 1)[y \otimes 1, s] = -(x^* \otimes 1)[1 \otimes y, s]$$

by  $\mathfrak{l}$ -invariance of s. This last expression is zero since  $s \in (\Lambda^2(\mathfrak{l}'))^{\mathfrak{l}}$ . Lemma 4 is proved.

It is clear how to generalize Lemma 4 to other expressions of the form

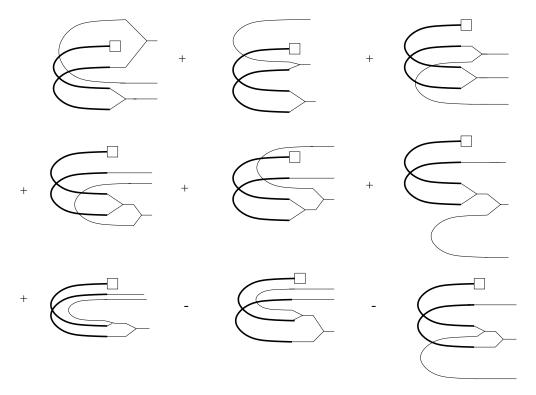
$$x^{*(k)}[CYB(s+\frac{\Omega}{2})^{123},s^{k4}].$$

Now, (13) can be drawn as

but by Lemma (4) we have, modulo  $Alt(\mathfrak{l} \otimes \mathfrak{g} \otimes \mathfrak{g})$ ,

It is easy to check that the sum of the terms of type [CYB(s), s] in this last expression is zero by the Jacobi identity. Moreover, by  $\mathfrak{g}$ -invariance of  $\Omega$ , we have

Thus, modulo  $Alt(\mathfrak{l} \otimes \mathfrak{g} \otimes \mathfrak{g})$ , (13) reduces to



The sums of terms in each column is zero by Jacobi Identity. This concludes the proof of Theorem 3.

### 5. Classification of dynamical r-matrices

Let  $\mathfrak{g}$  be a simple Lie algebra and let  $\Omega \in (S^2\mathfrak{g})^{\mathfrak{g}}$  be the Casimir element. In that case, (8) becomes

(14) 
$$r(\lambda) + r^{21}(\lambda) = \epsilon \Omega.$$

We will classify all solutions of equations (6,7,14) when  $\epsilon \neq 0$  and when  $\mathfrak{l}$  contains a semisimple regular element. In particular, in this case, the centralizer  $\mathfrak{h}$  of  $\mathfrak{l}$  is the unique Cartan subalgebra containing  $\mathfrak{l}$ . Notice that we can assume that  $\epsilon = 1$  ( since the assignment  $r(\lambda) \to \epsilon r(\epsilon \lambda)$  is a gauge transformation of (7)). We can also assume that the restriction of  $(\ ,\ )$  to  $\mathfrak{l}$  is nondegenerate. Indeed, for any dynamical r-matrix, we can replace  $\mathfrak{l}$  by the largest subspace of  $\mathfrak{h}$  for which r is invariant, and such a subspace is real. Let  $\mathfrak{h}_0$  be the orthogonal complement of  $\mathfrak{l}$  in  $\mathfrak{h}$  and let  $i:\mathfrak{l} \hookrightarrow \mathfrak{h}$  be the inclusion map. We will also write  $(\ ,\ )$  for the induced bracket on  $\mathfrak{l}^*$ . Let  $\Omega_{\mathfrak{h}_0}$  denote the Casimir element of the restriction of  $(\ ,\ )$  to  $\mathfrak{h}_0$ .

## **5.1. Statement of the theorem.** Let $\mathfrak{g} = \mathfrak{n}_+ \oplus \mathfrak{h} \oplus \mathfrak{n}_-$ be a polarization of $\mathfrak{g}$ .

**Definition.** A generalized Belavin-Drinfeld triple is a triple  $(\Gamma_1, \Gamma_2, \tau)$  where  $\Gamma_1, \Gamma_2 \subset \Pi$ , and  $\tau : \Gamma_1 \xrightarrow{\sim} \Gamma_2$  is a norm-preserving bijection.

In other terms, in a generalized Belavin-Drinfeld triple, we drop the nilpotency condition. We will say that a generalized Belavin-Drinfeld triple is  $\mathfrak{l}$ -graded if  $\tau$  preserves the decomposition of  $\mathfrak{g}$  in  $\mathfrak{l}$ -weight spaces. If  $(\Gamma_1, \Gamma_2, \tau)$  is a generalized Belavin-Drinfeld triple, we will denote by  $\Gamma_3$  the largest subset of  $\Gamma_1 \cap \Gamma_2$  which is stable under  $\tau$ , and  $\tilde{\Gamma}_1 = \Gamma_1 \backslash \Gamma_3$ ,  $\tilde{\Gamma}_2 = \Gamma_2 \backslash \Gamma_3$ . It is clear that  $(\tilde{\Gamma}_1, \tilde{\Gamma}_2, \tau)$  is a Belavin-Drinfeld triple. As before, for each choice of Chevalley generators  $(e_{\alpha}, f_{\alpha}, h_{\alpha})_{\alpha \in \Gamma_i}$ , the map  $\tau$  induces isomorphisms  $\mathfrak{g}_{\tilde{\Gamma}_1} \to \mathfrak{g}_{\tilde{\Gamma}_2}$  and  $\tau : \mathfrak{g}_{\Gamma_3} \to \mathfrak{g}_{\Gamma_3}$ . For  $\lambda \in \mathfrak{l}^*$ , consider the map:

$$\begin{split} K(\lambda) : \mathfrak{n}_+(\Gamma_1) &\to \mathfrak{n}_+(\Gamma_2) \\ e_\alpha &\mapsto \frac{1}{2} e_\alpha + e^{-(\alpha,\lambda)} \frac{\tau}{1 - e^{-(\alpha,\lambda)}\tau}(e_\alpha). \end{split}$$

Notice that we have

$$K(\lambda)(e_{\alpha}) = \frac{1}{2}e_{\alpha} + \sum_{n>0} e^{-n(\alpha,\lambda)} \tau^{n}(e_{\alpha}).$$

This sum is finite for  $\alpha \notin \langle \Gamma_3 \rangle$ .

**Theorem 4.** Let  $\mathfrak{g}$  be a simple Lie algebra with nondegenerate invariant bilinear form  $(\,,\,)$ ,  $\mathfrak{l} \subset \mathfrak{g}$  a commutative subalgebra containing a regular semisimple element on which  $(\,,\,)$  is nondegenerate,  $\mathfrak{h}$  the Cartan subalgebra containing  $\mathfrak{l}$  and  $\mathfrak{h}_0$  the orthogonal complement of  $\mathfrak{l}$  in  $\mathfrak{h}$ . Then

1. Any dynamical r-matrix is gauge-equivalent to a dynamical r-matrix  $\tilde{r}$  such that

(15) 
$$\tilde{r}(\lambda) - \tilde{r}(\lambda)^{21} \in (\mathfrak{l}^{\perp})^{\otimes 2} = (\bigoplus_{\alpha \neq 0} \mathfrak{g}_{\alpha} \oplus \mathfrak{h}_{0})^{\otimes 2}.$$

2. Let  $(\Gamma_1, \Gamma_2, \tau)$  be an  $\mathfrak{l}$ -graded generalized Belavin-Drinfeld triple and let  $(e_{\alpha}, f_{\alpha}, h_{\alpha})_{\Gamma_i}$  be a choice of Chevalley generators. Let  $r_{\mathfrak{h}_0, \mathfrak{h}_0} \in \mathfrak{h}_0 \otimes \mathfrak{h}_0$  satisfy the equation

(16) 
$$(\tau(\alpha) \otimes 1) r_{\mathfrak{h}_0,\mathfrak{h}_0} + (1 \otimes \alpha) r_{\mathfrak{h}_0,\mathfrak{h}_0} = \frac{1}{2} ((\alpha + \tau(\alpha)) \otimes 1) \Omega_{\mathfrak{h}_0}.$$

Then

$$r(\lambda) = \frac{1}{2}\Omega + r_{\mathfrak{h}_0,\mathfrak{h}_0} + \sum_{\alpha \in \langle \Gamma_1 \rangle \cap \Delta_+} K(\lambda)(e_\alpha) \wedge e_{-\alpha} + \sum_{\alpha \in \Delta_+,\, \alpha \not\in \langle \Gamma_1 \rangle} \frac{1}{2} e_\alpha \wedge e_{-\alpha}$$

is a solution the CDYBE satisfying (15).

3. Any solution of the CDYBE satisfying (15) is of the above type for a suitable polarization of  $\mathfrak{g}$ .

The proof of this theorem will occupy the rest of this section. Our methods are greatly inspired by the paper [BD]. Notice that 1. follows from Theorem 3, but we will describe the gauge transformations explicitly in this case.

**Notations.** Let  $\Delta \subset \mathfrak{h}^*$  be the root system of  $\mathfrak{g}$  with respect to  $\mathfrak{h}$  and set  $\Delta_{\mathfrak{l}} = i^*(\Delta) \subset \mathfrak{l}^*$ . We will denote by  $\mathfrak{g}_{\bar{\alpha}}$  the weight subspace associated to  $\bar{\alpha} = i^*(\alpha) \in \Delta_{\mathfrak{l}}$ , and we set  $\mathfrak{g}_{\overline{0}} = \mathfrak{h}_0$ . It is clear that

$$\mathfrak{g}_{\overline{\alpha}} = \bigoplus_{eta \in \Delta, \ i^*(eta) = \overline{\alpha}} \mathfrak{g}_{eta}$$

In particular, (, ) is a pairing  $\mathfrak{g}_{\overline{\alpha}} \times \mathfrak{g}_{-\overline{\alpha}} \to \mathbb{C}$ .

A vector space  $V \subset \mathfrak{g}$  will be called  $\mathfrak{h}$ -graded (resp.  $\mathfrak{l}$ -graded) if it is an  $\mathfrak{h}$ -submodule (resp.  $\mathfrak{l}$ -submodule) of  $\mathfrak{g}$ . Finally, let  $\Omega' \in (\mathfrak{l}^{\perp})^{\otimes 2}$  denote the Casimir (inverse element) of the restriction of (, ) to  $\mathfrak{l}^{\perp} = \mathfrak{h}_0 \bigoplus \mathfrak{g}_{\overline{\alpha}}$ .

Now let  $r: \mathfrak{l}^* \supset D \to (\mathfrak{g} \otimes \mathfrak{g})^{\mathfrak{l}}$  be a formal power series satisfying (14) (with  $\epsilon = 1$ ). By (6), we can write

(17) 
$$r(\lambda) = \frac{1}{2}\Omega + r_{\mathfrak{l},\mathfrak{l}}(\lambda) + r_{\mathfrak{l},\mathfrak{h}_0}(\lambda) + r_{\mathfrak{h}_0,\mathfrak{l}}(\lambda) + (\varphi(\lambda) \otimes 1)\Omega',$$

where  $r_{\mathfrak{l},\mathfrak{l}}(\lambda) \in \mathfrak{l} \otimes \mathfrak{l}$ ,  $r_{\mathfrak{l},\mathfrak{h}_0}(\lambda) \in \mathfrak{l} \otimes \mathfrak{h}_0$ ,  $r_{\mathfrak{h}_0,\mathfrak{l}}(\lambda) \in \mathfrak{h}_0 \otimes \mathfrak{l}$  and where  $\varphi(\lambda) \in \operatorname{End}\left(\mathfrak{h}_0 \bigoplus \mathfrak{g}_{\overline{\alpha}}\right)$  is a sum of maps  $\varphi_{\overline{\alpha}}(\lambda) \in \operatorname{End}\left(\mathfrak{g}_{\overline{\alpha}}\right)$ . By the unitarity condition,  $r_{\mathfrak{l},\mathfrak{l}}(\lambda) \in \Lambda^2\mathfrak{l}$ ,  $r_{\mathfrak{l},\mathfrak{h}_0}(\lambda) = -r_{\mathfrak{h}_0,\mathfrak{l}}^{21}(\lambda)$  and  $\varphi_{-\overline{\alpha}}(\lambda) = -\varphi_{\overline{\alpha}}^*(\lambda)$ .

With these notations, the CDYBE splits into 4 components: the  $\mathfrak{l} \otimes \mathfrak{l} \otimes \mathfrak{l}$ -part, the  $\mathfrak{l} \otimes \mathfrak{l} \otimes \mathfrak{h}_0$ -part, the  $\mathfrak{l} \otimes \mathfrak{g}_{\bar{\alpha}} \otimes \mathfrak{g}_{-\bar{\alpha}}$ -part and the  $\mathfrak{g}_{\bar{\alpha}} \otimes \mathfrak{g}_{\bar{\beta}} \otimes \mathfrak{g}_{\bar{\gamma}}$ -part where  $\bar{\alpha} + \bar{\beta} + \bar{\gamma} = 0$ .

• The  $l \otimes l \otimes l$ -part: let us set  $r_{l,l} = \sum_{i,j} C_{i,j}(\lambda) x_i \otimes x_j$ . This part of the CDYBE can then be written:

(18) 
$$\frac{\partial C_{j,k}}{\partial x_i} + \frac{\partial C_{k,i}}{\partial x_j} + \frac{\partial C_{i,j}}{\partial x_k} = 0 \qquad \forall i, j, k$$

and says that  $\sum_{i,j} C_{i,j} dx_i \wedge dx_j$  is a closed 2-form.

• The  $\mathfrak{l} \otimes \mathfrak{l} \otimes \mathfrak{h}_0$ -part: let us set  $r_{\mathfrak{l},\mathfrak{h}_0} = \sum_{i,j} D_{i,j}(\lambda) x_i \otimes y_j$  for some basis  $(y_j)$  of  $\mathfrak{h}_0$ . This part of the CDYBE is

(19) 
$$\frac{\partial D_{i,j}}{\partial x_k} = \frac{\partial D_{k,j}}{\partial x_i} \qquad \forall i, k, j$$

and says that for any j,  $\sum_{i} D_{i,j}(\lambda) dx_i$  is a closed 1-form.

Since r is defined on a polydisc, the above forms are exact. Let  $f: D \to \mathfrak{h}_0$  be such that  $df(\lambda) = \sum_i D_{i,j}(\lambda) dx_i \otimes y_j$  and let  $\xi$  be a 1-form on D such that  $d\xi = \sum_{i,j} C_{i,j} dx_i \wedge dx_j$ . Then  $\xi$  defines a function  $\overline{\xi}: D \to \mathfrak{l}$ . The gauge transformation which should be applied to r to make it satisfy (15) is easily seen to be the following:  $r(\lambda) \mapsto r(\lambda)^g = \frac{1}{2}\Omega + (e^{-ad\ f(\lambda)}\varphi(\lambda)e^{ad\ f(\lambda)}\otimes 1)\Omega'$  where  $g(\lambda) = e^{f(\lambda)}e^{-\overline{\xi}(\lambda)}$ .

Thus, we can assume that  $r_{\mathfrak{l},\mathfrak{l}}=r_{\mathfrak{l},\mathfrak{h}_0}=0$ , in which case the remaining components of the CDYBE can be written in the following way:

• The  $\mathfrak{l} \otimes \mathfrak{g}_{\bar{\alpha}} \otimes \mathfrak{g}_{-\bar{\alpha}}$ -part:

(20) 
$$d\varphi_{\bar{\alpha}} + (\varphi_{\bar{\alpha}}^2 - \frac{1}{4})dh_{\bar{\alpha}} = 0.$$

In particular,  $r_{\mathfrak{h}_0,\mathfrak{h}_0} \in \Lambda^2 \mathfrak{h}_0$  is constant.

• The  $\mathfrak{g}_{\bar{\alpha}} \otimes \mathfrak{g}_{\bar{\beta}} \otimes \mathfrak{g}_{\bar{\gamma}}$ -part where  $\bar{\alpha} + \bar{\beta} + \bar{\gamma} = 0$ :

(21) 
$$\Lambda(\varphi_{\bar{\alpha}} \otimes \varphi_{\bar{\beta}} \otimes 1 + \varphi_{\bar{\alpha}} \otimes 1 \otimes \varphi_{\bar{\gamma}} + 1 \otimes \varphi_{\bar{\beta}} \otimes \varphi_{\bar{\gamma}} + \frac{1}{4}Id) = 0$$

where 
$$\Lambda: \ \mathfrak{g}_{\bar{\alpha}} \otimes \mathfrak{g}_{\bar{\beta}} \otimes \mathfrak{g}_{\bar{\gamma}} \to \mathbb{C}, \ x \otimes y \otimes z \mapsto ([x,y],z).$$

This set of equations is sufficient by skew-symmetry of the CDYBE.

**5.2.** The Cayley transform. Let us set  $A_{\pm} = \operatorname{Im}(\varphi(\lambda) \pm \frac{1}{2})$ ,  $I_{\pm} = \operatorname{Ker}(\varphi(\lambda) \mp \frac{1}{2})$ . Notice that, by (20),  $A_{\pm}$  and  $I_{\pm}$  are indeed independent of  $\lambda$ . Furthermore,  $A_{\pm}$ ,  $I_{\pm}$  are  $\mathfrak{l}$ -graded by the weight-zero condition,  $I_{\pm} \subset A_{\pm}$  and  $A_{\pm} = I_{\pm}^{\perp}$  by the unitarity condition. Notice also that  $A_{+} + A_{-} \oplus \mathfrak{l} = \mathfrak{g}$ . Now consider

$$\psi(\lambda) = \frac{\varphi - \frac{1}{2}}{\varphi + \frac{1}{2}} : A_{+}/I_{+} \to A_{-}/I_{-}.$$

Extend  $\psi(\lambda)$  to  $\psi(\lambda): \mathfrak{l} \oplus A_+/I_+ \to \mathfrak{l} \oplus A_-/I_-$  by setting  $\psi_{|\mathfrak{l}} = Id$ . It is clear that  $\psi$  is a well-defined linear isomorphism. The following proposition is crucial:

**Proposition 2.** The maps  $\varphi_{\bar{\alpha}}$  satisfy (20, 21) if and only if the following hold:

- (i)  $A_{\pm} \oplus \mathfrak{l}$  is a subalgebra of  $\mathfrak{g}$  and  $I_{\pm} \oplus \mathfrak{l}$  is an ideal of  $A_{\pm} \oplus \mathfrak{l}$ .
- (ii) there exists a (constant) map  $\psi_0$ :  $\mathfrak{l} \oplus A_+/I_+ \to \mathfrak{l} \oplus A_-/I_-$  such that  $\psi(\lambda)_{|\mathfrak{g}_{\bar{\alpha}}} = e^{-(\bar{\alpha},\lambda)}\psi_{0|\mathfrak{g}_{\bar{\alpha}}}$ .
- (iii) The map  $\psi_0$  is a Lie algebra map:

$$[\psi_0(x), \psi_0(y)] = \psi_0[x, y].$$

*Proof.* Assume that  $\varphi$  satisfies (20,21) and let  $a \in \mathfrak{g}_{\bar{\alpha}}$ ,  $b \in \mathfrak{g}_{\bar{\beta}}$ ,  $c \in \mathfrak{g}_{\bar{\gamma}}$  with  $\bar{\alpha} + \bar{\beta} + \bar{\gamma} = 0$ . From (21), we have

$$([(\varphi_{\bar{\alpha}} + \frac{1}{2})a, (\varphi_{\bar{\beta}} + \frac{1}{2})b], c) + ([a, (\varphi_{\bar{\beta}} + \frac{1}{2})b], (\varphi_{\bar{\gamma}} - \frac{1}{2})c) + ([(\varphi_{\bar{\alpha}} - \frac{1}{2})a, b], (\varphi_{\bar{\gamma}} - \frac{1}{2})c) = 0.$$

Since  $\varphi_{\bar{\gamma}} = -\varphi_{-\bar{\gamma}}^*$ , and (, ) is a nondegenerate pairing  $\mathfrak{g}_{\bar{\gamma}} \otimes \mathfrak{g}_{-\bar{\gamma}} \to \mathbb{C}$ , this implies that  $A_+ \oplus \mathfrak{l}$  is a Lie subalgebra of  $\mathfrak{g}$ . Note that the term in  $\mathfrak{l}$  is necessary here

since  $[\mathfrak{g}_{\bar{\alpha}},\mathfrak{g}_{-\bar{\alpha}}] \not\subset \mathfrak{g}_{\bar{0}} = \mathfrak{h}_0$ , but is not consequential as  $A_+$  is  $\mathfrak{l}$ -graded. The second claim of (i) follows from the relation

$$\left( [(\varphi_{\bar{\alpha}} - \frac{1}{2})a, (\varphi_{\bar{\beta}} - \frac{1}{2})b], c \right) + \left( [a, (\varphi_{\bar{\beta}} + \frac{1}{2})b], (\varphi_{\bar{\gamma}} + \frac{1}{2})c \right) + \left( [(\varphi_{\bar{\alpha}} - \frac{1}{2})a, b], (\varphi_{\bar{\gamma}} + \frac{1}{2})c \right) = 0.$$

The proof is the same for  $A_{-}$  and  $I_{-}$ . The equivalence of (ii) and (20) follows from the equality

$$\begin{split} d\psi_{|\mathfrak{g}_{\bar{\alpha}}} &= \frac{d\varphi_{\alpha}(\varphi_{\alpha} + \frac{1}{2}) - (\varphi_{\alpha} - \frac{1}{2})d\varphi_{\alpha}}{(\varphi_{\alpha} + \frac{1}{2})^2} \\ &= -\frac{(\varphi_{\alpha}^2 - \frac{1}{4})}{(\varphi_{\alpha} + \frac{1}{2})^2}dh_{\bar{\alpha}} \\ &= -(\bar{\alpha}, \lambda)\psi_{|\mathfrak{g}_{\bar{\alpha}}}. \end{split}$$

where we used (20). Finally it follows from (21) that

$$(\varphi_{\overline{\alpha+\beta}}-\frac{1}{2})\big([(\varphi_{\bar{\alpha}}+\frac{1}{2})a,(\varphi_{\bar{\beta}}+\frac{1}{2})b]\big)=(\varphi_{\overline{\alpha+\beta}}+\frac{1}{2})\big([(\varphi_{\bar{\alpha}}-\frac{1}{2})a,(\varphi_{\bar{\beta}}-\frac{1}{2})b]\big).$$

This implies (iii).

Conversely, if (i-iii) are satisfied then for any  $x \in \mathfrak{g}_{\bar{\alpha}}, y \in \mathfrak{g}_{\bar{\beta}}$  ( $\bar{\alpha} + \bar{\beta} \neq 0$ ) there exist  $z \in \mathfrak{g}_{\overline{\alpha}+\beta}$  such that  $[(\varphi_{\bar{\alpha}} - \frac{1}{2})x, (\varphi_{\bar{\beta}} - \frac{1}{2})y] = (\varphi_{\overline{\alpha}+\beta} - \frac{1}{2})z$ . Since  $\psi$  is a Lie algebra map,  $[(\varphi_{\bar{\alpha}} + \frac{1}{2})x, (\varphi_{\bar{\beta}} + \frac{1}{2})y] - (\varphi_{\overline{\alpha}+\beta} + \frac{1}{2})z \in \text{Ker}(\varphi_{\overline{\alpha}+\beta} - \frac{1}{2})$ . Subtracting, we obtain  $[(\varphi_{\bar{\alpha}} + \frac{1}{2})x, y] + [x, (\varphi_{\bar{\beta}} + \frac{1}{2})y] - [x, y] - z \in \text{Ker}(\varphi_{\overline{\alpha}+\beta} - \frac{1}{2})$ . Applying  $(\varphi - \frac{1}{2})$  and dropping the indices, we have

$$(\varphi - \frac{1}{2})\Big([(\varphi + \frac{1}{2})x, y] + [x, (\varphi + \frac{1}{2})y] - [x, y]\Big) = [(\varphi - \frac{1}{2})x, (\varphi - \frac{1}{2})y].$$

Thus,

$$[(\varphi + \frac{1}{2})x, (\varphi + \frac{1}{2})y] - (\varphi + \frac{1}{2})\Big([(\varphi - \frac{1}{2})x, y] + [x, (\varphi + \frac{1}{2})y]\Big) = 0.$$

which is equivalent to (21).

We will call the triple  $(A_+, A_-, \psi_0)$  the Cayley transform of  $\varphi$ . We are now reduced to the classification of all triples satisfying (i-iii) and which arise as a Cayley transform (Cayley triples).

**5.3.** Classification of Cayley triples. Let  $(A_+, A_-, \psi_0)$  be a Cayley triple. If  $\mathfrak{g} = \mathfrak{n}_+ \oplus \mathfrak{h} \oplus \mathfrak{n}_-$  is a polarization of  $\mathfrak{g}$  and  $\Gamma \subset \Pi(\mathfrak{n}_+)$  we will denote by  $\mathfrak{q}_{\Gamma}^+$  (resp.  $\mathfrak{q}_{\Gamma}^-$ ) the subalgebra generated by  $\mathfrak{n}_+$  and  $\mathfrak{g}_{-\alpha}$ ,  $\alpha \in \Gamma$  (resp. generated by  $\mathfrak{n}_-$  and  $\mathfrak{g}_{\alpha}$ ,  $\alpha \in \Gamma$ ). We denote by  $\mathfrak{p}_{\Gamma}^{\pm} = \mathfrak{h} + \mathfrak{q}_{\Gamma}^{\pm}$  the parabolic subalgebras associated to  $\Gamma$ .

**Proposition 3.** There exists a polarization  $\mathfrak{g} = \mathfrak{n}_+^1 \oplus \mathfrak{h} \oplus \mathfrak{n}_-^1$ , two subsets  $\Gamma_+, \Gamma_- \subset \Pi(\mathfrak{n}_+^1)$  and two vector spaces  $V_+, V_- \subset \mathfrak{h}$  with  $V_{\pm}^{\perp} \subset V_{\pm}$  such that

$$\mathfrak{l} \oplus A_{+} = \mathfrak{q}_{\Gamma_{-}}^{+} \oplus V_{+}, \qquad \mathfrak{l} \oplus A_{-} = \mathfrak{q}_{\Gamma_{-}}^{-} \oplus V_{-}.$$

Proof. Notice that  $(\mathfrak{l} \oplus A_+)^{\perp} = I_+ \subset \mathfrak{l} \oplus A_+$ . It is known, (c.f [Bou, chap.VIII,§10, Thm. 1] or [BD]), that this implies that  $\mathfrak{l} \oplus A_+ = \tilde{\mathfrak{q}}_{\Gamma}^+ \oplus \tilde{V}_+$  for some polarization  $\mathfrak{g} = \mathfrak{n}'_+ \oplus \mathfrak{h}' \oplus \mathfrak{n}'_-$ . Similarly,  $\mathfrak{l} \oplus A_- = \tilde{\mathfrak{q}}_{\Gamma'}^- \oplus \tilde{V}_-$  for some polarization  $\mathfrak{g} = \mathfrak{n}''_+ \oplus \mathfrak{h}'' \oplus \mathfrak{n}''_-$ . Moreover,  $\mathfrak{l}$  acts semisimply on  $A_\pm$  so  $\mathfrak{l} \subset \mathfrak{h}'$ ,  $\mathfrak{l} \subset \mathfrak{h}''$ . But  $\mathfrak{l}$  contains a regular element, thus  $\mathfrak{l} = \mathfrak{h}' = \mathfrak{h}''$ . Proposition 3 is now an easy consequence of the following lemma:

**Lemma 5.** Let  $\mathfrak{g}$  be a simple Lie algebra and  $\mathfrak{h}$  a Cartan subalgebra. Let  $\mathfrak{a}_1$  and  $\mathfrak{a}_2$  be two parabolic subalgebras containing  $\mathfrak{h}$  such that  $\mathfrak{a}_1 + \mathfrak{a}_2 = \mathfrak{g}$ . Then there exists a polarization  $\mathfrak{g} = \mathfrak{n}_+ \oplus \mathfrak{h} \oplus \mathfrak{n}_-$  and  $\Gamma_+, \Gamma_- \subset \Pi$  such that  $\mathfrak{a}_1 = \mathfrak{p}_{\Gamma_+}^+$  and  $\mathfrak{a}_2 = \mathfrak{p}_{\Gamma_-}^-$ .

*Proof.* Let  $\mathfrak{n}_+ \oplus \mathfrak{h} \oplus \mathfrak{n}_-$  be a polarization of  $\mathfrak{g}$  such that  $\mathfrak{b}_+ \subset \mathfrak{a}_1$  and for which  $\dim (\mathfrak{n}_+ \cap \mathfrak{a}_2)$  is minimal. We claim that  $\mathfrak{b}_- \subset \mathfrak{a}_2$ . Suppose on the contrary that there exists a simple root  $\alpha \in \Pi$  such that  $\mathfrak{g}_{-\alpha} \not\subset \mathfrak{a}_2$ . Then  $\mathfrak{g}_{-\alpha} \subset \mathfrak{a}_1$  since  $\mathfrak{a}_1 + \mathfrak{a}_2 = \mathfrak{g}$  and  $\mathfrak{g}_{\alpha} \subset \mathfrak{a}_2$  since  $\mathfrak{a}_2$  is parabolic. But then  $s_{\alpha}\mathfrak{n}_+ \oplus \mathfrak{h} \oplus s_{\alpha}\mathfrak{n}_-$  is a polarization of  $\mathfrak{g}$  for which  $s_{\alpha}\mathfrak{b}_+ \subset \mathfrak{a}_1$  and  $\dim (s_{\alpha}\mathfrak{n}_+ \cap \mathfrak{a}_2) < \dim (\mathfrak{n}_+ \cap \mathfrak{a}_2)$ . Contradiction.

In particular,  $A_{\pm}$ ,  $I_{\pm}$  are all  $\mathfrak{h}$ -graded and

$$I_{+} = (\mathfrak{q}_{\Gamma_{+}}^{+} \oplus V_{+})^{\perp} = \bigoplus_{\alpha \in \Delta_{+} \setminus \langle \Gamma_{+} \rangle} \mathfrak{g}_{\alpha} \oplus (V_{+}^{\perp} \cap \mathfrak{h}_{0}),$$
  
$$I_{-} = (\mathfrak{q}_{\Gamma_{-}}^{-} \oplus V_{-})^{\perp} = \bigoplus_{\alpha \in \Delta_{-} \setminus \langle \Gamma_{-} \rangle} \mathfrak{g}_{\alpha} \oplus (V_{-}^{\perp} \cap \mathfrak{h}_{0}).$$

Thus  $A_+/I_+ = \mathfrak{g}_{\Gamma_+} \oplus V_1$  and  $A_-/I_- = \mathfrak{g}_{\Gamma_-} \oplus V_2$  for some suitable  $V_1, V_2 \subset \mathfrak{h}_0$ . Let  $L_{\pm\frac{1}{2}}(\lambda)$  be the generalized eigenspace of  $\varphi(\lambda)$  associated to  $\pm\frac{1}{2}$ . Since  $\varphi$  is a solution of an ordinary differential equation with stationary points at  $\frac{1}{2}, -\frac{1}{2}, L_{\pm\frac{1}{2}}(\lambda)$  is independent of  $\lambda$  and we will simply denote it by  $L_{\pm\frac{1}{2}}$ . Similarly, let L' be the sum of all other generalized eigenspaces so that  $\mathfrak{g} = \mathfrak{l} \oplus L_{\frac{1}{2}} \oplus L' \oplus L_{-\frac{1}{2}}$ .

**Proposition 4.** There exists a polarization  $\mathfrak{g} = \overline{\mathfrak{n}}_+ \oplus \mathfrak{h} \oplus \overline{\mathfrak{n}}_-$  and a subset  $\Gamma_3 \subset \Pi(\overline{\mathfrak{n}}_+)$  such that  $L_{\pm\frac{1}{2}} \subset \overline{\mathfrak{b}}_{\pm}$ ,  $L' \subset \mathfrak{g}_{\Gamma_3} + \mathfrak{h}$  and  $\varphi(\overline{\mathfrak{n}}_+) \subset \overline{\mathfrak{n}}_+$ .

*Proof.* We will construct a polarization satisfying the above conditions in several steps.

Lemma 6. We have:

- (i)  $\mathfrak{l} \oplus L_{\pm \frac{1}{2}}$  is an  $\mathfrak{h}$ -graded solvable subalgebra,
- (ii)  $\mathfrak{l} \oplus L'$  is an  $\mathfrak{h}$ -graded subalgebra,
- (iii) we have  $[L_{\pm \frac{1}{2}}, L'] \subset \mathfrak{l} \oplus L_{\pm \frac{1}{2}}$ .

*Proof.* This follows from the proofs of Lemma 12.3 and Theorem 12.6 in [BD].

Notice that  $L_{\pm\frac{1}{2}} \not\subset \mathfrak{b}_{\pm}^1$  in general. We first construct a polarization  $\mathfrak{g} = \mathfrak{n}_+^2 \oplus \mathfrak{h} \oplus \mathfrak{n}_-^2$  such that  $L_{\pm\frac{1}{2}} \subset \mathfrak{b}_{\pm}^2$ . We have  $I_{\pm} \subset L_{\pm\frac{1}{2}}$ . Notice that  $L_{\frac{1}{2}} \cap \mathfrak{n}_-^1 \subset \mathfrak{g}_{\Gamma_+} \cap \mathfrak{g}_{\Gamma_-} = \mathfrak{g}_{\Gamma_+ \cap \Gamma_-}$  since  $\mathfrak{n}_-^1 \subset (\mathfrak{g}_{\Gamma_-} \oplus I_-)$  and  $L_{\frac{1}{2}}$  is solvable. Similarly,  $L_{-\frac{1}{2}} \cap \mathfrak{n}_+^1 \subset \mathfrak{g}_{\Gamma_+ \cap \Gamma_-}$ . Moreover, by Lemma 6,  $\mathfrak{l} \oplus (L_{\frac{1}{2}} \cap \mathfrak{g}_{\Gamma_+ \cap \Gamma_-})$  and  $\mathfrak{l} \oplus (L_{-\frac{1}{2}} \cap \mathfrak{g}_{\Gamma_+ \cap \Gamma_-})$  are disjoint, solvable,  $\mathfrak{h}$ -graded subalgebras. By lemma 5 it follows that there exists an element s of the group  $W_{\Gamma_+ \cap \Gamma_-}$  such that  $\mathfrak{l} \oplus (L_{\pm\frac{1}{2}} \cap \mathfrak{g}_{\Gamma_+ \cap \Gamma_-}) \subset s\mathfrak{b}_{\pm}^1$ . Notice that s permutes elements of  $\Delta^+ \setminus \langle \Gamma_+ \cap \Gamma_- \rangle$ , leaving it globally unchanged. Thus,  $\mathfrak{l} \oplus L_{\pm\frac{1}{3}} \subset s\mathfrak{b}_{\pm}^1$ . Set  $\mathfrak{n}_{\pm}^2 = s\mathfrak{n}_{\pm}^1$ .

Now we construct a polarization of  $\mathfrak{g}$  satisfying the other conditions of proposition 4. Recall that  $\mathfrak{l} \oplus L \subset \mathfrak{g}_{\Gamma_+ \cap \Gamma_-} + (V_1 \cap V_2)$ . Thus  $(L' \cap \mathfrak{n}_+^2) \oplus (L_{\frac{1}{2}} \cap \mathfrak{n}_+^2 (\Gamma_+ \cap \Gamma_-)) = \mathfrak{n}_+^2 (\Gamma_+ \cap \Gamma_-)$ .

Since  $[L', L_{\frac{1}{2}}] \subset \mathfrak{l} \oplus L_{\frac{1}{2}}$  by Lemma 6,(iii),  $L_{\frac{1}{2}} \cap \mathfrak{n}_{+}^{2}(\Gamma_{+} \cap \Gamma_{-})$  is an ideal of  $\mathfrak{n}_{+}^{2}(\Gamma_{+} \cap \Gamma_{-})$ . But  $L' \cap \mathfrak{n}_{+}^{2}$  is a subalgebra. It is easy to see that this implies that  $L' \cap \mathfrak{n}_{+}^{2}$  is generated by a set of simple root subspaces of  $\mathfrak{n}_{+}^{2}(\Gamma_{+} \cap \Gamma_{-})$ , i.e  $L' \cap \mathfrak{n}_{+}^{2} = \mathfrak{n}_{+}^{2}(\Gamma)$  for some  $\Gamma \subset \Pi(\mathfrak{n}_{+}^{2})$ . Moreover, the restriction of (,) to L' is nondegenerate, hence  $L' \cap \mathfrak{n}_{-}^{2} = \mathfrak{n}_{-}^{2}(-\Gamma)$ . Thus  $\mathfrak{l} \oplus \mathfrak{g}_{\Gamma} \subset \mathfrak{l} \oplus L' \subset \mathfrak{l} \oplus \mathfrak{g}_{\Gamma} + (V_{1} \cap V_{2})$ .

Since  $\varphi(\lambda) + \frac{1}{2}$  is invertible in L',  $\psi(\lambda)$  is a well-defined operator  $L' \to L'$ , satisfying (22), and  $\psi(\lambda)(\mathfrak{h}_0 \cap L') \subset \mathfrak{h}_0 \cap L'$ . Now,  $\mathfrak{l}$  contains a regular element. Thus there exists a polarization of  $\mathfrak{g}$  compatible with the  $\mathfrak{l}$ -weight decomposition. This induces a polarization of  $\mathfrak{g}_{\Gamma}$ , compatible with the  $\mathfrak{l}$ -weight decomposition of  $\mathfrak{g}_{\Gamma}$ . Hence, there exists  $s' \in W_{\Gamma} \subset W$  such that  $\psi_{0|\mathfrak{g}_{\Gamma}}$  is compatible with the polarization  $s'\mathfrak{n}_+^2 \oplus \mathfrak{h} \oplus s'\mathfrak{n}_-^2$ . Since s' leaves  $\Delta_+ \setminus \langle \Gamma \rangle$  globally unchanged, the polarization  $\mathfrak{g} = \overline{\mathfrak{n}}_+ \oplus \mathfrak{h} \oplus \overline{\mathfrak{n}}_-$  with  $\overline{\mathfrak{n}}_{\pm} = s'\mathfrak{n}_{\pm}^2$  and  $\Gamma_3 = s'\Gamma$  satisfies the requirements of proposition 4.

To sum up, we have shown that there exists a polarization  $\mathfrak{g} = \overline{\mathfrak{n}}_+ \oplus \mathfrak{h} \oplus \overline{\mathfrak{n}}_-$ , compatible with  $\varphi$ , subsets  $\Gamma_1 = s's\Gamma_+$ ,  $\Gamma_2 = s's\Gamma_-$  and  $\Gamma_3 \subset \underline{\Pi}(\overline{\mathfrak{n}}_+)$  such that  $(A_+/I_+) \cap \mathfrak{n}_+ = \overline{\mathfrak{n}}_+(\Gamma_1)$ ,  $A_- \cap \mathfrak{n}_+ = \overline{\mathfrak{n}}_+(\Gamma_2)$  and  $L' \cap \mathfrak{n}_+ = \overline{\mathfrak{n}}_+(\overline{\Gamma_3})$ .

The map  $\psi_0$  now restricts to a Lie algebra isomorphism  $\overline{\mathfrak{n}}_+(\Gamma_1) \to \overline{\mathfrak{n}}_+(\Gamma_2)$ . This isomorphism maps weight spaces to weight spaces as  $\psi_0$  preserves  $\mathfrak{h}_0$  and  $\varphi$  is  $\mathfrak{l}$ -invariant. Define  $\tau:\Gamma_1\to\Gamma_2$  by  $\psi_0(\mathfrak{g}_\alpha)=\mathfrak{g}_{\tau(\alpha)}$ . It is a norm-preserving bijection. Thus  $(\Gamma_1,\Gamma_2,\Gamma_3)$  is a generalized Belavin-Drinfeld triple. It is clear that  $\Gamma_3$  is the largest subset of  $\Gamma_1\cap\Gamma_2$  stable under  $\tau$ , and that  $\psi_0:\overline{\mathfrak{n}}_+(\Gamma_3)\to\overline{\mathfrak{n}}_+(\Gamma_3)$  is a Lie algebra isomorphism. Finally, it is easy to see that the map  $\varphi$  is obtained from this data by formulas

$$\varphi(\lambda)(e_{\alpha}) = \frac{1}{2}e_{\alpha} \qquad (\alpha \notin \langle \Gamma_{1} \rangle)$$

$$\varphi(\lambda)(e_{\alpha}) = \frac{1}{2}e_{\alpha} + \frac{\psi_{0}}{1 - e^{(\alpha, \lambda)}\psi_{0}}(e_{\alpha}) \qquad (\alpha \in \langle \Gamma_{1} \rangle)$$

Conversely, it is clear how to construct from a generalized Belavin-Drinfeld triple  $(\Gamma_1, \Gamma_2, \tau)$  the subalgebras  $\mathfrak{n}_+(\Gamma_1)$ ,  $\mathfrak{n}_+(\Gamma_2)$ ,  $\mathfrak{n}_+(\Gamma_3)$  and, for each choice of

Chevalley generators, a Lie algebra isomorphism  $\psi_0 : \mathfrak{n}_+(\Gamma_1) \to \mathfrak{n}_+(\Gamma_2)$ , and the map  $\varphi(\lambda)$ . Condition (16) on the  $\mathfrak{h}_0 \otimes \mathfrak{h}_0$ -part comes from (21)-see [BD].

#### 6. Examples

**6.1.** Constant r-matrices. Our results imply the following:

**Corollary 1.** A dynamical r-matrix associated to a generalized Belavin-Drinfeld triple  $(\Gamma_1, \Gamma_2, \tau)$  is gauge equivalent to a constant r-matrix if and only if  $\Gamma_3 = \emptyset$ .

**6.2.**  $\mathfrak{h}$ -invariant dynamical r-matrices. When  $\mathfrak{l}=\mathfrak{h}$ , our classification coincides with that given in [EV]: the only  $\mathfrak{h}$ -graded generalized Belavin-Drinfeld triple is of the form  $(\Gamma, \Gamma, \tau = Id)$ . The dynamical r-matrices obtained are then (up to gauge transformations and choice of Chevalley generators):

$$r(\lambda) = \frac{\Omega}{2} + \sum_{\alpha \in \Delta_+, \, \alpha \not\in \langle \Gamma \rangle} \frac{1}{2} e_\alpha \wedge e_{-\alpha} + \sum_{\alpha \in \langle \Gamma \rangle \cap \Delta_+} \frac{1}{2} \coth(\frac{1}{2}(\alpha, \lambda) e_\alpha \wedge e_{-\alpha})$$

**6.3. Example for**  $\mathfrak{sl}_3$  and  $\mathfrak{sl}_n$ . The first nontrivial example is for  $\mathfrak{g} = \mathfrak{sl}_3$ : fix a polarization  $\mathfrak{g} = \mathfrak{h} \oplus \bigoplus_{\gamma \in \Delta} \mathfrak{g}_{\gamma}$  where  $\Delta^+ = \{\alpha, \beta, \alpha + \beta\}$  and set  $\mathfrak{l} = \mathbb{C}h_{\rho}$ . Consider the generalized Belavin-Drinfeld triple with  $\Gamma_1 = \Gamma_2 = \{\alpha, \beta\}$  and  $\tau : \alpha \mapsto \beta, \beta \mapsto \alpha$ . In this case, we can choose the map  $\psi_0$  to be the following

$$\begin{array}{lll} e_{\alpha}\mapsto e_{\beta}, & h_{\alpha}\mapsto h_{\beta}, & e_{-\alpha}\mapsto e_{-\beta} \\ e_{\beta}\mapsto e_{\alpha}, & h_{\beta}\mapsto h_{\alpha}, & e_{-\beta}\mapsto e_{-\alpha} \\ e_{\alpha+\beta}\mapsto -e_{\alpha+\beta}, & e_{-\alpha-\beta}\mapsto -e_{-\alpha-\beta}. \end{array}$$

The corresponding dynamical r-matrix is given by:

(23) 
$$r(\lambda) = \frac{\Omega}{2} + r_{\mathfrak{h}_{0},\mathfrak{h}_{0}} + \frac{1}{2} \coth(\alpha,\lambda) e_{\alpha} \wedge e_{-\alpha} + \frac{1}{2} \coth(\beta,\lambda) e_{\beta} \wedge e_{-\beta} + \frac{1}{2} \coth(\alpha,\lambda) e_{\alpha+\beta} \wedge e_{-\alpha-\beta} + \frac{1}{2 \sinh(\alpha,\lambda)} e_{\beta} \wedge e_{-\alpha} + \frac{1}{2 \sinh(\alpha,\lambda)} e_{\alpha} \wedge e_{-\beta}.$$

This dynamical r-matrix is gauge-equivalent to the dynamical r-matrix

(24) 
$$\tilde{r}(\lambda) = \frac{\Omega}{2} + r_{\mathfrak{h}_{0},\mathfrak{h}_{0}} + r_{\mathfrak{l},\mathfrak{h}_{0}} - r_{\mathfrak{l},\mathfrak{h}_{0}}^{21} + \frac{1}{2}\coth(\alpha,\lambda)e_{\alpha} \wedge e_{-\alpha} + \frac{1}{2}\coth(\beta,\lambda)e_{\beta} \wedge e_{-\beta} + \frac{1}{2}\operatorname{th}(\alpha+\beta,\lambda)e_{\alpha+\beta} \wedge e_{-\alpha-\beta} + \frac{e^{(\alpha,\lambda)}}{2\sinh(\alpha,\lambda)}e_{\beta} \wedge e_{-\alpha} + \frac{e^{-(\alpha,\lambda)}}{2\sinh(\alpha,\lambda)}e_{\alpha} \wedge e_{-\beta}.$$

when

$$(\alpha \otimes 1 + 1 \otimes \tau(\alpha)) (r_{\mathfrak{h}_0,\mathfrak{h}_0} + r_{\mathfrak{l},\mathfrak{h}_0} - r_{\mathfrak{l},\mathfrak{h}_0}^{21}) = \frac{1}{2} (\alpha + \tau(\alpha)) \Omega_{\mathfrak{h}}.$$

In particular,  $\tilde{r}(\lambda)$  interpolates the constant r-matrix obtained from the Belavin-Drinfeld triple  $(\Gamma_1 = \alpha, \Gamma_2 = \beta, \tau : \alpha \mapsto \beta)$  at  $(\alpha, \lambda) \to \infty$  and the r-matrix obtained from  $(\Gamma_1 = \beta, \Gamma_2 = \alpha, \tau : \beta \mapsto \alpha)$  at  $(\alpha, \lambda) \to -\infty$ .

Remark. The generalization of this example to  $\mathfrak{g} = \mathfrak{sl}_{2n+1}$  is the following. Fix a polarization and let  $\mathfrak{l} = \mathbb{C}h_{\rho}$ . Denote by  $\Delta$  the root system and by  $\Pi = (\alpha_1, \dots \alpha_{2n})$  the set of positive simple roots. Let  $i : \alpha_k \mapsto \alpha_{2n+1-k}$  be the involution of the Dynkin diagram. The dynamical r-matrix obtained from the generalized Belavin-Drinfeld triple  $(\Gamma_1 = \Gamma_2 = \Pi, \tau = i)$  interpolates the constant r-matrices obtained from the Belavin-Drinfeld triples  $(\Gamma_1 = (\alpha_1, \dots \alpha_n), \Gamma_2 = (\alpha_{n+1}, \dots \alpha_{2n}), \tau = i)$  and  $(\Gamma_1 = (\alpha_{n+1}, \dots \alpha_{2n}), \Gamma_2 = (\alpha_1, \dots \alpha_n), \tau = i^{-1})$ .

**6.4. Permutation dynamical r-matrices.** Consider  $\mathfrak{g} = \mathfrak{sl}_{2n}$ , and let  $\Pi = (\alpha_1, \dots \alpha_{2n-1})$  denote a system of simple roots. For any  $\sigma \in S_n$ , we can construct a generalized Belavin-Drinfeld triple by setting  $\Gamma_1 = \Gamma_2 = (\alpha_1, \alpha_3, \dots \alpha_{2n-1})$  and  $\tau : \alpha_{2k-1} \mapsto \alpha_{2\sigma(k)-1}$ .

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