Strict orbifold atlases and weighted branched manifolds

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This note revisits some of the ideas in [M1] on orbifolds and branched manifolds, showing how the constructions can be simplified by using a version of the Kuranishi atlases developed by McDuff–Wehrheim. We first show that every orbifold has such an atlas, and then use it to obtain an explicit model for the non-singular resolution of an oriented orbifold Y (which is a weighted nonsingular groupoid with the same fundamental class as Y) and for the Euler class of an oriented orbibundle. In this approach, instead of appearing as the zero set of a multivalued section, the Euler class is the zero set of a single-valued section of the pullback bundle over the resolution, and hence has the structure of a weighted branched manifold in which the weights and branching are canonically defined by the atlas.

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²⁰¹⁰ Mathematics Subject Classification: 57R18, 53D45.

Key words and phrases: orbifold, groupoid, strict atlas, Kuranishi atlas, weighted branched manifold.

Partially supported by NSF grant DMS1308669.

1. Introduction

A strict orbifold atlas is a special case of the Kuranishi atlases developed in [MW1, MW2, MW3] by McDuff–Wehrheim to provide a framework for the construction of the virtual moduli cycle in Gromov–Witten theory. When specialized to the orbifold case (i.e. all obstruction spaces are trivial), such an atlas encapsulates the structure of an étale proper (ep for short) groupoid in a way that is well adapted to certain constructions, for example that of the Euler class of an orbibundle. Although in this note we restrict attention to the finite dimensional case, our results about abstract orbifolds and their representing groupoids (such as the construction of orbifold atlases, groupoid completions and reductions) apply in any setting in which there is an adequate topological and analytical framework. In particular, as outlined in Remark 4.10 one should be able to use these ideas in the polyfold context of Hofer–Wysocki–Zehnder [HWZ] to describe the zero set of a transverse perturbation of the canonical section of a Fredholm bundle as a weighted branched manifold.

The first section defines the notion of a strict orbifold atlas, and gives examples showing how the structure hidden in the morphisms of a groupoid is made explicit in the atlas. Such an atlas \mathcal{K} determines an ep category $\mathbf{B}_{\mathcal{K}}$, which is not a groupoid because its morphisms are not all invertible. Our main results are:

- Proposition 2.3: The category $\mathbf{B}_{\mathcal{K}}$ has a unique completion to a groupoid with the same space of objects and realization, and hence determines a unique orbifold structure on the realization $|\mathbf{B}_{\mathcal{K}}| \cong Y$.
- Proposition 3.3: Conversely, every paracompact orbifold is the realization of a strict orbifold atlas, that is unique up to commensurability.

In §4, we first use the atlas to construct the nonsingular resolution of an orbifold. This is a weighted étale groupoid with at most one morphism between any two objects, that also has a weighting function. Thus its realization is a weighted branched manifold, that, if compact and oriented, carries a fundamental class. (See Remark 4.7 for a discussion of further cobordism invariants of weighted branched manifolds.) We then construct the Euler class of an oriented orbibundle over a compact oriented base using a single-valued section of the pullback of the bundle over a resolution rather than the more customary multi-valued section.

1.1. Definition and examples

As in Adem–Leida–Ruan [ALR] and Moerdijk [Mo] we take a naive approach to orbifolds, since that suffices for our current purposes, considering them as equivalence classes of groupoids rather than as stacks or 2-categories as in Lerman [L10]. Thus, we define orbifolds via the concept of **ep** (étale **proper**) groupoid **G**. This is a topological category whose spaces of objects $Obj_{\mathbf{G}}$ and morphisms $Mor_{\mathbf{G}}$ are smooth manifolds¹ of some fixed dimension d, such that

- all structural maps (i.e. source s, target t, identity, composition and inverse) are **étale** (i.e. local diffeomorphisms); and
- the map $s \times t : \operatorname{Mor}_{\mathbf{G}} \to \operatorname{Obj}_{\mathbf{G}} \times \operatorname{Obj}_{\mathbf{G}}$ given by taking a morphism to its source and target is **proper** (i.e. the inverse image of a compact set is compact).

The **realization** $|\mathbf{G}|$ of \mathbf{G} is the quotient of the space of objects by the equivalence relation given by the morphisms: thus $x \sim y \Leftrightarrow \mathrm{Mor}_{\mathbf{G}}(x,y) \neq \emptyset$. We denote the quotient map by $\pi_{\mathbf{G}} : \mathrm{Obj}_{\mathbf{G}} \to |\mathbf{G}|$. Note that, when (as here) the domains are locally compact, the properness condition implies that $|\mathbf{G}|$ is Hausdorff. We say that \mathbf{G} is

- effective if the only connected components of Mor_G on which the source map s equals the target map t consist entirely of identity morphisms;
- nonsingular if $Mor_{\mathbf{G}}(x, y)$ contains at most one element for all $x, y \in Obj_{\mathbf{G}}$;
- oriented if both manifolds $Obj_{\mathbf{G}}$ and $Mor_{\mathbf{G}}$ carry an orientation that is preserved by all structural maps.

For example, if a finite group Γ acts smoothly on a smooth manifold U then naively one thinks of the quotient $U/_{\Gamma}$ as an orbifold. In this situation we define the ep groupoid $\mathbf{G}_{(U,\Gamma)}$ to have

$$\operatorname{Obj}_{\mathbf{G}} = U$$
, $\operatorname{Mor}_{\mathbf{G}} = U \times \Gamma$, $(s \times t)(u, \gamma) = (\gamma^{-1}u, u)$,

with the obvious identity, inverse and composition maps. There is a map $f: U \to Y$ (the analog of the footprint map for a Kuranishi chart) that

 $^{^{1}}$ Manifolds are always assumed to be paracompact.

induces a homeomorphism $f: |\mathbf{G}| = {}^{U}/_{\Gamma} \to Y$. More generally, we make the following definitions.

Definition 1.1. An **orbifold structure** on a paracompact Hausdorff space Y is a pair (\mathbf{G}, f) consisting of an ep (étale proper) groupoid \mathbf{G} together with a map $f: \mathrm{Obj}_{\mathbf{G}} \to Y$ that factors through a homeomorphism $|f|: |\mathbf{G}| \to Y$. A **refinement** of (\mathbf{G}, f) is an orbifold structure (\mathbf{G}'', f'') on Y together with a functor $F: (\mathbf{G}'', f'') \to (\mathbf{G}, f)$ such that

- F is étale (i.e. the induced maps on objects and morphism spaces are local diffeomorphisms);
- F is full and faithful, i.e. $F_* : \operatorname{Mor}_{\mathbf{G}''}(x, y) \to \operatorname{Mor}_{\mathbf{G}}(F(x), F(y))$ is an isomorphism for all $x, y \in \operatorname{Obj}_{\mathbf{G}''}$;
- $f'' = f \circ F$.

Two orbifold structures (\mathbf{G}, f) and (\mathbf{G}', f') are said to be **Morita equivalent** if they have a common refinement, i.e. if there is a third structure (\mathbf{G}'', f'') on Y and functors $F : \mathbf{G}'' \to \mathbf{G}, F' : \mathbf{G}'' \to \mathbf{G}'$ as above. An **orbifold** is a paracompact Hausdorff space Y equipped with an equivalence class of orbifold structures. We say that Y is **oriented** if for each representing groupoid \mathbf{G} the spaces $\mathrm{Obj}_{\mathbf{G}}$ and $\mathrm{Mor}_{\mathbf{G}}$ have orientations that are preserved by all structure maps and by the functors $F : \mathbf{G} \to \mathbf{G}'$ considered above.

Definition 1.2. A **local chart** (U, Γ, ψ) on a topological space Y is a triple consisting of a connected open subset $U \subset \mathbb{R}^d$, a finite group Γ that acts by diffeomorphisms of U and a map $\psi: U \to Y$ that factors through a homeomorphism from the quotient $\underline{U} := {}^U\!/_{\Gamma}$ onto an open subset F of Y called the **footprint**.

If Y is an orbifold, then in addition we require this chart (in this case also called a **local uniformizer**) to determine the smooth structure of Y over F in the sense that for one (and hence any) orbifold structure (\mathbf{G} , f) on Y each $x \in f^{-1}(F)$ has a neighbourhood $V \subset f^{-1}(F)$ that is locally diffeomorphic to (U,Γ) . More precisely, if $\Gamma^x_{\mathbf{G}} := \operatorname{Mor}_{\mathbf{G}}(x,x)$, resp. Γ^x , is the stabilizer of x in \mathbf{G} , resp. Γ , then f lifts to a map $\widetilde{f}: V \to U$ that is an embedding (i.e. a diffeomorphism onto its image) and is such that

- \widetilde{f} is equivariant with respect to some isomorphism $\Gamma_{\mathbf{G}}^x \stackrel{\cong}{\to} \Gamma^x \subset \Gamma$ and
- the induced map $V/_{\Gamma_{\mathbf{G}}^x} \to U/_{\Gamma}$ is a homeomorphism to its image;

• if Y is oriented, then we also require U to be oriented compatibly with all the above maps.

It is well known that every orbifold Y has a locally finite covering family of such charts $(U_i, \Gamma_i, \psi_i)_{i \in A}$; i.e. we have $Y = \bigcup_{i \in A} \psi_i(U_i)$ and $\bigcap_{i \in I} \psi_i(U_i) \neq \emptyset \Longrightarrow |I| < \infty$. Indeed, given any representing groupoid (\mathbf{G}, f) Robbin–Salamon [RS, Lemma 2.10] construct a covering family from \mathbf{G} in the sense that each U_i is a subset of $\mathrm{Obj}_{\mathbf{G}}$ such that the full subcategory of \mathbf{G} with objects U_i is isomorphic to the category $\mathbf{G}_{(U_i,\Gamma_i)}$ defined above. Although, in this situation the covering family in some sense generates the groupoid \mathbf{G} , there could be many components in $\mathrm{Obj}_{\mathbf{G}}$ and $\mathrm{Mor}_{\mathbf{G}}$ that we know very little about. We might ask: what is the minimal extra structure needed to determine the orbifold structure on Y?

We will see that the following notion gives a simple answer to this question.

Definition 1.3. A strict orbifold atlas $\mathcal{K} = (\mathbf{K}_I, \rho_{IJ})_{I \subset J \in \mathcal{I}_Y}$ on a paracompact Hausdorff space Y consists of the following data:

- (i) a locally finite open cover $(F_i)_{i\in A}$ of Y, with associated set $\mathcal{I}_Y := \{I \subset A : F_I := \bigcap_{i\in I} F_i \neq \emptyset\}$;
- (ii) a collection $(W_I, \Gamma_I, \psi_I)_{I \in \mathcal{I}_Y}$ of local charts where $\Gamma_I := \prod_{i \in I} \Gamma_i$ with footprints $\psi_I(W_I) = F_I$ such that when |I| > 1 the group $\Gamma_{I \setminus \{i\}}$ acts freely on W_I for each $i \in I$; and
- (iii) a family of smooth local diffeomorphisms (or covering maps)

$$\rho_{IJ}: W_J \to W_{IJ} := (\psi_I)^{-1}(F_J) \subset W_I, \qquad I \subset J, \ I, J \in \mathcal{I}_Y,$$

satisfying the following conditions for all $I \subset J$, $I, J \in \mathcal{I}_Y$:

- (a) $\rho_{JJ} = id;$
- (b) if $I \subsetneq J$ then ρ_{IJ} is equivariant with respect to the projection ρ_{IJ}^{Γ} : $\Gamma_J \to \Gamma_I$, and is given by the composite of the quotient of W_J by the free action of $\Gamma_{J \setminus I}$ with a Γ_I -equivariant diffeomorphism ${}^{W_J}/_{\Gamma_{J \setminus I}} \to W_{IJ} \subset W_I$;
- (c) $\psi_I \circ \rho_{IJ} = \psi_J$, and $\rho_{IJ} \circ \rho_{JK} = \rho_{IK}$ for all $I \subset J \subset K$.

The charts of this atlas K are the tuples $(\mathbf{K}_I := (W_I, \Gamma_I, \psi_I))_{I \in \mathcal{I}_Y}$ with footprints $(F_I)_{I \in \mathcal{I}_Y}$ and footprint maps ψ_I , and the coordinate changes are induced by the covering maps ρ_{IJ} .

It is often useful to think of the charts $(\mathbf{K}_i := \mathbf{K}_{\{i\}})_{i \in A}$ as the **basic charts**, while the \mathbf{K}_I with |I| > 1 are **transition charts** that define how

the basic charts fit together. For short, we will often call an atlas with the above properties an orbifold atlas. 2

Remark 1.4. (i) It is not hard to check that the projections $(\rho_{IJ}, \rho_{IJ}^{\Gamma})$: $W_J \to W_{IJ}$ (which are called **group coverings** in [MW3, §2.1]) induce isomorphisms on the stabilizer subgroups, i.e. if $x = \rho_{IJ}(y)$ then $\rho_{IJ}^{\Gamma} : \Gamma_J^y \stackrel{\cong}{\to} \Gamma_I^x$. (ii) By slight abuse of language, we often call the group Γ_I the **isotropy group** of the chart \mathbf{K}_I , even though in general it does not equal the stabilizer subgroup Γ_I^x of any point $x \in W_I$. Although one could insist that the basic charts (W_i, Γ_i, ψ_i) are **minimal** in the sense that $\Gamma_i = \Gamma_i^x$ for some $x \in W_i$, this property is not preserved by arbitrary restrictions to Γ_i -invariant subsets of W_i and also, because the groups $\Gamma_{J \setminus I}$ act freely, will usually not hold for the transition charts. One can think of Γ_I as the automorphism group (or stabilizer) of the footprint map $\psi_I : W_I \to Y$ in an appropriately defined category of "stacky" maps (W, ψ) from manifolds W to the orbifold Y.

As we show in Proposition 2.3 below, the above notion of atlas on the topological space Y is sufficient to give a complete description of its structure as an orbifold. In particular, as in [MW3, Definition 2.3.5], each such atlas \mathcal{K} defines a category $\mathbf{B}_{\mathcal{K}}$ with $\mathrm{Obj}_{\mathbf{B}_{\mathcal{K}}} = \bigsqcup_{I \in \mathcal{I}_Y} W_I$ and morphisms $\mathrm{Mor}_{\mathbf{B}_{\mathcal{K}}} = \bigsqcup_{I \subset JI, J \in \mathcal{I}_Y} W_J \times \Gamma_I$, with source and target given by ³

$$(1.1) \quad \mathcal{I}_Y \times \mathcal{I}_Y \times W_J \times \Gamma_I \ \ni \ (I, J, y, \gamma) \in \mathrm{Mor}_{\mathbf{B}_{\kappa}} \big((I, \gamma^{-1} \rho_{IJ}(y)), (J, y) \big).$$

Composition is defined by

$$(1.2) \quad (I, J, y, \gamma) \circ (J, K, z, \delta) := (I, K, z, \rho_{IJ}^{\Gamma}(\delta)\gamma) \quad \text{if } \delta^{-1}\rho_{JK}(z) = y.$$

The **realization** $|\mathbf{B}_{\mathcal{K}}|$ of the category $\mathbf{B}_{\mathcal{K}}$ is defined to be the quotient $\mathrm{Obj}_{\mathbf{B}_{\mathcal{K}}}/\sim$, where \sim is the equivalence relation on objects generated by setting $x \sim y$ whenever $\mathrm{Mor}(x,y) \neq \emptyset$. The following lemma is a special case of [MW1, Lemma 2.3.7]. Its proof is elementary.

² We warn the reader that an orbifold atlas (or good atlas) is customarily defined to be a covering family of charts that satisfy a somewhat different compatibility condition on overlaps; see for example [ALR, MP, M1].

³ In hindsight, it might have been more natural to consider the tuple (I, J, y, γ) as a morphism with source (J, y) rather than $(I, \gamma^{-1}\rho_{IJ}(y))$ since the only way to obtain a smooth parametrization of the morphisms trom W_I to W_J is to parametrize them by the points in W_J . However we will follow the conventions in the papers [MW1, MW2, MW3]. Note also that below we write compositions in the categorical ordering.

Lemma 1.5. The category $\mathbf{B}_{\mathcal{K}}$ is well defined; in particular, composition is associative. It is étale and proper. Moreover, the footprint maps ψ_I induce a homeomorphism $|\psi|: |\mathbf{B}_{\mathcal{K}}| \to Y$.

Example 1.6. (Manifolds) Every manifold⁴ Y is the realization of the étale proper (ep) category $\operatorname{Op}(Y)$ with objects equal to the disjoint union $\bigsqcup_{\alpha \in \mathcal{A}} U_{\alpha}$ of all open subsets of Y and morphisms given by inclusion. Thus if $\iota_{\alpha}: U_{\alpha} \to Y$ is the inclusion and we order the elements of \mathcal{A} by the inverse inclusion relation so that $\alpha \leq \beta \Longrightarrow \operatorname{im}(\iota_{\alpha}) \supset \operatorname{im}(\iota_{\beta})$, then $\operatorname{Mor}_{\operatorname{Op}(Y)} = \bigsqcup_{\alpha \leq \beta} U_{\beta}$ with source and target given by

$$(\alpha, \beta, x) : (\alpha, \iota_{\alpha}^{-1} \circ \iota_{\beta}(x)) \mapsto (\beta, x), \quad \alpha \leq \beta, \ x \in U_{\beta}.$$

Every locally finite open covering $(W_i)_{i\in A}$ of Y defines an atlas on Y with trivial isotropy groups Γ_I whose corresponding category $\mathbf{B}_{\mathcal{K}}$ is a full subcategory of $\operatorname{Op}(Y)$. However, Definition 1.3 also allows for atlases on Y with nontrivial isotropy groups Γ_I . The condition for Y to be a manifold is that all stabilizer subgroups $\Gamma_I^x := \{ \gamma \in \Gamma_I \mid \gamma(x) = x \}$ of the points $x \in W_I$ are trivial; in other words, each group Γ_I must act freely on W_I so that the footprint maps $\psi_I : W_I \to Y$ are local homeomorphisms. Since $\Gamma_I := \prod_{i \in I} \Gamma_i$, the assumptions on the covering maps ρ_{IJ} imply that this will hold for all charts provided that it holds for the basic charts.

Example 1.7. (i) A first nontrivial example is a "football" $Y = S^2$ with two basic charts $(W_1, \Gamma_1 = \mathbb{Z}_2, \psi_1)$, $(W_2, \Gamma_2 = \mathbb{Z}_3, \psi_2)$ that parametrize neighbourhoods $\psi_i(W_i) = F_i \subset S^2$ of the northern resp. southern hemisphere with isotropy of order 2 resp. 3 at the north resp. south pole. The restrictions of the basic charts to the annulus $F_{12} := F_1 \cap F_2$ have domains given by the annuli $W_{i(12)} := \psi_i^{-1}(F_{12})$ that each support a free action of the relevant group Γ_i . There is no direct functor between these restrictions because the coverings $W_{1(12)} \to F_{12}$ and $W_{2(12)} \to F_{12}$ are incompatible. However, they can be related by a common free covering, namely the pullback defined by the diagram

$$(1.3) W_{12} - - > W_{1(12)}$$

$$\downarrow \psi_1 \\
\psi_1 \\
\psi_2 \\
W_{2(12)} \xrightarrow{\psi_2} Y.$$

⁴ assumed paracompact

Thus $W_{12} := \{(x,y) \in W_{1(12)} \times W_{2(12)} | \psi_1(x) = \psi_2(y)\}$ with group $\Gamma_{12} := \Gamma_1 \times \Gamma_2 = \mathbb{Z}_2 \times \mathbb{Z}_3$. The corresponding footprint map $\psi_{12} : W_{12} \to F_{12}$ is the 6-fold covering of the annulus, and the coordinate changes from $(W_i, \Gamma_i, \psi_i)|_{F_{12}}$ to $(W_{12}, \Gamma_{12}, \psi_{12})$ are the coverings $W_{12} \to W_{i(12)}$ in the diagram. Therefore the category $\mathbf{B}_{\mathcal{K}}$ in this example has index set $\mathcal{I}_Y = \{1, 2, 12\}$, objects the disjoint union $\bigcup_{I \in \mathcal{I}_Y} W_I$, and morphisms

$$\left(\bigsqcup_{I\in\mathcal{I}_Y}W_I\times\Gamma_I\right)\cup\left(\bigsqcup_{i=1,2}W_{12}\times\Gamma_i\right),$$

where for i = 1, 2 the elements in $W_{12} \times \Gamma_i$ represent the morphisms from W_i to W_{12} .

- (ii) The "simplest" groupoid G with |G| = Y would have objects $W_1 \sqcup W_2$ and the following morphisms:
 - morphisms from W_i to itself parametrized by $W_i \times \Gamma_i$;
 - morphisms from W_1 to W_2 parametrized by W_{12} with

$$s \times t : W_{12} \to W_{1(12)} \times W_{2(12)}, x \mapsto (\rho_{1(12)}(x), \rho_{2(12)}(x));$$

• another copy of W_{12} representing the inverses of these morphisms.

The fact that this groupoid has such a simple description is a consequence of the existence of the pullback diagram (1.3). However, even in this case it is not so easy to give an explicit formula for the composition $\operatorname{Mor}(W_1, W_2) \circ \operatorname{Mor}(W_2, W_1) \to \operatorname{Mor}(W_1, W_1) = W_1 \times \Gamma_1$, which is necessary if one wants to describe a groupoid rather than a category. In the atlas, the space W_{12} is considered as another component of the object space, which firstly allows us to order the components W_I of the object space so that we need not consider all morphisms but only those from W_I to W_J with $I \subset J$, and secondly allows us to replace the space of direct morphisms from W_1 to W_2 by the space of morphisms from $\sqcup_i W_i$ to W_{12} , thus decomposing the morphisms from W_1 to W_2 into constituents that are easier to describe.

The simple construction in Example 1.7 does not work for arbitrary orbifolds since the (set theoretic) pullback W_{12} considered above will not be a smooth manifold if any point in $\psi_1(W_1) \cap \psi_2(W_2)$ has nontrivial stabilizer. However, it turns out that there is a very simple substitute construction for the domain of the transition chart. Namely, if the charts (W_i, Γ_i) inject into a groupoid representative for Y then we can take W_{12} to be the morphisms in this groupoid from W_1 to W_2 ; see the proof of Proposition 3.3. This

morphism space is the "stacky" analog of the fiber product; see Pardon [P, §2.1.2], who also observes that this can be used to construct orbifold atlases.

Remark 1.8. (Variations on the definition) In certain geometric situations, such as the case of products discussed in Example 1.9 below, it is natural to generalize the definition of atlas ⁵ to allow for the possibility that the indices $i \in A$ associated to the footprints F_i and groups Γ_i of the basic covering family of Y do not all correspond to local uniformizers of Y, though there are enough charts with footprints equal to intersections F_I to cover Y.

Thus we define a **generalized orbifold atlas** to consist of a locally finite open cover $\{F_i\}_{i\in A}$ of Y, a family of finite groups $(\Gamma_i)_{i\in A}$, and a subset $\mathcal{I}_Y \subset \mathcal{P}^*(A)$ of the set of finite nonempty subsets of A satisfying the following conditions:

- $I \in \mathcal{I}_Y \Longrightarrow F_I := \bigcap_{i \in I} F_i \neq \emptyset$;
- if $I \in \mathcal{I}_Y$ and $I \subset J$ then $J \in \mathcal{I}_Y$ if and only if $F_J \neq \emptyset$;
- $\bigcup_{I \in \mathcal{I}_{\mathcal{V}}} F_I = Y;$
- for each $I \in \mathcal{I}_Y$ there is a local chart (W_I, Γ_I, ψ_I) with group $\Gamma_I := \prod_{i \in I} \Gamma_i$ and footprint F_I ;
- the family of charts $(W_I, \Gamma_I, \psi_I)_{I \in \mathcal{I}_Y}$ also satisfy conditions (ii), (iii) in the Definition 1.3 of an orbifold atlas.

Pardon's notion of an implicit atlas is yet more general, since he does not insist that the domains of his charts are manifolds. As he explains in [P, Remarks 2.1.3, 2.1.4], his definitions are in some respects simpler. However, we need an explicit description of the étale category $\mathbf{B}_{\mathcal{K}}$ in order to be able to perform certain geometric constructions, such as the construction of a perturbation section in [MW2, §7.3], or the nonsingular resolution below.

Example 1.9. (Products) Consider the product $Y = Y_1 \times Y_2$ of two orbifolds, where Y_{α} is equipped with the atlas $\mathcal{K}_{\alpha} = (W_I^{\alpha}, \Gamma_I^{\alpha}, \psi_I^{\alpha})_{I \in \mathcal{I}_{Y_{\alpha}}}$ with basic charts indexed by the elements of A_{α} . Then the family of product charts

$$(W_{I_1}^1 \times W_{I_2}^2, \Gamma_{I_1}^1 \times \Gamma_{I_2}^2, \psi_{I_1}^1 \times \psi_{I_2}^2), \quad (I_1, I_2) \in \mathcal{I}_{Y_1} \times \mathcal{I}_{Y_2}$$

⁵ The requirements below are similar to, but simpler than, the conditions in [M2] for a "semi-additive atlas": there we also had to take into consideration additivity requirements for the obstruction spaces.

is a generalized atlas indexed by $\mathcal{I}_Y \subset \mathcal{P}^*(A_1 \sqcup A_2)$, where $\mathcal{I}_Y := \{(I_1, I_2) : I_\alpha \in \mathcal{I}_{Y_\alpha}\}$. Here we take A to be the disjoint union $A_1 \sqcup A_2$, denoting the elements in A_1 by pairs (i,\emptyset) for $i \in A_1$ and those of A_2 by (\emptyset,j) for $j \in A_2$. If we write the elements of $\mathcal{P}^*(A)$ as pairs (I_1,I_2) , where $I_\alpha \in \mathcal{P}(A_\alpha)$ are not both empty, then \mathcal{I}_Y consists of pairs (I_1,I_2) where neither set I_α is empty. On the other hand, we can define footprints corresponding to all nonempty subsets of A as follows: define

$$F_{i,\emptyset} := F_i^1 \times Y_2, i \in A_1 \text{ and } F_{\emptyset j} := Y_1 \times F_j^2, j \in A_2,$$

and then set $F_{I_1,I_2} = F_{I_1}^1 \times F_{I_2}^2 = \bigcap_{i \in I_1} F_{i,\emptyset} \cap \bigcap_{j \in I_2} F_{\emptyset,j}^2$ Similarly, we can define $\Gamma_{i,\emptyset} := \Gamma_i^1, \Gamma_{\emptyset,j} := \Gamma_j^2$, and then define the other Γ_{I_1,I_2} as products of these groups.

In Pardon's approach, one can include a "chart" that is indexed by the empty set, namely $(W_{\emptyset} := Y, \Gamma_{\emptyset} = \mathrm{id}, \psi_{\emptyset} = \mathrm{id}_Y)$, and then include product charts of the form $Y_1 \times (W_J, \Gamma_J, \psi_J)$ as part of the atlas.

See Example 3.6 for a description of some atlases on noneffective orbifolds.

2. Groupoid completions

Although $\mathbf{B}_{\mathcal{K}}$ is not a groupoid since some of the nonidentity maps are not invertible, we now show that this category has a canonical **groupoid** completion $\mathbf{G}_{\mathcal{K}}$. (This justifies our language since it implies that any paracompact Hausdorff space Y with an orbifold atlas is in fact an orbifold.)

Definition 2.1. Let **M** be an étale proper category with objects $\bigsqcup_{I \in \mathcal{I}} W_I$ and realization $Y := \text{Obj}_{\mathbf{M}} / \sim \text{such that}$

- for each $I \in \mathcal{I}$ the full subcategory of \mathbf{M} with objects W_I can be identified with the group quotient (W_I, Γ_I) for some group Γ_I ;
- for each $I \in \mathcal{I}$ the realization map $\pi_{\mathbf{M}} : \mathrm{Obj}_{\mathbf{M}} \to Y$ induces a homeomorphism $W_I/_{\Gamma_I} \to F_I \subset Y$, where F_I is an open subset of Y.

Then we say that an ep groupoid \mathbf{G} is a **groupoid completion** of \mathbf{M} if there is an injective functor $\iota : \mathbf{M} \to \mathbf{G}$ that induces a bijection on objects, an isomorphism on stabilizer subgroups, and a homeomorphism on the realizations $Y = |\mathbf{M}| \to |\mathbf{G}|$.

Thus for each component W_I of $Obj_{\mathbf{M}}$ the groupoid completion (if it exists) has the same morphisms from W_I to W_I but (unless \mathbf{M} is already a groupoid) will have more morphisms between the different components of $Obj_{\mathbf{M}}$ that are obtained by adding inverses and composites. Before giving the general construction for \mathbf{G} , we consider the following simple example.

Example 2.2. Consider an atlas on the orbifold Y consisting of a single point with stabilizer group S with basic charts labelled by $\{1, \ldots, N\}$ so that \mathcal{I}_Y is the set of all subsets of $\{1,\ldots,N\}$. Each group Γ_i acts transitively on W_i , so that we can identify $W_i \cong \Gamma_i/S_i$, where S_i is the stabilizer of some point $x_i \in W_i$ and Γ_i acts on the quotient W_i by multiplication on the left $\gamma \cdot aS_i = 0$ γaS_i . Similarly for each I, the group $\Gamma_I = \prod_{i \in I} \Gamma_i$ acts transitively on W_I and we can identify $W_I := {\Gamma_I}/{S_I}$ where $S_I = \operatorname{Stab}_{\Gamma_I}(x_I)$. The equivariant covering map $(\rho_{iI}, \rho_{iI}^{\Gamma})$ identifies the stabilizer of the point $x_I \in W_I$ with the stabilizer of its image $\rho_{iI}(x_I) \in W_i$. Therefore the subgroups $S_I \subset \Gamma_I$ can be canonically identified provided that we can choose a family of base points $x_I \in W_I$ that are consistent in the sense that $\rho_{IJ}(x_J) = x_I$ for all $I \subset J$. This is possible because \mathcal{I}_Y has a maximal element $I_{\text{max}} = \{1, \dots, N\}$. Thus, we can fix $x_{\text{max}} \in W_{I_{\text{max}}}$ and then define $x_I := \rho_{I(I_{\text{max}})}(x_{\text{max}})$ for all $I \in \mathcal{I}_Y$ so that $\rho_{IJ}(x_J) = x_I$ for all $I \subset J$. This gives consistent identifications of $S := S_{I_{\max}}$ with $S_I := \operatorname{Stab}_{\Gamma_I}(x_I)$ for all I. In particular, we identify S with the subgroup $\operatorname{Stab}_{\Gamma_i}(x_i) \subset \Gamma_I$ for all i so that we may write $W_I := \frac{\Gamma_I}{S}$, where S acts diagonally on Γ_I by $(\gamma_{i_1}, \ldots, \gamma_{i_k}) \mapsto (\gamma_{i_1}s, \ldots, \gamma_{i_k}s)$. Thus the category \mathbf{B}_{S} corresponding to this atlas has the following description:

$$\mathrm{Obj}_{\mathbf{B}_S} = \bigsqcup_{I \subset \mathcal{I}_Y} W_I = {}^{\Gamma_I}\!/_{\!S}, \quad \mathrm{Mor}_{\mathbf{B}_S} = \bigsqcup_{I \subset J, I, J \in \mathcal{I}_Y} \mathrm{Mor}(W_I, W_J) = {}^{\Gamma_J}\!/_{\!S} \times \Gamma_I,$$

where, with $\gamma_I := (\gamma_I^i)_{i \in I} \in \Gamma_I$, $\gamma_I S := \{(\gamma_I^i s)_{i \in I} : s \in S\} \in \Gamma_I/S$, and abbreviating the projections ρ_{IJ} by restrictions denoted for example as $\gamma_J|_I$, we have

$$s \times t : {}^{\Gamma_J}/_S \times \Gamma_I \to {}^{\Gamma_I}/_S \times {}^{\Gamma_J}/_S,$$
$$(\gamma_J S, \delta_I) \mapsto \left(\delta_I^{-1} \rho_{IJ}(\gamma_J) S, \gamma_J S\right) =: \left(\delta_I^{-1} \gamma_J|_I S, \gamma_J S\right),$$

and, when $I \subset J \subset K$,

$$m_S((\gamma_J S, \delta_I), (\gamma_K S, \delta_J)) = (\gamma_K S, \delta_J|_I \delta_I)$$
 if $\gamma_J S = \delta_J^{-1} \gamma_K|_J S$.

As preparation for the general case, let us check that \mathbf{B}_S has a groupoid completion \mathbf{G}_S . If $S = \mathrm{id}$ then this is straightforward. The category \mathbf{B}_{id}

has objects $\bigsqcup_{I \in \mathcal{I}_Y} \Gamma_I$ and at most one morphism between any two points. Because the groupoid completion of \mathbf{B}_{id} (if it exists) has the same stabilizer subgroups as \mathbf{B}_{id} , the category \mathbf{G}_{id} must have a single morphism between any pair of points with the same image in Y, and hence between each pair of objects. But it is easy to construct such a groupoid. We take

$$\operatorname{Mor}_{\mathbf{G}_{\operatorname{id}}} = \bigsqcup_{I,J \in \mathcal{I}_Y} \Gamma_I \times \Gamma_J, \quad s \times t(\gamma_I, \gamma_J) = (\gamma_I, \gamma_J) \in \operatorname{Obj}_{\mathbf{G}_{\operatorname{id}}} \times \operatorname{Obj}_{\mathbf{G}_{\operatorname{id}}},$$

with composition given by

$$(2.1) \ m_{\mathrm{id}}: (\Gamma_I \times \Gamma_J) \times_{\Gamma_J} (\Gamma_J \times \Gamma_K) \to \Gamma_I \times \Gamma_K, \quad ((x,y),(y,z)) \mapsto (x,z).$$

More generally, the group S acts on \mathbf{G}_{id} by multiplication on the right; i.e. each $s \in S$ gives a functor $F_s : \mathbf{G}_{\mathrm{id}} \to \mathbf{G}_{\mathrm{id}}$ that acts on objects by $\gamma \mapsto \gamma s$ inducing isomorphisms $\mathrm{Mor}(x,y) \to \mathrm{Mor}(xs,ys)$. Since $F_s \circ F_t = F_{ts}$ for $s,t \in S$ there is a well defined quotient category $\mathbf{G}_{\mathrm{id}}/_S$ with objects $\bigsqcup_I \Gamma_I/_S$ and morphisms $\bigsqcup_{I,J} \Gamma_I \times \Gamma_J/_S$. We claim that this quotient category $\mathbf{G}_{\mathrm{id}}/_S$ can be identified with the groupoid completion \mathbf{G}_S of \mathbf{B}_S .

To prove this, consider the functor $F_S : \mathbf{B}_{\mathrm{id}} \to \mathbf{B}_S$ given on objects by the quotient maps $\Gamma_I \mapsto {}^{\Gamma_I}/{}_S =: W_I$, and on morphisms (which are only defined when $I \subset J$) by

(2.2)
$$F_S : \operatorname{Mor}_{\mathbf{B}_{\operatorname{id}}}(\Gamma_I, \Gamma_J) \to \operatorname{Mor}_{\mathbf{B}_S}(W_I, W_J), \quad \Gamma_I \times \Gamma_J \to \Gamma_J/_S \times \Gamma_I$$

 $(\gamma_I, \gamma_J) \mapsto (\gamma_J S, (\gamma_J|_I (\gamma_I)^{-1})).$

Then F_S commutes with the target map, and commutes with the source map because $F_S \circ s(\gamma_I, \gamma_J) = \gamma_I S$ while

$$s \circ F_S(\gamma_I, \gamma_J) = s(\gamma_J S, \gamma_J|_I (\gamma_I)^{-1})$$
$$= (\gamma_J|_I(\gamma_I)^{-1})^{-1}\gamma_J|_I S = \gamma_I S.$$

Further, $m_S \circ (F_S \times F_S) = F_S \circ m_{id}$ because when $I \subset J \subset K$

$$m_S \circ (F_S \times F_S) ((\gamma_I, \gamma_J), (\gamma_J, \gamma_K)) = m_S ((\gamma_J S, \gamma_J |_I \gamma_I^{-1}), (\gamma_K S, \gamma_K |_J \gamma_J^{-1}))$$
$$= (\gamma_K S, \gamma_K |_I \gamma_I^{-1}) = F_S (\gamma_I, \gamma_K).$$

Finally notice that $F_S \circ F_s = F_S$ for all $s \in S$ because $\gamma_J^i s (\gamma_I^i s)^{-1} = \gamma_J^i (\gamma_I^i)^{-1} \in \Gamma_I$ when $i \in I, s \in S$. Therefore F_S descends to the quotient $\mathbf{B}_{\mathrm{id}}/_{S}$ (considered as a submonoid of $\mathbf{G}_{\mathrm{id}}/_{S}$), inducing an isomorphism from this quotient $\mathbf{B}_{\mathrm{id}}/_{S}$ to \mathbf{B}_S . We therefore obtain from its inverse an inclusion $\mathbf{B}_S \to \mathbf{G}_{\mathrm{id}}/_{S}$ that exhibits $\mathbf{G}_{\mathrm{id}}/_{S}$ as the groupoid completion of \mathbf{B}_S .

Proposition 2.3. Let $K = (W_I, \Gamma_I, \rho_{IJ})_{I \subset J, I, J \in \mathcal{I}_K}$ be an orbifold atlas as above. Then the category \mathbf{B}_K has a canonical completion to an ep groupoid \mathbf{G}_K with the same objects and realization as \mathbf{B}_K and morphisms

$$\operatorname{Mor}_{\mathbf{G}_{\mathcal{K}}} = \bigsqcup_{I,J \in \mathcal{I}_{Y}: I \cup J \in \mathcal{I}_{Y}} \operatorname{Mor}_{\mathbf{G}_{\mathcal{K}}}(W_{I}, W_{J}),$$
$$\operatorname{Mor}_{\mathbf{G}_{\mathcal{K}}}(W_{I}, W_{J}) := W_{I \cup J} \times \Gamma_{I \cap J},$$

where $\Gamma_{\emptyset} := id$, and with the following structural maps.

(i) The source and target maps $s \times t : W_{I \cup J} \times \Gamma_{I \cap J} \to W_I \times W_J$ are

$$(s \times t)(z,\gamma) = ((I,\gamma^{-1}\rho_{I(I \cup J)}(z)), (J,\rho_{J(I \cup J)}(z))).$$

(ii) Composition is given by

$$m: \operatorname{Mor}_{\mathbf{G}_{\mathcal{K}}}(W_I, W_J)_t \times_s \operatorname{Mor}_{\mathbf{G}_{\mathcal{K}}}(W_J, W_K) \to \operatorname{Mor}_{\mathbf{G}_{\mathcal{K}}}(W_I, W_K),$$

 $((z, \gamma), (w, \delta)) \mapsto (v', \alpha \delta_{IJK} \gamma_{IJK}) \in W_{I \cup K} \times \Gamma_{I \cap K}, \quad v' := \rho_{I \cup K, I \cup J \cup K}(v),$

where $\gamma_{IJK}, \delta_{IJK}$ are the images of $\gamma \in \Gamma_{I\cap J}$, $\delta \in \Gamma_{J\cap K}$ under projection to $\Gamma_{I\cap J\cap K}$ and $(v,\alpha) \in W_{I\cup J\cup K} \times \Gamma_{(I\cap K)\smallsetminus J}$ is the unique pair such that

$$\rho_{I \cup J, I \cup J \cup K}(v) = \gamma_{IJ \setminus K}^{-1} \alpha \, \delta z, \quad \rho_{J \cup K, I \cup J \cup K}(v) = \gamma_{IJ \setminus K}^{-1} w,$$

where $\gamma_{IJ \setminus K} := \gamma \gamma_{IJK}^{-1} \in \Gamma_{(I \cap J) \setminus K}$.

(iii) The inverse is given by

$$\iota: \operatorname{Mor}_{\mathbf{G}_{\kappa}}(W_I, W_J) \to \operatorname{Mor}_{\mathbf{G}_{\kappa}}(W_J, W_I), \quad (z, \gamma) \mapsto (\gamma^{-1}z, \gamma^{-1}).$$

Proof. When $I \subset J \subset K$ the above formulas for $\operatorname{Mor}_{\mathbf{G}_{\mathcal{K}}}(W_I, W_J)$ and the composition in (ii) agree with the previous definitions for $\mathbf{B}_{\mathcal{K}}$. We must extend this definition to all pairs I, J with $F_I \cap F_J \neq \emptyset$ (or equivalently $I \cup J \in \mathcal{I}_Y$) so as to be consistent with the footprint maps and the local group actions. In particular, in order to see that the inclusion $\mathbf{B}_{\mathcal{K}} \to \mathbf{G}_{\mathcal{K}}$ induces a homeomorphism $|\mathbf{B}_{\mathcal{K}}| \stackrel{\cong}{\to} |\mathbf{G}_{\mathcal{K}}|$ we require

(*) \exists a morphism from $x \in W_I$ to $y \in W_J$ in \mathbf{G} iff $(I, x) \sim (J, y)$ in $\mathrm{Obj}_{\mathbf{B}_{\kappa}}$ iff $\psi_I(x) = \psi_J(y) \in F_{I \cup J} := F_I \cap F_J$;

To see that the morphisms as described above satisfy (*) note first that $\operatorname{Mor}_{\mathbf{G}}(x,y) \neq \emptyset$ implies that x,y have the same image in Y. Conversely,

suppose given $x \in W_I, y \in W_J$ with $I \not\subset J$ and such that $\psi_I(x) = \psi_J(y)$. Since $\rho_{J(I \cup J)} : W_{I \cup J} \to W_{J(I \cup J)} := \psi^{-1}(F_{I \cup J})$ is surjective and factors out by the free action of $\Gamma_{I \setminus J}$ we may choose $z \in W_{I \cup J}$ so that $\rho_{J(I \cup J)}(z) = y$. Then $\rho_{I(I \cup J)}(z)$ lies in the Γ_{I} -orbit of x because $\psi_{I \cup J}(z) = \psi_I(x)$, so that by replacing z by δz for some $\delta \in \Gamma_{I \setminus J}$ we may arrange that $\rho_{I(I \cup J)}(z)$ lies in the $\Gamma_{I \cap J}$ -orbit of x, where $\Gamma_{I \cap J} := \operatorname{id} \text{ if } I \cap J = \emptyset$. Therefore there is a pair $(z, \gamma) \in (W_{I \cup J}, \Gamma_{I \cap J})$ with $\rho_{I(I \cup J)}(z) = \gamma x, \rho_{J(I \cup J)}(z) = y$. Thus, if we define $\operatorname{Mor}(W_I, W_J) := W_{I \cup J} \times \Gamma_{I \cap J}$ with source and target maps as in (i), condition (*) is satisfied.

The next step is to check that composition as given by (ii) is well defined. To this end, observe that for any triple I, J, K with $I \cup J \cup K \in \mathcal{I}_Y$, the square in the commutative diagram

expresses $W_{I\cup J\cup K}$ as a fiber product over $W_{J\cup (I\cap K)}=W_{(I\cup J)\cap (J\cup K)}$, where to simplify notation we write $\rho_{I\bullet}:=\rho_{IJ}:W_J\to W_I$. (This holds because the projection $\rho_{I\bullet}$ is a principal $\Gamma_{\bullet \smallsetminus I}$ -bundle.) Hence any pair in $W_{I\cup J}\times W_{J\cup K}$ has a unique lift to $W_{I\cup J\cup K}$ provided that its components have the same image in $W_{J\cup (I\cap K)}$.

Now consider the composite $(w, \delta) \circ (z, \gamma) : W_I \to W_K$. The identity $s(w, \delta) = t(z, \gamma)$ implies that $\rho_{J(I \cup J)}(z) = \delta^{-1} \rho_{J(J \cup K)}(w)$, so that the elements $\gamma_{IJ \setminus K}^{-1} \delta z \in W_{I \cup J}$ and $\gamma_{IJ \setminus K}^{-1} w \in W_{J \cup K}$ have the same image in W_J . Hence, because $\rho_{J \bullet} : W_{J \cup (I \cap K)} \to W_J$ quotients out by a free action of $\Gamma_{(I \cap K) \setminus J}$, the properties of the above diagram imply there is a unique $\alpha \in \Gamma_{(I \cap K) \setminus J}$ such that

$$\rho_{J(I\cup J)}(\alpha\gamma_{IJ\smallsetminus K}^{-1}\delta\,z) = \rho_{J(J\cup K)}(\gamma_{IJ\smallsetminus K}^{-1}\,w), \text{ where } \gamma_{IJ\smallsetminus K} := \rho_{(I\cap J\smallsetminus K)(I\cap J)}^{\Gamma}(\gamma).$$

(Notice here that $\alpha \in \Gamma_K$ commutes with $\gamma_{IJ \setminus K} \in \Gamma_{(I \cap J) \setminus K}$ though it may not commute with δ .) Thus $v \in W_{I \cup J \cup K}$ is uniquely defined by the given conditions.

It remains to check that the morphism $(v', \alpha(\delta\gamma)_{IJK}) \in W_{(I \cup K)(I \cap K)}$ has source $s(z, \gamma)$ and target $t(w, \delta)$. But

$$t(v', \alpha(\delta\gamma)_{IJK}) = \rho_{K(I\cup K)}(v') = \rho_{K(I\cup J\cup K)}(v)$$

= $\rho_{K(J\cup K)}(\gamma_{I\cup J\setminus K}^{-1}w) = \rho_{K(J\cup K)}(w) = t(w, \delta),$

because $\gamma_{IJ \setminus K} \in \Gamma_{J \setminus K}$ has no component in Γ_K . Similarly,

$$\begin{split} s(v',\alpha(\delta\gamma)_{IJK}) &= \rho_{I(I\cup K)}((\alpha(\delta\gamma)_{IJK})^{-1}v') \\ &= (\alpha(\delta\gamma)_{IJK})^{-1}\rho_{I(I\cup J\cup K)}(v) \\ &= (\delta\gamma)_{IJK})^{-1}\alpha^{-1}\rho_{I(I\cup J)}(\alpha\gamma_{IJ\smallsetminus K}^{-1}\delta z) \\ &= (\delta\gamma)_{IJK})^{-1}\alpha^{-1}\alpha\gamma_{IJ\smallsetminus K}^{-1}\delta_{IJK}\rho_{I(I\cup J)}(z) \\ &= \gamma_{IJK}^{-1}\gamma_{IJ\smallsetminus K}^{-1}\delta_{IJK}^{-1}\delta_{IJK}\rho_{I(I\cup J)}(z) \\ &= \gamma^{-1}\rho_{I(I\cup J)}(z) = s(z,\gamma), \end{split}$$

where we have used the fact that $\rho_{I(I\cup J)}(\delta z) = \delta_{IJK}\rho_{I(I\cup J)}(z)$ because $\delta \in \Gamma_{J\cap K}$ so that $\delta\delta_{IJK}^{-1} \in \ker \rho_{I(I\cup J)}^{\Gamma}$, and the fact that $\gamma_{IJ \setminus K} \in \Gamma_{I \setminus K}$ and $\delta_{IJK} \in \Gamma_{K}$ commute.

Thus the formula for m in (ii) is well defined and compatible with source and target maps. Moreover, m is a local diffeomorphism. It is also easy to check that m is compatible with the formula for the inverse given in (iii). Indeed, if $(z, \gamma) \in \text{Mor}(W_I, W_J)$ it is immediate that $s \times t(z, \gamma) = t \times s(\gamma^{-1}z, \gamma^{-1}) = t \times s(\iota(z, \gamma))$. Further,

$$m((z,\gamma),(\gamma^{-1}z,\gamma^{-1}))=(v',\delta'\gamma')$$

where $\gamma' = \gamma^{-1}$, $\delta' = \delta = \gamma$, and $v' = \rho_{I(I \cup J)}(v)$ with $v \in W_{I \cup J}$ defined by the requirement that $\rho_{(I \cup J)(I \cup J)}(v) = \gamma^{-1}z$ so that $v = \gamma^{-1}z$ and $v' = s(z, \gamma)$. Thus the composite $m((z, \gamma), (\gamma^{-1}z, \gamma^{-1})) = (s(z, \gamma), id)$ is the identity morphism at $s(z, \gamma)$.

To prove that m is associative,⁶ it suffices to show that, for each $y \in Y$, m restricts to an associative multiplication on the full subcategory \mathbf{G}_y of $\mathbf{G}_{\mathcal{K}}$ with objects $\bigsqcup_{I \in \mathcal{I}_y} \psi_I^{-1}(y)$, where $\mathcal{I}_y := \{I \in \mathcal{I}_Y \mid y \in F_I\}$. Since Γ_I acts transitively on $\psi_I^{-1}(y)$ for each I, this is precisely the case considered in Example 2.2. Hence it will suffice to show that the above composition operation is the image of composition in the category \mathbf{G}_{id} . To this end, choose a compatible set of base points $(x_{\bullet} = x_I \in \psi_I^{-1}(y))_I \in \mathcal{I}_y$ and define

$$H_I: \Gamma_I \to \psi_I^{-1}(y), \quad \gamma_I \mapsto \gamma_I(x_{\bullet}),$$

$$H_{IJ}: \operatorname{Mor}_{\mathbf{G}_{\operatorname{id}}}(\Gamma_I, \Gamma_J) \to \operatorname{Mor}_{\mathbf{G}_y}(\psi_I^{-1}(y), \psi_J^{-1}(y)), \quad (\gamma_I, \gamma_J) \mapsto (\gamma'_{I \cup J} x_{\bullet}, \delta'_{I \cap J})$$

where $\delta'_{I\cap J}(\gamma_I|_{I\cap J}) = \gamma_J|_{I\cap J}$ and $\gamma'_{I\cup J} \in \Gamma_{I\cup J}$ is the unique element whose projection $\gamma'_{I\cup J}|_I$ to Γ_I is $\delta_{I\cap J}\gamma_I$ and whose projection $\gamma'_{I\cup J}|_J$ to Γ_J is γ_J .

 $^{^6}$ An alternative argument, valid in the case where the group actions are effective, is given in [M2].

The restriction to \mathbf{G}_y of the diagram (2.3) that is used to define the composite m takes the form

$$\begin{array}{ccc}
\Gamma_{I \cup J \cup K}(x_{\bullet}) & \xrightarrow{\Gamma_{I \setminus (J \cup K)}} & \Gamma_{J \cup K}(x_{\bullet}) \\
\Gamma_{K \setminus (I \cup J)} \downarrow & & \Gamma_{K \setminus (I \cap K)} \downarrow & & \Gamma_{I \cup J}(x_{\bullet}) \downarrow & & \Gamma_{I}(x_{\bullet}) \downarrow & & \Gamma_{I}(x_{\bullet})$$

where each arrow is labelled by the group that acts freely on its fibers. But this is the image under H_{\bullet} of a corresponding diagram for the groups Γ_{\bullet} that can be used in precisely the same way to define the composite in \mathbf{G}_{id} . This was previously written in the simple form $m_{\mathrm{id}}((\gamma_I, \gamma_J), (\gamma_J, \gamma_K)) = (\gamma_I, \gamma_K)$, but, with $H(\gamma_I, \gamma_J) = (\gamma'_{I \cup J}, \delta'_{I \cap J})$ and $H(\gamma_J, \gamma_K) = (\gamma''_{J \cup K}, \delta''_{I \cap K})$ satisfying the identities

$$\gamma'_{I\cup J}|_I = \delta'_{I\cap J}\gamma_I, \quad \gamma'_{I\cup J}|_J = \gamma_J, \quad \gamma''_{J\cup K}|_J = \delta''_{J\cap K}\gamma_J, \quad \gamma''_{J\cup K}|_K = \gamma_K,$$

one can check that there is a unique element $\alpha \in \Gamma_{I \cup J \cup K}$ with components given by

$$\alpha|_I = (\delta'_{I \cap J}^{-1} \gamma_J)|_I, \quad \alpha|_J = (\delta''_{J \cap K}^{-1} \gamma_K)|_J, \quad \alpha|_K = \gamma_K$$

that plays the role of the element v in the definition of m in (ii). Using this, it is straightforward to check that the multiplications correspond under H_{\bullet} . It follows that m is associative, which completes the definition of the groupoid $\mathbf{G}_{\mathcal{K}}$.

3. Existence of atlases

We now show that every orbifold has an orbifold atlas that is unique up to the following notion of commensurability.

Definition 3.1. Let \mathcal{K} , \mathcal{K}'' be orbifold at lases on Y. We say that \mathcal{K} is a **subatlas** of \mathcal{K}'' if there is an injective étale functor $\iota : \mathbf{B}_{\mathcal{K}} \to \mathbf{B}_{\mathcal{K}''}$ such that $|\psi| = |\psi''| \circ |\iota| : |\mathbf{B}_{\mathcal{K}}| \to Y$. Two orbifold at lases \mathcal{K} , \mathcal{K}' on Y are **directly commensurate** if they are subatlases of a common at las \mathcal{K}'' . They are **commensurate** there is a sequence of at lases $\mathcal{K} =: \mathcal{K}_1, \ldots, \mathcal{K}_\ell := \mathcal{K}'$ such that any consecutive pair $\mathcal{K}_i, \mathcal{K}_{i+1}$ are directly commensurate.

Remark 3.2. (i) It is not hard to see that commensurate at lases are cobordant, i.e. there is an orbifold at las on the product $[0,1] \times Y$ that restricts to

 \mathcal{K} on $\{0\} \times Y$ and to \mathcal{K}' on $\{1\} \times Y$. (For precise definitions, and a proof see [MW2, §6.2].) If we assume that all atlases (or, equivalently, their groupoid completions) have compatible orientations, we may conclude that any pair of atlases that are oriented commensurate have the same fundamental class; cf. [M1] and §4 below.

(ii) It is likely that commensurate atlases are directly commensurate, i.e. that the relation of direct commensurability is transitive; however we have not attempted to prove this since we are most interested in the cobordism relation.

Here is our main result.

Proposition 3.3. Every paracompact orbifold Y has an orbifold atlas K whose associated groupoid G_K is an orbifold structure on Y. Moreover, there is a bijective correspondence between commensurability classes of such atlases and Morita equivalence classes of ep groupoids.

Proof. Let \mathbf{G} be an ep groupoid with footprint map $f: \mathrm{Obj}_{\mathbf{G}} \to Y$. Our first aim is to construct an atlas \mathcal{K} on Y together with a functor $F: \mathbf{B}_{\mathcal{K}} \to \mathbf{G}$ that covers the identity map on Y and hence extends to an equivalence from the groupoid completion $\mathbf{G}_{\mathcal{K}}$ to \mathbf{G} .

By Moerdijk [Mo], each point in Y is the image of a group quotient that embeds into \mathbf{G} . Therefore since Y is paracompact we can find a locally finite set of basic charts $\mathbf{K}_i := (W_i, \Gamma_i, \psi_i)_{i \in A}$ on Y whose footprints $(F_i)_{i \in A}$ cover Y, together with smooth maps

$$\sigma: \bigsqcup_{i} W_{i} \hookrightarrow \mathrm{Obj}_{\mathbf{G}}, \quad \widetilde{\sigma}: \bigsqcup_{i} W_{i} \times \Gamma_{i} \hookrightarrow \mathrm{Mor}_{\mathbf{G}},$$

where $\sigma|_{W_i}$ is a diffeomorphism to its image, that are compatible in the sense that the following diagrams commute:

$$W_{i} \times \Gamma_{i} \xrightarrow{\widetilde{\sigma}_{i}} \operatorname{Mor}_{\mathbf{G}} \qquad W_{i} \xrightarrow{\sigma_{i}} \operatorname{Obj}_{\mathbf{G}}$$

$$s \times t \Big| \qquad s \times t \Big| \qquad \psi_{i} \Big| \qquad f \Big|$$

$$W_{i} \times W_{i} \xrightarrow{\sigma_{i}} \operatorname{Obj}_{\mathbf{G}} \times \operatorname{Obj}_{\mathbf{G}}, \qquad Y \xrightarrow{\operatorname{id}} Y.$$

We claim that there is an atlas K with these basic charts whose footprint maps ψ_I extend $f \circ \sigma : \bigsqcup_i W_i \to Y$. This atlas depends on the choice of a total order on A. To begin the construction, we define W_I where |I| = 2.

Since A is ordered, any set $I \in \mathcal{I}_Y$ with |I| = 2 may be written as $I := \{i_0, i_1\}$ with $i_0 < i_1$. Consider the set

$$W_I := W_{\{i_0, i_1\}} := \operatorname{Mor}_{\mathbf{G}}(\sigma(W_{i_0}), \sigma(W_{i_1})) := (s_{\mathbf{G}} \times t_{\mathbf{G}})^{-1} (\sigma(W_{i_0}) \times \sigma(W_{i_1}))$$

of morphisms in **G** from $\sigma(W_{i_0})$ to $\sigma(W_{i_1})$, where to avoid confusion the source and target maps in **G** are denoted $s_{\mathbf{G}}, t_{\mathbf{G}}$. Then W_I is the inverse image of an open subset of $\mathrm{Obj}_{\mathbf{G}} \times \mathrm{Obj}_{\mathbf{G}}$, hence open in $\mathrm{Mor}_{\mathbf{G}}$, and thus a smooth manifold. Since the points in $f^{-1}(F_I) \cap \sigma(W_{i_0})$ are identified with points in $f^{-1}(F_I) \cap \sigma(W_{i_1})$ by morphisms in **G**, the restrictions of $s_{\mathbf{G}}, t_{\mathbf{G}}$ to W_I have images

$$s_{\mathbf{G}}(W_I) = f^{-1}(F_I) \cap \sigma(W_{i_0}), \qquad t_{\mathbf{G}}(W_I) = f^{-1}(F_I) \cap \sigma(W_{i_1}).$$

Moreover, for any $x \in s_{\mathbf{G}}(W_I)$ and $\alpha \in \operatorname{Mor}_{\mathbf{G}}(x,y) \in W_I$, we have

$$s_{\mathbf{G}}^{-1}(x) \cap W_I \cong \operatorname{Mor}_{\mathbf{G}}(t_{\mathbf{G}}(\alpha), \sigma(W_{i_1})) \cong \Gamma_{i_1},$$

where the second isomorphism holds because by assumption $f \circ \sigma_{i_1} = \psi_{i_1}$: $W_{i_1} \mapsto F_{i_1}$ is the composite of the quotient map $W_{i_1} \to {}^{W_{i_1}}/_{\Gamma_{i_1}}$ with a homeomorphism. Rephrasing this in terms of the action of the group $\Gamma_I := \Gamma_{i_1} \times \Gamma_{i_0}$ on $\alpha \in W_I$ by

$$(\gamma_{i_1}, \gamma_{i_0}) \cdot \alpha = \widetilde{\sigma}(\gamma_{i_1}) \circ \alpha \circ \widetilde{\sigma}(\gamma_{i_0}^{-1}),$$

one finds that Γ_{i_1} acts freely on W_I and that the source map $s_{\mathbf{G}}: W_I \to \sigma(W_{i_0})$ induces a diffeomorphism $W_I/_{\Gamma_{i_1}} \to \sigma(W_{i_0}) \cap f^{-1}(F_I)$. Similarly, Γ_{i_0} acts freely, and the target map $t_{\mathbf{G}}: W_I \to \sigma(W_{i_1})$ induces a diffeomorphism $W_I/_{\Gamma_{i_0}} \to \sigma(W_{i_1}) \cap f^{-1}(F_I)$. Since the footprint map for the chart W_i factors out by the action of Γ_i , the same is true for this transition chart: in other words the footprint map

$$\psi_I: W_I \to Y, \quad \alpha \mapsto f(s_{\mathbf{G}}(\alpha)) = f(t_{\mathbf{G}}(\alpha))$$

induces a homeomorphism ${}^{W_I}/_{\Gamma_I} \stackrel{\cong}{\to} F_I$. Therefore W_I satisfies all the requirements of a sum of two charts.

To define the transition chart for general $I \in \mathcal{I}_Y$, enumerate the elements of I as $i_0 < i_1 < \cdots < i_k$, where $k + 1 := |I| \ge 2$ and define W_I to be the set

of composable k-tuples of morphisms $(\alpha_{i_k}, \dots, \alpha_{i_1})$, where

(3.1)
$$\alpha_{i_{\ell}} \in \operatorname{Mor}_{\mathbf{G}}(\sigma(W_{i_{\ell-1}}), \sigma(W_{i_{\ell}})).$$

If $H := (i_1, \dots, i_k)$, then W_I is the fiber product $W_{H s_{\mathbf{G}}} \times_{t_{\mathbf{G}}} W_{i_1 i_0}$. Since the maps $s_{\mathbf{G}} : W_{i_1 i_0} \to W_{i_0}$, $t_{\mathbf{G}} : W_{i_1 i_0} \to W_{i_1}$ are étale and so locally submersive, it follows by induction on |I| that W_I is a smooth manifold. Moreover, it supports an action of Γ_I given by

$$\gamma \cdot (\alpha_{i_k}, \cdots, \alpha_{i_1}) = (\alpha_{i_k}, \cdots, \alpha_{i_{\ell+1}} \widetilde{\sigma}(\gamma)^{-1}, \widetilde{\sigma}(\gamma) \alpha_{i_\ell}, \cdots, \alpha_{i_1}), \quad \gamma \in \Gamma_{i_\ell}.$$

For any $H \subsetneq I$ the subgroup $\Gamma_{I \setminus H}$ acts freely, and the quotient can be identified with W_H by means of the appropriate partial compositions and forgetful maps. More precisely, if $I = (i_0, \dots, i_k) \supset H = (i_{n_0}, \dots, i_{n_\ell})$ then

$$\rho_{HI}(\alpha_{i_k}, \dots, \alpha_{i_1})$$

$$= \begin{cases} (\alpha_{i_{n_\ell}} \circ \dots \circ \alpha_{i_{n_{\ell-1}+1}}, \dots, \alpha_{i_{n_2}} \circ \dots \circ \alpha_{i_{n_1+1}}), & \text{if } \ell \ge 1 \\ s_{\mathbf{G}}(\alpha_{i_p+1}) = t_{\mathbf{G}}(\alpha_{i_p}) & \text{if } \ell = 0, p := n_0 \end{cases}$$

For example if $H = \{1, 3, 6\} \subset I = \{0, 1, 2, 3, 4, 5, 6, 7\}$ then

$$\rho_{HI}: (\alpha_7, \cdots, \alpha_1) = (\alpha_6 \circ \alpha_5 \circ \alpha_4, \alpha_3 \circ \alpha_2),$$

$$\rho_{\{3\}I}: (\alpha_7, \cdots, \alpha_1) = s(\alpha_4) = t(\alpha_3).$$

It is clear from this description that $\rho_{HJ} = \rho_{HI} \circ \rho_{IJ}$ whenever $H \subset I \subset J$. Further the footprint map $\psi_I : W_I \to Y$ can be written as

$$\psi_I((\alpha_{i_k}, \cdots, \alpha_{i_1})) = f(\sigma \circ s_{\mathbf{G}}(\alpha_{i_p})) = f(\sigma \circ t_{\mathbf{G}}(\alpha_{i_p})), \quad \forall \ 1 \le p \le k.$$

This defines the atlas \mathcal{K} .

We define the functor $F_{\mathcal{K}}: \mathbf{B}_{\mathcal{K}} \to \mathbf{G}$ on objects by (3.2)

$$W_I \to \mathrm{Obj}_{\mathbf{G}}, \quad \begin{cases} x \mapsto \sigma(x), & \text{if } I = \{i_0\}, x \in W_{i_0}, \\ (\alpha_{i_k}, \cdots, \alpha_{i_1}) \mapsto t_{\mathbf{G}}(\alpha_{i_k}) \in \sigma(W_{i_k}) & \text{if } |I| > 1. \end{cases}$$

Recall from (1.2) that the morphisms in $\mathbf{B}_{\mathcal{K}}$ are given by $\bigsqcup_{I\subset J} W_J \times \Gamma_I$ where

$$(I, J, y, \gamma) : (I, \gamma^{-1} \rho_{IJ}(y)) \mapsto (J, y).$$

If $i_k = j_\ell$ then we define $F_K : W_J \times \Gamma_I \to \operatorname{Mor}_{\mathbf{G}}$ to be given by the initial inclusion $\widetilde{\sigma}$. More precisely, we define

$$F_{\mathcal{K}}((\alpha_{j_{\ell}}, \cdots, \alpha_{j_{1}}), (\gamma_{j_{\ell}}, \cdots, \gamma_{i_{0}})) = \widetilde{\sigma}(t(\alpha_{j_{\ell}}), \gamma_{j_{\ell}})$$

$$\in \operatorname{Mor}_{\mathbf{G}}(\widetilde{\sigma}(\gamma_{i_{\ell}}^{-1}) \ t(\alpha_{j_{\ell}}), t(\alpha_{j_{\ell}})),$$

where t denotes the target map in $\mathbf{B}_{\mathcal{K}}$. Similarly, if $i_k = j_p < j_\ell$ define

$$F_{\mathcal{K}}((\alpha_{j_{\ell}}, \cdots, \alpha_{j_{1}}), (\gamma_{i_{k}}, \cdots, \gamma_{i_{0}})) = (\alpha_{j_{\ell}} \circ \cdots \circ \alpha_{j_{p+1}})$$

$$\in \operatorname{Mor}_{\mathbf{G}}(t(\alpha_{j_{p}}), t(\alpha_{j_{\ell}})).$$

It is immediate that $F_{\mathcal{K}}$ is a functor that extends to an equivalence from the groupoid extension $\mathbf{G}_{\mathcal{K}}$ of $\mathbf{B}_{\mathcal{K}}$ to \mathbf{G} .

This shows that every orbifold has an atlas of the required type. To see that this atlas is unique up to commensurability, note first that any two atlases constructed in this way from the same groupoid are directly commensurate. More generally, suppose given groupoid structures $(\mathbf{G}, f), (\mathbf{G}', f')$ on Y with common refinement

$$F: (\mathbf{G}'', f'') \to (\mathbf{G}, f), \quad F': (\mathbf{G}'', f'') \to (\mathbf{G}', f'),$$

where $F: \operatorname{Obj}_{\mathbf{G}''} \to \operatorname{Obj}_{\mathbf{G}}$ and $F': \operatorname{Obj}_{\mathbf{G}''} \to \operatorname{Obj}_{\mathbf{G}}$ are local diffeomorphisms. Choose an atlas \mathcal{K}'' on \mathbf{G}'' with basic charts $(W_i'', \Gamma_i)_{i \in A})$ where for each i the group Γ_i is the stabilizer subgroup of some point $x_i \in W_i''$. Then, for each $1 \leq i \leq N$, the map $F: W_i'' \to W_i := F(W_i'') \subset \operatorname{Obj}_{\mathbf{G}}$ is injective because F induces an isomorphism $\Gamma_i := \operatorname{Mor}_{\mathbf{G}''}(x_i, x_i) \to \operatorname{Mor}_{\mathbf{G}}(F(x_i), F(x_i))$ and an injection on the quotient $W_i''/\Gamma_i \to Y$. Therefore the basic charts $(W_i'', \Gamma_i)_{i \in A}$ are pushed forward diffeomorphically by F to a family of basic charts $(W_i'', \Gamma_i)_{i \in A}$ in G. Further, it is immediate from the construction of the corresponding atlases \mathcal{K}'' and \mathcal{K} from the categories G'' and G that F induces an isomorphism between them. Hence all atlases on F that are constructed from F or from F are commensurate to this atlas that is pushed forward from F0, and hence they all belong to the same commensurability class.

Conversely, we must show that if $\mathcal{K}, \mathcal{K}'$ are commensurate, the groupoids $\mathbf{G}_{\mathcal{K}}$ and $\mathbf{G}_{\mathcal{K}'}$ are equivalent. It suffices to consider the case when $\mathcal{K}, \mathcal{K}'$ are directly commensurate. But then they are contained in a common atlas \mathcal{K}'' on Y that defines a groupoid $\mathbf{G}_{\mathcal{K}''}$ that contains both $\mathbf{G}_{\mathcal{K}}$ and $\mathbf{G}_{\mathcal{K}'}$ as subgroupoids with the same realization Y. Thus the inclusions $\mathbf{G}_{\mathcal{K}} \to \mathbf{G}_{\mathcal{K}''}$ and $\mathbf{G}_{\mathcal{K}'} \to \mathbf{G}_{\mathcal{K}''}$ are equivalences. This completes the proof.

Remark 3.4. The above construction for the atlas \mathcal{K} depends on a choice of ordering of the basic charts $(\mathbf{K}_i)_{i\in A}$. If we change this order, for example, by interchanging the order of 1 and 2, then it is not hard to show that the resulting atlas \mathcal{K}' is isomorphic to \mathcal{K} , but not in a way compatible with the functor $F_{\mathcal{K}}: \mathbf{B}_{\mathcal{K}} \to \mathbf{G}$ defined in (3.2). Indeed, each atlas $\mathcal{K}, \mathcal{K}'$ has the same basic charts, so that $F_{\mathcal{K}} = F'_{\mathcal{K}'} = \sigma$ on each W_i . Moreover, the transition charts $\mathbf{K}_I, \mathbf{K}'_I$ contain precisely the same tuples as long as $\{1,2\} \not\subset I$. However, $W_{12} = \operatorname{Mor}_{\mathbf{G}}(W_1, W_2)$ with $F_{\mathcal{K}}(W_{12}) \subset W_2$ while $W'_{12} := \operatorname{Mor}_{\mathbf{G}}(W_2, W_1)$ with $F'_{\mathcal{K}'}(W_{12}) \subset W_1$. The only natural map $S_{12}: W_{12} \to W'_{12}$ takes the morphism $\alpha \in \operatorname{Mor}_{\mathbf{G}}(W_1, W_2)$ to $\alpha^{-1} \in \operatorname{Mor}_{\mathbf{G}}(W_2, W_1) \subset \operatorname{Mor}_{\mathbf{G}_{\mathcal{K}}}$. In fact for any I we may define a map $S: \operatorname{Obj}_{\mathcal{B}_{\mathcal{K}}} \to \operatorname{Obj}_{\mathcal{B}_{\mathcal{K}}'}$ by setting

- $S_I = \mathrm{id}: W_I \to W_I'$ if $\{1, 2\} \not\subset I$;
- $S_I: W_I \to W_I'$, $(\alpha_{i_k}, \dots, \alpha_{i_3}, \alpha_2, \alpha_1) \mapsto (\alpha_{i_k}, \dots, \alpha_{i_3}, \alpha_2 \circ \alpha_1, \alpha_1^{-1})$ if $I = (1, 2, i_3, \dots)$, where $\alpha_1 \in \operatorname{Mor}(W_1, W_2), \alpha_2 \in \operatorname{Mor}(W_2, W_{i_3})$ as in (3.1)

We leave it to the interested reader to check that this is Γ_I -equivariant, and that it extends to a functorial isomorphism of the groupoid completions $\mathbf{G}_{\mathcal{K}} \stackrel{\cong}{\to} \mathbf{G}_{\mathcal{K}'}$.

Remark 3.5. The construction in Proposition 3.3 is reminiscent of that given in [M1, §4] for the resolution of an orbifold. However, the two constructions have different aims: here we want to build a simple model for $Y = |\mathbf{G}|$, while there we wanted to construct a nonsingular "resolution", i.e. a corresponding weighted branched manifold with the same fundamental class. We explain below how our current methods simplify the construction of such a resolution.

Example 3.6. (Noneffective orbifold structures on S^2 .) Consider an orbifold structure \mathbf{G} on $Y = S^2$ that locally has the form \mathbb{R}^2/Γ where $\Gamma := \mathbb{Z}/2\mathbb{Z}$ acts trivially. These are classified by the topological type of the corresponding classifying space $B\mathbf{G}$ (see [ALR]), which is a bundle over S^2 with fiber $B\mathbb{Z}_2 = K(\mathbb{Z}/2,1)$. Hence there are two such orbifolds, the trivial orbifold which has an atlas K^{triv} with a single chart $(S^2, \mathbb{Z}_2, \psi = \mathrm{id})$ and one other. They can be distinguished either by an element in $H^2(S^2, \mathbb{Z}_2) \cong \mathbb{Z}_2$ or by the fact that in the trivial case the bundle $B\mathbf{G} \to S^2$ has a section. One can see both these kinds of twisting from suitable atlases.

For example, consider an atlas with two basic charts with footprints equal to discs $(F_i)_{i=1,2}$ that intersect in an annulus F_{12} . If each has the trivial action of $\Gamma_i = \mathbb{Z}_2$, we may identify the domains W_i with F_i via the footprint

maps ψ_i , and hence identify the covering maps $\rho_{i,12}:W_{12}\to W_{i,12}\subset W_i$ with the footprint map $\psi_{12}:W_{12}\to F_{12}$. If ψ_{12} is the nontrivial 2-fold covering of the annulus, one can easily see that the boundary map $\pi_2(S^2)\to \pi_1(B\mathbf{G}_{\mathcal{K}})$ of the fibration $B\mathbf{G}_{\mathcal{K}}\to S^2$ is nonzero, so that this atlas describes the nontrivial orbifold.

On the other hand, suppose we choose an atlas whose footprints F_I are all contractible. Then W_I is a union of $2^{|I|-1}$ copies of F_I that are permuted by the action of Γ_I , with the diagonal subgroup acting trivially. For example, the basic charts have $W_i \cong F_i$, the charts with |I| = 2 have W_I equal to two copies of F_I that are permuted by the actions of Γ_i , $i \in I$, while the charts with with |J| = 3 have W_J equal to 4 copies of F_J . From this information, we can build a Čech cocycle representative $(\alpha_J: F_J \to \mathbb{Z}_2)_{|J|=3}$ for an element of $H^2(S^2,\mathbb{Z}_2)$ by choosing one component W_I^0 of W_I for each |I|=2, and then defining $\alpha_J := 0$ if there is a component W_J^0 of W_J such that $\rho_{IJ}(W_J^0) =$ W_I^0 for all $I \subset J$, |I| = 2, and setting $\alpha_J := 1$ otherwise. Notice that this information captures the structure of the triple intersections since there are only two possibilities: if $J = \{j_1, j_2, j_3\}$, then, because the groups $\Gamma_{J \setminus j_k}$ act freely on W_J for k=1,2,3, there is precisely one component of W_J that projects to $W_{J \setminus i_k}^0$ for k = 1, 2 and it either does or does not map to $W_{J>i_3}^0$. If we suppose in addition that all fourfold intersections are empty, then (α_J) is a cocycle. Moreover, it represents the trivial cohomology class if and only if one can choose a family of components W_I^0 of the domains that are compatible with the projections ρ_{IJ} and hence form the space of objects of a nonsingular subgroupoid $\mathbf{G}_{\mathcal{K}}^0$ of $\mathbf{G}_{\mathcal{K}}$ with realization S^2 . Since the classifying space of such a subgroupoid $\mathbf{G}_{\mathcal{K}}^0$ would provide a section of the bundle $B\mathbf{G}_{\mathcal{K}} \to S^2$, the triviality of the cocycle implies that the atlas defines the trivial orbifold structure on S^2 Conversely one can check that if the groupoid $G_{\mathcal{K}}$ defines the trivial structure then it has a nonsingular subgroupoid with realization S^2 : indeed, since such subgroupoids can be pulled back and pushed forward by equivalences, any groupoid that is Morita equivalent to the trivial groupoid $G_{K^{triv}}$ contains such a subatlas. Thus the cocycle described above does classify these orbifold structures.

In the above discussion we assumed for simplicity that all fourfold intersections are empty. However, it is not hard to check that (α_J) is always a cocycle so that the above argument goes through for any cover of S^2 . For this, we must show that, for every K with |K| = 4, an even number of the four terms $\alpha_{K \setminus j_k}$ are zero. To this end, consider $K = \{1, 2, 3, 4\}$ and suppose that $\alpha_{123} = 0$. Let W_{123}^0 be the component of W_{123} that projects to

 $^{^{7}}$ i.e. there is at most one morphism between any two objects

 $W_{12}^0,W_{13}^0,W_{23}^0$ and let W_{1234}^0 be the unique component of W_{1234} that projects to W_{123}^0 and W_{14}^0 . If in addition it projects to W_{k4}^0 for k=2 or k=3 then its image in W_{1k4} projects to $W_{1k}^0,W_{14}^0,W_{k4}^0$ so that $\alpha_{1k4}=0$. But if W_{1234}^0 projects to neither of W_{24}^0,W_{34}^0 then its image $\gamma_4W_{1234}^0$ under the nontrivial element $\gamma_4\in\Gamma_4$ projects to W_{23}^0,W_{24}^0 , and W_{34}^0 so that $\alpha_{234}=0$. Therefore, at least two of the $\alpha_{K\searrow j_k}$ vanish. On the other hand if three of them vanish, say $\alpha_{123},\alpha_{124},\alpha_{134}$, then the component W_{1234}^0 defined above must project to $W_{K\searrow k}^0$ for k=2,3,4 and hence project to all W_{ij}^0 for $i,j\in\{1,2,3,4\}$. Therefore we may take W_{234}^0 equal to its image in W_{234} ; in other words $\alpha_{234}=0$ as well.

4. Applications

We give two applications of our methods, first showing how the zero set construction in [MW3] gives a simple way to construct a nonsingular resolution of an orbifold, and second using this to construct a weighted branched manifold that represents the Euler class of an orbibundle.

We begin by defining the notion of a **resolution** of an ep groupoid **G**. This is obtained from a groupoid by first passing to a suitable Morita equivalent groupoid by pulling back via an open cover of the objects (a process called **reduction**) and then discarding some of its morphisms. The idea is to obtain a "simpler" groupoid that still has the same fundamental class; the groupoid is simpler in the sense that all stabilizers are trivial, however, because it is not proper, one must control its branching as explained below.

First recall that the realization of an ep groupoid \mathbf{G} carries a weighting function $\Lambda_G: |\mathbf{G}| \to \mathbb{Q}^+$ with values in the positive rational numbers \mathbb{Q}^+ , given by: $\Lambda_G(y) = \frac{1}{|\Gamma^y|}$, where $|\Gamma^y|$ is the order of the stabilizer subgroup Γ^y at one (and hence any) preimage of y in $\mathrm{Obj}_{\mathbf{G}}$. If \mathbf{G} is oriented and compact, the set of points $|\mathbf{G}|^*$ where $|\Gamma^y|$ is locally constant is open and dense, with complement of codimension ≥ 2 , and hence carries a fundamental class that can be represented by the singular cycle obtained by triangulating $|\mathbf{G}|^*$, giving each top dimensional simplex σ the weight $\Lambda_G(y), y \in \sigma$. (For more details, see [MP, M1].)

Roughly speaking, a **resolution** of an oriented compact ep groupoid **G** is a tuple $(\mathbf{V}, \Lambda_V, F)$ consisting of

- an oriented nonsingular étale groupoid V (more precisely a wnb groupoid) whose realization carries a weighting function $\Lambda_V : |V|_{\mathcal{H}} \to$

 \mathbb{Q}^+ where $|\mathbf{V}|_{\mathcal{H}}$ is the maximal Hausdorff quotient of $|\mathbf{V}|$ (defined below), together with

- an orientation preserving functor $F: \mathbf{V} \to \mathbf{G}$ that induces a surjection $|F|: |\mathbf{V}|_{\mathcal{H}} \to |\mathbf{G}|$ and is such that $F_*(\Lambda_V) = \Lambda_G$, where the pushforward $F_*(\Lambda_V): |\mathbf{G}| \to \mathbb{Q}^+$ is given by $F_*(\Lambda_V) = \sum_{x \in F^{-1}(y)} \Lambda_G(y)$.

As in [M1], one can define the notion of the fundamental class of $(\mathbf{V}, \Lambda_V, F)$, and show that under these circumstances F pushes this fundamental class forward to that of \mathbf{G} .

To make the above precise, we must define a wnb groupoid. Because these are in general not proper, the realization $|\mathbf{G}|$ may not be Hausdorff, and we write $|\mathbf{G}|_{\mathcal{H}}$ for its **maximal Hausdorff quotient**. Thus $|\mathbf{G}|_{\mathcal{H}}$ is a Hausdorff quotient of $|\mathbf{G}|$ that satisfies the following universal property: any continuous map from $|\mathbf{G}|$ to a Hausdorff space Y factors though the projection $|\mathbf{G}| \to |\mathbf{G}|_{\mathcal{H}}$. (The existence of such a quotient for any topological space is proved in [M1, Lemma 3.1]; see [MW3, Appendix] for a more detailed argument.) There are natural maps:

$$\pi_{\mathbf{G}}: \mathrm{Obj}_{\mathbf{G}} \to |\mathbf{G}|, \quad \pi_{|\mathbf{G}|}^{\mathcal{H}}: |\mathbf{G}| \longrightarrow |\mathbf{G}|_{\mathcal{H}}, \quad \pi_{\mathbf{G}}^{\mathcal{H}}:=\pi_{|\mathbf{G}|}^{\mathcal{H}} \circ \pi_{\mathbf{G}}: \mathrm{Obj}_{\mathbf{G}} \to |\mathbf{G}|_{\mathcal{H}}.$$

Moreover, for $U \subset \operatorname{Obj}_{\mathbf{G}}$ we write $|U| := \pi_{\mathbf{G}}(U) \subset |\mathbf{G}|$ and $|U|_{\mathcal{H}} := \pi_{\mathcal{H}}(U) \subset |\mathbf{G}|_{\mathcal{H}}$. The **branch locus** of \mathbf{G} is defined to be the subset of $|\mathbf{G}|_{\mathcal{H}}$ consisting of points with more than one preimage in $|\mathbf{G}|$.

Definition 4.1. A weighted nonsingular branched groupoid (or wnb groupoid for short) of dimension d is a pair (\mathbf{G}, Λ_G) consisting of an oriented, nonsingular étale groupoid \mathbf{G} of dimension d, together with a rational weighting function $\Lambda_G : |\mathbf{G}|_{\mathcal{H}} \to \mathbb{Q}^+ := \mathbb{Q} \cap (0, \infty)$ that satisfies the following compatibility conditions. For each $p \in |\mathbf{G}|_{\mathcal{H}}$ there is an open neighbourhood $N \subset |\mathbf{G}|_{\mathcal{H}}$ of p, a collection U_1, \ldots, U_ℓ of disjoint open subsets of $(\pi_{\mathbf{G}}^{\mathcal{H}})^{-1}(N) \subset \mathrm{Obj}_{\mathbf{G}}$ (called **local branches**), and a set of positive rational weights m_1, \ldots, m_ℓ such that the following holds:

(Covering)
$$(\pi_{|\mathbf{G}|}^{\mathcal{H}})^{-1}(N) = |U_1| \cup \cdots \cup |U_{\ell}| \subset |\mathbf{G}|;$$

(Local Regularity) for each $i = 1, ..., \ell$ the projection $\pi_{\mathbf{G}}^{\mathcal{H}}|_{U_i} : U_i \to |\mathbf{G}|_{\mathcal{H}}$ is a homeomorphism onto a relatively closed subset of N;

(Weighting) for all $q \in N$, the number $\Lambda_G(q)$ is the sum of the weights of the local branches whose image contains q:

$$\Lambda_G(q) = \sum_{i: q \in |U_i|_{\mathcal{H}}} m_i.$$

Further we define a **weighted branched manifold** of dimension d to be a pair (Z, Λ_Z) consisting of a topological space Z together with a function $\Lambda_Z : Z \to \mathbb{Q}^+$ and an equivalence class⁸ of wnb d-dimensional groupoids (\mathbf{G}, Λ_G) and homeomorphisms $f : |\mathbf{G}|_{\mathcal{H}} \to Z$ that induce the function $\Lambda_Z = \Lambda_G \circ f^{-1}$. Analogous definitions of a wnb cobordism groupoid (always assumed to be compact and have collared boundaries) and of a weighted branched cobordism are spelled out in [MW3, Appendix]. We say that two compact weighted branched manifolds $(\partial^{\alpha} Z, \Lambda^{\alpha})_{\alpha=0,1}$ are **cobordant** if they form the oriented boundary of a weighted branched cobordism.

Example 4.2. (i) A compact weighted branched manifold of dimension 0 consists of a finite set of points $Z = \{p_1, \ldots, p_k\}$, each with a positive rational weight $m(p_i) \in \mathbb{Q}^+$ and orientation $\mathfrak{o}(p_i) \in \{\pm\}$.

(ii) The prototypical example of a 1-dimensional weighted branched cobordism $(|\mathbf{G}|_{\mathcal{H}}, \Lambda)$ has $\mathrm{Obj}(\mathbf{G}) = I \sqcup I'$ equal to two copies of the interval I = I' = [0,1] with nonidentity morphisms from $x \in I$ to $x \in I'$ for $x \in [0,\frac{1}{2})$ and their inverses, where we suppose that I is oriented in the standard way. Then the realization and its Hausdorff quotient are

$$|\mathbf{G}| = \frac{I \sqcup I'}{\{(I, x) \sim (I', x) \text{ iff } x \in [0, \frac{1}{2})\}},$$
$$|\mathbf{G}|_{\mathcal{H}} = \frac{I \sqcup I'}{\{(I, x) \sim (I', x) \text{ iff } x \in [0, \frac{1}{2}]\}},$$

and the branch locus is a single point $\operatorname{Br}(\mathbf{G}) = \{[I, \frac{1}{2}] = [I', \frac{1}{2}]\} \subset |\mathbf{G}|_{\mathcal{H}}$. The choice of weights m, m' > 0 on the two local branches I and I' determines the weighting function $\Lambda : |\mathbf{G}|_{\mathcal{H}} \to (0, \infty)$ as

$$\Lambda([I,x]) = \begin{cases} m+m' & \text{if } x \in [0,\frac{1}{2}], \\ m & \text{if } x \in (\frac{1}{2},1], \end{cases}$$

$$\Lambda([I',x]) = \begin{cases} m+m' & \text{if } x \in [0,\frac{1}{2}], \\ m' & \text{if } x \in (\frac{1}{2},1]. \end{cases}$$

(iii) It is not hard to see that a wnb groupoid $\mathbf{Z} := ((p_i), m, \mathfrak{o})$ of dimension 0 is cobordant either to the empty groupoid (if $\lambda := \sum_i \mathfrak{o}(p_i) m(p_i) = 0$) or

⁸ The precise notion of equivalence is given in [M1, Definition 3.12]. In particular it ensures that the induced function $\Lambda_Z := \Lambda_{\mathbf{G}} \circ f^{-1}$ the dimension of $\mathrm{Obj}_{\mathbf{G}}$ and the pushforward of the fundamental class are the same for equivalent structures $(\mathbf{G}, \Lambda_G, f)$. However, it does not preserve the local branching structure of Z.

to a groupoid with one point p, weight $m(p) := |\lambda|$ and orientation $\mathfrak{o}(p)$ given by the sign of λ . Indeed suppose that

$$\lambda^+ := \sum_{i: \mathfrak{o}(p_i) = +} m(p_i) > \lambda^- := \sum_{i: \mathfrak{o}(p_i) = -} m(p_i).$$

Then one can first build a cobordism as in (ii) from **Z** to a groupoid with two points, p^+ with label $(\lambda^+, +)$ and p^- with label $(\lambda^-, -)$, then split p^+ into two labelled points $(q_1, \lambda^+ - \lambda^-, +), (q_2, \lambda^-, +)$ and then "cancel" $(q_2, \lambda^-, +)$ with $(p_-, \lambda^-, -)$ by joining them with an arc. The other cases are similar. Thus in dimension 0 the only cobordism invariant of a wnb groupoid is the total weight $\sum \mathfrak{o}(p_i)m(p_i)$.

Before constructing the resolution we need one further notion. We restrict to the compact case for simplicity.

Definition 4.3. Let $(F_i)_{i=1,\ldots,N}$ be an open covering of a space Y, and for $I \subset \{1,\ldots,N\}$ denote $F_I := \bigcap_{i\in I} F_i$. A collection of open sets $(Q_I)_{I\subset\{1,\ldots,N\}}$ is called a **cover reduction** of (F_i) if

- Q_I is a precompact subset of F_I for all I, written $Q_I \sqsubset F_I$;
- $\bullet \bigcup_I Q_I = Y;$
- $\overline{Q}_I \cap \overline{Q}_J \neq \emptyset \Longrightarrow (I \subset J \text{ or } I \subset J).$

It is well known that every finite open cover of a normal topological space has a cover reduction: see for example [MW1, Lemma 5.3.1] for a proof.

Let K be a strict orbifold atlas on a compact oriented orbifold Y with footprint covering $(F_i)_{i=1,...,N}$ and charts indexed by \mathcal{I}_Y , and let \mathbf{B}_K be the corresponding category with groupoid completion \mathbf{G}_K . Choose a reduction $(Q_I)_{I \in \mathcal{I}_Y}$ of the footprint cover, and define⁹

$$V_I := \psi_I^{-1}(Q_I) \sqsubset W_I, \quad \widetilde{V}_{IJ} := V_J \cap \psi_I^{-1}(Q_I) \sqsubset W_J, \ \forall I \subset J.$$

Definition 4.4. The resulting collection of sets $\mathcal{V} := (V_I)_{I \in \mathcal{I}_Y}$ is called a **reduction** of the atlas.

⁹ We write \widetilde{V}_{IJ} here to emphasize that, in distinction to the set $W_{IJ} = W_I \cap \psi_I^{-1}(F_J) \subset W_I$, we have $\widetilde{V}_{IJ} \subset V_J$. This notation is consistent with [MW3, M2]. Note also that $\widetilde{V}_{JJ} = V_J$.

Given a reduction \mathcal{V} , consider the subgroupoid $\mathbf{V}_{\mathcal{K}} \subset \mathbf{G}_{\mathcal{K}}$ with

(4.1)
$$\operatorname{Obj}_{\mathbf{V}_{\kappa}} := \bigsqcup_{I \in \mathcal{I}_{Y}} V_{I}, \quad \operatorname{Mor}_{\mathbf{V}_{\kappa}} := \bigsqcup_{I,J \in \mathcal{I}_{Y}} \operatorname{Mor}_{\mathbf{V}_{\kappa}}(V_{I}, V_{J}),$$

where

• if $I \subset J$ then

$$\operatorname{Mor}_{\mathbf{V}_{\kappa}}(V_{I}, V_{J}) = \bigcup_{\emptyset \neq K \subset I} (\widetilde{V}_{KJ} \cap \widetilde{V}_{IJ}) \times \Gamma_{I \setminus K} \subset \operatorname{Mor}_{\mathbf{G}_{\kappa}}(V_{I}, V_{J})$$

- if $I \supset J$ then $\operatorname{Mor}_{\mathbf{V}_{\kappa}}(V_I, V_J) = \{\mu^{-1} : \mu \in \operatorname{Mor}_{\mathbf{V}_{\kappa}}(V_J, V_I)\}.$
- $\operatorname{Mor}_{\mathbf{V}_{\kappa}}(V_I, V_J) = \emptyset$ otherwise.

Note that $\mathbf{V}_{\mathcal{K}}$ is not a full subcategory of $\mathbf{G}_{\mathcal{K}}$: for example, we do not include all the morphisms $V_J \times \Gamma_J$ from V_J to V_J but (besides the identities) just those with source (and hence target) in one of the sets $\widetilde{V}_{IJ}, I \neq J$, and over these points we include only the action of the subgroup $\Gamma_{J \smallsetminus I}$, which by definition of an atlas, is free. This is the key reason why $\mathbf{V}_{\mathcal{K}}$ is nonsingular. Another way of understanding $\mathbf{V}_{\mathcal{K}}$ is to see that its morphisms are generated by the projections $\rho_{IJ}: \widetilde{V}_{IJ} \to V_I$. When $I \subseteq J$, each $x \in \rho_{IJ}(\widetilde{V}_{IJ})$ has preimage $\rho_{IJ}^{-1}(x)$ consisting of the free orbit $\Gamma_{J \smallsetminus I}(\widetilde{x})$ for $\widetilde{x} \in \rho_{IJ}^{-1}(x) \subset \widetilde{V}_{IJ}$, and we recover the action $(J, \gamma^{-1}\widetilde{x}) \mapsto (J, \widetilde{x})$ of $\Gamma_{J \smallsetminus I}$ on \widetilde{V}_{IJ} as the set of composites

$$(J, J, \widetilde{x}, \gamma) = (I, J, \gamma^{-1} \widetilde{x}, \mathrm{id})^{-1} \circ (I, J, \widetilde{x}, \mathrm{id}),$$

$$(J, \gamma^{-1} \widetilde{x}) \mapsto (I, \rho_{IJ}(\gamma^{-1} \widetilde{x})) = (I, \rho_{IJ}(\widetilde{x})) \mapsto (J, \widetilde{x}).$$

where we use the notation in (1.1), and in particular categorical order for composites.

Here is the main result about the groupoid $V_{\mathcal{K}}$ from [MW3, Thm. 3.2.8].

Proposition 4.5. For each orbifold atlas K on Y, the following statements hold.

- i) The groupoid V_K is well defined, in particular its set of morphisms is closed under composition and taking the inverse.
- ii) Its maximal Hausdorff quotient $|\mathbf{V}_{\mathcal{K}}|_{\mathcal{H}}$ is the realization of the étale groupoid $\mathbf{V}_{\mathcal{K}}^{\mathcal{H}}$ obtained from $\mathbf{V}_{\mathcal{K}}$ by closing its space of morphisms in $\mathrm{Mor}_{\mathbf{G}_{\mathcal{V}}}$, where $\mathbf{G}_{\mathcal{V}}$ is the full subcategory of $\mathbf{G}_{\mathcal{K}}$ with objects $\mathcal{V} := \bigsqcup_{I} V_{I}$.

iii) $\mathbf{V}_{\mathcal{K}}$ may be given the structure of a wnb groupoid with weighting function given at $y \in \pi^{\mathcal{H}}_{\mathbf{V}_{r}}(V_{J})$ by

$$\Lambda_V(y) = \frac{n(y)}{|\Gamma_J|}, \qquad n(y) = \#\{x \in V_J \mid \pi_{\mathbf{V}_K}^{\mathcal{H}}(x) = y\}.$$

Further, for $y \in \pi_{\mathbf{V}_{\kappa}}^{\mathcal{H}}(V_J)$ the inverse image $V_J \cap (\pi_{\mathbf{V}_{\kappa}}^{\mathcal{H}})^{-1}(y)$ is a free $\Gamma_{J \setminus I_y}$ -orbit, where $I_y := \min\{I \subset J \mid y \in \overline{\pi_{\mathbf{V}_{\kappa}}^{\mathcal{H}}(V_I)}\}.$

iv) The inclusion $\mathbf{V}_{\mathcal{K}} \to \mathbf{G}_{\mathcal{K}}|_{\mathcal{V}}$ extends to an inclusion $\iota_{\mathbf{V}_{\mathcal{K}}^{\mathcal{H}}} : \mathbf{V}_{\mathcal{K}}^{\mathcal{H}} \to \mathbf{G}_{\mathcal{K}}|_{\mathcal{V}}$.

Moreover the pushforward of Λ_{V} by $|\psi| \circ |\iota_{\mathbf{V}_{\mathcal{K}}^{\mathcal{H}}}| : |\mathbf{V}_{\mathcal{K}}|_{\mathcal{H}} = |\mathbf{V}_{\mathcal{K}}^{\mathcal{H}}| \to Y$ is Λ_{Y} .

Proof. We sketch the proof very briefly; [M2, §3.4] gives more detail, while the full proof is in [MW3, §3.2]. The first claim is not hard to prove from the remarks after the definition of $\mathbf{V}_{\mathcal{K}}$. To prove (ii) it suffices to check that the closure of $\mathrm{Mor}_{\mathbf{V}_{\mathcal{K}}}$ in $\mathrm{Mor}_{\mathbf{G}_{\mathcal{K}}}$ defines a set of morphisms that is closed under composition. This holds for much the same reason as (i) because, as is easily seen, one can close $\mathrm{Mor}_{\mathbf{V}_{\mathcal{K}}}$ by adding in morphisms of the following type from V_I to V_J :

$$\bigcup_{F \subsetneq I} (\widetilde{V}_{IJ} \cap \operatorname{Fr}_{V_J}(\widetilde{V}_{FJ})) \times \Gamma_{I \setminus F} \subset V_J \times \Gamma_I,$$

where $\operatorname{Fr}_V(A) := \operatorname{cl}_V(A) \setminus A$ and $\operatorname{cl}_V(A)$ is given by the closure of A in V. Informally one can think of the sets V_J as the branches of $\mathbf{V}_{\mathcal{K}}$ each weighted by $\frac{1}{|\Gamma_J|}$. However, they do not inject into $|\mathbf{V}_{\mathcal{K}}|$ (and hence into $|\mathbf{V}_{\mathcal{K}}|_{\mathcal{H}}$) — rather they are wrapped around themselves by partial actions of the groups $\Gamma_{J \setminus I}$. One can check that the branch locus is the image in $|\mathbf{V}_{\mathcal{K}}|_{\mathcal{H}}$ of the sets $\operatorname{Fr}_{V_J}(\widetilde{V}_{IJ})$ for $I \subsetneq J$. The statements in (iii) then follow easily. Note that although the functor $\iota_{\mathbf{V}_{\mathcal{K}}^{\mathcal{H}}} : \mathbf{V}_{\mathcal{K}}^{\mathcal{H}} \to \mathbf{G}_{\mathcal{K}}|_{\mathcal{V}}$ is injective, its image is not usually a full subcategory, so that the induced map on realizations is not injective in general.

Example 4.6. (i) Consider the "football" discussed in Example 1.7, with reduction \mathcal{V} given by two discs $V_1 \sqsubset W_1, V_2 \sqsubset W_2$ with disjoint images Q_i in X, together with an open annulus $V_{12} \sqsubset W_{12}$. For j=1,2 the sets $\widetilde{V}_{j(12)} \subset V_{12}$ are disjoint open annuli that project into V_j by a covering map of degree 3 for j=1 (that quotients out by $\Gamma_{(12)\backslash 1}=\Gamma_2=\mathbb{Z}_3$) and degree 2 for j=2. Then $\mathrm{Obj}_{\mathbf{V}_{\mathcal{K}}}=V_1\sqcup V_2\sqcup V_{12}$. For j=1,2 the category $\mathbf{V}_{\mathcal{K}}$ has the following morphisms (besides identities);

- morphisms $V_j \to V_{12}$ given by the projection $\rho_{j,12} : \widetilde{V}_{j(12)} \to V_j$, together with their inverses;
- morphisms $V_{12} \to V_{12}$ given by the action of $\mathbb{Z}_3 = \Gamma_{(12) \setminus 1}$ on $\widetilde{V}_{1(12)}$, resp. of $\mathbb{Z}_2 = \Gamma_{(12) \setminus 2}$ on $\widetilde{V}_{2(12)}$.

To obtain $\mathbf{V}_{\mathcal{K}}^{\mathcal{H}}$ we add the morphisms given by the action of $\Gamma_{(12) \smallsetminus 1}$ on the boundary $\operatorname{Fr}_{V_{12}}(\widetilde{V}_{1(12)}) \subset V_{12} \smallsetminus \widetilde{V}_{1(12)}$ and the action of $\Gamma_{(12) \smallsetminus 2}$ on $\operatorname{Fr}_{V_{12}}(\widetilde{V}_{2(12)}) \subset V_{12} \smallsetminus \widetilde{V}_{2(12)}$. The weighting function Λ is given by:

$$\Lambda(p) = \frac{1}{2} \text{ if } p \in \overline{Q_1} = \pi_{\mathbf{V}}^{\mathcal{H}}(V_1) \cup \pi_{\mathbf{V}}^{\mathcal{H}}(\overline{\widetilde{V}_{1(12)}})
= \frac{1}{3} \text{ if } p \in \overline{Q_2} = \pi_{\mathbf{V}}^{\mathcal{H}}(V_2) \cup \pi_{\mathbf{V}}^{\mathcal{H}}(\overline{\widetilde{V}_{2(12)}})
= \frac{1}{6} \text{ if } p \in Q_{12} \setminus (\overline{Q_1} \cup \overline{Q_2}) = \pi_{\mathbf{V}}^{\mathcal{H}}(V_{12} \setminus \overline{\widetilde{V}_{1(12)} \cup \widetilde{V}_{2(12)}})$$

Notice that for j=1,2 the weighting function does not change along the boundary of the intersection $Q_1 \cap \partial \overline{Q_{12}}$, i.e. there is no branching there, while it does change along the internal boundaries $Q_{12} \cap \partial \overline{Q_i}$ in the middle annulus Q_{12} . Also, the pushforward of Λ_V by the map $|\iota_{\mathbf{V}_{\mathcal{H}}}| : |\mathbf{V}_{\mathcal{H}}| \to |\mathbf{B}_{\mathcal{K}}|_{\mathcal{V}}|$ takes the value 1 except at the poles N, S:

$$|\iota_{\mathbf{V}_{\mathcal{H}}}|_*(\Lambda_V)(q) := \sum_{p \in |\iota_{\mathbf{Z}_{\mathcal{H}}}|^{-1}(q)} \Lambda_{\mathbf{V}}(p) = 1, \quad \forall q \in Y \setminus \{N, S\}.$$

(ii) In Example 3.6 we considered the two different orbifold structures on S^2 with noneffective group \mathbb{Z}_2 , constructing at lases with two basic charts whose footprints intersect in an annulus F_{12} . They may be distinguished by the domain W_{12} , which is either connected (the nontrivial case) or disconnected. Let us choose the footprint reduction so that Q_{12} is a connected annulus. Then because we define V_{12} to be the full inverse image of Q_{12} under the footprint map, it is disconnected exactly if W_{12} is. Therefore the two resulting weighted branched manifolds (Z, Λ_Z) , which have two-fold branching along $Q_{12} \cap \partial \overline{Q_i}$ as in (i), may be distinguished by the set of points in the realization $Z = |\mathbf{V}_{\mathcal{K}}|_{\mathcal{H}}$ with weight $\frac{1}{4}$: this set is either connected (the nontrivial case) or disconnected.

Observe that each of these weighted branched manifolds is weighted branched cobordant to S^2 with the constant weight function $\frac{1}{2}$. In other words, the difference between these two orbifold structures is *not* preserved when we consider cobordism classes of resolutions. To see this, notice that in each case we may add morphisms to the groupoid $\mathbf{V}_{\mathcal{K}}$ so that it still remains nonsingular but has realization S^2 instead of a branched manifold: to do this

we simply add one morphism between any two points $(I, x), (J, y) \in \operatorname{Obj}_{\mathbf{V}_{\kappa}}$ that have the same image under the composite map $\operatorname{Obj}_{\mathbf{V}_{\kappa}} \to \operatorname{Obj}_{\mathbf{G}_{\kappa}} \to |\mathbf{G}_{\kappa}| = S^2$ but different images in $|\mathbf{V}_{\kappa}|$. (Because \mathbf{V}_{κ} is nonsingular there is no ambiguity about how to define composites.) One can check that this new groupoid \mathbf{V}'_{κ} is weighted cobordant to \mathbf{V}_{κ} by a cobordism groupoid \mathbf{C} obtained by adding the morphisms $[0, \frac{1}{2}) \times (\operatorname{Mor}_{\mathbf{V}'_{\kappa}} \setminus \operatorname{Mor}_{\mathbf{V}_{\kappa}})$ to the product groupoid $[0, 1] \times \mathbf{V}_{\kappa}$ (which has objects $[0, 1] \times \operatorname{Obj}_{\mathbf{V}_{\kappa}}$ and morphisms $[0, 1] \times \operatorname{Mor}_{\mathbf{V}_{\kappa}}$). The Hausdorff realization of this cobordism is the union of $S^2 \times [0, \frac{1}{2}]$ with weighting function $\frac{1}{2}$, together with $(\frac{1}{2}, 1] \times Z$ with weighting function $\lambda_Z \circ pr_Z$, where as above $Z := |\mathbf{V}_{\kappa}|_{\mathcal{H}}$.

Remark 4.7. Because any two choices of cover reductions are cobordant (see [MW1, Lemma 5.3.4]), one can easily show that if two orbifold atlases $\mathcal{K}_0, \mathcal{K}_1$ on Y are commensurate then any two resolutions $\mathcal{V}_{\mathcal{K}_0}, \mathcal{V}_{\mathcal{K}_1}$ that are constructed as above are themselves weighted branched cobordant. As Example 4.6 (ii) shows, inequivalent atlases may have cobordant resolutions. On the other hand, the Pontryagin numbers are invariants of weighted branched cobordism. To see this, note that each wnb groupoid (\mathbf{G}, Λ_G) has a tangent bundle TG that is an étale groupoid which (after appropriate taming) also has a natural structure as a wnb groupoid. Hence one can use Chern-Weil theory to construct top-dimensional differential forms that represent products of Pontryagin classes, and then integrate them over the fundamental class of (\mathbf{G}, Λ_G) to obtain the Pontryagin numbers. More generally, one could consider the bordism groups of maps from a weighted branched manifold into a space Y. See [CMS, Example 9.23] for a related discussion. (The notion of weighted branched manifold in [CMS] is closely related to ours, but not precisely the same.)

Computing the Euler class. By definition, an oriented orbibundle pr: $E \to X$ with fiber E_0 over a smooth oriented compact orbifold X is the realization of a smooth functor pr: $\mathbf{E} \to \mathbf{X}$ between oriented ep groupoids such that the induced map $\pi_0 : \mathrm{Obj}_{\mathbf{E}} \to \mathrm{Obj}_{\mathbf{X}}$ on objects is a locally trivial vector bundle with fiber E_0 . In this situation, the orbifolds $E = |\mathbf{E}|, X = |\mathbf{X}|$ have compatible local uniformizers. In other words, we may choose a covering of X by local charts $((W_i, \Gamma_i, \psi_i^X))_{i=1,\dots,N}$ with footprints $F_i \subset X$ so that

¹⁰ The issue here is that the Hausdorff completion $|\mathbf{T}\mathbf{G}|_{\mathcal{H}}$ should also form a bundle over $|\mathbf{G}|_{\mathcal{H}}$, which is the case when the branch locus is sufficiently well behaved. Such questions are discussed at length in [M1, §3], where it is shown that "tame" wnb groupoids support partitions of unity, and, if compact, support a well defined notion of the integral of a top dimensional differential form.

the action of Γ_i lifts to the pullback $(\psi_i^X)^*(E|_{F_i})$ and $((\psi_i^X)^*(E|_{F_i}), \Gamma_i, \psi_i^E)$ (where ψ_i^E lifts ψ_i^X) is a local uniformizer for E. By Proposition 3.3 we may extend this family of basic charts to an orbifold atlas \mathcal{K}_X on X with charts $((W_I, \Gamma_I, \psi_I^X))_{I \in \mathcal{I}_X}$ and footprint cover $(F_i)_i$. The orbifold E has a corresponding atlas \mathcal{K}_E with charts $((E|_{W_I}, \Gamma_I, \psi_I^E))_{I \in \mathcal{I}_X}$ and footprint cover $(E|_{F_i})_i \subset E$, where for simplicity we denote the pullback $(\psi_I^X)^*(E|_{F_I})$ of E to W_I simply by $E|_{W_I}$.

By Proposition 2.3 the categories

$$\mathbf{B}_X := \mathbf{B}_{\mathcal{K}_X}, \quad \mathbf{B}_E := \mathbf{B}_{\mathcal{K}_E},$$

corresponding to these orbifold atlases have completions to ep groupoids $\mathbf{G}_E, \mathbf{G}_X$. It follows from the construction that the projection pr induces a functor $\mathrm{pr}: \mathbf{G}_E \to \mathbf{G}_X$ that restricts on the object spaces to the bundle projection $\bigsqcup_I E|_{W_I} \to \bigsqcup_I W_I$.

By [M1, Proposition 4.19],¹¹ one way to define the Euler class of π : $E \to X$ is to consider a "nonsingular resolution" of the groupoid \mathbf{G}_X , pull the bundle $E \to X$ back to this resolution and then push forward to X the (weighted) zero set of a section ν of this bundle that is transverse to 0 (written $\nu \pitchfork 0$). As we explained above, we can take the resolution of \mathbf{G}_X to be the wnb groupoid \mathbf{V}_X formed as in Proposition 4.5 from a reduction of \mathbf{G}_X . The pullback of $\mathrm{pr}: \mathbf{G}_E \to \mathbf{G}_X$ by $\iota_{\mathcal{V}}: \mathbf{V}_X \to \mathbf{G}_X$ is the corresponding wnb groupoid with objects $\bigsqcup_I E|_{V_I}$. Let $\nu: \mathbf{V}_X \to \mathbf{E}_X$ be a section of this bundle. This is given by a compatible family of sections

$$(4.2) \nu_I: V_I \to E|_{V_I}, \quad \nu_J|_{\widetilde{V}_{I,I}} = \nu_I \circ \rho_{IJ}^X.$$

If $\nu \pitchfork 0$, there is a full subcategory \mathbf{Z}_X^{ν} of \mathbf{V}_X whose objects $\nu_I^{-1}(0) \subset V_I$ form a closed d-dimensional submanifold $\mathrm{Obj}_{\mathbf{Z}_X^{\nu}}$ of $\mathrm{Obj}_{\mathbf{V}_X}$ of codimension equal to the fiber dimension of E. It is not hard to check that this has the structure of a wnb groupoid \mathbf{Z}_X^{ν} with the induced weighting function Λ_Z equal to the restriction of Λ_V to the image of the inclusion $|\mathbf{Z}_X^{\nu}|_{\mathcal{H}} \to |\mathbf{V}_X|_{\mathcal{H}}$.

The following is a version of results proved in [M1, §3]; see also [M2, §5.2].

¹¹ This result concerns the effective case, but applies equally well to the noneffective case because each groupoid has an effective quotient; see [ALR, Def 2.33]. However, in [M1] we took the fundamental class of **G** to be that of its effective quotient, while here we use the more correct version that also takes into account the order of the group that acts noneffectively.

Lemma 4.8. Let $E \to X$ be an oriented orbibundle and $d := \dim X - \dim E$. Then the cobordism class of the wnb groupoid $(\mathbf{Z}_X^{\nu}, \Lambda_Z)$ constructed above is independent of choices, as is the image in $H_d(X; \mathbb{Q})$ of the pushforward of its fundamental class.

Example 4.9. Consider the football X considered in Example 1.7 with reduction as in Example 4.6. Its tangent bundle TX has a corresponding atlas with charts $(TW_I, \Gamma_I, \psi_I^{TX})$ and reduction TV with domains TV_I . Trivialize the bundle $TV_{12} \to V_{12}$ by choosing a nonvanishing Γ_{12} -invariant section ν_2 . This descends to a nonvanishing section of $TV_i|_{V_{i(12)}}$ (where $V_{i(12)} := \rho_{i(12)}(\tilde{V}_{i(12)})$). Since each V_i is a disc, for each i, this section extends to a section $\nu_i : V_i \to TV_i$ with precisely one zero, which has weight $\frac{1}{|\Gamma_i|}$ Hence the Euler class is represented by the zero dimensional branched manifold that is represented by two points, one with weight $\frac{1}{2}$ and one with weight $\frac{1}{3}$.

Remark 4.10. This abstract method should also apply to the infinite dimensional orbibundles of polyfold theory [HWZ]. Here one has an orbibundle whose base and total space are sc-Banach manifolds. Since the moduli space X of J-holomorphic stable maps is compact, one can define at lases $\mathbf{B}_{\mathcal{K}_X}, \mathbf{B}_{\mathcal{K}_E}$ as above that are finite (i.e. have finitely many basic charts) and such that $|\mathbf{B}_{\mathcal{K}_X}|$ is a neighbourhood of X. In particular, the projection is the realization of a functor $\pi: \mathbf{B}_{\mathcal{K}_E} \to \mathbf{B}_{\mathcal{K}_X}$ that restricts on each chart to a bundle $\pi: E_I \to U_I$ with infinite dimensional base and fibers on which the finite group $\Gamma_I := \prod_{i \in I} \Gamma_i$ acts. We are also given a canonical smooth section $\mathfrak{s} := (s_I)$ where each $s_I : U_I \to E_I$ is a Γ_I -equivariant Fredholm operator such that the realization $|\mathfrak{s}^{-1}(0)|$ of the zero set is canonically identified with X. We can choose a subgroupoid $V_{\mathcal{K}_X}$ of $G_{\mathcal{K}_X}$ as in (4.1). Then polyfold Fredholm theory implies that there are single valued sections ν of the pullback bundle such that $\mathfrak{s}|_{\mathbf{V}} + \nu \pitchfork 0$. The resulting zero set \mathbf{Z}^{ν} has domains that are d-dimensional manifolds, where d is the Fredholm index of \mathfrak{s} , and just as above is a nonsingular étale groupoid whose realization has a natural weighting function. The proof sketched above (and given in detail in [MW3]) that \mathbf{Z}^{ν} is a weighted branched manifold relies on the existence of a similar structure of the ambient groupoid $V_{\mathcal{K}_x}$. In the polyfold setup, $V_{\mathcal{K}_x}$ is infinite dimensional. Hence, in order to complete the proof that the zero set is a weighted branched manifold of dimension d one would have to carefully check the properties of the local branching structure of the zero set. However, since this is entirely controlled by the behavior of the group actions, this should pose no problem, hence giving a simple model for the virtual cycles constructed in polyfold theory. We hope to return to this question in the future.

Acknowledgements. I would like to thank Dominic Joyce, Eugene Lerman and John Pardon for useful discussions about orbifolds. This paper also builds on the insights of Katrin Wehrheim and the work in our joint project on Kuranishi atlases. I also thank the referees for their careful reading and helpful suggestions.

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RECEIVED JUNE 17, 2015