Open Gromov-Witten invariants in dimension four

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Given a closed orientable Lagrangian surface L in a closed symplectic four-manifold (X, ω) together with a relative homology class $d \in H_2(X, L; \mathbb{Z})$ with vanishing boundary in $H_1(L; \mathbb{Z})$, we prove that the algebraic number of J-holomorphic discs with boundary on L, homologous to d and passing through the adequate number of points neither depends on the choice of the points nor on the generic choice of the almost-complex structure J. We furthermore get analogous open Gromov-Witten invariants by counting, for every non-negative integer k, unions of k discs instead of single discs.

1. Introduction

Let (X, ω) be a closed connected symplectic four-manifold. Let $L \subset X$ be a closed Lagrangian surface which we mainly assume to be orientable. We denote by $\mu_L \in H^2(X, L; \mathbb{Z})$ its Maslov class, that is the obstruction to extend TL as a Lagrangian subbundle of TX. We denote by $\mathcal{J}_\omega$ the space of almost-complex structures of class C^l tamed by ω, where $l \gg 1$ is a fixed integer. Let $d \in H_2(X, L; \mathbb{Z})$ be such that $\mu_L(d) > 0$ and $r, s \in \mathbb{N}$ such that $r + 2s = \mu_L(d) - 1$. Let $\underline{x} \subset L^r$ (resp. $\underline{y} \subset (X \setminus L)^s$) be a collection of r (resp. s) distinct points. Then, for every generic choice of $J \in \mathcal{J}_\omega$, X contains only finitely many J-holomorphic discs with boundary on L, homologous to d and which pass through $\underline{x} \cup \underline{y}$. These discs are all immersed and we denote by $\mathcal{M}_d(\underline{x}, \underline{y}, J)$ their finite set. For every $D \in \mathcal{M}_d(\underline{x}, \underline{y}; J)$, we denote by $m(D) = [\overset{\circ}{D}] \circ [L] \in \mathbb{Z}/2\mathbb{Z}$ the intersection index between the interior of D and the surface L. We then set

$$GW_d^r(X, L; \underline{x}, \underline{y}, J) = \sum_{D \in \mathcal{M}_d(\underline{x}, \underline{y}; J)} (-1)^{m(D)} \in \mathbb{Z}.$$

Our main result is the following (see Theorem 3.1).

Theorem 1.1. *Assume that L is orientable and that $\partial d = 0 \in H_1(L; \mathbb{Z})$. Then, the integer $GW_d^r(X, L; \underline{x}, \underline{y}, J)$ neither depends on the choice of $\underline{x}, \underline{y}$ nor on the generic choice of J.*

This result thus provides an integer valued invariant which we can denote without ambiguity by $GW_d^r(X, L)$, providing a relative analog to the genus zero Gromov-Witten invariants in dimension four. Note that some open Gromov-Witten invariants have already been defined by C.C. Liu and M. Katz in the presence of an action of the circle, see [13], [19], and by myself when L is fixed by an antisymplectic involution, see [26], [28], [32] or also [5], [24]. When X is six-dimensional, some open Gromov-Witten invariants have been defined by K. Fukaya [8] and V. Iacovino [15] in the case of Calabi-Yau six-manifolds and by myself [33] in the absence of Maslov zero discs.

When L is a Lagrangian sphere fixed by such an antisymplectic involution, the invariant χ_r^d introduced in [30], [28] is computed in terms of $GW_d^r(X, L)$, see Lemma 3.4. We deduce as a consequence that 2^{s-1} divides χ_r^d, improving a congruence already obtained in [31] using symplectic field theory. When the genus of L is greater than one, the invariant $GW_d^r(X, L)$ vanishes, see Proposition 3.3, since one can find a generic almost complex structure J for which the set $\mathcal{M}_d(\underline{x}, \underline{y}; J)$ is empty. I could not get any result when L is not orientable, except a result modulo two when L is homeomorphic to a real projective plane, see Theorem 3.6.

We also obtain an analog of Theorem 1.1 by counting unions of k discs, $k > 0$, instead of single discs. More precisely, let $k > 0$ be such that $\mu_L(d) \geq k$ and assume now that $r + 2s = \mu_L(d) - k$. For every generic choice of $J \in \mathcal{J}_\omega$, X only contains finitely many unions of k J-holomorphic discs with boundary on L, total homology class d and which pass through $\underline{x} \cup \underline{y}$. These discs are all immersed and we denote by $\mathcal{M}_{d,k}(\underline{x}, \underline{y}, J)$ their finite set. For every $D = D_1 \cup \cdots \cup D_k \in \mathcal{M}_{d,k}(\underline{x}, \underline{y}; J)$, we denote by $m(D) = \sum_{i=1}^k m(D_i) \in \mathbb{Z}/2\mathbb{Z}$ and set

$$GW_{d,k}^r(X, L; \underline{x}, \underline{y}, J) = \sum_{D \in \mathcal{M}_{d,k}(\underline{x}, \underline{y}; J)} (-1)^{m(D)} \in \mathbb{Z}.$$

We then get (see Theorem 3.16).

Theorem 1.2. *Assume that L is orientable and that $\partial d = 0 \in H_1(L; \mathbb{Z})$. Then, the integer $GW_{d,k}^r(X, L; \underline{x}, \underline{y}, J)$ neither depends on the choice of $\underline{x}, \underline{y}$ nor on the generic choice of J.*

Note that the individual discs involved in the definition of this k-discs open Gromov-Witten invariant $GW_{d,k}^r(X, L) \in \mathbb{Z}$ are no more subject to have trivial boundary in homology.

The first part of this paper is devoted to notations and generalities on moduli spaces of pseudo-holomorphic discs in any dimensions. We introduce the numbers $GW_d^r(X, L)$, $GW_{d,k}^r(X, L)$ and prove their invariance in the second paragraph.

2. Pseudo-holomorphic discs with boundary on a Lagrangian submanifold

2.1. Moduli spaces of simple discs

Let $\Delta = \{z \in \mathbb{C} \mid |z| \leq 1\}$ be the closed complex unit disc. We denote by $\mathcal{P}(X, L) = \{(u, J) \in C^1(\Delta, X) \times \mathcal{J}_\omega \mid u(\partial\Delta) \subset L$ and $du + J|_u \circ du \circ j_{st} = 0\}$ the space of pseudo-holomorphic maps from Δ to the pair (X, L), where j_{st} denotes the standard complex structure of Δ. Note that J being of class C^l, the regularity of such pseudo-holomorphic maps u is actually more than C^l, see [20]. More generally, for every $r, s \in \mathbb{N}$, we denote by $\mathcal{P}_{r,s}(X, L) = \{((u, J), \underline{z}, \underline{\zeta}) \in \mathcal{P}(X, L) \times ((\partial\Delta)^r \setminus \mathrm{diag}_{\partial\Delta}) \times ((\overset{\circ}{\Delta})^s \setminus \mathrm{diag}_\Delta)\}$, where $\mathrm{diag}_{\partial\Delta} = \{(z_1, \ldots, z_r) \in (\partial\Delta)^r \mid \exists i \neq j, z_i = z_j\}$ and $\mathrm{diag}_\Delta = \{(\zeta_1, \ldots, \zeta_s) \in \Delta^s \mid \exists i \neq j, \zeta_i = \zeta_j\}$.

Following [17], [14], [3], we define

Definition 2.1. A pseudo-holomorphic map u is said to be simple iff there is a dense open subset $\Delta_{inj} \subset \Delta$ such that $\forall z \in \Delta_{inj}, u^{-1}(u(z)) = \{z\}$ and $du|_z \neq 0$.

Recall for instance that the map $z \in \mathbb{C} \mapsto z^3 \in \mathbb{C}$ restricted to the upper half plane $\mathbb{H} \subset \mathbb{C}$ induces, after composition by a biholomorphism $\Delta \to \overline{\mathbb{H}} \subset \mathbb{C}P^1$, a holomorphic map $u : \Delta \to (\mathbb{C}P^1, \mathbb{R}P^1)$ which is not simple in the sense of Definition 2.1, though it is somewhere injective, compare [20].

We denote by $\mathcal{P}_{r,s}^*(X, L)$ the subset of simple elements of $\mathcal{P}_{r,s}(X, L)$. It is a separable Banach manifold which is naturally embedded as a submanifold of class C^{l-k} of the space $W^{k,p}(\Delta, X) \times \mathcal{J}_\omega$ for every $1 \ll k \ll l$ and $p > 2$, see Proposition 3.2 of [20].

For every $d \in H_2(X, L; \mathbb{Z})$, we denote by $\mathcal{P}_{r,s}^d(X, L) = \{(u, J) \in \mathcal{P}_{r,s}^*(X, L) \mid u_*[\Delta] = d\}$ and by $\mathcal{M}_{r,s}^d(X, L) = \mathcal{P}_{r,s}^d(X, L)/\mathrm{Aut}(\Delta)$, where $\mathrm{Aut}(\Delta)$ is the group of biholomorphisms of Δ which acts by composition on the right. The

latter is equipped with a projection $\pi : [u, J, \underline{z}, \underline{\zeta}] \in \mathcal{M}_{r,s}^d(X, L) \mapsto J \in \mathcal{J}_\omega$ and an evaluation map eval $: [u, J, \underline{z}, \underline{\zeta}] \in \mathcal{M}_{r,s}^d(X, L) \mapsto (u(\underline{z}), u(\underline{\zeta})) \in L^r \times X^s$.

   We recall the following classical result due to Gromov (see [10], [20], [9]).

Theorem 2.2. *For every closed Lagrangian submanifold L of a $2n$-dimensional closed symplectic manifold (X, ω) and for every $d \in H_2(X, L; \mathbb{Z})$, $r, s \in \mathbb{N}$, the space $\mathcal{M}_{r,s}^d(X, L)$ is a separable Banach manifold and the projection $\pi : \mathcal{M}_{r,s}^d(X, L) \to \mathcal{J}_\omega$ is Fredholm of index $\mu_L(d) + n - 3 + r + 2s$.*

   Note that from Sard-Smale's theorem [23], the set of regular values of π is dense of the second category. As a consequence, for a generic choice of $J \in \mathcal{J}_\omega$, the moduli space $\mathcal{M}_{0,0}^d(X, L; J) = \pi^{-1}(J)$ is a manifold of dimension $\mu_L(d) + n - 3$ as soon as it is not empty. Likewise, if $\underline{x}$ (resp. $\underline{y}$) is a set of r (resp. s) distinct points of L (resp. $X \setminus L$), then $\mathcal{M}_{r,s}^d(X, L; \underline{x}, \underline{y}, J) = (\pi \times \text{eval})^{-1}(J, \underline{x}, \underline{y})$ is a manifold of dimension $\mu_L(d) + n - 3 - (n-1)(r + 2s)$. We denote by $\mathcal{M}_{r,s}^d(X, L; \underline{x}, \underline{y})$ the preimage $\text{eval}^{-1}(\underline{x}, \underline{y})$ and with a slight abuse by $\pi : [u, J, \underline{z}, \underline{\zeta}] \in \mathcal{M}_{r,s}^d(X, L; \underline{x}, \underline{y}) \mapsto J \in \mathcal{J}_\omega$ the Fredholm projection of index $\mu_L(d) + n - 3 - (n-1)(r + 2s)$.

   Recall also that the tangent bundle to the space $\mathcal{P}_{r,s}^*(X, L)$ writes, for every $(u, J) \in \mathcal{P}_{r,s}^*(X, L)$,

$$T_{(u,J)}\mathcal{P}_{r,s}^*(X, L) = \{(v, \dot{J}) \in \Gamma^1(\Delta, u^*TX) \times T_J\mathcal{J}_\omega \mid$$
$$Dv + \dot{J} \circ du \circ j_{st} = 0 \text{ and } v|_{\partial\Delta} \subset u^*TL\},$$

where D is the Gromov operator defined for every $v \in \Gamma^1(\Delta, u^*TX)$ by the formula $Dv = \nabla v + J \circ \nabla v \circ j_{st} + \nabla_v J \circ du \circ j_{st} \in \Gamma^0(D, \Lambda^{0,1}D \otimes u^*TX)$ for any torsion free connection ∇ on TX. This operator induces an operator $\overline{D}$ on the normal sheaf $\mathcal{N}_u = u^*TX/du(T\Delta)$, see formula 1.5.1 of [12], and we denote by $H_D^0(\Delta, \mathcal{N}_u) \subset \Gamma^1(\Delta, u^*TX, u^*TL)/du(\Gamma^1(\Delta, T\Delta, T\partial\Delta))$ the kernel of this operator $\overline{D}$, see [12] or §1.4 of [28]. Likewise, we denote by $H_D^0(\Delta, \mathcal{N}_{u,-\underline{z},-\underline{\zeta}})$ the kernel of $\overline{D}$ restricted to elements which vanish at the points $\underline{z}$ and $\underline{\zeta}$.

Proposition 2.3. *Under the hypothesis of Theorem 2.2, let $\underline{x}$ (resp. $\underline{y}$) be a set of r (resp. s) distinct points of L (resp. $X \setminus L$) and let J be a generic element of $\mathcal{J}_\omega$. Then, at every point $[u, J, \underline{z}, \underline{\zeta}]$ of $\mathcal{M}_{r,s}^d(X, L; J, \underline{x}, \underline{y})$ the tangent space $T_{[u,J,\underline{z},\underline{\zeta}]}\mathcal{M}_{r,s}^d(X, L; \underline{x}, \underline{y})$ is isomorphic to $H_D^0(\Delta, \mathcal{N}_{u,-\underline{z},-\underline{\zeta}})$.*

   This classical result is proved in [20] or [12] for example (compare §1.8 of [28]).

Recall finally that the moduli space $\mathcal{M}_{r,s}^d(X, L; J, \underline{x}, \underline{y})$ given by Proposition 2.3 is not in general compact for two reasons. Firstly, a sequence of elements of $\mathcal{M}_{r,s}^d(X, L; J, \underline{x}, \underline{y})$ may converge to a pseudo-holomorphic disc which is not simple in the sense of Definition 2.1, see §2.2. Secondly, a sequence of elements of $\mathcal{M}_{r,s}^d(X, L; J, \underline{x}, \underline{y})$ may converge to a pseudo-holomorphic curve which no more admits a parameterization by a single disc Δ, in the same way as a sequence of smooth plane conics may converge to a pair of distinct lines. However, the latter phenomenon is well understood by the following Gromov compactness' theorem.

Theorem 2.4. *Under the hypothesis of Proposition 2.3, every sequence of elements of $\mathcal{M}_{r,s}^d(X, L; J, \underline{x}, \underline{y})$ has a subsequence which converges in the sense of Gromov to a stable J-holomorphic disc.*

A proof of Theorem 2.4 as well as the definitions of stable discs and convergence in the sense of Gromov can be found in [7].

2.2. Theorem of decomposition into simple discs

We recall in this paragraph the theorem of decomposition into simple discs established by Kwon-Oh and Lazzarini, see [14], [17], [18].

Theorem 2.5. *Let L be a closed Lagrangian submanifold of a $2n$-dimensional closed symplectic manifold (X, ω). Let $u : (\Delta, \partial\Delta) \to (X, L)$ be a non-constant pseudo-holomorphic map. Then, there exists a graph $\mathcal{G}(u)$ embedded in Δ such that $\Delta \setminus \mathcal{G}(u)$ has only finitely many connected components. Moreover, for every connected component $\mathcal{D} \subset \Delta \setminus \mathcal{G}(u)$, there exists a surjective map $\pi_{\overline{\mathcal{D}}} : \overline{\mathcal{D}} \to \Delta$, holomorphic on $\mathcal{D}$ and continuous on $\overline{\mathcal{D}}$, as well as a simple pseudo-holomorphic map $u_{\mathcal{D}} : \Delta \to X$ such that $u|_{\overline{\mathcal{D}}} = u_{\mathcal{D}} \circ \pi_{\overline{\mathcal{D}}}$. The map $\pi_{\overline{\mathcal{D}}}$ has a well defined degree $m_{\mathcal{D}} \in \mathbb{N}$, so that $u_*[\Delta] = \sum_{\mathcal{D}} m_{\mathcal{D}}(u_{\mathcal{D}})_*[\Delta] \in H_2(X, L; \mathbb{Z})$, the sum being taken over all connected components $\mathcal{D}$ of $\Delta \setminus \mathcal{G}(u)$.*

The graph $\mathcal{G}(u)$ given by Thm. 2.5 is called the frame or non-injectivity graph, see [17], [18] (or §3.2 of [3]) for its definition.

2.3. Pseudo-holomorphic discs in dimension four

We assume in this paragraph that the ambient closed symplectic manifold (X, ω) is of dimension four and recall several facts specific to this dimension.

Proposition 2.6. *Let L be a closed Lagrangian surface of a closed connected symplectic four-manifold (X, ω). Let $d \in H_2(X, L; \mathbb{Z})$ be such that $\mu_L(d) > 0$ and $r, s \in \mathbb{N}$ such that $r + 2s = \mu_L(d) - 1$. Let $\underline{x}$ (resp. $\underline{y}$) be a set of r (resp. s) distinct points of L (resp. $X \setminus L$). Then, the critical points of the projection $\pi : [u, J, \underline{z}, \underline{\zeta}] \in \mathcal{M}^d_{r,s}(X, L; \underline{x}, \underline{y}) \mapsto J \in \mathcal{J}_\omega$ are those for which u is not an immersion.*

Proof. This Proposition 2.6 is analogous to Lemma 2.13 of [28] and follows from the automatic transversality in dimension four, see Theorem 2 of [11]. From Theorem 2.2, π is of vanishing index whereas from Proposition 2.3, its kernel is isomorphic to $H^0_D(\Delta, \mathcal{N}_{u,-\underline{z},-\underline{\zeta}})$. When u is not an immersion, the sheaf $\mathcal{N}_{u,-\underline{z},-\underline{\zeta}}$ contains a skyscraper part carried by its critical points and which contributes to the kernel $H^0_D(\Delta, \mathcal{N}_{u,-\underline{z},-\underline{\zeta}})$, so that $[u, J, \underline{z}, \underline{\zeta}]$ is indeed a critical point of π. When u is an immersion, this normal sheaf is the sheaf of sections of a bundle of Maslov index -1. From Theorem 2 of [11], $H^0_D(\Delta, \mathcal{N}_{u,-\underline{z},-\underline{\zeta}})$ is then reduced to $\{0\}$. □

Proposition 2.7. *Under the hypothesis of Proposition 2.6 :*

1) If $J \in \mathcal{J}_\omega$ is generic, then all elements of $\mathcal{M}^d_{r,s}(X, L; J, \underline{x}, \underline{y})$ are immersed discs.

2) If $t \in [0, 1] \mapsto J_t \in \mathcal{J}_\omega$ is a generic path, then every element of $\cup_{t \in [0,1]} \mathcal{M}^d_{r,s}(X, L; J_t, \underline{x}, \underline{y})$ which is not immersed has a unique ordinary cusp which is on $\partial \Delta$. The latter are non-degenerated critical points of π.

The ordinary cusps given by Proposition 2.7 are by definition modeled on the map $t \in \mathbb{R} \mapsto (t^2, t^3) \in \mathbb{R}^2$ at the neighborhood of the origin.

Proof. The first part follows from Proposition 2.6 and Sard-Smale's theorem [23]. The second part is proven exactly in the same way as the first part of Proposition 2.7 of [28] and the fact that these critical points are non-degenerated follows along the same lines as Lemma 2.13 of [28]. We do not reproduce these proofs here. □

3. Open Gromov-Witten invariants in dimension four

3.1. One-disc open Gromov-Witten invariants

Let (X, ω) be a closed connected symplectic four-manifold. Let $L \subset X$ be a closed Lagrangian surface, of Maslov class $\mu_L \in H^2(X, L; \mathbb{Z})$. Let $d \in H_2(X, L; \mathbb{Z})$ be such that $\mu_L(d) > 0$ and $r, s \in \mathbb{N}$ such that $r + 2s = \mu_L(d) - 1$. Let $\underline{x}$ (resp. $\underline{y}$) be a set of r (resp. s) distinct points of L (resp. $X \setminus L$). For

every $J \in \mathcal{J}_\omega$ generic, the moduli space $\mathcal{M}^d_{r,s}(X, L; J, \underline{x}, \underline{y})$ is then finite and consists only of immersed discs, see Proposition 2.7. We denote, for every $[u, J, \underline{z}, \underline{\zeta}] \in \mathcal{M}^d_{r,s}(X, L; J, \underline{x}, \underline{y})$, by $m(u)$ the intersection index $[u(\overset{\circ}{\Delta})] \circ [L] \in \mathbb{Z}/2\mathbb{Z}$, where $\overset{\circ}{\Delta} = \{z \in \mathbb{C} \mid |z| < 1\}$ denotes the interior of the disc Δ. In fact, J being generic, the intersection $u(\overset{\circ}{\Delta}) \cap L$ is transversal, so that the intersection index $m(u)$ coincides with the parity of the number of intersection points between $u(\overset{\circ}{\Delta})$ and L, compare §2.1 of [28].

We then set

$$GW^r_d(X, L; \underline{x}, \underline{y}, J) = \sum_{[u,J,\underline{z},\underline{\zeta}] \in \mathcal{M}^d_{r,s}(X,L;J,\underline{x},\underline{y})} (-1)^{m(u)} \in \mathbb{Z}.$$

Theorem 3.1. *Let (X, ω) be a closed connected symplectic four-manifold and $L \subset X$ be a closed Lagrangian surface which we assume to be orientable. Let $d \in H_2(X, L; \mathbb{Z})$ be such that $\mu_L(d) > 0$ and $\partial d = 0 \in H_1(L; \mathbb{Z})$. Let $r, s \in \mathbb{N}$ be such that $r + 2s = \mu_L(d) - 1$ and $\underline{x}$ (resp. $\underline{y}$) be a collection of r (resp. s) distinct points of L (resp. $X \setminus L$). Let finally $J \in \mathcal{J}_\omega$ be generic. Then, the integer $GW^r_d(X, L; \underline{x}, \underline{y}, J)$ neither depends on the choice of $\underline{x}, \underline{y}$ nor on the generic choice of J.*

Before proving Theorem 3.1 in Section 3.2, let us first formulate further results or consequences. The invariant provided by Theorem 3.1 can be denoted without ambiguity by $GW^r_d(X, L) \in \mathbb{Z}$. As the usual Gromov-Witten invariants, it also does not change under deformation of the symplectic form ω, whereas it indeed depends in general on d and r, compare §3 of [28]. Note that Theorem 3.1 also holds true when (X, ω) is convex at infinity. Moreover, if X does not contain any Maslov zero pseudo-holomorphic disc with boundary on L, for instance if L is monotone, then assuming in Theorem 3.1 that $\partial d = 0 \in H_1(L; \mathbb{Z}/q\mathbb{Z})$ for some $q > 1$ instead of $\partial d = 0 \in H_1(L; \mathbb{Z})$, one concludes that the reduction modulo q of the integer $GW^r_d(X, L; \underline{x}, \underline{y}, J)$ neither depends on the choice of $\underline{x}, \underline{y}$ nor on the generic choice of J.

Corollary 3.2. *Under the hypothesis of Theorem 3.1, the cardinality of the set $\mathcal{M}^d_{r,s}(X, L; J, \underline{x}, \underline{y})$ is bounded from below by $|GW^r_d(X, L)|$.*

Proposition 3.3. *Under the hypothesis of Theorem 2.1, assume that L is a Lagrangian sphere and that $r = 1$. Then, the lower bounds given by Corollary 3.2 are sharp, achieved by any generic almost-complex structure with a very long neck near L. Moreover, $(-1)^{[d]\circ[L]} GW^1_d(X, L) \leq 0$.*

When L is a torus and $r = 1$, $GW_d^1(X, L) = 0$, while $GW_d^r(X, L)$ always vanishes, whatever r is, when L is of genus greater than one. However, in both cases, the lower bounds given by Corollary 3.2 are still sharp, achieved by any generic almost-complex structure with a very long neck near L.

The notion of almost-complex structure with very long neck has been introduced by Y. Eliashberg, A. Givental and H. Hofer in [6]. Also, the intersection index $[d] \circ [L] \in \mathbb{Z}/2\mathbb{Z}$ is well defined even though $d \in H_2(X, L; \mathbb{Z})$ is only a relative homology class, since it does not depend on the choice of a lift of d in $H_2(X; \mathbb{Z})$.

Proof. When the genus of L is greater than one, this result is a particular case of Proposition 1.10 of [31] (see also Proposition 4.4 of [32]). When L is a torus, the proof goes along the same lines as Theorem 1.4 of [31] and we do not reproduce it here. The upshot is that after splitting (X, ω) near the flat L in the sense of symplectic field theory, for all J-holomorphic disc homologous to d and passing through $\underline{x}, \underline{y}$, the component in the Weinstein neighborhood of L which contains the unique real point x is just a once punctured disc - while it could have more punctures if $r > 1$. At the puncture, the disc is asymptotic to a closed Reeb orbit. The boundary of the disc is thus homologous to a closed geodesic of the flat torus L and thus not homologous to zero in L. As a consequence, for an almost-complex structure with very long neck, none of the J-holomorphic discs homologous to d which pass through $\underline{x}, \underline{y}$ have trivial boundary in homology.

Finally, when L is a sphere, the proof goes along the same lines as Theorem 1.1 of [31] and we do not reproduce it here. Again, the upshot is that for an almost-complex structure with very long neck and standard near L, all the J-holomorphic discs homologous to d which pass through $\underline{x}, \underline{y}$ have boundary close to a geodesic - while this boundary would be some immersed loop of L if $r > 1$. This boundary thus divides L into two components $L^{\pm}$ which are both homeomorphic to Lagrangian discs. We can then glue one such Lagrangian disc to our J-holomorphic disc D to get an integral two-cycle which lifts d in homology. The intersection index of this two-cycle with L equals $m(D) + 1 \mod (2)$, where the $+1$ term is the Euler characteristic of the Lagrangian disc. We thus deduce that for every such disc D, $m(D) = [d] \circ [L] + 1$, the sharpness and the result. $\square$

The following Lemma 3.4 relates this open Gromov-Witten invariant with the real enumerative invariant introduced in [26], [28].

Lemma 3.4. *Let (X, ω, c_X) be a closed real symplectic four-manifold which contains a Lagrangian sphere L in its real locus $\mathbb{R}X = fix(c_X)$. Let $d \in H_2(X; \mathbb{Z})$ be such that $c_1(X)d > 0$ and $(c_X)_* d = -d$ and let $1 \leq r \leq c_1(X)d - 1$ be an odd integer. Then,*

$$\chi_r^d(L) = 2^{s-1} \sum_{d' \in H_2(X,L;\mathbb{Z}) \,|\, d' - (c_X)_* d' = d} (-1)^{d' \circ [\mathbb{R}X \setminus L]} GW_{d'}^r(X, L) \in \mathbb{Z},$$

where $s = \frac{1}{2}(c_1(X)d - 1 - r)$. In particular, 2^{s-1} divides χ_r^d.

Recall that a real symplectic manifold is a symplectic manifold (X, ω) together with an antisymplectic involution c_X, see [25], [26]. The invariant χ_r^d has been introduced in [26], [28]. When the real locus $\mathbb{R}X$ is not connected, it is understood that $\chi_r^d(L)$ denotes the part of the invariant obtained by choosing all the r real points in the component L, see [29], [27]. Note that if r does not have the same parity as $c_1(X)d - 1$, then all invariants vanish by convention so that the formula of Lemma 3.4 holds true. Note finally that even though $d' \in H_2(X, L; \mathbb{Z})$, the difference $d' - (c_X)_* d'$ is well defined in $H_2(X; \mathbb{Z})$ since it does not depend on the choice of a lift of d' in $H_2(X; \mathbb{Z})$. Also, the intersection index of d' with the complement $\mathbb{R}X \setminus L$ is well defined.

Proof. Let $J \in \mathbb{R}\mathcal{J}_\omega$ be generic, see [28] and $\underline{x}$ (resp. $\underline{y}$) be a collection of r distinct points in L (resp. s pairs of complex conjugated points in $X \setminus \mathbb{R}X$). By definition, $\chi_r^d(L) = \sum_{C \in \mathcal{R}_d(\underline{x}, \underline{y}, J)} (-1)^{m(C)} \in \mathbb{Z}$, where $\mathcal{R}_d(\underline{x}, \underline{y}, J)$ denotes the finite set of real rational J-holomorphic curves homologous to d which contain $\underline{x} \cup \underline{y}$. Each such real rational curve is the union of two holomorphic discs with boundary on L, exchanged by c_X. Their relative homology class d' thus satisfies $d' - (c_X)_* d' = d$. Moreover, each of these discs contains $\underline{x}$ and one point of every pair of complex conjugated points $\{y_i, \overline{y}_i\}$, $1 \leq i \leq s$. There are 2^s ways to choose such a point in every pair and we denote by Y this set of 2^s s-tuples. Now, Schwarz reflection associates to every J-holomorphic disc $u' : \Delta \to X$ with boundary on L a real rational J-holomorphic curve $u : \mathbb{C}P^1 \to X$ such that $u \circ conj = conj \circ u$ and its restriction to the upper hemisphere coincides with u'. We deduce from this Schwarz reflection a $2 : 1$ surjective map

$$S : \bigcup_{\underline{y}' \in Y} \quad \bigcup_{d' \in H_2(X,L;\mathbb{Z}) \,|\, d' - (c_X)_* d' = d} \mathcal{M}_{r,s}^{d'}(X, L; J, \underline{x}, \underline{y}') \to \mathcal{R}_d(\underline{x}, \underline{y}, J).$$

By definition, for every $[u, J, \underline{z}, \underline{\zeta}] \in \mathcal{M}_{r,s}^{d'}(X, L; J, \underline{x}, \underline{y})$, $m(u) + d' \circ [\mathbb{R}X \setminus L] = m(S(u)) \mod (2)$. Indeed, $m(S(u))$ denotes the number of isolated real

double points of the real rational J-holomorphic curve $S(u)$, see [28]. These isolated real double points are exactly the transverse intersection points of u with $\mathbb{R}X$. In the component L of $\mathbb{R}X$, there are $m(u)$ such intersection points by definition, while in the complement of L in $\mathbb{R}X$, this number of intersection points is counted modulo two by the intersection index $d' \circ [\mathbb{R}X \setminus L]$. The result follows. $\square$

Remark 3.5. 1) In the case of the quadric ellipsoid, the invariant $\chi_r^d(L)$ has been computed in [30], [31] for small r. One can proceed in the same way and express $GW_d^r(X, L)$ in terms of a similar invariant defined in the cotangent bundle of the two-sphere and of enumerative invariants computed by Ravi Vakil in the second Hirzebruch surface, see Theorem 3.16 of [31]. When r is small, the open Gromov-Witten invariant of the cotangent bundle of the two-sphere is easy to compute, see Lemma 3.5 of [31], but for larger r, such a computation is not known yet. Note that an algorithm to compute $\chi_r^d(L)$ for every r has been proposed in [22].

2) The last part of Lemma 3.4 actually provides a stronger congruence than the one I already established in [30], [31] using symplectic field theory, see Theorem 2.1 of [31] or Theorem 1.4 of [32].

3) Lemma 3.4 indicates an obstruction to get similar results for higher genus membranes, that is higher genus J-holomorphic curve with boundary on L. Indeed, we know that in a simply connected real projective surface, there is one and only one smooth real curve (of genus $\frac{1}{2}(L^2 - c_1(X)L + 2)$) in the linear system of an ample real line bundle L, which pass through a real collection of $\frac{1}{2}(L^2 + c_1(X)L)$ points, whatever this collection is. Now, if there were an analogous open Gromov-Witten invariant obtained by just counting membranes, we would deduce for configurations with s pairs of complex conjugated points that 2^{s-1} divides one, a contradiction. Already for genus zero membranes with two boundary components one sees such an obstruction. For instance, through say six real points and one complex point in the quadric ellipsoid, there could be, depending on the position of the points, either one or zero such genus zero membranes with two boundary components homologous to the hyperplane section in $H_2(X, L; \mathbb{Z})$. The reason is that applying Schwarz reflection to such a membrane, one gets a dividing real algebraic curve of bidegree $(2, 2)$ in the quadric passing through six real points and two complex conjugated ones. But depending on the position of these points we know that the unique real curve passing through these points can be either dividing or non-dividing, a contradiction.

When the Lagrangian surface L is not orientable, we only obtain the following quite weaker result at the moment.

Theorem 3.6. *Let (X, ω) be a closed connected symplectic four-manifold and $L \subset X$ be a closed Lagrangian surface homeomorphic to the real projective plane. Let $d \in H_2(X, L; \mathbb{Z})$ be such that $\mu_L(d) > 0$ and $\partial d \neq 0 \in H_1(L; \mathbb{Z}/ 2\mathbb{Z})$. Let $r, s \in \mathbb{N}$ be such that $r + 2s = \mu_L(d) - 1$ and $\underline{x}$ (resp. $\underline{y}$) be a collection of r (resp. s) distinct points of L (resp. $X \setminus L$). Let finally $J \in \mathcal{J}_\omega$ be generic. Then, the reduction modulo 2 of the integer $GW_d^r(X, L; \underline{x}, \underline{y}, J)$ neither depends on the choice of $\underline{x}, \underline{y}$ nor on the generic choice of J.*

This Theorem 3.6 thus only provides an invariant $GW_d^r(X, L) \in \mathbb{Z}/2\mathbb{Z}$.

3.2. Proof of Theorems 3.1 and Theorem 3.6

Lemma 3.7. *Let L be a connected Lagrangian submanifold of a connected $2n$-dimensional symplectic manifold (X, ω), $n > 1$. Then, for every $r, s \geq 0$, the group of Hamiltonian diffeomorphisms of X which preserve L acts transitively on the configuration space of distinct points $\{(\underline{x}, \underline{y}) \in L^r \times (X \setminus L)^s \mid \underline{x}, \underline{y}$ are distinct points$\}$.*

Proof. Let us assume first that $r = 1$ and $s = 0$. Let $x_0, x_1 \in L$ and $(x_t)_{t \in [0,1]}$ be a smooth path of L joining them. Then, there exists a Hamiltonian flow $(\phi_t)_{t \in [0,1]}$ of X which preserves L and such that for every $t \in [0, 1]$, $\phi_t(x_0) = x_t$. Moreover, outside of an arbitrary small neighborhood of $\cup_{t \in [0,1]}\{x_t\}$ in X and for every $t \in [0, 1]$, ϕ_t can be the identity. Indeed, from Weinstein's neighborhood theorem and the compactness of $[0, 1]$, it suffices to prove this result for $(X, L) = (\mathbb{C}^n, \mathbb{R}^n)$. Moreover, the path $(x_t)_{t \in [0,1]}$ can then be assumed to be linear in $\mathbb{R}^n$ since any diffeomorphism of $\mathbb{R}^n$ extends to a symplectomorphism of $\mathbb{C}^n = T^*\mathbb{R}^n$. Now, the translation in the path $(x_t)_{t \in [0,1]}$ is induced by some linear Hamiltonian H on $\mathbb{C}^n$. Given a neighborhood U of $\cup_{t \in [0,1]}\{x_t\}$, there exists a smooth function χ of $\mathbb{C}^n$, invariant under the complex conjugation, which vanishes in the complement of U and equals one in a neighborhood of $\cup_{t \in [0,1]}\{x_t\}$. The Hamiltonian flow $(\phi_t)_{t \in [0,1]}$ induced by the Hamiltonian χH is then the identity outside of U and is such that for every $t \in [0, 1]$, $\phi_t(x_0) = x_t$. The result follows when $r = 1$, $s = 0$ and follows along the same lines in general. $\square$

Let J_0 and J_1 be two generic elements of $\mathcal{J}_\omega$. From Lemma 3.7, it suffices to prove that $GW_d^r(X, L; \underline{x}, \underline{y}, J_0) = GW_d^r(X, L; \underline{x}, \underline{y}, J_1)$. Let $\gamma : t \in [0, 1] \mapsto J_t \in \mathcal{J}_\omega$ be a generic path such that $\gamma(0) = J_0$ and $\gamma(1) = J_1$. Denote by $\mathcal{M}_\gamma = \pi^{-1}(Im(\gamma))$ the one-dimensional submanifold of $\mathcal{M}_{r,s}^d(X, L; \underline{x}, \underline{y})$ and by $\pi_\gamma : \mathcal{M}_\gamma \to [0, 1]$ the associated projection. From Propositions 2.7, 3.12, π_γ has finitely many critical points, all non-degenerated, which correspond

to simple discs with a unique ordinary cusp on their boundary. All the other points of $\mathcal{M}_\gamma$ correspond to immersed discs.

Lemma 3.8. *Let (X, ω) be a closed symplectic four-manifold and $L \subset X$ be a closed Lagrangian surface. Let $t \in [0,1] \mapsto J_t \in \mathcal{J}_\omega$ be a generic path of tame almost-complex structures. Let $u_t : \Delta \to X$, $t \in [0,1]$, be a continuous family of J_t-holomorphic immersions such that $u_t(\partial\Delta) \subset L$. Then, the intersection index $[u_t(\overset{\circ}{\Delta})] \circ [L] \in \mathbb{Z}/2\mathbb{Z}$ does not depend on $t \in [0,1]$.*

Proof. Since these maps are immersions, L is Lagrangian and $[0,1]$ compact, there exists $\epsilon > 0$ such that for every $t \in [0,1]$, $[u_t(\overset{\circ}{\Delta})] \circ [L] = [u_t(\Delta(1-\epsilon))] \circ [L] \in \mathbb{Z}/2\mathbb{Z}$ and $u_t(\partial\Delta(1-\epsilon)) \cap L = \emptyset$, where $\Delta(1-\epsilon) = \{z \in \mathbb{C} \mid |z| \leq 1 - \epsilon\}$. The sum of $u_0(\Delta(1-\epsilon))$, the chain $(t,z) \in [0,1] \times \partial\Delta(1-\epsilon) \mapsto (t, u_t(z))$ and $-u_1(\Delta(1-\epsilon))$ defines an integral two-cycle homologous to zero. Its intersection index modulo two with L equals $[u_1(\overset{\circ}{\Delta})] \circ [L] - [u_0(\overset{\circ}{\Delta})] \circ [L]$, hence the result. $\qquad\square$

Denote by B^4 the open unit ball of $\mathbb{C}^2$ and by J_{st} the standard complex structure on this ball.

Lemma 3.9. *Let J be an almost complex structure of class C^l on B^4 tamed by the standard symplectic form. Let $u_0 : \{z \in \mathbb{C} \mid \Im(z) \geq 0 \text{ and } |z| \leq 1\} \to B^4$ be a J-holomorphic map having an isolated singularity of order μ at $0 = u_0(0)$ and mapping the boundary $[-1,1]$ to $\mathbb{R}^2$. Then, as soon as J is close enough to $J_{st} = J(0)$ in C^1 norm, for every $v \in \mathbb{R}^2$ and every integer $\nu \leq 2\mu + 1$, there exist $\epsilon > 0$ and a family of maps $w_\lambda \in L^{k,p}(\{z \in \mathbb{C} \mid \Im(z) \geq 0 \text{ and } |z| \leq 1\}; \mathbb{C}^2, \mathbb{R}^2)$, $\lambda \in]-\epsilon, \epsilon[$, such that $w_0 = 0$, $\dot{w}_0 = \frac{d}{d\lambda}|_{\lambda=0}(w_\lambda)(0) = 0$ and for every $\lambda \in]-\epsilon, \epsilon[$, the map $u_\lambda(t) = u_0(t) + t^\nu(\lambda v + w_\lambda(t))$ is J-holomorphic.*

This is a version of (a weaker form of) Lemma 3.1.1 of [21] for a boundary point of a disc. A sketch of proof of such a version for an interior point was already given in [28], Lemma 2.5, and we reproduce the analog here.

Sketch of proof. One can write the equation $\sigma_{\overline{\partial}}(u_\lambda, j_{st}, J) = 0$, where j_{st} denotes the complex structure of $\{z \in \mathbb{C} \mid \Im(z) \geq 0 \text{ and } |z| \leq 1\}$, in the form

$$(x + yj_{st})^{-\nu}\sigma_{\overline{\partial}}(u_0(t) + (x + yj_{st})^\nu(\lambda v + w_\lambda(t)), j_{st}, J) = 0,$$

where by definition $x + yj_{st} = t$. The linearization of this equation writes

$$(x + yj_{st})^{-\nu}(\overline{\partial} + R)|_{(u_\lambda, j_{st}, J)}((x + yj_{st})^\nu(v + \dot{w}_\lambda(t))) = 0,$$

which takes the form

$$(\overline{\partial} + R)^{(\nu)}|_{(u_\lambda, j_{st}, J)} \; \dot{w}_\lambda \, (t) = -(\overline{\partial} + R)^{(\nu)}|_{(u_\lambda, j_{st}, J)}(v)$$

for some generalized $\overline{\partial}$-type operator $D^{(\nu)} = (\overline{\partial} + R)^{(\nu)} = (x + yj_{st})^{-\nu}(\overline{\partial} + R)|_{(u_\lambda, j_{st}, J)}(x + yj_{st})^{\nu}$. To solve this equation, it is thus sufficient to find a right inverse $T^{(\nu)}$ of this operator $D^{(\nu)}$ such that $T^{(\nu)}(\alpha)(0) = 0$ for every $\alpha \in L^{k-1,p}(\{z \in \mathbb{C} \mid \Im(z) \geq 0 \text{ and } |z| \leq 1\}, \Lambda^{0,1}\{z \in \mathbb{C} \mid \Im(z) \geq 0 \text{ and } |z| \leq 1\} \otimes \mathbb{C}^2)$. As soon as J is close enough to $J_{st} = J(0)$ in C^1 norm, the existence of such a right inverse follows from the existence of a right inverse for the standard $\overline{\partial}$-operator on $\{z \in \mathbb{C} \mid \Im(z) \geq 0 \text{ and } |z| \leq 1\}$, which follows by restriction from the existence of a right inverse for the standard $\overline{\partial}$-operator on the disc $\{z \in \mathbb{C}P^1 \mid \Im(z) \geq 0\}$, see Lemma 1.2.2 of [16] for instance. $\qquad \square$

Remark 3.10. Without loosing that much generality, we could have restricted ourselves throughout this paper to almost-complex structures J on X, tamed by the symplectic form and which in a given Weinstein neighborhood of the Lagrangian surface L turn the canonical involution $(q, p) \in T^*L \mapsto (q, -p) \in T^*L$ into a J-holomorphic one. Then, Lemma 3.9 would follow by Schwarz reflection from the corresponding Lemma 2.5 of [28]

Lemma 3.11. *Let* $[u_{t_0}, J_{t_0}, \underline{z}_{t_0}, \underline{\zeta}_{t_0}] \in \mathcal{M}_\gamma$ *be a critical point of* π_γ *which is a local maximum (resp. minimum). There exists a neighborhood* W *of* $[u_{t_0}, J_{t_0}, \underline{z}_{t_0}, \underline{\zeta}_{t_0}]$ *in* $\mathcal{M}_\gamma$ *and* $\eta > 0$ *such that for every* $t \in]t_0 - \eta, t_0[$ *(resp.* $t \in]t_0, t_0 + \eta[)$, $\pi_\gamma^{-1}(t) \cap W$ *consists of two points* $[u_t^\pm, J_t, \underline{z}_t^\pm, \underline{\zeta}_t^\pm]$ *such that* $m(u_t^+) \neq m(u_t^-) \in \mathbb{Z}/2\mathbb{Z}$ *and for every* $t \in]t_0, t_0 + \eta[$ *(resp.* $t \in]t_0 - \eta, t_0[)$, $\pi_\gamma^{-1}(t) \cap W$ *is empty.*

Proof. This Lemma 3.11 is analog to Proposition 2.16 of [28] and we only sketch its proof. Let B be a small enough ball centered at the critical value of u_{t_0} in X. Let $\mathcal{P}$ be the space of pseudo-holomorphic maps from $\{z \in \mathbb{C} \mid \Im(z) \geq 0 \text{ and } |z| < 1\}$ to B mapping the boundary $]-1, 1[$ to $L \cap B$. Let $\mathcal{C} \subset \mathcal{P}$ be the subspace of maps which are immersions away from a unique point of $]-1, 1[$ which is cuspidal of multiplicity two. This space $\mathcal{C}$ is a submanifold of codimension one of $\mathcal{P}$ since its defining condition on the first jet of the pseudo-holomorphic maps costs one degree of freedom, which is proven as Lemma 2.6 of [28] by replacing the reference to Lemma 2.5 of [28] with a reference to Lemma 3.9, compare Lemma 4.4.3 of [21]. The one-parameter family of pseudo-holomorphic discs parameterized by W provides by restriction to B a path of $\mathcal{P}$ transversal to $\mathcal{C}$ at $[u_{t_0}, J_{t_0}]$. This is

due to the fact that the tangent vector of this path at $[u_{t_0}, J_{t_0}, \underline{z}_{t_0}, \underline{\zeta}_{t_0}]$ generates $H_D^0(\Delta, \mathcal{N}_{u,-\underline{z},-\underline{\zeta}})$ by Proposition 2.3, while the normal sheaf $\mathcal{N}_{u,-\underline{z},-\underline{\zeta}}$ is skyscaper, compare Proposition 2.6. A generator of the latter provides a complex vector field tangent to the image of u_{t_0} with a simple pole at the cusp, see Lemma 4.3.1 of [21]. Such a tangent vector is precisely transverse to $T_{[u_{t_0}, J_{t_0}]}\mathcal{C}$ in $T_{[u_{t_0}, J_{t_0}]}\mathcal{P}$, compare Lemma 2.6 [28]. For the same reason, the perturbation $t \in \mathbb{C} \mapsto (t^2, t^3 + \epsilon t) \in \mathbb{C}^2$ of the standard real ordinary cusp provides by restriction to a ball B' of $\mathbb{C}^2$ centered at the origin and symplectomorphic to B a path u'_ϵ of $\mathcal{P}'$ transversal to $\mathcal{C}'$ at $\epsilon = 0$, where $\mathcal{P}'$ and $\mathcal{C}'$ are the analogs of $\mathcal{P}$ and $\mathcal{C}$ in B'. Note that $m(u'_\epsilon) = 1$ (resp. $m(u'_\epsilon) = 0$) for $\epsilon > 0$ (resp. $\epsilon < 0$), while from Lemma 3.8 follows that the intersection index m is constant on each component of $\mathcal{P}' \setminus \mathcal{C}'$. Let us choose a symplectic diffeomorphism ϕ between B and B' which maps $L \cap B$ onto $\mathbb{R}^2 \cap B'$. It suffices then to connect $\phi \circ u_{t_0}$ to u'_0 or any point sufficently close to u'_0 by a smooth path in $\mathcal{C}'$. This can be done by zooming at the origin of B', since we may assume that $\phi_* J_{t_0}$ is the standard complex structure at the origin and that $\phi \circ u_{t_0} : z \to (z^2, z^3) + o(z^3) \in B'$, as follows from Lemma 3.9, compare Corollary 1.4.3 of [16]. Let $a_\delta : (z_1, z_2) \in \mathbb{C}^2 \mapsto (\delta^2 z_1, \delta^3 z_2) \in \mathbb{C}^2$, $\delta \in]0,1]$ and $h_\delta : z \in \mathbb{C} \mapsto \delta z \in \mathbb{C}$, then $a_\delta^{-1} \circ \phi \circ h_\delta$ provides a path of $\mathcal{C}'$ parameterized by $\delta \in]0,1]$ which is close to the standard cusp u'_0 for δ close to zero and equals $\phi \circ u_{t_0}$ for $\delta = 1$. The result follows. $\qquad\square$

When the one-dimensional cobordism $\mathcal{M}_\gamma$ is compact, Lemmas 3.8 and 3.11 imply Theorem 3.1, since as t varies in $[0,1]$, Lemma 3.8 guarantees the invariance of $GW_d^r(X, L; \underline{x}, \underline{y}, J_t)$ between two critical values of π_γ whereas Lemma 3.11 guarantees its invariance while crossing the critical values.

When $\mathcal{M}_\gamma$ is not compact, its Gromov compactification is given by the following Proposition 3.12.

Proposition 3.12. *Let L be a closed orientable Lagrangian surface of a closed connected symplectic four-manifold (X, ω). Let $d \in H_2(X, L; \mathbb{Z})$ be such that $\mu_L(d) > 0$ and $r, s \in \mathbb{N}$ such that $r + 2s = \mu_L(d) - 1$. Let $\underline{x}$ (resp. $\underline{y}$) be a set of r (resp. s) distinct points of L (resp. $X \setminus L$). Let $t \in [0,1] \mapsto J_t \in \mathcal{J}_\omega$ be a generic path. Then, every J_t-holomorphic element of $\mathcal{P}_{r,s}(X, L)$, homologous to d and containing $\underline{x} \cup \underline{y}$, $t \in [0,1]$, is simple. Likewise, every J_t-holomorphic stable disc homologous to d which contains $\underline{x} \cup \underline{y}$, $t \in [0,1]$, is either irreducible, or its image contains exactly two irreducible components which are both immersed discs transversal to each other. In the latter case, if the Maslov index of such a component is positive, then the source contains a unique disc mapped to this component and the map is an immersion.*

Proof. Let us assume that a J_t-holomorphic element of $\mathcal{P}_{r,s}(X, L)$ homologous to d and containing $\underline{x} \cup \underline{y}$, $t \in [0, 1]$, is not simple. From Theorem 2.5, such a J_t-holomorphic disc $u : \Delta \to X$ splits into simple discs $u_{\mathcal{D}} : \Delta \to X$, so that $d = \sum_{\mathcal{D}} m_{\mathcal{D}}(u_{\mathcal{D}})_*[\Delta] \in H_2(X, L; \mathbb{Z})$. Let us denote by $(\mathcal{D}_i)_{i \in I}$ the connected components of the complement $\Delta \setminus \mathcal{G}(u)$ given by Theorem 2.5 and set $d_i = (u_{\mathcal{D}_i})_*[\Delta]$. From Theorem 2.2, the $\mu_L(d_i)$ are non-negative. But the union of these simple discs has to contain the points $\underline{x} \cup \underline{y}$, so that from Theorem 2.2, $\sum_{i \in I}(\mu_L(d_i) - 1) \geq \#(\underline{x} \cup \underline{y}) - 1 \geq \mu_L(d) - 2$. Since $\sum_{i \in I} m_{\mathcal{D}_i} \mu_L(d_i) = \mu_L(d)$ and these Maslov indices are even, we deduce that $\#I = 2$. Hence, either $m_{\mathcal{D}_1} = m_{\mathcal{D}_2} = 1$ or $\mu_L(d_i) = 0$ for some $i \in \{1, 2\}$. In both cases, one of the discs, say $u_{\mathcal{D}_2}$, together with its incidence conditions, has vanishing Fredholm index, while the other one, $u_{\mathcal{D}_1}$, has index -1 and a common edge with $u_{\mathcal{D}_2}$. Perturbing the almost-complex structure on the image of $u_{\mathcal{D}_2}$, one observes that the latter condition is of positive codimension while it is independent of the former Fredholm -1 condition. As a consequence, such a non-simple disc cannot appear over a generic path of almost-complex structures $(J_t)_{t \in [0,1]}$.

Let us assume now that there exists a J_t-holomorphic disc u given by Theorem 2.4 which contains $\underline{x} \cup \underline{y}$ and is homologous to d, $t \in \,]0, 1[$. The preceding arguments again lead to the fact that such a J_t-holomorphic disc contains in its image exactly two irreducible components, both being discs. Indeed, from Theorem 2.2, the Fredholm index of a simple disc in a class $d_1 \in H_2(X, L; \mathbb{Z})$ is $\mu_L(d_1) - 1$ whereas the index of a pseudo-holomorphic sphere in a class $d_2 \in H_2(X; \mathbb{Z})$ is $\mu_L(d_2) - 2$. As a consequence, the index of a stable disc with α disc-components and β spherical components in its image equals $\mu_L(d') - \alpha - 2\beta$, where $d' \in H_2(X, L; \mathbb{Z})$ denotes the total homology class of these image components. We deduce that $\mu_L(d') - \alpha - 2\beta \geq \#(\underline{x} \cup \underline{y}) - 1$, so that either $\alpha = 2$, $\beta = 0$ and $\mu_L(d') = \mu_L(d)$, or $\alpha = 0$ and $\beta = 1$. The latter is however excluded since r is odd so that the index of a J_t-holomorphic sphere passing through $\underline{x} \cup \underline{y}$ is then less than -1 in this case. Hence, the image of u contains two irreducible components of classes $d_1, d_2 \in H_2(X; \mathbb{Z})$ such that $\mu_L(d_1) + \mu_L(d_2) = \mu_L(d)$.

Moreover, these two irreducible components of the image of u are immersed from Proposition 2.7 and transverse to each other, since to have a point of non transverse intersection for two discs costs one degree of freedom, so that in the space of pairs of discs passing through $\underline{x}$, $\underline{y}$ and of total homology class d, the ones which are not transversal to each other form a codimension one stratum, compare Proposition 2.11 of [28]. As a consequence, the projection from this stratum to $\mathcal{J}_\omega$ gets of Fredholm index -2 and its image is avoided by the generic path $t \in [0, 1] \mapsto J_t \in \mathcal{J}_\omega$.

Finally, we deduce as in the first part of this proof that if $\mu_L(d_1)$ (resp. $\mu_L(d_2)$) is positive, then the stable disc at the source of u contains a unique component which is mapped onto the disc of class d_1 (resp. d_2). Moreover, the restriction of u to this component has to be an immersion, since the image disc is immersed. □

Let $([u_1, J_{t_0}, \underline{z}_1, \underline{\zeta}_1], [u_2, J_{t_0}, \underline{z}_2, \underline{\zeta}_2])$ be a pair of discs given by Proposition 3.12, $D_i = Im(u_i)$, and $d_i = (u_i)_*(\Delta) \in H_2(X, L; \mathbb{Z})$, $i \in \{1, 2\}$. We may assume without loss of generality that $\mu_L(d_2)$ is positive and deduce from Proposition 3.12 that there exists a positive integer b such that $bd_1 + d_2 = d$, with $b = 1$ in case $\mu_L(d_1) > 0$. From the hypothesis we know that $b[\partial d_1] = -[\partial d_2] \in H_1(L, \mathbb{Z})$, so that $[\partial d_1] \circ [\partial d_2] = 0$. Let us equip L with an orientation and denote by R^+ (resp. R^-) the number of positive (resp. negative) intersection points between ∂D_1 and ∂D_2, the latter being canonically oriented by the complex structure. We deduce that $R^+ = R^-$. Our main observation is then the following, which we formulate in a more general setting since it will be useful as well in the next paragraph.

Proposition 3.13. *Let (X, ω) be a closed connected symplectic 4-manifold and $L \subset X$ be a closed Lagrangian surface. Let $([u_1, J_0, \underline{z}_1, \underline{\zeta}_1], [u_2, J_0, \underline{z}_2, \underline{\zeta}_2])$ $\in \mathcal{M}^{d_1}_{r_1, s_1}(X, L; J_0, \underline{x}_1, \underline{y}_1) \times \mathcal{M}^{d_2}_{r_2, s_2}(X, L; J_0, \underline{x}_2, \underline{y}_2)$ be a pair of immersed pseudo-holomorphic discs transversal to each other. Assume that $r_1 + 2s_1 = \mu_L(d_1)$, $r_2 + 2s_2 = \mu_L(d_2) - 1$ and that L is orientable and oriented in the neighborhood of $u_1(\partial \Delta)$. Let $(J_\lambda)_{\lambda \in]-\epsilon, \epsilon[}$ be a path transversal to the Fredholm -1 projection $\pi_1 : \mathcal{M}^{d_1}_{r_1, s_1}(X, L; \underline{x}_1, \underline{y}_1) \to \mathcal{J}_\omega$. Then, as soon as ϵ is small enough, for every intersection point w of $u_1(\partial \Delta) \cap u_2(\partial \Delta)$, the pair $([u_1, J_0, \underline{z}_1, \underline{\zeta}_1], [u_2, J_0, \underline{z}_2, \underline{\zeta}_2])$ deforms by perturbation of w to exactly one disc in $\mathcal{M}^{d_1+d_2}_{r_1+r_2, s_1+s_2}(X, L; J_\lambda, \underline{x}_1 \cup \underline{x}_2, \underline{y}_1 \cup \underline{y}_2)$ for positive λ and does not deform in $\mathcal{M}^{d_1+d_2}_{r_1+r_2, s_1+s_2}(X, L; J_\lambda, \underline{x}_1 \cup \underline{x}_2, \underline{y}_1 \cup \underline{y}_2)$ for negative λ, or vice versa. Moreover, the values of λ for which such a deformation holds only depend on the sign of the local intersection index $u_1(\partial \Delta) \circ u_2(\partial \Delta)$ at w in L.*

In the statement of Proposition 3.13, it is understood that the points $\underline{x}_1, \underline{x}_2, \underline{y}_1, \underline{y}_2$ are not on singular points of the stable disc. Also, the last part of the statement means that the values of λ for which the deformation holds do not depend on the Maslov index $\mu_L(d_2)$, the value of r_2 or on the chosen disc $[u_2, J_0, \underline{z}_2, \underline{\zeta}_2]$ and intersection point w.

Proof. Since all nearby discs to the stable one are immersed, we may, without loss of generality, deform $(J_\lambda)_{\lambda \in]-\epsilon, \epsilon[}$ or J_0 in the image of π_1 as long as

$([u_1, J_0, \underline{z}_1, \underline{\zeta}_1], [u_2, J_0, \underline{z}_2, \underline{\zeta}_2])$ remains J_0-holomorphic, as follows from symplectic isotopy. We may then assume that J_0 is standard near $\underline{x}_2, \underline{y}_2$ and blow up these points to restrict ourselves to the case where $r_2 = s_2 = 0$. We are then going to deduce Proposition 3.13 from Proposition 2.14 of [28]. Let $b, f \in \mathbb{R}P^1$ and $F' = \{b\} \times \mathbb{C}P^1$, $B' = \mathbb{C}P^1 \times \{f\}$ be the two associated real rational curves of $\mathbb{C}P^1 \times \mathbb{C}P^1$. These curves transversely intersect at one real point. We may add a finite number of pairs of complex conjugated sections $B_i = \mathbb{C}P^1 \times \{f_i\}$ to F', where $f_i \in CP^1 \setminus \mathbb{R}P^1$ and blow up some pairs of complex conjugated points on F' together with one real point on B' in order to get, after perturbation, a real projective surface (Y, c_Y) whose real locus is a once blown-up torus, together with smooth real rational curves B, F intersecting transversely at one real point. This number of sections and blown-up points can moreover be chosen such that $c_1(Y)[F] = \mu_L(d_1)$, where $d_i = (u_i)_*(\Delta) \in H_2(X, L; \mathbb{Z})$, $i \in \{1, 2\}$. Let F^+ be one hemisphere of F, so that its interior is a connected component of $F \setminus \mathbb{R}F$. It induces an orientation on $\partial F^+ = \mathbb{R}F$. Let us choose an orientation of $\mathbb{R}Y$ near $\mathbb{R}F$ and denote by B^+ (resp. B^-) the hemisphere of B such that $[\partial F^+] \circ [\partial B^{\pm}] = \pm 1$ locally at the unique intersection point. Let U^+ (resp. U^-) be a neighborhood of $F^+ \cup B^+$ (resp. $F^+ \cup B^-$) in Y. Choose r_1 distinct points on $\mathbb{R}F \setminus B$ and s_1 distinct pairs of complex conjugated points on $F \setminus \mathbb{R}F$, where $r_1 + 2s_1 = c_1(Y)[F]$. Denote by $\mathcal{J}_Y$ (resp. $\mathbb{R}\mathcal{J}_Y$) the space of almost-complex structures of Y tamed by a chosen symplectic form ω_Y (resp. for which c_Y is antiholomorphic) and by J'_0 the given complex structure of Y. Let us denote by $\mathcal{J}_Y^+$ (resp. $\mathbb{R}\mathcal{J}_Y^+$) the codimension one subspace of $\mathcal{J}_Y$ (resp. $\mathbb{R}\mathcal{J}_Y$) for which F^+ deforms as a pseudo-holomorphic disc with boundary on $\mathbb{R}Y$ passing through the chosen points on F^+. This space contains J'_0 and coincides with the space for which the pair $F^+ \cup B^+$ or $F^+ \cup B^-$ deforms as a pair of pseudo-holomorphic discs with boundary on $\mathbb{R}Y$ passing through the chosen points. Let z be a smooth point of $F^+ \setminus \partial F^+$ away from the already chosen ones and $(J'_\lambda)_{\lambda \in]-\epsilon, \epsilon[}$ be a path of $\mathbb{R}\mathcal{J}_Y$ which coincides with J'_0 outside of a neighborhood of z and is transversal to $\mathcal{J}_Y^+$, see [28]. From Proposition 2.14 of [28], we may assume that for $\lambda \in]0, \epsilon[$ (resp. $\lambda \in]-\epsilon, 0[$), $F^+ \cup B^+$ (resp. $F^+ \cup B^-$) deforms as a unique J'_λ-holomorphic disc with boundary on $\mathbb{R}Y$ passing through the chosen points, whereas for $\lambda \in]-\epsilon, 0[$ (resp. $\lambda \in]0, \epsilon[$), it has no J'_λ-holomorphic deformation with boundary on $\mathbb{R}Y$ passing through the chosen points. These deformations, being close to $F^+ \cup B^{\pm}$, are all immersed and thus regular from Proposition 2.6. As a consequence, we deduce by symplectic isotopy that the latter result neither depends on the choice of the transversal path $(J'_\lambda)_{\lambda \in]-\epsilon, \epsilon[}$, nor even of the crossing point J'_0 in $\mathcal{J}_Y$ which makes $F^+ \cup B^{\pm}$ holomorphic, since this set

is connected. Moreover, this result does not depend on the specific position of the chosen points on F, r_1 being fixed, since this set is again connected.

Now, for every positive (resp. negative) intersection point w_+ (resp. w_-) of $u_1(\partial\Delta) \cap u_2(\partial\Delta)$, there exists, deforming ω_Y if necessary, a symplectic immersion from U^+ (resp. U^-) to a neighborhood V of $u_1(\Delta) \cup u_2(\Delta)$ in X which maps $\mathbb{R}Y \cap U^+$ (resp. $\mathbb{R}Y \cap U^-$) on L and w on w_+ (resp. w_-). Moreover, there exists holomorphic parameterizations $v_1 : \Delta \to F^+$ and $v_2 : \Delta \to B^+$ (resp. $v_2 : \Delta \to B^-$) such that $u_1 = \phi \circ v_1$ and $u_2 = \phi \circ v_2$. We then fix the points $v_1(\underline{z}_1)$, $v_1(\underline{\zeta}_1)$ on F^+. The immersion ϕ maps the wall $\mathcal{J}_Y^+$ on the corresponding codimension one subspace of $\mathcal{J}_\omega$ made of almost-complex structures for which the disc $[u_1, J_{t_0}, \underline{z}_1, \underline{\zeta}_1]$ deforms as a disc passing through $\underline{x}_1 \cup \underline{y}_1$. The result now follows from the fact that, up to homotopy, the latter does not depend on the choice of the point w_+ (resp. w_-), so that on one side of the codimension one subspace of $\mathcal{J}_\omega$, the stable disc $([u_1, J_{t_0}, \underline{z}_1, \underline{\zeta}_1], [u_2, J_{t_0}, \underline{z}_2, \underline{\zeta}_2])$ deforms by perturbation of $w^\pm$ to a simple disc while on the other side, it does not, the side only depending on the sign $\pm$. $\qquad\square$

Proposition 3.14. *Under the hypothesis of Theorem 3.1, Let $([u_1, J_{t_0}, \underline{z}_1, \underline{\zeta}_1],$ $[u_2, J_{t_0}, \underline{z}_2, \underline{\zeta}_2]) \in \mathcal{M}_{r_1,s_1}^{d_1}(X, L; J_0, \underline{x}_1, \underline{y}_1) \times \mathcal{M}_{r_2,s_2}^{d_2}(X, L; J_0, \underline{x}_2, \underline{y}_2)$ be a pair of transversal immersed pseudo-holomorphic discs in the Gromov compactification $\overline{\mathcal{M}}_\gamma$ of $\mathcal{M}_\gamma$ such that $bd_1 + d_2 = d$, $b \geq 1$. There exists a neighborhood W of $([u_1, J_{t_0}, \underline{z}_1, \underline{\zeta}_1], [u_2, J_{t_0}, \underline{z}_2, \underline{\zeta}_2])$ in $\overline{\mathcal{M}}_\gamma$ and $\eta > 0$ such that the contribution of $\pi_\gamma^{-1}(t) \cap W$ to $GW_d^r(X, L; \underline{x}, \underline{y}, J_t)$ does not depend on $t \in]t_0 - \eta, t_0 + \eta[\setminus\{t_0\}$.*

Proof. Let R^+ (resp. R^-) be the number of positive (resp. negative) intersection points between $u_1(\partial\Delta)$ and $u_2(\partial\Delta)$. By hypothesis, $R^+ = R^-$. If $b = 1$, then the result follows from Proposition 3.13. Let us assume that $b > 1$, so that $\mu_L(d_1) = 0$, $r + 2s = \mu_L(d_2) - 1$ and let $u : \underline{\Delta} \to X$ be a stable disc in the Gromov compactification $\overline{\mathcal{M}}_\gamma$ of $\mathcal{M}_\gamma$ with image $([u_1, J_{t_0}], [u_2, J_{t_0}, \underline{z}, \underline{\zeta}])$, see Proposition 3.12. We set $\underline{\Delta} = \Delta^0 \cup \cdots \cup \Delta^b$ the decomposition of $\underline{\Delta}$ into irreducible components, where Δ^0 denotes the unique one which has the same image as u_2. This uniqueness follows from Proposition 3.12, since $\mu_L(d_2)$ is positive.

The union $\Delta^1 \cup \cdots \cup \Delta^b$ contains k connected components $\underline{\Delta}_1, \ldots, \underline{\Delta}_k$, $1 \leq k \leq b$, which are k nodal discs attached to Δ^0 at k of the $R^+ + R^-$ preimages under u of $u_1(\partial\Delta) \cap u_2(\partial\Delta)$. These nodal discs are mapped onto $u_1(\Delta)$. We denote by u_i the restriction of u to $\underline{\Delta}_i$ and by $a_i \in \underline{\Delta}_i$ the marked point where $\underline{\Delta}_i$ is attached to Δ^0, $1 \leq i \leq k$, so that $u_i : \underline{\Delta}_i \to X$ is a stable

map. Given any ordered subset $\alpha_1, \ldots, \alpha_k$ of k of the $R^+ + R^-$ special points of $\partial \Delta^0$ and any stable maps $u_i : \underline{\Delta}_i \to u_1(\Delta)$ such that $u_i(a_i) = u(\alpha_i)$, we get by attaching $(\underline{\Delta}_i, a_i)$ to (Δ^0, α_i) a stable map which might be in the Gromov compactification $\overline{\mathcal{M}}_\gamma$ of $\mathcal{M}_\gamma$.

Now let us glue k copies of a neighborhood of $u_1(\Delta)$ in X to a neighborhood of $u_2(\Delta) = u(\Delta^0)$ along neighborhoods of the α_i, $1 \leq i \leq k$, in order to get a manifold V together with an immersion $v : V \to X$ such that u factors through v. By pulling back J_{t_0} under v and successively deforming $v^* J_{t_0}$ to $v^* J_t$ in each of the k copies of the neighborhood of $u_1(\Delta)$, we see as in the proof of Proposition 3.13 that the algebraic number of $v^* J_t$ holomorphic curves we get for $t > t_0$ or $t < t_0$ only depends on the stable maps u_i up to deformation and on the signs of the special points $\alpha_1, \ldots, \alpha_k$ where they are attached. Since $R^+ = R^-$, whatever the stable maps u_i are, we get as many of them attached to positive as to negative special points of $\partial \Delta^0$. The result follows. $\qquad \square$

Remark 3.15. 1) In Remark 2.12 of [28], I forgot to consider the case where elements of $\mathbb{R}\mathcal{M}^d(x)$ degenerate to an element of the diagonal Δ of Corollary 2.10. This may happen in the presence of a sphere of vanishing first Chern class as in Proposition 3.12. This case should have been included in Proposition 2.14 of [28] and can for instance be treated as in Proposition 3.14, since real rational curves are pairs of complex conjugated discs.

2) Note that, as pointed out to me by R. Crétois, stable discs in the compactification $\overline{\mathcal{M}}_\gamma$ of $\mathcal{M}_\gamma$, with $b = 2$ say, can for instance contain at the source three components, the component Δ^0 mapped onto $u_2(\Delta)$, a component Δ^1 attached to it and mapped onto $u_1(\Delta)$ and a component Δ^2, which is attached to $\partial \Delta^1$ at one point where u is not injective (let us assume here that $u_1(\partial \Delta)$ contains double points) and thus also mapped onto $u_1(\Delta)$. Such a map u can then be an immersion and we can prove as in Propositions 3.13 and 3.14 that it indeed appears in the Gromov compactification $\overline{\mathcal{M}}_\gamma$.

This Proposition 3.14, together with Lemmas 3.8 and 3.11, implies Theorem 3.1 in general, since it guarantees the invariance of $GW^r_d(X, L; \underline{x}, \underline{y}, J_t)$ while crossing the limit values $\pi_\gamma(\overline{\mathcal{M}}_\gamma \setminus \mathcal{M}_\gamma)$.

Finally, Theorem 3.6 follows along the same lines as Theorem 3.1. When $\mathcal{M}_\gamma$ is compact, $GW^r_d(X, L)$ is invariant. When $\mathcal{M}_\gamma$ is not compact, its Gromov compactification is given from Proposition 3.12 by adding to it pairs of transversal immersed pseudo-holomorphic discs. Let $([u_1, J_{t_0}, \underline{z}_1, \underline{\zeta}_1], [u_2, J_{t_0}, \underline{z}_2, \underline{\zeta}_2])$ be such a pair, $D_i = Im(u_i)$, and $d_i = (u_i)_*(\Delta) \in H_2(X, L; \mathbb{Z})$, $i \in \{1, 2\}$. From the hypothesis we know that either $[\partial d_1]$ or $[\partial d_2]$ vanishes in

$H_1(L, \mathbb{Z}/2\mathbb{Z})$. As a consequence, the discs $([u_1, J_{t_0}, \underline{z}_1, \underline{\zeta}_1]$, $[u_2, J_{t_0}, \underline{z}_2, \underline{\zeta}_2])$ have an even number of intersection points. Now, the analog to Proposition 3.14 tells us that there exists $R^+, R^- \in \mathbb{N}$, such that $R^+ + R^-$ is this even number of intersection points and one checks that the contribution of $\pi_\gamma^{-1}(t) \cap W$ to $GW_d^r(X, L; \underline{x}, \underline{y}, J_t)$ then jumps by a multiple of two as t crosses the value t_0, hence the result.

3.3. Higher open Gromov-Witten invariants

We are now going to extend the results of §3.1 by introducing k-disc open Gromov-Witten invariants, for every positive integer k. The advantage is that not only pseudo-holomorphic discs with vanishing boundary will play a rôle here. Let us adopt again the notations of §3.1. Let (X, ω) be a closed connected symplectic four-manifold. Let $L \subset X$ be a closed Lagrangian surface of Maslov class $\mu_L \in H^2(X, L; \mathbb{Z})$ and $k \in \mathbb{N}^*$. Let $d \in H_2(X, L; \mathbb{Z})$ be such that $\mu_L(d) \geq k$ and $r, s \in \mathbb{N}$ such that $r + 2s = \mu_L(d) - k$. Let finally $\underline{x}$ (resp. $\underline{y}$) be a set of r (resp. s) distinct points of L (resp. $X \setminus L$). For every $J \in \mathcal{J}_\omega$ generic, denote by $\mathcal{M}_{r,s}^{d,k}(X, L; J, \underline{x}, \underline{y})$ the union

$$\bigcup_{d_1, \ldots, d_k \in H_2(X, L; \mathbb{Z}) \mid d_1 + \cdots + d_k = d} \mathcal{M}_{r,s}^{d_1, \ldots, d_k}(X, L; J, \underline{x}, \underline{y}),$$

where $\mathcal{M}_{r,s}^{d_1, \ldots, d_k}(X, L; J, \underline{x}, \underline{y})$ denotes the finite set of unions of k J-holomorphic discs with boundaries on L, containing $\underline{x}, \underline{y}$ and with respective relative homology classes $d_1, \ldots, d_k$. We do not prescribe how these $r + 2s$ points $\underline{x}, \underline{y}$ get distributed among the k discs. For every unions of k discs

$$[u, J, \underline{z}, \underline{\zeta}] = \{[u_1, J, \underline{z}_1, \underline{\zeta}_1], \ldots, [u_k, J, \underline{z}_k, \underline{\zeta}_k]\} \in \mathcal{M}_{r,s}^{d,k}(X, L; \underline{x}, \underline{y}),$$

we set $m(u) = \sum_{i=1}^k m(u_i) \in \mathbb{Z}/2\mathbb{Z}$. Then, we set

$$GW_{d,k}^r(X, L; \underline{x}, \underline{y}, J) = \sum_{[u, J, \underline{z}, \underline{\zeta}] \in \mathcal{M}_{r,s}^{d,k}(X, L; J, \underline{x}, \underline{y})} (-1)^{m(u)} \in \mathbb{Z}.$$

Theorem 3.16. *Let (X, ω) be a closed connected symplectic four-manifold, $L \subset X$ be a closed Lagrangian surface which we assume to be orientable and $k \in \mathbb{N}^*$. Let $d \in H_2(X, L; \mathbb{Z})$ be such that $\mu_L(d) \geq k$ and $\partial d = 0 \in H_1(L; \mathbb{Z})$. Let $r, s \in \mathbb{N}$ be such that $r + 2s = \mu_L(d) - k$ and $\underline{x}$ (resp. $\underline{y}$) be a collection of r (resp. s) distinct points of L (resp. $X \setminus L$). Let finally $J \in \mathcal{J}_\omega$ be generic. Then, the integer $GW_{d,k}^r(X, L; \underline{x}, \underline{y}, J)$ neither depends on the choice of $\underline{x}, \underline{y}$*

nor on the generic choice of J. The same holds true modulo two when L is homeomorphic to the real projective plane and $\partial d \neq 0 \in H_1(L; \mathbb{Z}/2\mathbb{Z})$.

The invariant provided by Theorem 3.16 can be denoted without ambiguity by $GW_{d,k}^r(X, L) \in \mathbb{Z}$, it is also left invariant under deformation of the symplectic form ω, whereas it depends in general of d and r. Examples where this invariant can be non-trivial are given by toric fibers of toric surfaces, already when counting the finite union of Maslov two discs for $r = k$, see Proposition 6.1.4 of [3].

Corollary 3.17. *Under the hypothesis of Theorem 3.16, the cardinality of the set $\mathcal{M}_{r,s}^{d,k}(X, L; J, \underline{x}, \underline{y})$ is bounded from below by $|GW_{d,k}^r(X, L)|$.*

Proof of Theorem 3.16. The proof of Theorem 3.16 goes along the same lines as the one of Theorems 3.1 and 3.6. Let J_0 and J_1 be two generic elements of $\mathcal{J}_\omega$, it suffices to prove that $GW_{d,k}^r(X, L; \underline{x}, \underline{y}, J_0) = GW_{d,k}^r(X, L; \underline{x}, \underline{y}, J_1)$. Let $\gamma : t \in [0,1] \mapsto J_t \in \mathcal{J}_\omega$ be a generic path such that $\gamma(0) = J_0$ and $\gamma(1) = J_1$, $\mathcal{M}_\gamma = \cup_{t \in [0,1]} \mathcal{M}_{r,s}^{d,k}(X, L; J_t, \underline{x}, \underline{y})$ the corresponding one-dimensional manifold and $\pi_\gamma : \mathcal{M}_\gamma \to [0,1]$ the associated projection. When $\mathcal{M}_\gamma$ is compact, Theorem 3.16 again follows from Lemmas 3.8 and 3.11. When $\mathcal{M}_\gamma$ is not compact, its Gromov compactification is given from Proposition 3.12 by adding to it $(k + 1)$-tuple of transversal immersed pseudo-holomorphic discs. Let $([u_1, J_{t_0}, \underline{z}_1, \underline{\zeta}_1]$, ... , $[u_{k+1}, J_{t_0}, \underline{z}_{k+1}, \underline{\zeta}_{k+1}])$ be such a $(k + 1)$-tuple, $D_i = Im(u_i)$, and $d_i = (u_i)_*(\Delta) \in H_2(X, L; \mathbb{Z})$, $i \in \{1, 2\}$. One of these $k + 1$ discs, say D_1, is, together with its incidence conditions, of Fredholm index -1 while the other are of vanishing Fredholm index. Again, from the hypothesis we deduce that $[\partial d_1] \circ ([\partial d_2] + \cdots + [\partial d_{k+1}]) = 0$, so that by equipping L with an orientation and denoting by R^+ (resp. R^-) the set of positive (resp. negative) intersection points between ∂D_1 and $\partial D_2 \cup \cdots \cup \partial D_{k+1}$, we have $R^+ = R^-$. The latter holds true modulo 2 when L is a real projective plane. Theorem 3.16 then follows from Propositions 3.13 and 3.14. $\qquad\square$

When L is a Lagrangian sphere, these k-discs open Gromov-Witten invariants are deduced from the one-disc invariants introduced in §3.1 in the following way.

Lemma 3.18. *Let (X, ω) be a closed connected symplectic four-manifold, $L \subset X$ be a Lagrangian sphere and $k \in \mathbb{N}^*$. Let $d \in H_2(X, L; \mathbb{Z})$ be such that $\mu_L(d) \geq k$ and $r, s \in \mathbb{N}$ such that $r + 2s = \mu_L(d) - k$. Then,*

$$GW_{d,k}^r(X, L)$$

$$= \frac{1}{k!} \sum_{d_1,\ldots,d_k \mid \sum d_i = d} \sum_{r_1,\ldots,r_k \mid \sum r_i = r} \binom{r}{r_1,\ldots,r_k} \binom{s}{s_1,\ldots,s_k} \prod_{i=1}^k GW_{d_i}^{r_i}(X, L),$$

where for $1 \le i \le k$,

$$s_i = \frac{1}{2}(\mu_L(d_i) - r_i - 1) \quad and$$

$$\binom{r}{r_1,\ldots,r_k} = \binom{r}{r_1}\binom{r - r_1}{r_2} \cdots \binom{r_{k-1} + r_k}{r_{k-1}}.$$

Note that if $r_i = \mu_L(d_i) \mod (2)$, $GW_{d_i}^{r_i}(X, L) = 0$.

Proof. Let $\underline{x}$ (resp. $\underline{y}$) be a collection of r (resp. s) distinct points of L (resp. $X \setminus L$) and $J \in \mathcal{J}_\omega$ be generic. Then, $k! \, GW_{d,k}^r(X, L)$ counts the number of ordered unions of k discs $([u_1, J, \underline{z}_1, \underline{\zeta}_1], \ldots, [u_k, J, \underline{z}_k, \underline{\zeta}_k])$ containing $\underline{x} \cup \underline{y}$ and of total homology class d. The images of $\underline{z}_i, \underline{\zeta}_i$ under u_i induce a partition of $\underline{x}, \underline{y}$ into subsets $\underline{x}_i, \underline{y}_i$ of respective cardinalities r_i, s_i, $1 \le i \le k$. The number of such partitions equals respectively $\binom{r}{r_1,\ldots,r_k}$ and $\binom{s}{s_1,\ldots,s_k}$, while $([u_1, J, \underline{z}_1, \underline{\zeta}_1], \ldots, [u_k, J, \underline{z}_k, \underline{\zeta}_k])$ provides an element counted by the product $\prod_{i=1}^k GW_{d_i}^{r_i}(X, L)$. Conversely, for every such partition, any k-tuple of discs counted by the invariant $\prod_{i=1}^k GW_{d_i}^{r_i}(X, L)$ provides an element counted by $k! \, GW_{d,k}^r(X, L)$ with respect to the same sign. Hence the result. $\square$

When L is fixed by an antisymplectic involution, the invariant χ_r^d introduced in [26], [28] counts real rational curves which thus consist of pairs of complex conjugated discs, the sum of the boundaries of which vanish in homology. However, the invariant $GW_{d,2}^r(X, L)$ seems to count a much larger number of pairs so that I do not see a relation between the two in general.

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