

THE EQUIVARIANT FUNDAMENTAL GROUPOID AS AN ORBIFOLD INVARIANT

DORETTE PRONK AND LAURA SCULL

(communicated by Emily Riehl)

Abstract

We construct a 2-category version of tom Dieck’s equivariant fundamental groupoid for representable orbifolds and show that the discrete fundamental groupoid is Morita invariant; hence it is an orbifold invariant for representable orbifolds.

1. Introduction

The equivariant fundamental category $\pi_1(G, X)$ of a G -space X was first defined by tom Dieck in [22, Definition 10.7]. This category incorporates information from the fundamental groupoids of the fixed sets X^H of X for subgroups H of G , combining them to create a category fibred in groupoids over the orbit category of G . When G is a compact Lie group, tom Dieck also defines a discrete fundamental group category $\pi_1^d(G, X)$ in [22, Definition 10.9], which removes some of the information coming from the topology of the group itself. Since their introduction, these have been used in a variety of equivariant applications, such as covering spaces, orientation theory, equivariant surgery theories, and homology theories with twisted coefficients; see [6, 7, 12, 13, 16].

In this paper, we define a discrete tom Dieck fundamental group category as a homotopy invariant for representable orbifolds. An orbifold is representable if it is a quotient of an action of a compact Lie group on a manifold. Many, possibly all, orbifolds can be represented in this way. Given such a representation, we can apply tom Dieck’s definition to create a category $\pi_1^d(G, X)$. However, the G -space representing an orbifold is not unique: two translation groupoids coming from group actions represent the same orbifold if and only if they are Morita equivalent.

Morita equivalence in general corresponds to a zig-zag of essential equivalences between groupoids. However, in [17], we showed that for translation groupoids, Morita equivalence is generated by two specific types of equivariant maps: one coming from the quotient of a subgroup which acts freely, and the other by including a space into a larger space with an induced action of a larger group (Prop. 3.5 of [17], described in detail in Section 5).

Tom Dieck’s (non-discrete) $\pi_1(G, X)$ is not necessarily invariant under Morita

The first author’s research is funded by an NSERC Discovery Grant.

Received October 4, 2019, revised February 18, 2020; published on August 5, 2020.

2010 Mathematics Subject Classification: 55Q91, 18E15, 57R18.

Key words and phrases: equivariant homotopy theory, orbifold, fundamental groupoid, groupoid, Morita invariance.

Article available at <http://dx.doi.org/10.4310/HHA.2021.v23.n1.a3>

Copyright © 2020, International Press. Permission to copy for private use granted.

equivalence. However, we will build a 2-category version $\Pi_G(X)$ of this category which is functorial with respect to equivariant maps, and show that each of our types of Morita equivalence induces a weak equivalence of 2-categories. This shows that the 2-category $\Pi_G(X)$ is an orbifold invariant. Furthermore, when we quotient this 2-category by its 2-cells we obtain tom Dieck's discrete category $\pi_1^d(G, X)$. So we arrive at the main result of this paper: $\pi_1^d(G, X)$ is an orbifold invariant for representable orbifolds.

We note that there are other ways of defining an orbifold fundamental group and groupoid. In particular, Thurston introduced the fundamental group of an orbifold as the group of deck transformations of its universal covering orbifold. This group can also be obtained as the fundamental group of the topos of sheaves on X with an action of G (or equivalently, as the fundamental group of the classifying space $B(G \times X)$). For simply connected spaces X , the Borel approach produces the groupoid $G \times X$ regardless of any potentially non-trivial fixed sets. This way of thinking has been developed further by David Roberts in his doctoral thesis [19], where he introduces the homotopy bigroupoid for a groupoid, classifying the homotopy 2-type. When applied to representable orbifolds this is in line with the Borel homotopy perspective on G -spaces. The tom Dieck fundamental groupoid that we develop in this paper is in line with the Bredon homotopy perspective on G -spaces and provides a finer invariant, as illustrated in Example 3.6. Another example of the Bredon approach was given by Johann Leida in [10]. The tom Dieck fundamental groupoid includes information of the Borel orbifold fundamental group, since this group is isomorphic to the fibre of the tom Dieck structure associated with the trivial subgroup $\{e\}$.

Acknowledgments

The authors thank the referee for asking them to clarify and hence strengthen the result of Sections 4 and 5.

2. Background on categorical constructions

In this section, we review some categorical constructions that we will use to frame our definition of tom Dieck's equivariant fundamental groupoid.

Definition 2.1. Let \mathcal{C} be a category, and $\mathcal{F}: \mathcal{C}^{\text{op}} \rightarrow \text{Cat}$ be a contravariant functor, where Cat is the 1-category of 1-categories. The Grothendieck category $\int_{\mathcal{C}} \mathcal{F}$ is defined by:

- An object is a pair (C, x) with $C \in \mathcal{C}_0$ and $x \in F(C)_0$.
- An arrow $(g, \psi): (C, x) \rightarrow (C', x')$ is a pair with $g: C \rightarrow C'$ in \mathcal{C}_1 and $\psi: x \rightarrow \mathcal{F}(g)(x')$ in $\mathcal{F}(C)_1$.
- Composition is defined using the fact that $\mathcal{F}(g): \mathcal{F}(C') \rightarrow \mathcal{F}(C)$ is a functor between categories:

$$\left((C, x) \xrightarrow{(g, \psi)} (C', x') \xrightarrow{(g', \psi')} (C'', x'') \right) = (C, x) \xrightarrow{(g' \circ g, \mathcal{F}(g)(\psi') \circ \psi)} (C'', x''),$$

This category comes with a projection functor $\int_{\mathcal{C}} \mathcal{F} \rightarrow \mathcal{C}$.

A bicategorical version of this construction was introduced in [1], and full details of this construction and its properties for both the 2-categorical and bicategorical cases were worked out in [5]. The 2-categorical case deals with a functor into the 3-category of 2-categories. This is more general than what we need to express tom Dieck's constructions. Therefore we will spell out explicitly what Buckley's category of elements [5] becomes in the case of a functor $F: C^{op} \rightarrow \mathbf{Cat}$ when C is a 2-category, and \mathbf{Cat} is the 2-category of 1-categories. For further details we refer to [5].

Definition 2.2. Let C be a 2-category, and $\mathcal{F}: C^{op} \rightarrow \mathbf{Cat}$ be a contravariant 2-functor. The 2-dimensional Grothendieck construction $\int_C \mathcal{F}$ is a 2-category defined by:

- An object is a pair (C, x) with $C \in \mathcal{C}_0$ and $x \in F(C)_0$ as in Definition 2.1.
- An arrow $(g, \psi): (C, x) \rightarrow (C', x')$ is a pair with $g: C \rightarrow C'$ in \mathcal{C}_1 and $\psi: x \rightarrow \mathcal{F}(g)(x')$ in $\mathcal{F}(C)_1$ as in Definition 2.1.
- A 2-cell $\alpha: (g, \psi) \Rightarrow (g', \psi'): (C, x) \rightrightarrows (C', x')$ is a 2-cell $\alpha: g \Rightarrow g'$ in C such that the diagram

$$\begin{array}{ccc} x & \xrightarrow{\psi} & \mathcal{F}(g)(x') \\ \parallel & & \downarrow \mathcal{F}(\alpha)_{x'} \\ x & \xrightarrow{\psi'} & \mathcal{F}(g')(x') \end{array}$$

commutes in $\mathcal{F}(C)$.

Horizontal and vertical composition of 2-cells is defined using the usual compositions of natural transformations. It is obvious that vertical composition thus defined gives rise to the required commutative squares. Horizontal composition is a little more involved, and we include the details here.

Let $\alpha: (g, \psi) \Rightarrow (g', \psi'): (C, x) \rightrightarrows (C', x')$ and $\beta: (h, \theta) \Rightarrow (h', \theta'): (C', x') \rightrightarrows (C'', x'')$ be 2-cells in $\int_C \mathcal{F}$. Thus, we have commuting squares

$$\begin{array}{ccc} x \xrightarrow{\psi} \mathcal{F}(g)(x') & & x' \xrightarrow{\varphi} \mathcal{F}(h)(x'') \\ \parallel \quad \downarrow \mathcal{F}(\alpha)_{x'} & \text{in } \mathcal{F}(C), & \parallel \quad \downarrow \mathcal{F}(\beta)_{x''} \\ x \xrightarrow{\psi'} \mathcal{F}(g')(x') & & x' \xrightarrow{\varphi'} \mathcal{F}(h')(x'') \end{array} \quad \text{and} \quad (1)$$

Apply both $\mathcal{F}(g)$ and $\mathcal{F}(g')$ to the second square in (1) to obtain two commuting squares in $\mathcal{F}(C)$. By the naturality of $\mathcal{F}(\alpha)$ the two resulting squares are part of a commuting cube. We append to this cube the first commuting square from (1):

$$\begin{array}{ccccc} & & x & \xrightarrow{\psi} & \mathcal{F}(g)(x') & \xrightarrow{\mathcal{F}(g)(\varphi)} & \mathcal{F}(g)\mathcal{F}(h)(x'') \\ & \swarrow & \parallel & \swarrow \mathcal{F}(\alpha)_{x'} & \parallel & \swarrow \mathcal{F}(\alpha)_{\mathcal{F}(h)(x'')} & \downarrow \mathcal{F}(g)(\mathcal{F}(\beta)_{x''}) \\ x & \xrightarrow{\psi'} & \mathcal{F}(g')(x') & \xrightarrow{\mathcal{F}(g')(\varphi)} & \mathcal{F}(g')\mathcal{F}(h)(x'') & & \\ & \swarrow & \parallel & \swarrow \mathcal{F}(\alpha)_{x'} & \parallel & \swarrow \mathcal{F}(\alpha)_{\mathcal{F}(h')(x'')} & \downarrow \mathcal{F}(g)(\mathcal{F}(\beta)_{x''}) \\ & & \mathcal{F}(g)(x') & \xrightarrow{\mathcal{F}(g)(\varphi')} & \mathcal{F}(g)\mathcal{F}(h')(x'') & & \\ & \swarrow & \parallel & \swarrow \mathcal{F}(\alpha)_{x'} & \parallel & \swarrow \mathcal{F}(\alpha)_{\mathcal{F}(h')(x'')} & \downarrow \mathcal{F}(g)(\mathcal{F}(\beta)_{x''}) \\ & & \mathcal{F}(g')(x') & \xrightarrow{\mathcal{F}(g')(\varphi')} & \mathcal{F}(g')\mathcal{F}(h')(x'') & & \end{array}$$

Then $\mathcal{F}(\beta \circ \alpha) = \mathcal{F}(g')(\mathcal{F}(\beta)_{x''}) \circ \mathcal{F}(\alpha)_{\mathcal{F}(h)(x'')} = \mathcal{F}(\alpha)_{\mathcal{F}(h')(x'')} \circ \mathcal{F}(g)(\mathcal{F}(\beta)_{x''})$ is the diagonal of the right side of the cube, so the diagram

$$\begin{array}{ccc} x & \xrightarrow{\mathcal{F}(g)(\varphi) \circ \psi} & \mathcal{F}(g)\mathcal{F}(h)(x'') \\ \parallel & & \downarrow \mathcal{F}(\beta \circ \alpha) \\ x & \xrightarrow{\mathcal{F}(g')(\varphi') \circ \psi'} & \mathcal{F}(g')\mathcal{F}(h')(x'') \end{array}$$

commutes and defines the horizontal composition $\mathcal{F}(\beta \circ \alpha)$.

3. The equivariant fundamental groupoid

We will present tom Dieck's equivariant fundamental groupoid from [22] from a categorical point of view, using the framework of the previous section.

Fix a compact Lie group G . When studying a G -space X , we often look at the diagram of its fixed sets $\{X^H\} = \{x \in X \mid hx = x \text{ for all } h \in H\}$ for the closed subgroups $H \leq G$, with the inclusion maps between these spaces. This is a diagram in the shape of the orbit category \mathcal{O}_G of G . This category \mathcal{O}_G has objects given by canonical orbits G/H for a closed subgroup of G , with arrows defined by G -equivariant maps between them. Explicitly, an equivariant map $G/H \rightarrow G/K$ is defined by $eH \mapsto \alpha K$ for some $\alpha \in G$ such that $H \leq \alpha K \alpha^{-1}$; then equivariance requires that $gH \rightarrow g\alpha K$. Two elements $\alpha, \beta \in G$ define the same map when $\alpha K = \beta K$, so the map is defined by a coset αK . Thus, maps $G/H \rightarrow G/K$ are defined by elements $\alpha \in (G/K)^H$.

A G -map $G/H \xrightarrow{x} X$ is determined by $eH \mapsto x$ for some point $x \in X^H$; then $gH \mapsto gx$. We think of such a map as defining a G -point in X , consisting of the point x and its orbit $\{gx\}$. Then X defines a contravariant functor $\Phi: \mathcal{O}_G \rightarrow \mathbf{Spaces}$: $G/H \mapsto X^H$, and if $\alpha: G/H \rightarrow G/K$, then given $G/K \xrightarrow{x} X$ we can compose and get $G/H \xrightarrow{\alpha} G/K \xrightarrow{x} X$. This is defined by $eH \mapsto \alpha K \mapsto \alpha x$, so $x \circ \alpha$ is just given by the action αx : it is easy to confirm that if $\alpha \in (G/K)^H$ and $x \in X^K$, then $\alpha x \in X^H$ and the action agrees with the composition above. In what follows, we will use the group action notation, αx , rather than the composition notation.

We can create equivariant invariants as diagrams indexed by \mathcal{O}_G by applying topological invariants to the diagram of fixed sets. Tom Dieck used this idea to create a category out of the fundamental groupoids of the fixed sets.

Definition 3.1 ([22, Definition 10.7]). Objects of $\pi_1(G, X)$ are G -maps $x: G/H \rightarrow X$. An arrow from $x: G/H \rightarrow X$ to $y: G/K \rightarrow X$ is a pair $(\alpha, [\gamma])$ consisting of a G -map $\alpha: G/H \rightarrow G/K$, and a G -homotopy class (rel $G/H \times \partial I$) of G -paths $\gamma: G/H \times I \rightarrow X$ such that $\gamma(0) = x$ and $\gamma(1) = \alpha y$.

We can interpret $\pi_1(G, X)$ as a Grothendieck category as in Definition 2.1. Define the functor $\underline{\Pi}_X$ from spaces into the category of groupoids: $\underline{\Pi}_X(G/H) = \Pi(X^H)$ is the fundamental groupoid of X^H . Explicitly, $\underline{\Pi}_X(G/H)$ is the category which has objects given by equivariant maps $G/H \xrightarrow{x} X$, or equivalently, points $x \in X^H$, and arrows given by homotopy classes of paths in X^H .

For $\alpha: G/H \rightarrow G/K$, we define a functor $\underline{\Pi}_X(\alpha): \underline{\Pi}_X(G/K) \rightarrow \underline{\Pi}_X(G/H)$. This $\underline{\Pi}_X(\alpha)$ is the functor $\Pi(X^K) \rightarrow \Pi(X^H)$ which sends an object $x \in X^K$ to $\alpha x \in X^H$,

and a homotopy class of paths $[\gamma]$ in X^K to $[\alpha\gamma]$ in X^H . Then we consider the Grothendieck category

$$\int_{\mathcal{O}_G} \underline{\Pi}_X.$$

Explicitly, objects are pairs $(G/H, x)$ with $x \in X^H$, and arrows are pairs

$$(\alpha, [\gamma]): (G/H, x) \rightarrow (G/K, y),$$

where $\alpha: G/H \rightarrow G/K$ and $[\gamma]$ is a homotopy class (rel endpoints) of paths in X^H from x to αy , recovering Definition 3.1. The resulting category is not a groupoid, but rather a category fibred in groupoids over \mathcal{O}_G .

For non-discrete groups, tom Dieck also gives a version of the fundamental groupoid which accounts for the topology of G .

Definition 3.2 ([22], Definition 10.9). Objects of $\pi_1^d(G, X)$ are again G -maps $x: G/H \rightarrow X$. Morphisms are now given by equivalence classes of the morphisms of Definition 3.1, where $(\alpha_0, [\gamma_0])$ is equivalent to $(\alpha_1, [\gamma_1])$ when there exists a G -homotopy $\sigma: G/H \times I \rightarrow G/K$ between α_0 and α_1 and a G -homotopy $\Lambda: G/H \times I \times I \rightarrow X$ such that

$$\begin{aligned} \Lambda(gH, 0, t) &= x, \\ \Lambda(gH, 1, t) &= \sigma(t)y, \\ \Lambda(gH, s, 0) &= \gamma_0(s), \\ \Lambda(gH, s, 1) &= \gamma_1(s). \end{aligned}$$

To define $\pi_1^d(G, X)$ categorically, we use Definition 2.2, a 2-categorical version of the Grothendieck category. When G is a compact Lie group, \mathcal{O}_G is a 2-category: $\mathcal{O}_G[G/H, G/K] \cong (G/K)^H$ is a topological space. So given two arrows $\alpha, \beta: G/H \rightarrow G/K$, we define a 2-cell $[s]: \alpha \rightarrow \beta$ to be a homotopy class (rel endpoints) of paths, $[s]: I \rightarrow (G/K)^H$, from α to β . Then the functor $\underline{\Pi}_X$ defined above can be extended to a 2-functor $\underline{\Pi}_X: \mathcal{O}_G \rightarrow \mathbf{Cat}$, where \mathbf{Cat} is the 2-category of small categories. For $G/H \in \mathcal{O}_G$, $\underline{\Pi}_X(G/H) = \Pi(X^H)$, the fundamental groupoid of X^H , and $\underline{\Pi}_X(\alpha)$ is the functor $\Pi(X^K) \rightarrow \Pi(X^H)$ as described above. Given a 2-cell in \mathcal{O}_G defined by a homotopy class $[\sigma]$ of paths from α to β in $\mathcal{O}_G[G/H, G/K]$, we define a natural transformation $\underline{\Pi}_X([\sigma]): \underline{\Pi}_X(\alpha) \rightarrow \underline{\Pi}_X(\beta)$. This natural transformation has components $\underline{\Pi}_X([\sigma])_x = \sigma x$ for $x: G/K \rightarrow X$:

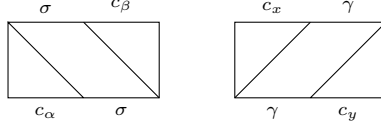
$$\begin{array}{ccc} \alpha x & \xrightarrow{[\sigma x]} & \beta x \\ [\alpha\gamma] \downarrow & & \downarrow [\beta\gamma] \\ \alpha y & \xrightarrow{[\sigma y]} & \beta y. \end{array}$$

This is well-defined, since if σ' is homotopic to σ in $(G/K)^H$, then the path defined by $\sigma'x$ is homotopic to σx in X^H . The compositions are defined by $\sigma x * \beta\gamma$ and $\alpha\gamma * \sigma y$, where $*$ denotes the usual concatenation of paths. These can be written as

$$\begin{aligned} \sigma x * \beta\gamma &= (\sigma * c_\beta)(c_x * \gamma), \\ \alpha\gamma * \sigma y &= (c_\alpha * \sigma)(\gamma * c_y), \end{aligned}$$

where c denotes the constant path at the respective point. It is straightforward to show that these are homotopic by sliding σ along from $0 \leq t \leq \frac{1}{2}$ to $\frac{1}{2} \leq t \leq 1$, and

sliding γ in the opposite way:



Therefore this defines a natural transformation as required.

Definition 3.3. Apply Definition 2.2 to the 2-functor $\underline{\Pi}_X: \mathcal{O}_G \rightarrow \text{Cat}$. This defines a Grothendieck 2-category:

$$\Pi_G(X) = \int_{\mathcal{O}_G} \underline{\Pi}_X.$$

The category obtained by identifying all arrows connected by 2-cells will be denoted by $\Pi_G^d(X)$.

The 2-category $\Pi_G(X)$ and its quotient $\Pi_G^d(X)$ will be our main objects of study from here on. We begin by explicitly describing $\Pi_G(X)$. Objects are pairs $(G/H, x)$ with $x \in X^H$, and arrows are pairs

$$(\alpha, [\gamma]): (G/H, x) \rightarrow (G/K, y),$$

where $\alpha: G/H \rightarrow G/K$ and $[\gamma]$ is a homotopy class (rel endpoints) of paths in X^H from x to αy , as in the 1-category case.

To describe 2-cells, let $(\alpha, [\gamma]), (\alpha', [\gamma']): (G/H, x) \rightarrow (G/K, y)$ be maps in $\int_{\mathcal{O}_G} \underline{\Pi}_X$. A 2-cell $(\alpha, [\gamma]) \Rightarrow (\alpha', [\gamma'])$ is given by a homotopy class of paths $[\sigma]: \alpha \rightarrow \alpha'$ in $\mathcal{O}_G[G/H, G/K]$ such that the following diagram commutes in $\underline{\Pi}_X(G/H)$:

$$\begin{array}{ccc} x & \xrightarrow{[\gamma]} & \alpha y \\ id_x \Big\| & & \Big\| [\sigma y] \\ x & \xrightarrow{[\gamma']} & \alpha' y \end{array} .$$

Arrows of $\underline{\Pi}_X(G/H)$ are homotopy classes of paths in X^H , and so this means that for any choice of representatives γ, γ' , and σ , we have that the concatenation $\gamma * \sigma y$ is homotopic (rel endpoints) to γ' in X^H . So there is a homotopy Λ in X^H that fills the following square

$$\begin{array}{ccc} x & \xrightarrow{\gamma} & \alpha y \\ id_x \Big\| & \Lambda(\gamma, \gamma', \sigma) & \Big\| \sigma y \\ x & \xrightarrow{\gamma'} & \alpha' y \end{array} .$$

Then $\pi_1^d(G, X)$ from Definition 3.2 is exactly the quotient of the 2-category $\Pi_G(X)$ by these 2-cells. So tom Dieck's discrete category is exactly $\Pi_G^d(X)$.

For future use, we explicitly describe the horizontal composition of 2-cells for this category. Given a 2-cell $[\sigma]$ from $(\alpha, [\gamma])$ to $(\alpha', [\gamma'])$ and a 2-cell $[\omega]$ from $(\beta, [\zeta])$ to

$(\beta', [\zeta'])$, we know that we have homotopies

$$\begin{array}{ccc} x & \xrightarrow{\gamma} & \alpha y \\ \parallel & & \downarrow \sigma y \\ x & \xrightarrow{\gamma'} & \alpha' y \end{array} \quad \text{and} \quad \begin{array}{ccc} y & \xrightarrow{\zeta} & \beta z \\ \parallel & & \downarrow \omega z \\ y & \xrightarrow{\zeta'} & \beta' z \end{array} .$$

The composition of $[\sigma]$ and $[\omega]$ is defined by applying both α and α' to the second square, to get

$$\begin{array}{ccc} \alpha y & \xrightarrow{\alpha \zeta} & \alpha \beta z \\ \parallel & & \downarrow \alpha \omega z \\ \alpha y & \xrightarrow{\alpha \zeta'} & \alpha \beta' z \end{array} \quad \text{and} \quad \begin{array}{ccc} \alpha' y & \xrightarrow{\alpha' \zeta} & \alpha' \beta z \\ \parallel & & \downarrow \alpha' \omega z \\ \alpha' y & \xrightarrow{\alpha' \zeta'} & \alpha' \beta' z \end{array} .$$

Then we form the diagram

$$\begin{array}{ccccc} & & x & \xrightarrow{\gamma} & \alpha y & \xrightarrow{\alpha \zeta} & \alpha \beta z \\ & \swarrow & \parallel & \searrow \sigma y & \parallel & \swarrow \sigma \beta z & \downarrow \alpha \omega z \\ x & \xrightarrow{\gamma'} & \alpha' y & \xrightarrow{\alpha' \zeta} & \alpha' \beta z & & \\ & \swarrow & \parallel & \searrow \sigma y & \parallel & \swarrow \sigma \beta' z & \\ & & \alpha' y & \xrightarrow{\alpha' \zeta'} & \alpha' \beta' z & & \end{array}$$

Define the composition by

$$[\sigma][\omega] = [S] = [\sigma \beta * \alpha' \omega] \simeq [\alpha \omega * \sigma \beta'] .$$

This is a 2-cell from $(\alpha \beta, [\gamma * \alpha \zeta])$ to $(\alpha' \beta', [\gamma' * \alpha' \zeta'])$ as required, since we have a homotopy

$$\begin{array}{ccc} x & \xrightarrow{\gamma * \alpha \zeta} & \alpha \beta z \\ \parallel & & \downarrow S z \\ x & \xrightarrow{\gamma' * \alpha' \zeta'} & \alpha' \beta' z \end{array} .$$

Example 3.4. Let $G = \mathbb{Z}/2 = \{e, \tau\}$ and $X = S^1$ where τ acts on X by reflection through the horizontal axis. Then $X^G = \{E, W\}$, where E and W are the east and west cardinal points on the circle, and $X^e = S^1$. Then the objects of $\Pi_G(X)$ consist of $(G/e, \lambda)$ for any $\lambda \in S^1$, and the points $(G/G, E)$ and $(G/G, W)$.

In between the points $(G/e, \lambda_1)$ and $(G/e, \lambda_2)$, there are arrows of type $(e, [\gamma])$ where γ is a path in S^1 from λ_1 to λ_2 ; these correspond to winding numbers in \mathbb{Z} . Additionally, there are arrows of type $(\tau, [\zeta])$ where ζ is a path from λ_1 to $\tau \lambda_2$. Together with the arrows of the first type, we get a D_∞ worth of arrows between points of this type.

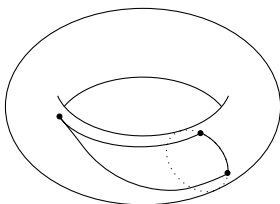
There are also arrows from $(G/e, \lambda)$ to $(G/G, E)$, again corresponding to winding numbers in \mathbb{Z} ; and similarly to $(G/G, W)$. Since G is discrete, there are no non-trivial

2-cells; so $\Pi_G^d(X) = \Pi_G(X)$ in this case. A skeleton of this category is given below; for more details, see [4].

$$\begin{array}{ccc}
 & \begin{array}{c} D_\infty \\ \curvearrowright \\ (G/e, \lambda) \end{array} & \\
 \mathbb{Z} \swarrow & & \searrow \mathbb{Z} \\
 (G/G, E) & & (G/G, W)
 \end{array}$$

Example 3.5. Let $G = S^1$, the circle group, and $X = T^2 = S^1 \times S^1$, where the action is given by $\lambda(\alpha, \beta) = (\alpha, \lambda\beta)$. Then the fixed set X^H is empty for any $H \neq \{e\}$, so the objects of $\Pi_G(X)$ are all of the form $(G/e, (\alpha, \beta))$. Between objects $(G/e, (\alpha_1, \beta_1))$ and $(G/e, (\alpha_2, \beta_2))$, there are maps defined by $(\lambda, [\gamma])$ for $\lambda \in S^1$, where γ is a path in T^2 from (α_1, β_1) to $(\alpha_2, \lambda\beta_2)$. Again, we can classify $[\gamma]$ using winding numbers in the α and β coordinates, so there are $S^1 \times (\mathbb{Z} \oplus \mathbb{Z})$ worth of arrows between any two points. This time, however, G has non-trivial topology, so many of these are connected by 2-cells. In fact, we can look at the projection of γ onto the β coordinate and use this to define a path σ in S^1 . Then we have a 2-cell from $(e, [\gamma])$ to $(e, [\gamma * \sigma^{-1}(\alpha_2, \beta_2)])$, showing that every arrow has a 2-cell connecting it to an arrow which has the same projection onto the first coordinate, but is constant in the second coordinate:

$$\begin{array}{ccc}
 (\alpha_1, \beta_1) & \xrightarrow{\gamma} & (\alpha_2, \lambda\beta_2) \\
 id \Big| & & \Big| \sigma^{-1}(\alpha_2, \beta_2) \\
 (\alpha_1, \beta_1) & \xrightarrow{\gamma'} & (\alpha_2, \beta_1) \quad .
 \end{array}$$



Thus two arrows are connected by 2-cells if the projections of the paths onto the first coordinates are homotopic, and $\Pi_G^d(X)$ has a \mathbb{Z} worth of paths between any two points. Hence, $\Pi_G^d(X)$ is a category equivalent to the fundamental groupoid of the circle.

The following example gives a case where the extra information coming from the fixed sets contains important topological information.

Example 3.6. Let $G = \mathbb{Z}/2$ and $X = S^2$, with the group acting by reflection through the equatorial plane. Since all paths are homotopic in the sphere, the fundamental groupoid contains only two arrows between points $(G/e, x)$ and $(G/e, y)$: $(e, [\gamma])$ where γ is the unique homotopy class of paths from x to y , and $(\tau, [\gamma'])$ where γ' is the unique homotopy class of paths from x to τy . However, when we look at arrows between points of the form $(G/G, x)$ and $(G/G, y)$, where $x, y \in X^G$, the arrows correspond

to homotopy classes of paths from x to y inside of the fixed set X^G , which is the equatorial circle. Thus these points have a \mathbb{Z} worth of arrows connecting them, and the category has recovered information about the fundamental groupoid of the fixed set.

Remark 3.7. Tom Dieck also defined a notion of an equivariant π_0 , such that each $\pi_0(G, X)$ can be viewed as a Grothendieck category but this notion is not invariant under Morita equivalence.

4. Functoriality of $\Pi_G(X)$

In this section, we study the functoriality of the $\Pi_G(X)$ construction. To do this we will represent a G -space X for a Lie group G by a smooth translation groupoid $G \times X$. We define a 2-category of translation groupoids and equivariant smooth maps, denoted EqTrGpd , below. Our goal is to show that the construction of $\Pi_G(X)$ extends to a 2-functor Π from EqTrGpd to the 2-category of small 2-categories with 2-functors and pseudo natural transformations.

We begin by describing the 2-category of translation groupoids EqTrGpd in detail.

Definition 4.1. Let G be a Lie group with a smooth left action on a manifold M . Then the translation groupoid (also called action groupoid) $G \times M$ is defined as follows. The space of objects is M , and the space of arrows is defined to be $G \times M$ with the source of an arrow (g, x) defined by $s(g, x) = x$, and the target by using the action of G on M , $t(g, x) = gx$. So (g, x) is an arrow from x to gx . The units map is defined by $u(x) = (e, x)$, where e is the identity element in G , composition by $(g', gx) \circ (g, x) = (g'g, x)$, and inverses by $(x, g)^{-1} = (gx, g^{-1})$.

Definition 4.2. An *equivariant map* $G \times X \rightarrow H \times Y$ between translation groupoids is a pair (φ, f) , where $\varphi: G \rightarrow H$ is a group homomorphism and $f: X \rightarrow Y$ is a φ -equivariant smooth map, i.e., $f(gx) = \varphi(g)f(x)$ for $g \in G$ and $x \in X$.

The maps described in Definition 4.2 form a particular kind of smooth functors between the smooth groupoids of Definition 4.1. We want to consider the 2-category of translation groupoids, with 2-cells given by smooth natural transformations between these functors.

Definition 4.3. Let $(\varphi_1, f_1), (\varphi_2, f_2): G_1 \times X_1 \rightrightarrows G_2 \times X_2$ be equivariant smooth maps. A smooth natural transformation $(\varphi_1, f_1) \Rightarrow (\varphi_2, f_2)$ is given by a smooth map $r: X_1 \rightarrow G_2 \times X_2$ such that $r(x): f_1(x) \rightarrow f_2(x)$ (as arrow in $G_2 \times X_2$) for all $x \in X_1$, satisfying the naturality condition. So r is determined by a map $\hat{r}: X_1 \rightarrow G_2$ such that $\hat{r}(x) = r_x$ satisfies $r_x f_1(x) = f_2(x)$. The naturality condition is equivalent to requiring that for any $g \in G_1$ the following diagram commutes in $G_2 \times X_2$:

$$\begin{array}{ccc} f_1(x) & \xrightarrow{(r_x, f_1(x))} & f_2(x) \\ (\varphi_1(g), f_1(x)) \downarrow & & \downarrow (\varphi_2(g), f_2(x)) \\ f_1(gx) = \varphi_1(g)f_1(x) & \xrightarrow{(r_{gx}, f_1(gx))} & f_2(gx) = \varphi_2(g)f_2(x) \end{array} .$$

Thus, $r_{gx}\varphi_1(g) = \varphi_2(g)r_x$ in G_2 , for all $g \in G_1$ and $x \in X_1$.

We will show that $\Pi_G(X)$ extends to a 2-functor $\Pi: \mathbf{EqTrGpd} \rightarrow 2\text{-Cat}$, where 2-Cat is the 2-category of small 2-categories, 2-functors and pseudo natural transformations. We start by considering the effect of a map as in Definition 4.2 on the orbit categories.

Lemma 4.4. *If $\varphi: G_1 \rightarrow G_2$ is a group homomorphism, then we have a functor $\mathcal{O}_{G_1} \rightarrow \mathcal{O}_{G_2}$ defined by $\varphi(G_1/H) = G_2/\varphi(H)$, and $\varphi(\alpha): G_2/\varphi(H) \rightarrow G_2/\varphi(K)$ for $\alpha: G_1/H \rightarrow G_1/K$.*

Proof. The map α is defined by a coset αK where $H \subseteq \alpha K \alpha^{-1}$. Then $\varphi(\alpha)\varphi(K)$ defines a coset and $\varphi(H) \subseteq \varphi(\alpha)\varphi(K)\varphi(\alpha)^{-1}$. \square

Next, we verify that an equivariant map respects fixed sets.

Lemma 4.5. *Let $(\varphi, f): G_1 \times X_1 \rightarrow G_2 \times X_2$ be a homomorphism of translation groupoids. If $x \in X_1^H$ for $H \leq G_1$, then $f(x) \in X_2^{\varphi(H)}$.*

Proof. Suppose that $x \in X_1^H$, so $hx = x$ for all $h \in H$. Then $f(hx) = f(x)$, and so $\varphi(h)f(x) = f(x)$. So $f(x) \in X_2^{\varphi(H)}$ as claimed. \square

Now we define Π on the maps of Definition 4.2.

Proposition 4.6. *Let $(\varphi, f): G_1 \times X_1 \rightarrow G_2 \times X_2$. Then we get an induced 2-functor between the 2-categories, $\Pi(\varphi, f): \Pi_{G_1}(X_1) \rightarrow \Pi_{G_2}(X_2)$*

Proof. We have shown in Lemma 4.4 that $G_1/H \rightarrow G_2/\varphi(H)$ defines a functor from \mathcal{O}_{G_1} to \mathcal{O}_{G_2} . We define a functor $F = \Pi(\varphi, f): \Pi_{G_1}(X_1) \rightarrow \Pi_{G_2}(X_2)$ as follows:

Objects: $F(G_1/H, x) = (G_2/\varphi(H), f(x))$. If $x \in X_1^H$, then Lemma 4.5 shows that $f(x) \in X_2^{\varphi(H)}$, so this is well-defined.

Arrows: If $(\alpha, [\gamma]): (G_1/H, x) \rightarrow (G_1/K, y)$ is an arrow in $\Pi_{G_1}(X_1)$, then $\alpha: G_1/H \rightarrow G_1/K$ and $[\gamma]$ is a homotopy class of paths $x \rightarrow \alpha y$ in X_1^H . Then $f[\gamma] = [f\gamma]$ defines a homotopy class of paths from $f(x)$ to $f(\alpha y) = \varphi(\alpha)f(y)$, defining an arrow $F(\alpha, [\gamma]) = (\varphi(\alpha), f[\gamma]): (G_2/\varphi(H), f(x)) \rightarrow (G_2/\varphi(K), f(y))$ in $\Pi_{G_2}(X_2)$.

We show that this assignment preserves composition on the nose. Given

$$(G_1/H, x) \xrightarrow{(\alpha, [\gamma])} (G_1/K, y) \xrightarrow{(\beta, [\delta])} (G_1/L, z), \quad (2)$$

its composition in $\Pi_{G_1}(X_1)$ is given by

$$(\alpha\beta, [\gamma] * \alpha[\delta]): (G_1/H, x) \rightarrow (G_1/L, z).$$

Taking the images of the arrows in (2) under $\Pi(\varphi, f)$ gives us

$$(G_2/\varphi(H), f(x)) \xrightarrow{(\varphi(\alpha), f[\gamma])} (G_2/\varphi(K), f(y)) \xrightarrow{(\varphi(\beta), f[\delta])} (G_2/\varphi(L), f(z)).$$

Composition of these arrows in $\Pi_{G_2}(X_2)$ results in

$$(\varphi(\alpha)\varphi(\beta), f[\gamma] * \varphi(\alpha)f[\delta]): (G_2/\varphi(H), f(x)) \rightarrow (G_2/\varphi(L), f(z)).$$

Now, $(\varphi(\alpha)\varphi(\beta), f[\gamma] * \varphi(\alpha)f[\delta]) = (\varphi(\alpha\beta), f[\gamma] * f[\alpha\delta]) = \Pi(\varphi, f)(\alpha\beta, [\gamma] * \alpha[\delta])$ as claimed.

2-Cells: Suppose that $[\sigma]$ is a homotopy class of maps $G_1/H \rightarrow G_1/K$, given by $\sigma: I \rightarrow (G_1/K)^H$ from α to α' such that the following commutes:

$$\begin{array}{ccc} x & \xrightarrow{[\gamma]} & \alpha y \\ id_x \parallel & & \downarrow [\sigma y] \\ x & \xrightarrow{[\gamma']} & \alpha' y \end{array} .$$

So we have a homotopy Λ from $\gamma * \sigma y$ to γ' . Define $F([\sigma]) = [\varphi(\sigma)]: \varphi(\alpha) \rightarrow \varphi(\alpha')$. This gives a homotopy class of paths in $(G_2/\varphi(H))^{\varphi(K)}$, and $f(\Lambda)$ provides a homotopy from $f(\gamma) * \varphi(\sigma)f(y)$ to $f(\gamma')$ making the following diagram commute:

$$\begin{array}{ccc} f(x) & \xrightarrow{[\gamma]} & \varphi(\alpha)f(y) \\ id_{f(x)} \parallel & & \downarrow [\varphi(\sigma)f(y)] \\ f(x) & \xrightarrow{[\gamma']} & \varphi(\alpha')f(y) \end{array} .$$

It can be checked by a straightforward verification that this preserves both horizontal and vertical composition. \square

Lastly, we extend the definition of Π to the 2-cells of EqTrGpd .

Proposition 4.7. *Let r be a natural transformation of smooth groupoids, $r: (\varphi_1, f_1) \Rightarrow (\varphi_2, f_2): G_1 \times X_1 \Rightarrow G_2 \times X_2$. Then we have an induced pseudo natural transformation $\Pi(r): \Pi(\varphi_1, f_1) \Rightarrow \Pi(\varphi_2, f_2)$.*

Proof. Given a natural transformation r , represented by a smooth map $r: X_1 \rightarrow G_2$, $x \mapsto r_x$, we will define a map from $\Pi_{G_1}(X_1)_0 \rightarrow \Pi_{G_2}(X_2)_1$ such that an object $(G/H, x)$ gets mapped to an arrow $(\beta, [\gamma])$ where γ is a path from $f_1(x)$ to $\beta f_2(x)$ in $X_2^{\varphi(H)}$. First, we claim that $\varphi_1(H) = r_x^{-1}\varphi_2(H)r_x$: we know that $r_{hx}\varphi_1(h) = \varphi_2(h)r_x$. But since $x \in X^H$, $hx = x$ and so $r_x\varphi_1(h) = \varphi_2(h)r_x$, and hence $\varphi_1(h) = r_x^{-1}\varphi_2(h)r_x$. Therefore r_x^{-1} defines a map $G_2/\varphi_1(H) \rightarrow G_2/\varphi_2(H)$ in \mathcal{O}_{G_2} .

So now define the components of the pseudo natural transformation: to every point $(G/H, x)$ we assign the arrow

$$(r_x^{-1}, [c_{f_1(x)}]): (G_2/\varphi_1(H), f_1(x)) \rightarrow (G_2/\varphi_2(H), f_2(x)),$$

where $c_{f_1(x)}$ is the constant path from $f_1(x)$ to $r_x^{-1}f_2(x) = f_1(x)$. Now let

$$(\alpha, [\gamma]): (G_1/H, x) \rightarrow (G_1/K, y)$$

be an arrow of $\Pi_{G_1}(X_1)$, and consider the naturality square

$$\begin{array}{ccc} f_1(x) & \xrightarrow{(r_x^{-1}, [c_{f_1(x)}])} & f_2(x) \\ (\varphi_1(\alpha), [f_1(\gamma)]) \downarrow & & \downarrow (\varphi_2(\alpha), [f_2(\gamma)]) \\ f_1(gx) & \xrightarrow{(r_y^{-1}, [c_{f_1(y)}])} & f_2(y) \end{array} .$$

Comparing the two compositions, we see that going one way we have

$$(r_x^{-1}\varphi_2(\alpha), [c_{f_1(x)} * r_x^{-1}f_2(\gamma)]) = (r_x^{-1}\varphi_2(\alpha), [r_x^{-1}f_2(\gamma)]).$$

Going the other way gives

$$(\varphi_1(\alpha)r_y^{-1}, [f_1(\gamma) * c_{f_1(y)}]) = (\varphi_1(\alpha)r_y^{-1}, [f_1(\gamma)]).$$

These are not equal, so this is not a strict natural transformation.

To define this as a pseudo natural transformation, to every morphism $(\alpha, [\gamma])$ we need to assign a 2-cell $[s]: \varphi_1(\alpha)r_y^{-1} \rightarrow r_x^{-1}\varphi_2(\alpha)$ in G_2 which will fill in the diagram

$$\begin{array}{ccc} f_1(x) & \xrightarrow{f_1(\gamma)} & \varphi_1(\alpha)r_y^{-1}f_2(y) \\ \parallel & & \\ f_1(x) & \xrightarrow{r_x^{-1}f_2(\gamma)} & r_x^{-1}\varphi_2(\alpha)f_2(y) \end{array}$$

and satisfy the required coherence properties. We will leverage the fact that we know that $f_1(\gamma) = r_\gamma^{-1}f_2(\gamma)$. So we are trying to compare the following:

$$\begin{array}{ccc} f_1(x) & \xrightarrow{r_\gamma^{-1}f_2(\gamma)} & r_y^{-1}\varphi_2(\alpha)f_2(y) \\ \parallel & & \\ f_1(x) & \xrightarrow{r_x^{-1}f_2(\gamma)} & r_x^{-1}\varphi_2(\alpha)f_2(y), \end{array}$$

where across the top the adjustment elements r_γ are changing while the single adjustment element r_x^{-1} has been used along the bottom. Written in this form, it becomes evident that we can define a 2-cell

$$s(\alpha, [\gamma])(t) = s(t) = r_{\gamma(t-1)}^{-1}\varphi_2(\alpha).$$

We can define a homotopy between $f_1(\gamma) * s(t)f_2(y)$ and $r_x^{-1}f_2(\gamma)$ by writing the first map as

$$\begin{aligned} f_1(\gamma) * s(t)f_2(y) &= \left(r_{\gamma(t)}^{-1}f_2(\gamma)\right) * \left(r_{\gamma(1-t)}^{-1}\varphi_2(\alpha)f_2(y)\right) \\ &= \left(r_{\gamma(t)}^{-1} * r_{\gamma(1-t)}^{-1}\right) \left(f_2(\gamma) * c_{f_2(\alpha y)}\right). \end{aligned}$$

Then it is easy to write a homotopy collapsing the first part to the constant map r_x^{-1} and expanding the second to $f_2(\gamma)$:

$$\begin{array}{ccc} \begin{array}{ccc} r_{\gamma(t)}^{-1} & r_{\gamma(1-t)}^{-1} & \\ \diagdown & & \diagup \\ & c_x & c_x \\ \diagup & & \diagdown \end{array} & & \begin{array}{ccc} f_1(\gamma) & c_{f_2(\alpha y)} & \\ & \diagdown & \\ & & \\ & \diagup & \\ f_1(\gamma) & & \end{array} \end{array}$$

Coherence conditions can be verified by a straightforward calculation. \square

Theorem 4.8. *The assignment of Π on objects, $\Pi(G, X) = \Pi_G(X)$ as in Definition 3.3, on arrows as in Proposition 4.6 and on 2-cells as in Proposition 4.7 defines a 2-functor*

$$\Pi: \text{EqTrGpd} \rightarrow \text{2-Cat}.$$

Proof. We show that Π preserves composition of arrows on the nose and leave the other details to the reader. Let

$$\begin{array}{ccc} (G_1, X_1) & \xrightarrow{(\varphi'\varphi, f'f)} & (G_3, X_3) \\ & \searrow^{(\varphi, f)} & \nearrow^{(\varphi', f')} \\ & (G_2, X_2) & \end{array}$$

be a commutative triangle in $\mathbf{EqTrGpd}$. The image under Π is the following triangle in $\mathbf{2-Cat}$:

$$\begin{array}{ccc} \Pi_{G_1}(X_1) & \xrightarrow{\Pi(\varphi'\varphi, f'f)} & \Pi_{G_3}(X_3) \\ & \searrow^{\Pi(\varphi, f)} & \nearrow^{\Pi(\varphi', f')} \\ & \Pi_{G_2}(X_2) & \end{array} .$$

We check commutativity of this triangle on objects: Let $(G_1/H, x)$ be an object in $\Pi_{G_1}(X_1)$. Then

$$\begin{aligned} \Pi(\varphi', f')(\Pi(\varphi, f)(G_1/H, x)) &= \Pi(\varphi', f')(G_2/\varphi(H), f(x)) \\ &= (G_3/\varphi'\varphi(H), f'f(x)) \\ &= \Pi(\varphi'\varphi, f'f)(G_1/H, x) \end{aligned}$$

as required. The verification on arrows and 2-cells is equally straightforward. \square

5. The fundamental category as an orbifold invariant

The classical definition of orbifolds is a generalization of the definition of manifolds based on charts and atlases, where the local neighbourhoods are homeomorphic to $U = \tilde{U}/G$ where G is a finite group acting on an open set $\tilde{U} \subseteq \mathbb{R}^n$. Note that we will not require that G acts effectively on \tilde{U} . An orbifold can then be defined in terms of an orbifold atlas, which is a locally compatible family of charts (\tilde{U}, G) such that the sets \tilde{U}/G give a cover of M . The usual notion of equivalence of atlases through common refinement is used; details can be found in [20, 21] for the effective case and in [18] for the more general case.

Working with orbifold atlases is cumbersome, and an alternate way of representing orbifolds using groupoids has been developed. It was shown in [15] that every smooth orbifold can be represented by a Lie groupoid, which is determined up to essential equivalence. We are interested in representing orbifolds by a particular type of Lie groupoid: translation groupoids $G \ltimes M$ coming from the smooth action of a compact Lie group G on a manifold M as in Definition 4.1, where all of the isotropy groups are finite. Many, possibly all, orbifolds can be represented this way. Satake showed that every effective orbifold can be represented in this way [21]. His proof does not hold for non-effective orbifolds, but a partial result was obtained by Henriques and Metzler [9]; their Corollary 5.6 shows that all orbifolds for which all the ineffective isotropy groups have trivial centres are representable. It is conjectured that all orbifolds are representable, but this is currently unknown.

For this paper, we restrict our attention to those orbifolds that are representable, so that we can work with their translation groupoids. In what follows, we think of a groupoid of $\mathbf{EqTrGpd}$ as a representation of its underlying quotient space, encoding

this orbifold and its singularity types. However, this representation is not unique; the same orbifold can be represented by different groupoids. To represent orbifolds, the equivalence relation on groupoids is generated by the notion of essential equivalence for categories internal to the category of smooth manifolds: an equivalence of categories that respects the topology on the groupoids. It is shown in [17] that for representable orbifolds, we only need to look at equivariant essential equivalences, that is, essential equivalences of the form of Definition 4.2. Thus we can describe the category of representable orbifolds as a bicategory of fractions $\text{EqTrGpd}(W^{-1})$, where the objects of this category are Lie translation groupoids with finite isotropy groups, and a morphism $\mathcal{G} \rightarrow \mathcal{H}$ is a span of homomorphisms

$$\mathcal{G} \xleftarrow{\omega} \mathcal{K} \xrightarrow{\varphi} \mathcal{H},$$

where ω is an equivariant essential equivalence. Such morphisms are also called *generalized maps*. We can think of this as replacing the source groupoid \mathcal{G} with an essentially equivalent groupoid \mathcal{K} and then using the new representative \mathcal{K} to define our map.

The main results of this paper are:

Theorem 5.1. *For every equivariant essential equivalence of smooth translation groupoids*

$$\varphi: G \times X \rightarrow H \times Y,$$

the induced functor between the equivariant fundamental groupoids,

$$\Pi(\varphi): \Pi_G(X) \rightarrow \Pi_H(Y),$$

is a weak equivalence of 2-categories.

Corollary 5.2. *For every equivariant essential equivalence of smooth translation groupoids*

$$\varphi: G \times X \rightarrow H \times Y,$$

the induced functor between the discrete equivariant fundamental groupoids,

$$\Pi^d(\varphi): \Pi_G^d(X) \rightarrow \Pi_H^d(Y),$$

is a weak equivalence of categories.

There are a couple of obvious types of maps which are equivariant essential equivalences: if we have a G -space X such that a normal subgroup N of G acts freely on X , then the quotient map

$$G \times X \rightarrow G/N \times X/N, \tag{3}$$

is an essential equivalence. Similarly, for any (not necessarily normal) subgroup L of a group G and L -space X , we can create a G -space $G \times_L X = G \times Z / \sim$, where $[g\ell, z] \sim [g, \ell z]$ for any $\ell \in L$, and the inclusion $X \rightarrow G \times_L X$ defined by $x \rightarrow [e, x]$ gives an essential equivalence

$$L \times X \rightarrow G \times (G \times_L X). \tag{4}$$

It turns out that these are the only forms of equivariant weak equivalences we need to deal with, since they generate all other equivariant essential equivalences through composition.

Proposition 5.3 ([17, Prop. 3.5]). *Any equivariant essential equivalence is a composite of maps of the forms (3) and (4) described above.*

Thus we have an explicit description of the equivalences in $\mathbf{EqTrGpd}(W^{-1})$, and can verify that we have an orbifold invariant by checking its behaviour under these two types of maps. The proof of Theorem 5.1 will follow from Propositions 5.6 and 5.9 below, showing that Π induces a weak equivalence of 2-categories under each of these types of equivariant essential equivalences.

We will start by considering the case where a normal subgroup N of G acts freely.

Definition 5.4. We set the following notation: X is a G space and N is a normal subgroup acting freely. Then we denote the projection by $p: G \rightarrow G/N$, and abbreviate $G/N = \bar{G}$, $p(g) = \bar{g}$ and $p(H) = \bar{H}$ for any subgroup $H \subseteq G$. Similarly, we denote the projection $p: X \rightarrow X/N$, and $p(x) = \bar{x}$.

Proving the equivalence of fundamental categories in this case will use some lifting of paths, and we will make use of the following lemma comparing different lifts.

Lemma 5.5. *Suppose that G is a compact Lie group acting smoothly on X and N is a normal subgroup of G which acts freely on X . Suppose that γ and ζ are two paths $[0, 1] \rightarrow X^H$ such that $\gamma(0) = \zeta(0)$ and $p(\gamma) = p(\zeta)$ in $\bar{X}^{\bar{H}}$. Then there exists a continuous path $\eta: I \rightarrow G$ with $\eta(0) = e$, such that $\gamma(t) = \eta(t)\zeta(t)$ and $\eta(t) \in N(H)$ for all $t \in [0, 1]$.*

Proof. Consider the map $\epsilon: N \times X \rightarrow X \times_{\bar{X}} X$ defined by $\epsilon(n, x) = (nx, x)$, where $X \times_{\bar{X}} X = \{(x, y) | \bar{x} = \bar{y}\}$. Because N acts freely on X , this map is a homeomorphism. Now consider the map $I \rightarrow (X \times_{\bar{X}} X)$ defined by (ζ, γ) . Composing with ϵ^{-1} gives a map $I \rightarrow N \times X$ defined by $(n_t, x_t) = (\eta, \gamma)$ where $\eta(t)\gamma(t) = \zeta(t)$. Since $\gamma(0) = \zeta(0)$ we must have $\eta(0) = e$.

Now we know that γ and ζ lie in X^H . Thus if $h \in H$, then $h\gamma(t) = \gamma(t)$ and $h\zeta(t) = \zeta(t)$, so $h\eta(t)\gamma(t) = \eta(t)\gamma(t)$. So $\eta(t)h\gamma(t) = \eta(t)\gamma(t) = h\eta(t)\gamma(t) = \eta'(t)h\gamma(t)$, where $\eta'(t) = h\eta(t)h^{-1}$. This means that $\eta'(t)h\gamma(t) = \eta(t)h\gamma(t)$, and since N acts freely, $\eta(t) = \eta'(t)$. Thus, $h\eta(t)h^{-1} = \eta(t)$, so $\eta(t) \in N(H)$. \square

Proposition 5.6. *Suppose that G is a compact Lie group acting smoothly on X , and N is a normal subgroup of G which acts freely on X . Then the map $\Pi_G(X) \rightarrow \Pi_{G/N}(X/N)$ induced by the projection is an equivalence of 2-categories.*

Proof. Throughout this proof, we use the notation from Definition 5.4.

Subjective on objects: Suppose that $(\bar{G}/\bar{L}, \bar{x})$ is an object of $\Pi_{\bar{G}}(\bar{X})$. Let $x \in X$ be such that $p(x) = \bar{x}$, and define $L = p^{-1}(\bar{L}) \cap I_x$ where I_x denotes the isotropy of x . Then $L \subseteq I_x$ and so $x \in X^L$. We claim that $p(L) = \bar{L}$: if $\bar{\ell} \in p(L)$, then $\bar{\ell} = p(\ell)$ for $\ell \in L$, and so $\ell \in p^{-1}(\bar{L})$ and hence $\ell \in \bar{L}$. Conversely, if $\bar{\ell} \in \bar{L}$, then choose ℓ in G such that $p(\ell) = \bar{\ell}$. So since $\bar{\ell}\bar{x} = \bar{x}$, we know there exists $n \in N$ such that $n\ell x = x$. So $n\ell \in I_x$ and $n\ell \in p^{-1}(\bar{L})$, and so $n\ell \in L$ such that $p(n\ell) = \bar{\ell}$, showing that $\bar{L} \subseteq p(L)$. Therefore $(G/L, x)$ is an element of $\Pi_G(X)$ such that $p(G/L, x) = (\bar{G}/\bar{L}, \bar{x})$.

Subjective on arrows: Suppose we have objects $(G/H, x)$ and $(G/K, y)$ of $\Pi_G(X)$, and an arrow $(\bar{G}/\bar{H}, \bar{x}) \rightarrow (\bar{G}/\bar{K}, \bar{y})$ in $\Pi_{\bar{G}}(\bar{X})$. This arrow is given by $(\bar{\alpha}, [\bar{\gamma}])$ where $\bar{\alpha}: \bar{G}/\bar{H} \rightarrow \bar{G}/\bar{K}$, so $\bar{\alpha} \in \bar{G}/\bar{K}$ with $\bar{\alpha}^{-1}\bar{H}\bar{\alpha} \subseteq \bar{K}$, and $\bar{\gamma}$ represents a homotopy class of paths $\bar{\gamma}: \bar{x} \rightarrow \bar{\alpha}\bar{y}$ in $\bar{X}^{\bar{H}}$.

First, choose $\hat{\alpha} \in G$ such that $p(\hat{\alpha}) = \bar{\alpha}$. Next, $p: X^H \rightarrow \bar{X}^{\bar{H}}$ is the quotient of the free action of N , so this is a principal fibration and we can lift $\bar{\gamma}$ to $\gamma \in X^H$ starting at x . So we have $\gamma: x \rightarrow z$ in X^H , and we know that $\bar{z} = \bar{\alpha}\bar{y} = \overline{\alpha y}$. Therefore there exists $n \in N$ such that $n\hat{\alpha}y = z$. Define $\alpha = n\hat{\alpha}$, so that $\gamma: x \rightarrow \alpha y$ in X^H . Then $p(\alpha, [\gamma]) = (\bar{\alpha}, [\bar{\gamma}])$. So we just need to show that $\alpha: G/H \rightarrow G/K$. To see this, we need to show that $\alpha H \alpha^{-1} \subseteq K$.

Let $h \in H$. Then $\bar{h} \in \bar{\alpha}\bar{K}\bar{\alpha}^{-1}$, and $h = \alpha k \alpha^{-1} n$ for some $n \in N$. Now $ky = y$ for any $k \in K$, and we know that $\alpha y \in X^H$, so $h\alpha y = \alpha y$ for any $h \in H$, and hence $\alpha^{-1}h\alpha y = y$. Thus $y = ky = \alpha^{-1}h\alpha y = \alpha^{-1}(\alpha k \alpha^{-1} n)\alpha y = k\hat{n}y$. So $y = \hat{n}y$ and $\hat{n} = e$ since N acts freely. So $h = \alpha k \alpha^{-1}$ as required.

Full on 2-cells: Suppose we have two arrows $(\alpha, [\gamma])$ and $(\beta, [\zeta])$ from $(G/H, x)$ to $(G/K, y)$ in $\Pi_G(X)$. So $\gamma: x \rightarrow \alpha y$ and $\zeta: x \rightarrow \beta y$ in X^H . And suppose there exists a 2-cell from $p(\alpha, [\gamma])$ to $p(\beta, [\zeta])$ in $\Pi_{\bar{G}}(\bar{X})$. This means that we have $\bar{\sigma}$ in $\overline{(G/K)}^{\bar{H}}$ from $\bar{\alpha}$ to $\bar{\beta}$ such that $\bar{\gamma} * \bar{\sigma} \bar{y}$ is homotopic to $\bar{\sigma}$ via $\bar{\Lambda}$ in $\bar{X}^{\bar{H}}$:

$$\begin{array}{ccc} \bar{x} & \xrightarrow{\bar{\gamma}} & \bar{\alpha}\bar{y} \\ & \searrow \bar{\Lambda} & \downarrow \bar{\sigma}\bar{y} \\ & \zeta & \bar{\beta}\bar{y}. \end{array}$$

Now $y \in X^K$, so $K \cap N = \{e\}$ since N acts freely. So the map $(G/K)^H \rightarrow \overline{(G/K)}^{\bar{H}}$ is a principal fibration and we can lift $\bar{\sigma}$ to σ in $(G/K)^H$ starting at α . Next, we can lift the homotopy $\bar{\Lambda}$ to X^H starting at $\gamma * \sigma y$ to get a homotopy Λ :

$$\begin{array}{ccc} x & \xrightarrow{\gamma} & \alpha y \\ & \searrow \Lambda & \downarrow \sigma y \\ & \omega & z. \end{array}$$

Now we have a new end path $\Lambda(s, 1) = \omega$ such that $\bar{\omega} = \bar{\zeta}$ in $\bar{X}^{\bar{H}}$. By Lemma 5.5, there is a continuous $\eta: I \rightarrow N$ such that $\zeta = \eta\omega$, and $\eta(t) \in N(H)$. We will use this η to adjust Λ : define $\Lambda'(s, t) = \eta(t)\Lambda(s, t)$. This homotopy fits in the following triangle of paths:

$$\begin{array}{ccc} x & \xrightarrow{\gamma} & \alpha y \\ & \searrow \Lambda' & \downarrow \eta\sigma y \\ & \zeta = \eta\omega & \beta y. \end{array}$$

We claim that $\eta\sigma$ together with the homotopy Λ' gives a 2-cell in $\Pi_G(X)$. So we need that $\eta\sigma \in (G/K)^H$ and Λ' is in X^H . This follows from the fact that σ satisfies $\sigma^{-1}H\sigma \subseteq K$ and $\eta(t) \in N(H)$, so $(\eta\sigma)^{-1}H(\eta\sigma) = \sigma^{-1}H\sigma \subseteq K$; similarly $\Lambda \in X^H$, so $\Lambda' = \eta\Lambda \in X^{\eta^{-1}H\eta} = X^H$.

Faithful on 2-cells: Suppose we have σ_1 and σ_2 representing 2-cells from $(\alpha, [\gamma])$ to $(\beta, [\zeta])$ in $\Pi_G(X)$. So there are homotopies $\Lambda_1: \zeta \simeq \gamma * \sigma_1 y$ and $\Lambda_2: \zeta \simeq \gamma * \sigma_2 y$ in X^H . And suppose that $[\bar{\sigma}_1] = [\bar{\sigma}_2]$, meaning that there is a homotopy $\bar{\Omega}$ between $\bar{\sigma}_1$ and $\bar{\sigma}_2$ in $\overline{(G/K)}^{\bar{H}}$. Let $Y = (G/K)$; then since $K \cap N = \{e\}$, Y is a free N -space, and so the projection p is a principal fibration and we can lift $\bar{\Omega}$ in $\bar{Y}^{\bar{H}}$ to Ω in Y^H , starting at σ_1 . Thus we have a homotopy from σ_1 to ω , where $\bar{\sigma}_2 = \bar{\omega}$. Applying Lemma 5.5 gives $\eta(t): I \rightarrow N$ such that $\eta\omega = \sigma_2$ and $\eta \in N(H)$. Again, we define a

new homotopy $\Omega'(s, t) = \eta(t)\Omega(s, t)$, and note that since $\Omega \in Y^H$, so is $\eta\Omega$. Thus Ω' gives a homotopy from $\sigma_1 \simeq \sigma_2$ in $(G/K)^H$, showing that $[\sigma_1] = [\sigma_2]$ in $\Pi_G(X)$. \square

Now we consider the other case, where we have an L -space X and take the inclusion of X to $G \times_L X$. For this, we need the following lemmas.

Lemma 5.7. *Given a path γ in $(G \times_L X)^H$ defined by $\gamma(t) = (g_t, x_t)$ with $g_0 = e$, there exists a continuous path $\ell_t \in L$ with $\ell_0 = e$, such that*

- $(g_t \ell_t)^{-1} H g_t \ell_t = H$ and
- $(g_t \ell_t)^{-1} \gamma$ lies in the image of X^H in $(G \times_L X)^H$.

Proof. Suppose we have a path γ in $(G \times_L X)^H$ defined by $\gamma(t) = (g_t, x_t)$ with $g_0 = e$. By the equivariant slice theorem, at any point $x \in X$, there exists a neighbourhood of the form $L \times_{I_x} Y$ for I_x the isotropy group of x , and Y an I_x space. By compactness, we can cover the path x_t with a finite number of such neighbourhoods $N_0, N_1, N_2, \dots, N_k$ around $x_0, x_{s_1}, x_{s_2}, \dots, x_{s_k}$. Now for each neighbourhood, γ takes the form $(g_t, (n_t, y_t))$ where $y_t \in Y_j$ and Y_j is an $I_{x_{s_j}}$ -space. Our strategy will be to choose, for each neighbourhood, a ‘transition’ element $\hat{\ell}_j$ and then define $\ell_t = n_t \hat{\ell}_j$. We will also choose transition points $x_{t_1}, x_{t_2}, x_{t_3}, \dots, x_{t_n}$ where each $x_{t_i} \in N_{i-1} \cap N_i$; these are the points where we will switch from using one coordinate system to another.

Start with the first neighbourhood, so $\gamma = (g_t, x_t)$ and $x_t = (n_t, y_t)$ for a continuous choice of $n_t \in L$ and $y_t \in Y_0$. Now by assumption, $(g_t, (n_t, y_t)) \in (G \times_L X)^H$, so $x_t = (n_t, y_t) \in X^{g_t^{-1} H g_t}$ and therefore $y_t \in Y^{\ell_t^{-1} g_t^{-1} H g_t \ell_t}$; note that $g_0 = e$ and $n_0 = e$. Now $\ell_t^{-1} g_t^{-1} H g_t \ell_t$ forms a continuous family of conjugate subgroups of I_{x_0} , starting from H at $t = 0$; and since I_{x_0} is discrete, this family must be constant. So for the first neighbourhood, we take the transition element $\hat{\ell}_0 = e$, and define $\ell_t = n_t$ for $0 \leq t \leq t_1$, so that $\ell_t^{-1} g_t^{-1} H g_t \ell_t = H$ and $(g_t \ell_t)^{-1} \gamma = (e, (e, y_t))$ lies in the image of X^H .

Now we will inductively assume that the neighbourhood around $x_{s_{j-1}}$ gives coordinates (m_t, y_t) for $y_t \in Y$ for Y an $I_{x_{s_{j-1}}}$ -space, and that $\ell_t = m_t \hat{\ell}_{j-1}$ has been defined for $0 \leq t_j$. We want to extend to N_j , given by coordinates (n_t, z_t) where $z_t \in Z$ for Z an $I_{x_{s_j}}$ -space. We use the fact that at our chosen transition point in the intersection, x_{t_j} can be written both as (m_{t_j}, y_{t_j}) and (n_{t_j}, z_{t_j}) , and define our new transition element $\hat{\ell}_j = n_{t_j}^{-1} m_{t_j} \hat{\ell}_{j-1}$. So for $t_j \leq t \leq t_{j+1}$ we will define $\ell_t = n_t \hat{\ell}_j$; this will be continuous since at $t = t_j$, we have $\ell_{t_j} = m_{t_j} \hat{\ell}_{j-1} = n_{t_j} n_{t_j}^{-1} m_{t_j} \hat{\ell}_{j-1} = n_{t_j} \hat{\ell}_j$.

Now we know by assumption, $(g_{t_j} \ell_{t_j})^{-1} H g_{t_j} \ell_{t_j} = H$, and so

$$\hat{\ell}_{j-1}^{-1} m_{t_j}^{-1} g_{t_j}^{-1} H g_{t_j} m_{t_j} \hat{\ell}_{j-1} = H.$$

Therefore,

$$m_{t_j}^{-1} g_{t_j}^{-1} H g_{t_j} m_{t_j} = \hat{\ell}_{j-1} H \hat{\ell}_{j-1}^{-1}$$

and so

$$\begin{aligned} n_{t_j}^{-1} g_{t_j}^{-1} H g_{t_j} n_{t_j} &= n_{t_j}^{-1} m_{t_j} m_{t_j}^{-1} g_{t_j}^{-1} H g_{t_j} m_{t_j} m_{t_j}^{-1} n_{t_j} \\ &= n_{t_j}^{-1} m_{t_j} \hat{\ell}_{j-1} H \hat{\ell}_{j-1}^{-1} m_{t_j}^{-1} n_{t_j} \\ &= \hat{\ell}_j H \hat{\ell}_j^{-1}. \end{aligned}$$

So in N_j , we have a family of subgroups $n_t^{-1} g_t^{-1} H g_t n_t$ of $I_{x_{s_j}}$ which is equal to $\hat{\ell}_j H \hat{\ell}_j^{-1}$

at t_j , and so by discreteness of I_{x_s} they must be constant. Thus, we have that

$$\hat{\ell}_j^{-1} n_t^{-1} g_t^{-1} H g_t n_t \hat{\ell}_j = H,$$

and so $(g_t \ell_t)^{-1} H g_t \ell_t = H$ for $t_j \leq t \leq t_{j+1}$, and

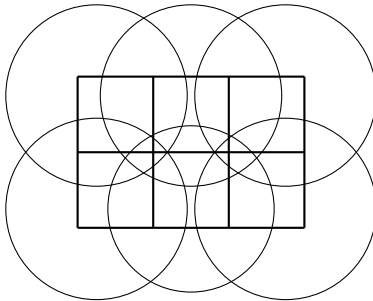
$$(g_t \ell_t)^{-1} \gamma = \hat{\ell}_j^{-1} n_t^{-1} g_t^{-1} (g_t, (n_t, z_t)) = (e, (\hat{\ell}_j, z_t)),$$

which lies in the image of X^H . \square

Lemma 5.8. *Given a homotopy Λ in $(G \times_L X)^H$ defined by $\Lambda(t) = (g_{s,t}, x_{s,t})$ with $g_{0,0} = e$, there exists a continuous family $\ell_{s,t} \in L$ such that*

- $(g_{s,t} \ell_{s,t})^{-1} H g_{s,t} \ell_{s,t} = H$ and
- $(g_{s,t} \ell_{s,t})^{-1} \Lambda$ lies in the image of X^H .

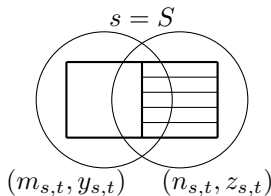
Proof. We use a similar strategy as in the proof of Lemma 5.7, working with local neighbourhoods of the form $L \times_I Y$ and producing adjustment elements that allow us to piece together the local coordinates into a continuous whole. So we begin by covering the image of $x_{x,t}$ by a set of neighbourhoods of the form $L \times_{I_x} Y$ where I_x is the isotropy of a point x , and Y is a space with I_x action. By compactness, we will assume that the number of these neighbourhoods is finite, and that they cover a grid pattern where the horizontal and vertical sides of the images of the grid are in overlapping neighbourhoods:



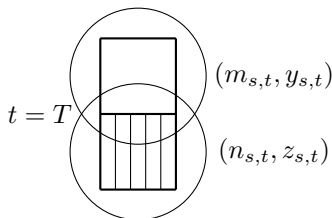
In the first neighbourhood, centred at $x_{0,0}$, we have coordinates $(n_{s,t}, y_{s,t})$ and can define $\ell_{s,t} = n_{s,t}$; note that $\ell_{0,0} = e$. To extend to new neighbourhoods, we work across the top row, then down the left row, and then through the middle of the grid, row by row. So we need to be able to extend in the following scenarios: when the $\ell_{s,t}$ have been defined for the neighbourhood to the left; when the $\ell_{s,t}$ have been defined for the neighbourhood above; and when $\ell_{s,t}$ have been defined for both the neighbourhood to the left and the neighbourhood above. In each case, we will use the grid edges in the overlap of adjacent neighbourhoods to give us our new adjustment elements. These overlaps occur along lines instead of single points, so our adjustment elements will not be constant on each neighbourhood, but rather an extension of the edge adjustment lines. All of our extensions will produce continuous adjustment factors, hence continuous choices of $\ell_{s,t}$, and the discreteness of the isotropy group I_x on each neighbourhood will ensure that we retain the properties we need.

To extend across the top row of neighbourhoods, we assume that we have defined our $\hat{\ell}_{s,t}$ on the neighbourhood to the left, and look along the transition line at $s = S$,

along the segment $x_{S,t}$ for $0 \leq t \leq t_1$. Then we have two neighbourhood parametrizations, $(m_{s,t}, y_{s,t})$ for the left neighbourhood and $(n_{s,t}, z_{s,t})$ for the right where we are looking to extend; and the vertical transition line at $s = S$. We define the new transition element using the values along this transition line, constant horizontally, by $\hat{\ell}_{s,t} = n_{S,t}^{-1} m_{S,t} \hat{\ell}_{S,t}$:

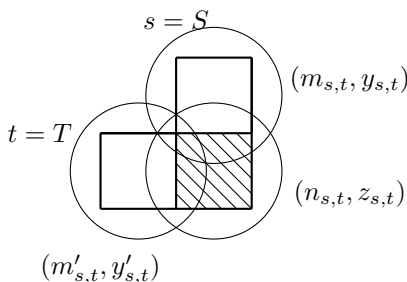


Similarly, to extend down the left row, we use neighbourhood parametrizations $(m_{s,t}, y_{s,t})$ for the upper and $(n_{s,t}, z_{s,t})$ neighbourhood, and look at the horizontal transition line at $t = T$. We define the new transition elements using values along this line, constant vertically, by $\hat{\ell}_{s,t} = n_{s,T}^{-1} m_{s,T} \hat{\ell}_{s,T}$:



Lastly, consider how to extend to a neighbourhood where $\hat{\ell}_{s,t}$ has been defined for a neighbourhood above and to the left of it. Suppose that the neighbourhood above our new one has coordinates $(m_{s,t}, y_{s,t})$, and the one to the left has coordinates $(m'_{s,t}, y'_{s,t})$; and the new neighbourhood has coordinates $(n_{s,t}, z_{s,t})$. Then we have two transition segments. Along the horizontal segment at $t = T$, we know that $x_{s,T}$ can be written as both $(m_{s,T}, y_{s,T})$ and $(n_{s,T}, z_{s,T})$; and along the vertical segment $s = S$, we know that $x_{S,t}$ can be written as $(m'_{S,t}, y'_{S,t})$ and $(n_{S,t}, z_{S,t})$. Then we can extend diagonally across the new neighbourhood using transition element

$$\hat{\ell}_{s,t} = \begin{cases} n_{s-t,T}^{-1} m_{s-t,T} \hat{\ell}_{s-t,T} & \text{if } s - S \leq t - T, \\ n_{S,s-t}^{-1} m'_{S,s-t} \hat{\ell}_{S,s-t} & \text{else.} \end{cases}$$



In this way we can define our transition elements on the entire region. \square

Proposition 5.9. *If L is a compact Lie group which acts smoothly on X with finite isotropy groups, and $L \subseteq G$ for some compact Lie group G , then there is an inclusion map $L \hookrightarrow G$, and an equivariant inclusion $\varphi: X \rightarrow G \times_L X$ by $\varphi(x) = [e, x]$. Then $\varphi: \Pi_L(X) \rightarrow \Pi_G(G \times_L X)$ is an equivalence of 2-categories.*

Proof. Essentially surjective on objects: Given $(G/H, [g, y])$ in $\Pi_G(G \times_L X)$, we know that $[g, y] \in (G \times_L X)^H$, and so $[e, y] \in (G \times_L X)^{g^{-1}Hg}$. So $y \in X^{g^{-1}Hg}$. Consider $(L/g^{-1}Hg, y) \in \Pi_L(X)$. Then $\varphi(L/g^{-1}Hg, y) = (G/g^{-1}Hg, [e, y])$ and (g, c) represents an arrow from $(G/H, [g, y])$ to $(G/g^{-1}Hg, [e, y])$, where c is the constant path at $[g, y]$.

Essentially surjective on arrows: Suppose we have $(L/H, x)$ and $(L/K, y)$ in $\Pi_L(X)$, and an arrow $(\alpha, [\gamma]): (G/H, [e, x]) \rightarrow (G/K, [e, y])$ in $\Pi_G(G \times_L X)$. So we have a path $\gamma: [e, x] \rightarrow [\alpha, y]$ in $(G \times_L X)^H$, and γ takes the form $\gamma(t) = [g_t, x_t]$. By Lemma 5.7, we know that there exists a continuous family ℓ_t such that $(g_t \ell_t)^{-1} H g_t \ell_t = H$ and $(g_t \ell_t)^{-1} \gamma \in (e \times_L X^H)$. Define $\zeta = (g_t \ell_t)^{-1} \gamma$. Then ζ is a path in X^H which starts at x and ends at $\ell_1^{-1} y$, and so $(e, (\ell_1^{-1}, \zeta))$ is an arrow in $\Pi_L(X)$ from $(L/H, x)$ to $(L/K, y)$. Now define a 2-cell $\sigma = (g_t \ell_t)^{-1}$ from (α, γ) to $\varphi(\ell_1^{-1}, \zeta)$: to show this is a 2-cell in $\Pi_G(G \times_L X)$, we need a homotopy $\gamma * \sigma y \simeq \zeta$. We define $\Lambda(s, t) = \sigma(s) \gamma(t)$:

$$\begin{array}{ccc} x & \xrightarrow{\gamma} & \alpha y \\ & \searrow & \downarrow \sigma y \\ & \zeta = \sigma \gamma & \ell^{-1} y \end{array}$$

Thus, every arrow between $\varphi(L/H, x)$ and $\varphi(L/K, y)$ has an invertible 2-cell to an arrow in the image of $\Pi_L(X)$.

Full on 2-cells Suppose we have two arrows $(\alpha, [\gamma])$ and $(\beta, [\zeta])$ from $(L/H, x)$ to $(L/K, y)$ in $\Pi_L(X)$, and that when we take their images under φ , there is a 2-cell connecting them in $\Pi_G(G \times_L X)$. Specifically, γ is a path from x to αy in X^H , and ζ is a path from x to βy in X^H ; and there is a σ from α to β in $(G/K)^H$, and a homotopy Λ from $[e, \gamma] * [\sigma, y]$ to $[e, \zeta]$ in $(G \times_L X)^H$. Now apply Lemma 5.8 to $\Lambda(s, t) = [g_{s,t}, x_{s,t}]$ to get a continuous $\ell_{s,t} \in L$ such that $(g_t \ell_t)^{-1} \gamma \in (e \times_L X^H)$ and $(g_t \ell_t)^{-1} H g_t \ell_t = H$.

Define $\omega(t) = (g_{1,t} \ell_{1,t})^{-1} \sigma(t)$ and $\Omega(s, t) = (g_{s,t} \ell_{s,t})^{-1} \Lambda(s, t)$. Then ω is a map in $(L/K)^H$ from $(g_{1,0} \ell_{0,1})^{-1} \alpha$ to $(g_{1,1} \ell_{1,1})^{-1} \beta$, and Ω gives a homotopy in X^H from $(g_{s,0} \ell_{s,0})^{-1} \gamma * \omega y$ to $(g_{s,1} \ell_{s,1})^{-1} \zeta$.

$$\begin{array}{ccc} [e, x] & \xrightarrow{(g_{s,0} \ell_{s,0})^{-1} \gamma} & (g_{1,0} \ell_{1,0})^{-1} \alpha y \\ & \searrow & \downarrow \omega y \\ & (g_{s,1} \ell_{s,1})^{-1} \zeta & (g_{1,0} \ell_{1,0})^{-1} \beta y \end{array}$$

We want to use this to create a 2-cell in $\Pi_L(X)$ from $(\alpha, [\gamma])$ to $(\beta, [\zeta])$. Now we know that $\gamma \in X^H$, and $[e, \gamma(s)] = \Lambda_{s,0} = (g_{s,0}, x_{s,0})$. So we must have $g_{s,0} \in L$. Thus, we can define a 2-cell in $\Pi_L(X)$ from $(\alpha, [\gamma])$ to $((g_{1,0} \ell_{1,0})^{-1} \alpha, [(g_{s,0} \ell_{s,0})^{-1} \gamma])$ using $g_{s,0} \ell_{s,0}$.

Similarly, on the other end, we have a 2-cell from $((g_{1,1}\ell_{1,1})^{-1}\beta, [(g_{s,0}\ell_{s,0})^{-1}\zeta])$ to $(\beta, [\zeta])$ using $g_{s,1}\ell_{s,1}$, again using the fact that $\Lambda_{s,1} = [e, \zeta]$ and hence $g_{s,1} \in L$.

Faithful on 2-cells Suppose we have two 2-cells σ, ω in $\Pi_L(X)$ from $(\alpha, [\gamma])$ to $(\beta, [\zeta])$. And when we embed in $G \times_L X$, they are homotopic: we have $\Gamma: \sigma \rightarrow \omega$ in $(G/K)^H$, which gives $\Gamma y: \sigma y \rightarrow \omega y$ in $(G \times_L X)^H$. Note that when we write Γy in the form $(g_{s,t}, x_{s,t})$ we can take $g_{s,t} = \Gamma(s, t)$ and $x_{s,t} = y$. Apply Lemma 5.8 to Γy written in this form to get $\ell_{s,t}$; then define $\hat{\Gamma} = (g_{s,t}\ell_{s,t})^{-1}\Gamma = \ell_{s,t}^{-1}$. Because $\Gamma \in (G/K)^H$, we know that $g_{s,t}Hg_{s,t}^{-1} \leq K$, and so $\ell_{s,t}^{-1}g_{s,t}^{-1}Hg_{s,t}\ell_{s,t} \leq \ell_{s,t}^{-1}K\ell_{s,t}$ and so $\ell_{s,t}^{-1}$ gives a map from L/H to L/K as required; giving a 2-cell in $\Pi_L(X)$ from $g_{s,0}^{-1}\sigma$ to $(g_{s,1}\ell_{s,1})^{-1}\omega$. Then since $\sigma \in L$, we know that $g_{s,0} \in L$, allowing us to create a homotopy from $g_{s,0}^{-1}\sigma$ to σ ; and similarly from $(g_{s,1}\ell_{s,1})^{-1}\omega$ to ω in $(L/K)^H$. Concatenating these homotopies gives the required homotopy from σ to ω , showing that these 2-cells were equivalent in $\Pi_L(X)$. \square

Remark 5.10. In Section 4 we presented $\Pi: \text{EqTrGpd} \rightarrow 2\text{-Cat}$ as a strict 2-functor. The 2-equivalences of this section are only weak 2-equivalences. However, subject to the axiom of choice we are able to choose a pseudo inverse for each Morita equivalence and to induce a pseudo functor

$$\text{Orbifolds} \simeq \text{EqTrGpd}(W^{-1}) \xrightarrow{\hat{\Pi}} 2\text{-Cat}$$

that extends Π , although this functor is not canonical.

Example 5.11. Suppose that $G = \mathbb{Z}/2$ acts on the circle $X = S^1$, where τ acts by rotation by π . Then G acts freely on X , with quotient space $\bar{X} \simeq S^1$, and so the projection $G \times X \rightarrow e \times \bar{X}$ is an equivariant essential equivalence.

Now $\bar{G} = \{e\}$ and so $\Pi_{\bar{G}}\bar{X}$ is just the usual fundamental groupoid of \bar{X} , with arrows indexed by the winding number of their path in \mathbb{Z} between any two points. Since G is discrete, $\Pi_{\bar{G}}\bar{X} = \Pi_G^d\bar{X}$.

On the other hand, $\Pi_G(X)$ consists of points $(G/e, x)$ and arrows $(e, [\gamma])$ where γ is a path from x to y , again classified by winding number n ; and arrows $(\tau, [\zeta])$ where ζ is a path from x to τy , classified by winding number m . Then the projection map takes $(e, [\gamma])$ to $(\bar{e}, [\bar{\gamma}])$, which will have winding number $2n$; and takes $(\tau, [\zeta])$ to $(\bar{e}, [\bar{\zeta}])$ with winding number $2m + 1$. Again, $\Pi_G(X) = \Pi_G^d(X)$. So we have the equivalence of categories $\Pi_G^d(X) \rightarrow \Pi_G^d\bar{X}$.

Example 5.12. Consider $G = S^1$ acting on the torus $X = T^2$ as in Example 3.5. The circle acts freely, so again the projection $G \times X \rightarrow e \times \bar{X}$ is an equivariant essential equivalence. Here $\bar{X} \simeq S^1$ and again $\Pi_{\bar{G}}\bar{X} = \Pi_G^d\bar{X}$ is the groupoid with arrows indexed by \mathbb{Z} between any objects.

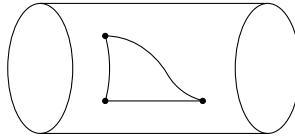
The category $\Pi_G(X)$ was described in Example 3.5, where it was shown that every arrow had a 2-cell to an arrow of the form $(e, [\gamma])$ where γ was constant in the second coordinate. Therefore, $\Pi_G^d(X)$ is isomorphic to $\Pi_G^d\bar{X}$.

Example 5.13. Consider $L = \mathbb{Z}/2$ and $X = S^1$ from Example 3.4. We can consider L as a subgroup of $G = S^1$, and form the space $G \times_L X = (G \times X) / \sim$, where $(\lambda, x) \sim (\tau\lambda, \tau x)$ for $\tau = e^{i\pi}$. Since τ acts on X via a reflection, this is topologically a Klein bottle.

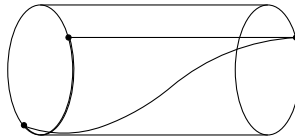
The objects of $\Pi_G(G \times_L X)$ are of the form $(G/e, [\alpha, \beta])$ for $[\alpha, \beta] \in S^1 \times_L S^1$, and $(G/G, [\alpha, z])$ for $z \in X^{\mathbb{Z}/2}$, so $z \in \{E, W\}$.

Between points of the first type, we have arrows of the form $(\lambda, [\gamma])$ for γ a path from x to λy in the Klein bottle; so we have a copy of $S^1 \times (\mathbb{Z} \oplus \mathbb{Z})/\langle abab^{-1} \rangle$. Similarly the points $(G/G, [\alpha, z])$ have arrows $(\lambda, [\zeta])$ between them, where ζ is a path from (α, z) to (α', z) in $(G \times_L X)^{\mathbb{Z}/2} \simeq S^1$; and arrows $(\lambda, [\gamma])$ from $(G/e, [\alpha, \beta])$ to $(G/G, [\alpha, z])$.

There are 2-cells identifying many of these arrows. Between $(G/e, [\alpha_1, \beta_1])$ and $(G/e, [\alpha_2, \beta_2])$, there are 2-cells between arrows $(\lambda, [\gamma])$ and $(e, [\gamma * \Lambda^{-1}(\alpha_2, \beta_2)])$ by defining Λ to be a path in S^1 from e to λ .



Now consider the arrow $(e, [b])$ corresponding to a generating loop along β . This has a 2-cell to the map $(\tau, [\hat{b}])$ which is constant in β , where \hat{b} is a path from x to τx .



Then $(\tau, [\hat{b}])^2 = e$. Thus, in $\Pi_G^d(G \times_L X)$, we have arrows indexed by elements of the group $\mathbb{Z} \oplus \mathbb{Z}/\langle abab^{-1}, b^2 \rangle$, recovering the infinite dihedral maps of Example 3.4. Similarly, arrows from $(G/\mathbb{Z}/2, [\alpha, z])$ to $(G/\mathbb{Z}/2, [\alpha', z])$ are identified in $\Pi_G^d(G \times_L X)$ by taking a path from α to α' in S^1 and using it to produce a 2-cell, and we get our equivalence $\Pi_L^d(X) \xrightarrow{\sim} \Pi_G^d(G \times_L X)$.

References

- [1] I. Bakovic, Fibrations of bicategories, <http://www.irb.hr/korisnici/ibakovic/groth2fib.pdf>.
- [2] M. Bunge and R. Paré, Stacks and equivalence of indexed categories, *Cah. Topol. Géom. Différ. Catég.* **20** (1979), pp. 373–399.
- [3] G.E. Bredon, *Introduction to Compact Transformation Groups*, Academic Press (1972).
- [4] M. Bullejos and L. Scull, *A van Kampen theorem for equivariant fundamental groupoids* J. Pure Appl. Algebra **212** (2008), pp 2059–2068
- [5] M. Buckley, Fibred 2-categories and bicategories, *J. Pure Appl. Algebra* **218** (2014), pp. 1034–1074.
- [6] S. Costenoble, S. Waner, Equivariant covering spaces and homotopy covering spaces, *Homology Homotopy Appl.* **6** (2004), pp. 473–500.
- [7] S. Costenoble, S. Waner, Equivariant orientation theory. *Homology Homotopy Appl.* **3** (2001), pp. 265–339.

- [8] W. Chen, Y. Ruan, A new cohomology theory of orbifold, *Comm. Math. Phys.* **248** (2004), pp. 1–31.
- [9] A. Henriques, D. Metzler, Presentations of noneffective orbifolds, *Trans. Amer. Math. Soc.* **356** (2004), pp. 2481–2499.
- [10] J. Leida, Orbifolds and stable homotopy groups, [arXiv:math/0505431](https://arxiv.org/abs/math/0505431).
- [11] E. Lupercio, B. Uribe, Gerbes over orbifolds and twisted K-theory, *Comm. Math. Phys.* **245** (2004), pp. 449–489.
- [12] W. Lück, I. Madsen, Equivariant L-theory. I. *Math. Z.* **203** (1990), pp. 503–526.
- [13] W. Lück, I. Madsen, Equivariant L-theory. II. *Math. Z.* **204** (1990), pp. 253–268.
- [14] I. Moerdijk, J. Mrčun, Lie groupoids, sheaves and cohomology, in S. Gutt, J. Rawnsley, and D. Sternheimer (Eds.), *Poisson Geometry, Deformation Quantisation and Group Representations* (London Mathematical Society Lecture Note Series, pp. 145–146). Cambridge: Cambridge University Press, 2005.
- [15] I. Moerdijk, D.A. Pronk, Orbifolds, sheaves and groupoids, *K-theory* **12** (1997), pp. 3–21.
- [16] G. Mukherjee, N. Pandey, Equivariant cohomology with local coefficients. *Proc. Amer. Math. Soc.* **130** (2002), pp. 227–232.
- [17] D. Pronk and L. Scull, Translation Groupoids and Orbifold Bredon Cohomology, *Canad. J. Math.* **62** (2010), pp. 614–645.
- [18] D. Pronk, L. Scull, M. Tommasini, Atlases for general orbifolds, [arXiv:1606.04439](https://arxiv.org/abs/1606.04439).
- [19] D.M. Roberts, Fundamental Bigroupoids and 2-Covering Spaces, PhD-thesis, University of Adelaide, School of Mathematical Sciences, 2010, <http://hdl.handle.net/2440/62680>.
- [20] I. Satake, On a generalization of the notion of manifold, *Proc. Natl. Acad. Sci. USA* **42** (1956), pp. 359–363.
- [21] I. Satake, The Gauss-Bonnet theorem for V-manifolds, *J. Math. Soc. Japan* **9** (1957), pp. 464–492.
- [22] T. tom Dieck, *Transformation Groups*, Walter de Gruyter (1987).

Dorette Pronk pronk@mathstat.dal.ca

Department of Mathematics and Statistics, Chase Building, Dalhousie University, Halifax, NS, B3H 4R2, Canada

Laura Scull scull_l1@fortlewis.edu

Department of Mathematics, Fort Lewis College, 1000 Rim Drive, Durango, Colorado 81301, USA