

Long-time asymptotics of the second grade fluid equations on \mathbb{R}^2

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ABSTRACT. We study the large time behavior of solutions of the second grade fluid system in the space \mathbb{R}^2 . Using scaled variables and introducing several functionals in weighted Sobolev spaces, we prove that the solution of the second grade fluid equations converges to the Oseen vortex, if the initial data are small enough. We also give an estimate of the rate of convergence.

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1. Introduction

The classical theory of Newtonian fluids is unable to explain properties observed in some fluids in the nature. Most of such fluids belong to the class of non-Newtonian fluids. This is the case, for example, of many polymer solutions and many commonly substances found in the industry (petroleum industry, plastic manufacture, application of paints,...).

Several models have been introduced to describe and explain the behavior of non-Newtonian fluids. Among these models, fluids of differential type introduced by Rivlin-Erickson [23] have attracted much attention from a theoretical point of view. In this article, we are interested in the study of a special class of non-Newtonian fluids of differential type, namely fluids of second grade. Their study was initiated in

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1974 by J.E.Dunn and R.L.Fosdick [7] and then by R.L.Fosdick and K.R.Rajakopal [8], [9]. For such fluids, the Cauchy stress tensor T is a polynomial of degree less than 2 in the first two Rivlin-Ericksen kinematical tensors A_1 and A_2 .

$$T = -pI + \nu A_1 + \alpha(A_2 - A_1^2)$$

where p is the pressure, ν is the viscosity and the tensors A_1 and A_2 are defined by

$$A_1 = (\text{grad } u) + (\text{grad } u)^T,$$

$$A_2 = \frac{dA_1}{dt} + A_1(\text{grad } u) + (\text{grad } u)^T A_1$$

where u is the velocity of the fluid and $\frac{d}{dt} = \partial_t + u \cdot \nabla$.

The Newton laws and a classical computation lead to the following system, which describes the motion of an incompressible fluid of second grade

$$(SGF) \begin{cases} \partial_t(u - \alpha \Delta u) + \text{rot}(u - \alpha \Delta u) \times u &= \nu \Delta u - \nabla p \\ \text{div } u &= 0 \\ u(x, 0) &= u_0 \end{cases}$$

where $u = u(x, t) \in \mathbb{R}^2$ is the velocity field, $p = p(x, t)$ is the pressure, α is a material coefficient, ν is the viscosity and $x \in \mathbb{R}^2$, $t \geq 0$.

In the system (SGF), we have used the following notations and identifications. We have identified any two-component vector field $v = (v_1, v_2)^t$ with the three-component field $v = (v_1, v_2, 0)^t$ and denoted $\text{rot } v$ the 3-component vector field given by

$$\text{rot } v = (0, 0, \partial_1 v_2 - \partial_2 v_1)^t.$$

Several authors have been interested in the study of the second grade fluid equations ([1], [6], [10], [11], [12], [18], [21], [20]). The first mathematical result of existence and uniqueness of solutions was obtained by Cioranescu and Ouazar in [6]. More precisely, when Ω is a bounded domain in \mathbb{R}^2 , Cioranescu and Ouazar have proved that for divergence-free initial data u_0 in $(H^3(\Omega))^2 \cap (H_0^1(\Omega))^2$, the solution of the system (SGF) exists and is unique in the space $L^\infty(\mathbb{R}^+, (H^3(\Omega))^2) \cap L^2(\mathbb{R}^+, (H^1(\Omega))^2)$. The existence and uniqueness results are the same in the case of periodic conditions, for more details, see [21]. When the equations are considered in the whole space, a similar result is proved [1].

In the three-dimensional case, Cioranescu and Ouazar have also proved local existence (and uniqueness) of solutions of System (SGF) (see [6]). Later, in [5], Cioranescu and Girault established global existence (and uniqueness) of solutions for small initial data.

On the other hand, the problem of existence of classical solutions has been studied in [11] by Galdi, Grobbelaar and Sauer, who showed local existence and uniqueness of classical solutions for (SGF). Furthermore, when the size of the initial data is suitably restricted and when the coefficient $\alpha\rho$ is sufficiently large, where ρ is the density of the fluid, they obtained a global existence result. Later, Galdi and Sequeira have relaxed the condition on α in [12].

Let us remark that, when α vanishes, we recover the classical system of the Navier-Stokes equations.

In this paper, we are interested in studying the large time asymptotic behavior of the solution of (SGF) in the whole space \mathbb{R}^2 . Our motivation comes from the

case $\alpha = 0$ (the Navier-Stokes equations). In [16], Gallay and Wayne used ideas from the theory of dynamical systems in order to determine the long-time behavior of solutions of the Navier-Stokes equations on \mathbb{R}^2 . They showed that small solutions of the corresponding vorticity equation, with non-zero total vorticity, asymptotically approach the Oseen vortex. In their work, they constructed finite-dimensional invariant manifolds of these equations, and proved that all solutions in a neighborhood of the origin approach one of these manifolds with a rate which can be determined. Thus, computing the asymptotics of solutions is reduced to the task of determining the asymptotics of the resulting systems of ordinary differential equations on these invariant manifolds.

This result was improved later in [17], where the authors showed that the Oseen vortices are not only locally stable but also globally stable. In other words, any solution of the two-dimensional vorticity equation whose initial vorticity is integrable will approach one of the Oseen vortices. The proof of the global stability was based on the construction of a pair of Lyapunov functionals for the rescaled vorticity equation. Later, in [15], Gallay and Rodrigues gave an estimation of the time that the solutions of the two-dimensional vorticity equation take to reach a neighborhood of the Oseen vortex, when the initial data are integrable and well localized in space (in [24], Rodrigues extended these results to slightly inhomogeneous incompressible fluids).

In this paper, we will prove that the solutions of the system (*SGF*) have the same behavior as the solutions of the Navier-Stokes equations, that is, the vorticities converge to an Oseen vortex when the time goes to infinity.

As in the case of the Navier-Stokes equations, we will determine the asymptotics of the solutions of the system (*SGF*) by studying the evolution of the vorticity, rather than the velocity. This is especially convenient in the two-dimensional case, where the vorticity is a scalar.

In fact, taking the curl of the first equation in (*SGF*), and using the identity

$$\operatorname{rot} (\operatorname{rot} \tilde{u} \times u) = u \cdot \nabla (\operatorname{rot} \tilde{u}),$$

which is true for any divergence free smooth vector fields u and \tilde{u} in \mathbb{R}^2 , we obtain the following equation for the vorticity $w = \operatorname{rot} u$

$$(1.1) \quad \partial_t(w - \alpha \Delta w) - \nu \Delta w + u \cdot \nabla(w - \alpha \Delta w) = 0$$

One can then recover the solution $u(x, t)$ of (*SGF*) via the Biot-Savart law (see Section 2.1).

In order to understand the long-time asymptotics of (*SGF*), it is helpful to introduce scaling variables. Scaling variables have been used in the study of the long-time behavior of parabolic and also damped hyperbolic equations, in particular to prove convergence to self-similar solutions (see for example [16], [17], [13]). Following the ideas of Gallay and Wayne in [16] (see also [13]), for any fixed, large enough time T , we introduce the new scaled variables

$$(1.2) \quad \xi = \frac{x}{\sqrt{\nu(t+T)}}, \quad \tau = \log(t+T).$$

We also define the new functions $W(\xi, \tau)$ and $V(\xi, \tau)$ by

$$(1.3) \quad w(x, t) = \frac{1}{t+T} W\left(\frac{x}{\sqrt{\nu(t+T)}}, \log(t+T)\right)$$

and

$$(1.4) \quad u(x, t) = \sqrt{\frac{\nu}{t+T}} V\left(\frac{x}{\sqrt{\nu(t+T)}}, \log(t+T)\right)$$

where $w(x, t)$ is a solution of (1.1) and $u(x, t)$ is the corresponding velocity field.

Let

$$(1.5) \quad \tau_0 = \log T, \quad \bar{\alpha} = \frac{\alpha}{\nu T}, \quad \bar{\epsilon} = \frac{\epsilon}{\nu^2 T}.$$

Then, $W(\xi, \tau)$ satisfies the following system

$$(1.6) \quad \begin{aligned} \partial_\tau (W - \bar{\alpha} e^{-\tau} \Delta_\xi W) - \mathcal{L}W + V \cdot \nabla_\xi (W - \bar{\alpha} e^{-\tau} \Delta_\xi W) \\ + \bar{\alpha} e^{-\tau} \Delta_\xi W + \frac{\bar{\alpha}}{2} e^{-\tau} \xi \cdot \nabla_\xi \Delta_\xi W = 0, \end{aligned}$$

where $W(\xi, \tau_0) = W_0(\xi) = Tw_0(x)$ and

$$(1.7) \quad \mathcal{L}W = \Delta W + \frac{1}{2} \xi \cdot \nabla W + W.$$

The second idea that helps to understand the long-time asymptotics of (SGF) is the introduction of weighted Sobolev spaces. For any $m \geq 0$, we define the Hilbert space $L^2(m)$ by

$$(1.8) \quad L^2(m) = \{f \in L^2(\mathbb{R}^2) \mid \int_{\mathbb{R}^2} (1 + |\xi|^2)^m |f|^2 d\xi < \infty\}$$

We denote

$$\|f\|_{L^2(m)} = \left(\int_{\mathbb{R}^2} (1 + |\xi|^2)^m |f|^2 d\xi \right)^{\frac{1}{2}} < \infty.$$

We notice that the spectrum of the operator \mathcal{L} acting on $L^2(m)$ consists of a discrete spectrum and a continuous one. Choosing m large enough, we can move the continuous spectrum to the left as much as wanted. The eigenvectors corresponding to the isolated eigenvalues can be computed explicitly and are rapidly decaying at infinity (For more details, see section 3.1).

If $m > 1$, $L^2(m)$ is embedded into $L^1(\mathbb{R}^2)$. We denote by $L_0^2(m)$ the closed subspace of $L^2(m)$ given by

$$L_0^2(m) = \{f \in L^2(m) \mid \int_{\mathbb{R}^2} f(\xi) d\xi = 0\}$$

We also define the higher order Sobolev spaces

$$H^1(m) = \{f \in L^2(m) \mid \partial_i f \in L^2(m), i = 1, 2\}$$

$$H^2(m) = \{f \in H^1(m) \mid \partial_i \partial_j f \in L^2(m), i, j = 1, 2\}$$

We also use the classical Lebesgue spaces $L^p(\mathbb{R}^2)$ equipped with the classical norm

$$\|u\|_{L^p} = \left(\int_{\mathbb{R}^2} |u(x)|^p dx \right)^{\frac{1}{p}}, \text{ for all } p \geq 1.$$

The first step in the study of the asymptotic behavior of the solutions of Equation (1.1) is to prove a local existence theorem in the weighted Sobolev spaces $H^2(m)$, $m \geq 0$.

For this purpose and for some technical reasons, we regularize Equation (1.1) by adding the smoothing term $\epsilon \Delta^2 w$. Then, we study the asymptotic behavior of the solution w_ϵ of the regularized equation and establish energy estimates that are uniform with respect to ϵ . Finally, using these energy estimates, we prove that the

family of solutions $(w_\epsilon)_\epsilon$ of these regularized equations admits a limit w , which is a solution of Equation (1.1). We also show that this limiting solution w has the same rate of decay as the regularized solution. We obtain the following theorem which describe the large time asymptotic behavior of the solutions of Equation (1.6) (the vorticity equation written in the scaled variables).

THEOREM 1.1. *Let $T > 0$ be a fixed time. There exist two positive constants $\bar{\alpha}_0$ and γ_0 such that, for all $\bar{\alpha} \leq \bar{\alpha}_0$, for all W_0 in $H^2(2)$ satisfying*

$$(1.9) \quad \|W_0\|_{H^1}^2 + \bar{\alpha}e^{-\tau_0} \|\Delta W_0\|_{L^2}^2 + \|\|\xi\|^2 W_0\|_{L^2}^2 + \bar{\alpha}e^{-\tau_0} \|\|\xi\|^2 \Delta W_0\|_{L^2}^2 \leq \gamma_0,$$

where $\tau_0 = \log T$, Equation (1.6) has a unique solution $W(\tau) \in C^0([\tau_0, +\infty[, H^2(2))$ satisfying $W(\tau_0) = W_0$.

Moreover, the following inequality is satisfied, for all $\tau \geq \tau_0$,

$$\|(1 - \bar{\alpha}e^{-\tau} \Delta)(W(\tau) - \beta G)\|_{L^2(2)} \leq Ce^{-\frac{\theta}{2}\tau}$$

where C and θ are positive constants, $\theta < \frac{1}{2}$,

$$\beta = \int_{\mathbb{R}^2} W_0(\xi) d\xi$$

and where G is the Oseen vortex defined by

$$G(\xi) = \frac{1}{4\pi} e^{-|\xi|^2/4}, \quad \xi \in \mathbb{R}^2.$$

The interpretation of the result in the unscaled variables (x, t) is as follows:
Let

$$(1.10) \quad \Omega(x, t) = \frac{1}{t+T} G\left(\frac{x}{\sqrt{\nu(t+T)}}\right)$$

and

$$(1.11) \quad u^\Omega(x, t) = \sqrt{\frac{\nu}{t+T}} V^G\left(\frac{x}{\sqrt{\nu(t+T)}}\right).$$

From Theorem 1.1, we deduce the following result.

COROLLARY 1.2. *Let $T > 0$ be a fixed time so that $\frac{\alpha}{\nu T} < \bar{\alpha}_0$. Then, there exists a positive constant γ such that for all w_0 in $H^2(2)$ satisfying*

$$T \|w_0\|_{L^2}^2 + T^{\frac{3}{2}} \|\nabla w_0\|_{L^2}^2 + \alpha T \|\Delta w_0\|_{L^2}^2 + \|x^2 w_0\|_{L^2}^2 + \alpha \|x^2 \Delta w_0\|_{L^2}^2 \leq \gamma,$$

the unique solution $w(x, t)$ of Equation (1.1) satisfies, for all $t \geq 0$,

$$(1.12) \quad \begin{aligned} \|(1 - \frac{\alpha}{T} \Delta)(w(t) - \beta \Omega)\|_{L^p} &\leq C_p (T+t)^{-1-\frac{\theta}{2}+\frac{1}{p}}, \quad 1 \leq p \leq 2, \\ \|x^2(1 - \frac{\alpha}{T} \Delta)(w(t) - \beta \Omega)\|_{L^2} &\leq C(T+t)^{-1-\frac{\theta}{2}} \end{aligned}$$

where C, C_p and $\theta, \theta < 1/2$, are three positive constants and Ω is given by (1.10). If $u(x, t)$ is the velocity field obtained from $w(x, t)$ via the Biot-Savart law, then

$$(1.13) \quad \|(1 - \frac{\alpha}{T} \Delta)(u(t) - \beta u^\Omega)\|_{L^q} \leq C_q (T+t)^{-\frac{1}{2}-\frac{\theta}{2}+\frac{1}{q}}, \quad 1 < q < \infty$$

where $0 < \theta < 1/2, C_q > 0$ is a constant and u^Ω is given by (1.11).

We emphasize that, although the system (SGF) converges to the system of the Navier-Stokes equations when α tends to zero, the results that we obtained here, are true for all values of α and not only for small values of α . Indeed, if we look at the rescaled equation (1.6), we remark that the coefficient $\bar{\alpha}$ can be as small as we want provided that we choose the parameter T large enough. This shows that the Oseen vortex is an asymptotic solution of the system (SGF) .

We also note that the techniques that we use to prove Theorem 1.1 are quite different from the one used in the case of the Navier-Stokes equations ([16]). Actually, we use the method of energy functionals developed in [13] and [14]. As in [13] and [14], we introduce “primitives” of the function W . More precisely, we introduce the auxiliary function $F(\xi, \tau)$ given by

$$(1.14) \quad F(\xi, \tau) = (-\Delta)^{-\frac{3}{4}}(W(\xi, \tau) - \beta G(\xi)).$$

This function $F(\xi, \tau)$ has a better decay rate than $W(\xi, \tau) - \beta G(\xi)$.

This paper is organized as follows. In the next section, we state the Biot-Savart law and recall some useful estimates of the velocity in terms of the vorticity. We also prove the local existence of the solution of the regularized vorticity equation in the space $H^2(m)$, $m \geq 0$. In Section 3, we study some spectral properties of the operator \mathcal{L} , we decompose the solution w and we give some auxiliary lemmas on the auxiliary function F defined by (1.14). In section 4, we introduce several functionals and we derive energy estimates in the space $H^2(2)$. We also state the theorem (see Theorem 3.3) which describes the first order asymptotics of small solutions of the regularized equation. The last section is devoted to the proof of Theorem 3.3. Finally, we pass to the limit when ϵ tends to zero and we prove Theorem 1.1 and Corollary 1.2.

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2. Preliminaries and regularized vorticity equation

2.1. The Biot-Savart law. As we explained in the introduction, our approach consists first in studying the behavior of the solutions of the vorticity equation (1.1) and then, to derive information about the solutions of the system (SGF) . For this reason, we begin our study by recalling the relationship between the velocity field u and the associated vorticity w . In two dimensions, the velocity field u is defined in terms of the vorticity via the Biot-Savart law

$$(2.1) \quad u(x) = \frac{1}{2\pi} \int_{\mathbb{R}^2} \frac{(x-y)^\perp}{|x-y|^2} w_3(y) dy$$

where $x^\perp = (-x_2, x_1)^T$ and $w = (0, 0, w_3)$.

The following lemma collects useful estimates for the velocity u in terms of the vorticity w (see [16]).

LEMMA 2.1. *Let u be the velocity field obtained from w via the Biot-Savart law (2.1).*

(a) Assume that $1 < p < 2 < q < \infty$ and $\frac{1}{q} = \frac{1}{p} - \frac{1}{2}$. If $w \in L^p(\mathbb{R}^2)$, then $u \in L^q(\mathbb{R}^2)^2$, and there exists a positive constant C_p such that

$$\|u\|_{L^q} \leq C_p \|w\|_{L^p}.$$

(b) Assume that $1 \leq p < 2 < q \leq \infty$ and define $\lambda \in (0, 1)$ by the relation $\frac{1}{2} = \frac{\lambda}{p} + \frac{1-\lambda}{q}$.

If $w \in L^p(\mathbb{R}^2) \cap L^q(\mathbb{R}^2)$, then $u \in L^\infty(\mathbb{R}^2)^2$, and there exists $C > 0$ such that

$$\|u\|_{L^\infty} \leq C \|w\|_{L^p}^\lambda \cdot \|w\|_{L^q}^{1-\lambda}.$$

(c) Assume that $1 < p < \infty$. If $w \in L^p(\mathbb{R}^2)$, then $\nabla u \in L^p(\mathbb{R}^2)^4$, and there exists a positive constant \tilde{C}_p such that

$$\|\nabla u\|_{L^p} \leq \tilde{C}_p \|w\|_{L^p}.$$

(d) Let $s \in \mathbb{R}$ and $J = (-\Delta)^{\frac{1}{2}}$.

If $J^{s-1}w \in L^2(\mathbb{R}^2)$, then $J^s u \in L^2(\mathbb{R}^2)^2$, and there exists a positive constant C such that

$$\|J^s u\|_{L^2} \leq C \|J^{s-1}w\|_{L^2}.$$

In addition, $\operatorname{div} u = 0$ and $\operatorname{rot} u = \partial_1 u_2 - \partial_2 u_1 = w$.

For the proof of (a), (b) and (c), we refer to [16]. To prove (d), it is sufficient to write the expression of the Biot-Savart law in Fourier variables:

$$\hat{u}(\eta) = \frac{i\eta^\perp}{|\eta|^2} \hat{w}(\eta).$$

LEMMA 2.2. Let u be the velocity field obtained from w via the Biot-Savart law. There exists a positive constant C such that, for any w in $L^2(2) \cap H^1(\mathbb{R}^2)$, we have,

$$(a) \quad \|u\|_{L^\infty} \leq C \|w\|_{H^1}^{\frac{1}{2}} \|w\|_{L^2(2)}^{\frac{1}{2}},$$

$$(b) \quad \|u\|_{L^4} \leq C \|w\|_{L^2(2)},$$

Proof : In order to prove Inequality (a), we use Lemma 2.1, part (b), with $\lambda = \frac{1}{2}$, $p = \frac{6}{5}$, $q = 6$, for example, and the fact that $H^1(\mathbb{R}^2)$ and $L^2(2)$ are continuously embedded into $L^6(\mathbb{R}^2)$ and $L^{\frac{6}{5}}(\mathbb{R}^2)$ respectively.

To prove Inequality (b), we use Lemma 2.1, part (a) and the continuous injection of $L^2(2)$ into $L^{\frac{4}{3}}(\mathbb{R}^2)$. \square

We remark that, according to the Biot-Savart law, the velocity is, in general, not in $L^2(\mathbb{R}^2)$. However, if $\int_{\mathbb{R}^2} w(\xi) d\xi = 0$, then $u \in L^2(\mathbb{R}^2)$ and we have the following lemma.

LEMMA 2.3. For any w in $L^2(1)$, with $\int_{\mathbb{R}^2} w(\xi) d\xi = 0$, the corresponding velocity field u obtained from w via the Biot-Savart law belongs to $L^2(\mathbb{R}^2)$ and we have:

$$\|u\|_{L^2} \leq C \| |\xi| w \|_{L^2}.$$

where C is a constant independent of w and u .

Proof : Let \hat{w} be the Fourier transform of w . Then, using the Biot-Savart law and the fact that $\hat{w}(0) = 0$, we can write

$$\begin{aligned} \|u\|_{L^2}^2 &= \int_{\mathbb{R}^2} \frac{1}{|k|^2} |\hat{w}(k)|^2 dk = \int_0^1 \int_{\mathbb{R}^2} |\nabla \hat{w}(sk)|^2 dk ds \\ &\leq C \|\nabla \hat{w}\|_{L^2}^2 \leq C \|\xi\| w\|_{L^2}. \end{aligned}$$

□

LEMMA 2.4. *Let h belongs to $L^2(1)$, then $(-\Delta)^{-\frac{1}{4}}h$ belongs to $L^2(\mathbb{R}^2)$ and we have*

$$\left\| (-\Delta)^{-\frac{1}{4}} h \right\|_{L^2} \leq C \|h\|_{L^2(1)}$$

Proof : Using the Fourier transformation, we can write

$$\begin{aligned} \left\| (-\Delta)^{-\frac{1}{4}} h \right\|_{L^2}^2 &= \int_{\mathbb{R}^2} \frac{1}{|k|} |\hat{h}(k)|^2 dk \\ &\leq \int_{|k| \leq 1} \frac{1}{|k|} |\hat{h}(k)|^2 dk + \int_{|k| \geq 1} |\hat{h}(k)|^2 dk \end{aligned}$$

On one hand, the second term in this inequality can be bounded $\|h\|_{L^2}^2$. On the other hand, applying Hölder's inequality to the first term in the right-hand side of this inequality together with a classical Sobolev embedding theorem, we obtain

$$\begin{aligned} \left\| (-\Delta)^{-\frac{1}{4}} h \right\|_{L^2}^2 &\leq \left\| \hat{h} \right\|_{L^6}^2 \left(\int_{|k| \leq 1} \frac{1}{|k|^{\frac{3}{2}}} dk \right)^{\frac{2}{3}} + \|h\|_{L^2}^2 \\ &\leq C \left\| \hat{h} \right\|_{H^1}^2 + \|h\|_{L^2}^2 \\ &\leq C \|(1 + |\xi|)h\|_{L^2}^2 \leq C \|h\|_{L^2(1)}^2 \end{aligned}$$

□

REMARK 2.5. *Using the Fourier transform, it is easy to remark that*

$$\left\| (-\Delta)^{-\frac{3}{4}} \partial_i h \right\|_{L^2} \leq \left\| (-\Delta)^{-\frac{1}{4}} h \right\|_{L^2}, \quad i = 1, 2.$$

In fact, we have,

$$\begin{aligned} \left\| (-\Delta)^{-\frac{3}{4}} \partial_i h \right\|_{L^2}^2 &= \int_{\mathbb{R}^2} \frac{|k_i|^2}{|k|^3} |\hat{h}(k)|^2 dk \leq \int_{\mathbb{R}^2} \frac{1}{|k|} |\hat{h}(k)|^2 dk \\ &= \left\| (-\Delta)^{-\frac{1}{4}} h \right\|_{L^2}^2. \end{aligned}$$

2.2. Local existence of the regularized vorticity equation. As we already said in the introduction, in order to study the solutions of Equation (1.1), in the weighted Sobolev spaces, we introduce the regularized equation (2.2) below. Indeed, since Equation (1.1) contains a nonlinearity that involves derivatives of order three, we cannot directly use classical methods of proofs to obtain the local existence. In order to overcome this difficulty, we add the smoothing term $\epsilon \Delta^2$. to

the equation (1.1) and study the local well-posedness of the following equation in the space $H^2(m)$, $m \geq 0$,

$$(2.2) \quad \begin{aligned} \partial_t(w_\epsilon - \alpha\Delta w_\epsilon) + \epsilon\Delta^2 w_\epsilon - \nu\Delta w_\epsilon + u_\epsilon \cdot \nabla(w_\epsilon - \alpha\Delta w_\epsilon) &= 0 \\ w_\epsilon(0) &= w_0 \end{aligned}$$

THEOREM 2.6. *Let $\epsilon > 0$. There exists a time $t_{max} > 0$ such that, for all $w_0 \in H^2(m)$, $m \geq 0$, Equation (2.2) has a unique solution w_ϵ in the space $C^0([0, t_{max}], H^2(m)) \cap C^1((0, t_{max}], L^2(m))$, with $w_\epsilon(0) = w_0$.*

Proof : Let β be a small positive constant (whose choice will be made more precise later). In order to prove the local existence of the solutions of Equation (2.2), we introduce the auxiliary variable and auxiliary unknown

$$X = \beta x, \text{ and } w_\epsilon(x, t) = s_\epsilon(\beta x, t) = s_\epsilon(X, t).$$

The equation satisfied by s_ϵ is given by

$$(2.3) \quad \partial_t(s_\epsilon - \alpha\beta^2\Delta_X s_\epsilon) - \nu\beta^2\Delta_X s_\epsilon + \epsilon\beta^4\Delta_X^2 s_\epsilon + \beta u_\epsilon \cdot \nabla_X(s_\epsilon - \alpha\beta^2\Delta_X s_\epsilon) = 0$$

We will see, in the proof of the local existence of solutions, that the above change of variables allows us to avoid restrictions on the size of α .

Let $q(X) = (1 + |X|^2)^{m/2}$, and $z_\epsilon(t, X) = q(X)s_\epsilon(X, t)$.

Then $s_\epsilon \in C^0([0, t_{max}], H^2(m)) \cap C^1((0, t_{max}], L^2(m))$ is a solution of Equation (2.3) if and only if the function $z_\epsilon \in C^0([0, t_{max}], H^2(\mathbb{R}^2)) \cap C^1((0, t_{max}], L^2(\mathbb{R}^2))$ is a solution of the following equations

$$(2.4) \quad \begin{aligned} \partial_t[z_\epsilon - \alpha\beta^2\Delta_X z_\epsilon - \alpha\beta^2q\Delta_X(q^{-1})z_\epsilon - 2\alpha\beta^2q\nabla_X(q^{-1})\nabla_X z_\epsilon] + \epsilon\beta^4\Delta_X^2 z_\epsilon \\ = P(z_\epsilon), \\ z_\epsilon(0) = q(X)w_0(X) = z_0 \in H^2(\mathbb{R}^2), \end{aligned}$$

$$\begin{aligned} \text{where } P(z_\epsilon) = \nu\beta^2\Delta_X z_\epsilon + q(X) \left[\nu\beta^2\Delta_X(q^{-1})z_\epsilon + 2\nu\beta^2\nabla_X(q^{-1}) \cdot \nabla_X z_\epsilon \right. \\ \left. - \beta(u_\epsilon \cdot \nabla_X)(q^{-1}z_\epsilon) + \alpha\beta^3(u_\epsilon \cdot \nabla_X) \left(\Delta_X(q^{-1})z_\epsilon + 2\nabla_X(q^{-1}) \cdot \nabla_X(z_\epsilon) \right) \right. \\ \left. + \alpha\beta^3(u_\epsilon \cdot \nabla_X)(q^{-1}\Delta_X z_\epsilon) - \epsilon\beta^4\Delta_X \left(\Delta_X(q^{-1})z_\epsilon + 2\nabla_X(q^{-1}) \cdot \nabla_X z_\epsilon \right) \right. \\ \left. - \epsilon\beta^4 \left(\Delta_X(q^{-1})\Delta_X z_\epsilon + 2\nabla_X(q^{-1}) \cdot \nabla_X \Delta_X z_\epsilon \right) \right]. \end{aligned}$$

Let A be the linear operator: $D(A) = H^2(\mathbb{R}^2) \rightarrow L^2(\mathbb{R}^2)$, given by

$$A = \alpha\beta^2\Delta_X + \alpha\beta^2q\Delta_X(q^{-1}).$$

If we suppose that β is small enough, then $Id - A$ is invertible from $L^2(\mathbb{R}^2)$ into $H^2(\mathbb{R}^2)$. Indeed, for $f \in L^2(\mathbb{R}^2)$, we consider the following problem.

Find $u \in H^2(\mathbb{R}^2)$ such that

$$(2.5) \quad (Id - A)u = f$$

Let a be the bilinear form defined, for $u, v \in H^1(\mathbb{R}^2)$, by

$$\begin{aligned} a(u, v) = \int_{\mathbb{R}^2} u(X) \cdot v(X) dX + \alpha\beta^2 \int_{\mathbb{R}^2} \nabla u(X) \cdot \nabla v(X) dX \\ - \alpha\beta^2 \int_{\mathbb{R}^2} q\Delta(q^{-1})u(X)v(X) dX. \end{aligned}$$

Then, we have, for any $u \in H^1(\mathbb{R}^2)$,

$$a(u, u) \geq \int_{\mathbb{R}^2} |u(X)|^2 dX + \alpha\beta^2 \int_{\mathbb{R}^2} |\nabla u(X)|^2 dX \\ - \alpha\beta^2 \int_{\mathbb{R}^2} |q\Delta(q^{-1})| |u(X)|^2 dx$$

We notice that $|q\Delta(q^{-1})| \leq C_0$, where $C_0 > 0$ is a constant.

Thus,

$$a(u, u) \geq (1 - \alpha\beta^2 C_0) \|u\|_{L^2}^2 + \alpha\beta^2 \|\nabla u\|_{L^2}^2.$$

Supposing that β is small enough such that $1 - \alpha\beta^2 C_0 > 0$, we obtain from the Lax-Milgram theorem that there exists a unique solution $u \in H^1(\mathbb{R}^2)$ of (2.5). Since f belongs to $L^2(\mathbb{R}^2)$, we deduce from a classical regularity theorem that u belongs to $H^2(\mathbb{R}^2)$ and

$$\|u\|_{H^2} \leq C_\beta \|f\|_{L^2},$$

where $C_\beta > 0$ is a constant, independent of f and u .

On the other hand, if β is small enough, we can show by the same way that $(Id - A - \alpha\beta^2 q\nabla(q^{-1})\nabla)^{-1}$ exists and is defined from $L^2(\mathbb{R}^2)$ into $H^2(\mathbb{R}^2)$.

In fact, remarking that $|q\nabla(q^{-1})| \leq C_1$, where $C_1 > 0$, we have

$$a(u, u) - \alpha\beta^2 \int_{\mathbb{R}^2} q\nabla(q^{-1})\nabla u(X)u(X)dX \geq \\ (1 - \alpha\beta^2 C_0) \|u\|_{L^2}^2 + \alpha\beta^2 \|\nabla u\|_{L^2}^2 - \alpha\beta^2 C_1 \|\nabla u\|_{L^2} \|u\|_{L^2}$$

Then, applying the Young inequality and supposing that

$1 - \alpha\beta^2 C_0 - \frac{1}{2}\alpha\beta^2 C_1^2 > 0$, we obtain,

$$a(u, u) - \alpha\beta^2 \int_{\mathbb{R}^2} q\nabla(q^{-1})\nabla u(x)u(x)dx \geq \\ (1 - \alpha\beta^2 C_0 - \frac{1}{2}\alpha\beta^2 C_1^2) \|u\|_{L^2}^2 + \frac{1}{2}\alpha\beta^2 \|\nabla u\|_{L^2}^2$$

Finally, using the Lax-Milgram theorem, we can show that the operator

$(Id - A - \alpha\beta^2 q\nabla(q^{-1})\nabla)$ is invertible.

Now, let $B = -\alpha\beta^2 q\nabla(q^{-1})\nabla$.

Then, Equation (2.4) can be written as

$$(2.6) \quad \partial_t z_\epsilon + \epsilon(I - A + B)^{-1} \Delta_X^2 z_\epsilon = (I - A + B)^{-1} P(z_\epsilon) \equiv \tilde{P}(z_\epsilon)$$

The operator $(I - A + B)^{-1} \Delta_X^2$ can be defined from $H^2(\mathbb{R}^2)$ into $L^2(\mathbb{R}^2)$ and can be written as

$$(I - A + B)^{-1} \Delta_X^2 = (I - A)^{-1} \Delta_X^2 - (I - A + B)^{-1} B (I - A)^{-1} \Delta_X^2$$

The operator $(I - A)^{-1} \Delta_X^2$ defined from $H^2(\mathbb{R}^2)$ into $L^2(\mathbb{R}^2)$ is self-adjoint and positive, thus, $-(I - A)^{-1} \Delta_X^2$ is the generator of an analytic semigroup in $L^2(\mathbb{R}^2)$.

Let

$$R = -(I - A + B)^{-1} B (I - A)^{-1} \Delta_X^2 : H^1(\mathbb{R}^2) \longrightarrow L^2(\mathbb{R}^2).$$

Then, there exists a constant $C_\beta > 0$ such that, for all $u \in H^1(\mathbb{R}^2)$,

$$\|Ru\|_{L^2} \leq C_\beta \|u\|_{H^1}.$$

Therefore, $(I - A)^{-1} \Delta_X^2 + R$ is the generator of an analytic semigroup in $L^2(\mathbb{R}^2)$ (see [22] Corollary 2.2 page 81).

Since $\tilde{P}(z_\epsilon)$ is a locally Lipschitz continuous mapping from $H^1(\mathbb{R}^2)$ into $L^2(\mathbb{R}^2)$, we deduce, from a classical result ([22], [4]) that there exists a time $t_{max} > 0$ such that, for all $z_0 \in H^2(\mathbb{R}^2)$, Equation (2.4) has a unique classical solution

$z_\epsilon \in C^0([0, t_{max}], H^2(\mathbb{R}^2)) \cap C^1((0, t_{max}], L^2(\mathbb{R}^2))$ satisfying $z_\epsilon(0) = z_0$. Therefore, we have proved the local existence and uniqueness of solutions of Equation (2.3) in the space $C^0([0, t_{max}], H^2(m)) \cap C^1((0, t_{max}], L^2(m))$ and thus, of the regularized vorticity equation (2.2). \square

To complete the proof of the local existence of the solution w of Equation (1.1), we need to take the limit of w_ϵ when ϵ tends to zero, but we do not know how to prove that the existence time of w_ϵ is independent of ϵ . Therefore in the next sections, the study of the asymptotic behavior will be done for w_ϵ . We will establish energy estimates on w_ϵ , which are uniform in ϵ . Then passing to the limit when ϵ tends to zero, we will prove that the limit of w_ϵ is the solution of Equation (1.1) and satisfies the same energy estimates as w_ϵ .

3. Spectral study of the operator \mathcal{L} and decomposition of the solution

One of the main ideas in our analysis of the long-time asymptotics of Equation (2.2) is based on rewriting this equation in terms of the scaled variables (ξ, τ) given by (1.2). We recall that the new functions W_ϵ and V_ϵ in the rescaled variables are given by

$$(3.1) \quad w_\epsilon(x, t) = \frac{1}{t+T} W_\epsilon\left(\frac{x}{\sqrt{\nu(t+T)}}, \log(t+T)\right)$$

and

$$(3.2) \quad u_\epsilon(x, t) = \sqrt{\frac{\nu}{t+T}} V_\epsilon\left(\frac{x}{\sqrt{\nu(t+T)}}, \log(t+T)\right)$$

where $w_\epsilon(x, t)$ is a solution of (2.2) and $u_\epsilon(x, t)$ is the corresponding velocity field. We remark that $t = 0$ corresponds to $\tau_0 = \log T$.

The ‘‘rescaled vorticity’’ $W_\epsilon(\xi, \tau)$ satisfies the following system

$$(3.3) \quad \begin{aligned} \partial_\tau(W_\epsilon - \bar{\alpha}e^{-\tau}\Delta_\xi W_\epsilon) - \mathcal{L}W_\epsilon + V_\epsilon \cdot \nabla_\xi(W_\epsilon - \bar{\alpha}e^{-\tau}\Delta_\xi W_\epsilon) + \bar{\epsilon}e^{-2\tau}\Delta_\xi^2 W_\epsilon \\ + \bar{\alpha}e^{-\tau}\Delta_\xi W_\epsilon + \frac{\bar{\alpha}}{2}e^{-\tau}\xi \cdot \nabla_\xi \Delta_\xi W_\epsilon = 0, \end{aligned}$$

$$W_\epsilon(\xi, \tau_0) = W_0(\xi) = Tw_0(x),$$

where the operator \mathcal{L} has been defined in (1.7), $\tau_0, \bar{\alpha}, \bar{\epsilon}$ are given by (1.5) and, according to the Biot-Savart law,

$$V_\epsilon(\xi, \tau) = \frac{1}{2\pi} \int_{\mathbb{R}^2} \frac{(\xi - \eta)^\perp}{|\xi - \eta|^2} W_3^\epsilon(\eta, \tau) d\eta$$

where $W_\epsilon = (0, 0, W_3^\epsilon)$.

We point out that Equation (3.3) preserves the total mass of W_ϵ . Indeed, integrating (3.3) over \mathbb{R}^2 , and using the fact that $\text{div } V_\epsilon = 0$, we obtain

$$(3.4) \quad \int_{\mathbb{R}^2} W_\epsilon(\xi, \tau) d\xi = \int_{\mathbb{R}^2} W_0(\xi) d\xi.$$

3.1. The operator \mathcal{L} . As we already explained in the introduction, working in weighted Sobolev spaces allows to push the continuous spectrum of \mathcal{L} to the left. If one studies the spectrum of the operator \mathcal{L} acting on $L^2(m)$, one finds that it consists of a sequence of eigenvalues

$$\sigma_d = \left\{ -\frac{k}{2} \mid k = 0, 1, 2, \dots, m-2 \right\}$$

and continuous spectrum

$$\sigma_c = \left\{ \lambda \in \mathbb{C} \mid \operatorname{Re}(\lambda) \leq -\frac{m-1}{2} \right\}$$

(for more details, see Appendix A in [16]).

The eigenvectors corresponding to the isolated eigenvalues can be explicitly computed and are rapidly decaying at infinity (see Appendix B in [16]).

In our study, we will consider the behavior of small solutions of (3.3) in the space $L^2(m)$ with $m = 2$. The operator \mathcal{L} has a simple isolated eigenvalue $\lambda_0 = 0$ in $L^2(2)$, with corresponding eigenfunction

$$(3.5) \quad G(\xi) = \frac{1}{4\pi} e^{-|\xi|^2/4}, \quad \xi \in \mathbb{R}^2.$$

For any $\beta \in \mathbb{R}$,

$$(3.6) \quad W(\xi) = \beta G(\xi)$$

is called the Oseen vortex. The corresponding velocity field V^G (such that $\operatorname{rot} V^G = G$) is given by

$$(3.7) \quad V^G(\xi) = \frac{1 - e^{-|\xi|^2/4}}{2\pi |\xi|^2} \begin{pmatrix} -\xi_2 \\ \xi_1 \end{pmatrix}$$

REMARK 3.1. *It is clear that ξ is orthogonal to V^G , therefore*

$$(3.8) \quad V^G \cdot \nabla G(\xi) = 0$$

and

$$(3.9) \quad V^G \cdot \nabla \Delta G(\xi) = 0$$

As a consequence of the equality (3.8), the Oseen vortex defined by (3.6) is a stationary solution of the equation

$$(3.10) \quad \partial_\tau W - \mathcal{L}W + V \cdot \nabla W = 0$$

where V is the velocity field corresponding to the vorticity W .

Note that this equation is precisely the vorticity equation corresponding to the Navier-Stokes equations in space dimension two.

REMARK 3.2. *Remarking that $|V^G| \sim |\xi|^{-1}$ as $|\xi| \rightarrow +\infty$, we obtain that $V^G \in L^q(\mathbb{R}^2)^2$, $\forall q > 2$.*

3.2. Decomposition of the solution and auxiliary lemmas. In this paper, we will prove the following result.

THEOREM 3.3. *Let $T > 0$ be a fixed time. There exist two positive constants $\bar{\alpha}_0$ and γ_0 such that for all $\bar{\alpha} \leq \bar{\alpha}_0$ and for all W_0 in $H^2(2)$ satisfying*

$$(3.11) \quad \|W_0\|_{H^1}^2 + \bar{\alpha}e^{-\tau_0} \|\Delta W_0\|_{L^2}^2 + \|\|\xi\|^2 W_0\|_{L^2}^2 + \bar{\alpha}e^{-\tau_0} \|\|\xi\|^2 \Delta W_0\|_{L^2}^2 \leq \gamma_0,$$

where $\tau_0 = \log T$, Equation (3.3) has a unique solution $W_\epsilon(\tau) \in C^0([\tau_0, +\infty[, H^2(2))$ satisfying $W_\epsilon(\tau_0) = W_0$. Moreover, the following inequality is satisfied, for all $\tau \geq \tau_0$,

$$\|(1 - \bar{\alpha}e^{-\tau} \Delta)(W_\epsilon(\tau) - \beta G)\|_{L^2(2)}^2 \leq Ce^{-\theta\tau}$$

where C and θ , $\theta < \frac{1}{2}$, are positive constants, $\beta = \int_{\mathbb{R}^2} W_0(\xi) d\xi$ and G is the Oseen vortex defined by (3.6).

Since we are interested in studying the behavior of the solution of (3.3) with initial data W_0 near an Oseen vortex in the space $H^2(2)$, it is convenient to introduce the following change of functions:

$$(3.12) \quad W_\epsilon(\xi, \tau) = \beta G(\xi) + f_\epsilon(\xi, \tau),$$

where, due to the conservation of mass property (3.4),

$$(3.13) \quad \beta \equiv \int_{\mathbb{R}^2} W_0(\xi) d\xi = \beta.$$

Thus, $f_\epsilon(\xi, \tau)$ belongs to $L_0^2(2)$ for any $\tau \geq 0$, where $L_0^2(m) = \{f \in L^2(m) / \int_{\mathbb{R}^2} f(\xi) d\xi = 0\}$.

In what follows, we will drop the index ϵ and simply denote $f_\epsilon(x, t)$ by $f(x, t)$.

Taking into account the properties (3.8) and (3.9), we see that $f(\xi, \tau)$ satisfies the following equation

$$(3.14) \quad \begin{aligned} & \partial_\tau(f - \bar{\alpha}e^{-\tau} \Delta f) - \mathcal{L}f + \bar{\epsilon}e^{-2\tau} \Delta^2 f + \bar{\alpha}e^{-\tau} \Delta f + \frac{\bar{\alpha}}{2} e^{-\tau} \xi \cdot \nabla \Delta f \\ & + K_f \cdot \nabla(f - \bar{\alpha}e^{-\tau} \Delta f) + \beta V^G \cdot \nabla(f - \bar{\alpha}e^{-\tau} \Delta f) + \beta K_f \cdot \nabla(G - \bar{\alpha}e^{-\tau} \Delta G) \\ & + \bar{\epsilon} \beta e^{-2\tau} \Delta^2 G + \beta \bar{\alpha} e^{-\tau} \Delta G + \beta \frac{\bar{\alpha}}{2} e^{-\tau} \xi \cdot \nabla \Delta G = 0 \end{aligned}$$

where $K_f(\xi, \tau) = V(\xi, \tau) - \beta V^G$.

As we explained in the introduction, the main argument in the study of the asymptotic behavior of f is the use of functional method. This method consists in writing various energy estimates for f and in considering a linear combination of these functionals in order to establish that f converges to zero with an exponential decay rate in the space $H^2(2)$.

In what follows, we will establish various energy estimates for $f(\xi, \tau)$ in the spaces $H^2(2)$. So, in a first step, we will control the L^2 -norm of f . Unfortunately, we cannot obtain good estimates of f in the space $L^2(\mathbb{R}^2)$.

Indeed, if (\cdot, \cdot) denotes the scalar product in $L^2(\mathbb{R}^2)$, we have,

$$(3.15) \quad (-\mathcal{L}f, f) = \|\nabla f\|_{L^2}^2 - \frac{1}{2} \|f\|_{L^2}^2,$$

which is not helpful in the functional method.

In the paper [13] (where the asymptotic behavior was studied in the one-dimensional space), the authors considered the primitive of f , because it had a better decay than f . In our study, since we are in the two-dimensional case, we will introduce the function

$$(3.16) \quad F(\xi, \tau) = (-\Delta)^{-\frac{3}{4}} f(\xi, \tau)$$

Before continuing our analysis, we give the following lemmas that will be useful later.

LEMMA 3.4. *Let f belong to $L^2(2)$ such that $\int_{\mathbb{R}^2} f(\xi) d\xi = 0$, then $(-\Delta)^{-\frac{3}{4}} f$ belongs to $L^2(\mathbb{R}^2)$ and we have*

$$(3.17) \quad \left\| (-\Delta)^{-\frac{3}{4}} f \right\|_{L^2} \leq C \|f\|_{L^2(2)},$$

where $C > 0$ is independent of f .

Proof : Let \hat{f} be the Fourier transform of f given by

$$(3.18) \quad \hat{f}(k) = \int_{\mathbb{R}^2} f(\xi) \exp(-ik \cdot \xi) d\xi.$$

Since $\hat{f}(0) = 0$, we can write

$$\begin{aligned} \left\| (-\Delta)^{-\frac{3}{4}} f \right\|_{L^2}^2 &= \int_{\mathbb{R}^2} \frac{1}{|k|^3} |\hat{f}(k)|^2 dk \\ &\leq \int_{|k| \leq 1} \frac{1}{|k|^3} |\hat{f}(k)|^2 dk + \int_{|k| \geq 1} |\hat{f}(k)|^2 dk \\ &\leq \int_0^1 \int_{|k| \leq 1} \frac{1}{|k|} |\nabla \hat{f}(sk)|^2 dk ds + \|f\|_{L^2}^2 \end{aligned}$$

Applying Hölder's inequality on the first term in the above inequality, we obtain

$$\begin{aligned} \left\| (-\Delta)^{-\frac{3}{4}} f \right\|_{L^2}^2 &\leq \int_0^1 \left(\int_{|k| \leq 1} |\nabla \hat{f}(sk)|^6 dk \right)^{\frac{1}{3}} \left(\int_{|k| \leq 1} \frac{1}{|k|^{\frac{3}{2}}} dk \right)^{\frac{2}{3}} ds + \|f\|_{L^2}^2 \\ &\leq C \left\| \nabla \hat{f} \right\|_{L^6}^2 + \|f\|_{L^2}^2 \leq C \left\| \nabla \hat{f} \right\|_{H^1}^2 + \|f\|_{L^2}^2 \end{aligned}$$

Therefore,

$$\left\| (-\Delta)^{-\frac{3}{4}} f \right\|_{L^2}^2 \leq C \|(1 + |\xi|^2) f\|_{L^2}^2 \leq C \|f\|_{L^2(2)}^2$$

□

We emphasize that in order to bound the L^2 -norm of f , it is sufficient to bound the L^2 -norms of ∇F and of ∇f .

In fact, applying Hölder's inequality, we have

$$\|f\|_{L^2}^2 = \int_{\mathbb{R}^2} (-\Delta)^{\frac{1}{4}} f (-\Delta)^{\frac{1}{2}} (-\Delta)^{-\frac{3}{4}} f \leq \left\| (-\Delta)^{\frac{1}{4}} f \right\|_{L^2} \left\| (-\Delta)^{\frac{1}{2}} F \right\|_{L^2}$$

Then, using the fact that $\|(-\Delta)^{\frac{1}{2}}F\|_{L^2} = \|\nabla F\|_{L^2}$ and applying Young's inequality, we obtain

$$\begin{aligned} \|f\|_{L^2}^2 &\leq \|f\|_{L^2}^{\frac{1}{2}} \left\| (-\Delta)^{\frac{1}{2}}f \right\|_{L^2}^{\frac{1}{2}} \|\nabla F\|_{L^2} \leq \|f\|_{L^2}^{\frac{1}{2}} \|\nabla f\|_{L^2}^{\frac{1}{2}} \|\nabla F\|_{L^2} \\ &\leq \frac{1}{2} \|\nabla F\|_{L^2}^2 + \frac{1}{4} \|\nabla f\|_{L^2}^2 + \frac{1}{4} \|f\|_{L^2}^2 \end{aligned}$$

Thus,

$$(3.19) \quad \|f\|_{L^2}^2 \leq \frac{2}{3} \|\nabla F\|_{L^2}^2 + \frac{1}{3} \|\nabla f\|_{L^2}^2$$

In order to bound the L^2 -norm of ∇F , the first step consists in writing the equation satisfied by F . The lemma stated below will help us to write this equation.

LEMMA 3.5. *Let F be given by (3.16). We have*

$$\left((-\Delta)^{-\frac{3}{4}}(\xi \cdot \nabla f) \right) = -\frac{3}{2}F + \xi \cdot \nabla F$$

and

$$(-\Delta)^{-\frac{3}{4}}\mathcal{L}f = \Delta F + \frac{1}{2}\xi \cdot \nabla F + \frac{1}{4}F.$$

Proof : In what follows, the Fourier transform of f is sometimes denoted by $P(f)$. Using the Fourier transformation and integrating by parts, we can write

$$\begin{aligned} P\left((-\Delta)^{-\frac{3}{4}}(\xi \cdot \nabla f) \right)(k) &= -2P\left((-\Delta)^{-\frac{3}{4}}f \right)(k) + \frac{ik_i}{|k|^{\frac{3}{2}}} \int_{\mathbb{R}^2} \xi_i f(\xi) \exp(-ik \cdot \xi) d\xi \\ &= -2P\left((-\Delta)^{-\frac{3}{4}}f \right)(k) - \frac{k_i}{|k|^{\frac{3}{2}}} \partial_{k_i} \int_{\mathbb{R}^2} f(\xi) \exp(-ik \cdot \xi) d\xi \\ &= -\frac{3}{2}P\left((-\Delta)^{-\frac{3}{4}}f \right)(k) + P(\xi \cdot \nabla (-\Delta)^{-\frac{3}{4}}f)(k) \end{aligned}$$

Thus,

$$(-\Delta)^{-\frac{3}{4}}\mathcal{L}f = \Delta F + \frac{1}{2}\xi \cdot \nabla F + \frac{1}{4}F. \quad \square$$

Lemma 3.5 at once implies that

$$\left(-(-\Delta)^{-\frac{3}{4}}\mathcal{L}f, F \right) = \|\nabla F\|_{L^2}^2 + \frac{1}{4} \|F\|_{L^2}^2,$$

which will help us in obtaining “good L^2 -estimates” on F .

Using Lemma 3.5, we see that F satisfies the following equation

$$\begin{aligned} (3.20) \quad &\partial_\tau (F - \bar{\alpha} e^{-\tau} \Delta F) - \Delta F - \frac{1}{2} \xi \cdot \nabla F - \frac{1}{4} F + \bar{\epsilon} e^{-2\tau} \Delta^2 F + \frac{\bar{\alpha}}{4} e^{-\tau} \Delta F \\ &+ \frac{\bar{\alpha}}{2} e^{-\tau} \xi \cdot \nabla \Delta F + (-\Delta)^{-\frac{3}{4}} \left((K_f + \beta V_G) \cdot \nabla \left((-\Delta)^{\frac{3}{4}} F + \bar{\alpha} e^{-\tau} (-\Delta)^{\frac{7}{4}} F \right) \right) \\ &+ \beta (-\Delta)^{-\frac{3}{4}} \left(K_f \cdot \nabla (G - \bar{\alpha} e^{-\tau} \Delta G) \right) \\ &+ \frac{\bar{\alpha}}{2} e^{-\tau} \xi \cdot \nabla (-\Delta)^{\frac{1}{4}} G + \bar{\epsilon} \beta e^{-2\tau} (-\Delta)^{\frac{5}{4}} G + \frac{\bar{\alpha} \beta}{4} e^{-\tau} (-\Delta)^{\frac{1}{4}} G = 0 \end{aligned}$$

4. Asymptotic behavior of solutions and energy estimates

In this section, we will establish various energy estimates of the solutions of Equation (3.14) in the space $H^2(2)$.

In what follows, we introduce a positive constant δ_0 (that will be fixed later) and let $0 < \delta \leq \delta_0$. We also assume that, for some $\tau_0 < \tau_1 < \hat{\tau}$, where $\hat{\tau} = \log(T + t_{\max})$, we are given a solution $f \in C([\tau_0, \tau_1], H^2(2))$ of Equation (3.14) satisfying the following bound

$$(4.1) \quad |\beta|^2 + \|f(\tau)\|_{H^1}^2 + \|\xi^2 f(\tau)\|_{L^2}^2 < \delta, \quad \tau_0 \leq \tau \leq \tau_1$$

where β is given by (3.13).

Our aim is to control the behavior of the solution f on the time interval $[\tau_0, \tau_1]$, using energy functionals.

4.1. Energy estimates in $L^2(\mathbb{R}^2)$. In this section, we will introduce several functionals in order to establish energy estimates of f in various “unweighted” Sobolev spaces, in particular in the space $H^2(\mathbb{R}^2)$.

For this purpose, we will bound $\|f(\tau)\|_{H^1}^2 + \bar{\alpha}e^{-\tau} \|\Delta f(\tau)\|_{L^2}^2$. As we have explained in the previous section, it is essential to bound the L^2 -norm of ∇F in order to bound the L^2 -norm of f .

4.1.1. *Estimates of F and ∇F .* Let F be given by (3.16). In order to estimate $\|F\|_{L^2}$ and $\|\nabla F\|_{L^2}$, we introduce our first functional $E_0(\tau)$ given by

$$(4.2) \quad E_0(\tau) = \frac{1}{2}(\|F(\tau)\|_{L^2}^2 + \bar{\alpha}e^{-\tau} \|\nabla F(\tau)\|_{L^2}^2).$$

We have the following lemma for the functional E_0 .

LEMMA 4.1. *Assume that $f \in L^\infty([\tau_0, \tau_1], H^2(2))$ is a solution of (3.14) satisfying the bound (4.1). Then, there exists two positive constants C_0 and θ , $\theta < \frac{1}{2}$, such that for all $\tau \in [\tau_0, \tau_1]$,*

$$(4.3) \quad \begin{aligned} \partial_\tau E_0(\tau) + \theta E_0(\tau) + (1 + \frac{3\bar{\alpha}}{4}e^{-\tau} - \frac{\theta\bar{\alpha}}{2}e^{-\tau}) \|\nabla F\|_{L^2}^2 + \bar{\epsilon}(\frac{3}{4} - \frac{\theta}{2})e^{-2\tau} \|\Delta F\|_{L^2}^2 \\ \leq C_0 |\beta|^2 (\bar{\alpha}^2 + \bar{\epsilon})e^{-2\tau} + C_0 |\beta|^2 \|\nabla f\|_{L^2}^2 \\ + C_0(\delta + |\beta|^2)(\|f\|_{L^2}^2 + \|\xi^2 f\|_{L^2}^2) \\ + C_0(\delta + |\beta|^2)\bar{\alpha}^2 e^{-2\tau} (\|\Delta f\|_{L^2}^2 + \|\xi^2 \Delta f\|_{L^2}^2) \end{aligned}$$

Proof : In order to estimate the L^2 -norm of F , we take the scalar product in $L^2(\mathbb{R}^2)$ of Equation (3.20) with F . We obtain

$$(4.4) \quad \begin{aligned} \partial_\tau E_0(\tau) + \frac{1}{4} \|F\|_{L^2}^2 + (1 - \frac{\bar{\alpha}}{4}e^{-\tau}) \|\nabla F\|_{L^2}^2 + \frac{\bar{\alpha}}{2}e^{-\tau} (\xi \cdot \nabla \Delta F, F) \\ + \bar{\epsilon}e^{-2\tau} \|\Delta F\|_{L^2}^2 + \frac{\bar{\alpha}\beta}{2}e^{-\tau} (\xi \cdot \nabla (-\Delta)^{\frac{1}{4}} G, F) + \bar{\epsilon}\beta e^{-2\tau} ((-\Delta)^{\frac{5}{4}} G, F) \\ + \frac{\bar{\alpha}\beta}{4}e^{-\tau} ((-\Delta)^{\frac{1}{4}} G, F) + I_1 + I_2 + I_3 = 0 \end{aligned}$$

where

$$(4.5) \quad I_1 = \left((-\Delta)^{-\frac{3}{4}} (K_f \cdot \nabla ((-\Delta)^{\frac{3}{4}} F + \bar{\alpha}e^{-\tau} (-\Delta)^{\frac{7}{4}} F)), F \right),$$

$$(4.6) \quad I_2 = \beta \left((-\Delta)^{-\frac{3}{4}} \left(K_f \cdot \nabla (G - \bar{\alpha} e^{-\tau} \Delta G) \right), F \right),$$

$$(4.7) \quad I_3 = \beta \left((-\Delta)^{-\frac{3}{4}} \left((V^G \cdot \nabla ((-\Delta)^{\frac{3}{4}} F + \bar{\alpha} e^{-\tau} (-\Delta)^{\frac{7}{4}} F)) \right), F \right).$$

First, integrating by parts several times, we remark that

$$(4.8) \quad \begin{aligned} (\xi \cdot \nabla \Delta F, F) &= -2 \int_{\mathbb{R}^2} \Delta F F d\xi - \int_{\mathbb{R}^2} \xi \cdot \nabla F \Delta F d\xi \\ &= 2 \|\nabla F\|_{L^2}^2 + \sum_{k=1}^2 \int_{\mathbb{R}^2} \xi \cdot \nabla \partial_k F \partial_k F d\xi + \sum_{k=1}^2 \int_{\mathbb{R}^2} |\partial_k F|^2 d\xi \\ &= 2 \|\nabla F\|_{L^2}^2 \end{aligned}$$

Next, integrating by parts, we obtain the following estimates:

$$(4.9) \quad \left(\xi \cdot \nabla (-\Delta)^{\frac{1}{4}} G, F \right) \leq \left\| |\xi| \nabla (-\Delta)^{\frac{1}{4}} G \right\|_{L^2} \|F\|_{L^2} \leq C \|F\|_{L^2},$$

$$(4.10) \quad \left((-\Delta)^{\frac{1}{4}} G, F \right) \leq \left\| (-\Delta)^{\frac{1}{4}} G \right\|_{L^2} \|F\|_{L^2} \leq C \|F\|_{L^2},$$

$$(4.11) \quad \begin{aligned} \left((-\Delta)^{\frac{5}{4}} G, F \right) &= - \left((-\Delta)^{\frac{1}{4}} G, \Delta F \right) \leq \left\| (-\Delta)^{\frac{1}{4}} G \right\|_{L^2} \|\Delta F\|_{L^2} \\ &\leq C \|\Delta F\|_{L^2}. \end{aligned}$$

It remains to bound the terms I_1 , I_2 and I_3 . Using the fact that $\operatorname{div} K_f = 0$, we can write

$$I_1 = \left(\sum_{i=1}^2 (-\Delta)^{-\frac{3}{4}} \partial_i \left(K_f^i \left((-\Delta)^{\frac{3}{4}} F + \bar{\alpha} e^{-\tau} (-\Delta)^{\frac{7}{4}} F \right) \right), F \right)$$

where K_f^i denotes the i^{th} component of K_f . We recall that $K_f = V - \beta V^G$. Therefore, applying Hölder's inequality and using Lemma 2.4, we obtain

$$\begin{aligned} |I_1| &\leq \|F\|_{L^2} \sum_{i=1}^2 \left\| (-\Delta)^{-\frac{3}{4}} \partial_i \left(K_f^i (-\Delta)^{\frac{3}{4}} F \right) \right\|_{L^2} \\ &\quad + \bar{\alpha} e^{-\tau} \|F\|_{L^2} \sum_{i=1}^2 \left\| (-\Delta)^{-\frac{3}{4}} \partial_i \left(K_f^i (-\Delta)^{\frac{7}{4}} F \right) \right\|_{L^2} \\ &\leq \|F\|_{L^2} \sum_{i=1}^2 \left\| (-\Delta)^{-\frac{1}{4}} \left(K_f^i (-\Delta)^{\frac{3}{4}} F \right) \right\|_{L^2} \\ &\quad + \bar{\alpha} e^{-\tau} \|F\|_{L^2} \sum_{i=1}^2 \left\| (-\Delta)^{-\frac{1}{4}} \left(K_f^i (-\Delta)^{\frac{7}{4}} F \right) \right\|_{L^2} \\ &\leq C \|F\|_{L^2} \sum_{i=1}^2 \left(\left\| K_f^i (-\Delta)^{\frac{3}{4}} F \right\|_{L^2(1)} + \bar{\alpha} e^{-\tau} \left\| K_f^i (-\Delta)^{\frac{7}{4}} F \right\|_{L^2(1)} \right) \\ &\leq C \|F\|_{L^2} \|K_f\|_{L^\infty} \left(\|f\|_{L^2(1)} + \bar{\alpha} e^{-\tau} \|\Delta f\|_{L^2(1)} \right) \end{aligned}$$

Using Lemma 2.2, part (a), we obtain

$$|I_1| \leq C \|F\|_{L^2} \|f\|_{H^1}^{\frac{1}{2}} \|f\|_{L^2(2)}^{\frac{1}{2}} (\|f\|_{L^2(1)} + \bar{\alpha} e^{-\tau} \|\Delta f\|_{L^2(1)})$$

Using the assumption on the bound (4.1) of f , we get

$$(4.12) \quad |I_1| \leq C \sqrt{\delta} \|F\|_{L^2} (\|f\|_{L^2(1)} + \bar{\alpha} e^{-\tau} \|\Delta f\|_{L^2(1)})$$

The terms I_2 and I_3 are estimated in the same way as above and we get

$$(4.13) \quad \begin{aligned} |I_2| &\leq C |\beta| \|F\|_{L^2} \|f\|_{H^1}^{\frac{1}{2}} \|f\|_{L^2(2)}^{\frac{1}{2}} (\|G\|_{L^2(1)} + \bar{\alpha} e^{-\tau} \|\Delta G\|_{L^2(1)}) \\ &\leq C |\beta| (1 + \bar{\alpha} e^{-\tau}) \|F\|_{L^2} (\|f\|_{H^1} + \|f\|_{L^2(2)}) \end{aligned}$$

and

$$(4.14) \quad \begin{aligned} |I_3| &\leq C |\beta| \|F\|_{L^2} \|V^G\|_{L^\infty} (\|f\|_{L^2(1)} + \bar{\alpha} e^{-\tau} \|\Delta f\|_{L^2(1)}) \\ &\leq C |\beta| \|F\|_{L^2} (\|f\|_{L^2(1)} + \bar{\alpha} e^{-\tau} \|\Delta f\|_{L^2(1)}) \end{aligned}$$

Collecting the bounds (4.8) to (4.14), we deduce from (4.4) that

$$\begin{aligned} \partial_\tau E_0(\tau) + \frac{1}{4} \|F\|_{L^2}^2 + (1 + \frac{3\bar{\alpha}}{4} e^{-\tau}) \|\nabla F\|_{L^2}^2 + \bar{\epsilon} e^{-2\tau} \|\Delta F\|_{L^2}^2 \\ \leq C |\beta| \bar{\alpha} e^{-\tau} \|F\|_{L^2} + C |\beta| \bar{\epsilon} e^{-2\tau} \|\Delta F\|_{L^2} \\ + C(\sqrt{\delta} + |\beta|) \|F\|_{L^2} (\|f\|_{L^2(1)} + \bar{\alpha} e^{-\tau} \|\Delta f\|_{L^2(1)}) \\ + C |\beta| (1 + \bar{\alpha} e^{-\tau}) \|F\|_{L^2} (\|f\|_{H^1} + \|f\|_{L^2(2)}) \end{aligned}$$

Applying Young's inequality yields that for all $\mu_0 > 0$, there exists a constant $C_{\mu_0} > 0$ such that

$$(4.15) \quad \begin{aligned} \partial_\tau E_0(\tau) + (\frac{1}{4} - \mu_0) \|F\|_{L^2}^2 + (1 + \frac{3\bar{\alpha}}{4} e^{-\tau}) \|\nabla F\|_{L^2}^2 + \bar{\epsilon} e^{-2\tau} (1 - \mu_0) \|\Delta F\|_{L^2}^2 \\ \leq C_{\mu_0} |\beta|^2 (\bar{\alpha}^2 + \bar{\epsilon}) e^{-2\tau} \\ + C_{\mu_0} (\delta + |\beta|^2) (\|f\|_{L^2(1)}^2 + \bar{\alpha}^2 e^{-2\tau} \|\Delta f\|_{L^2(1)}^2) \\ + C_{\mu_0} |\beta|^2 (1 + \bar{\alpha}^2 e^{-2\tau}) (\|f\|_{H^1}^2 + \|f\|_{L^2(2)}^2) \end{aligned}$$

Remarking that

$$(4.16) \quad \begin{aligned} \|f\|_{L^2(1)}^2 &= \int_{\mathbb{R}^2} (1 + |\xi|^2) |f(\xi)|^2 d\xi \\ &\leq \|f\|_{L^2} \|f\|_{L^2(2)} \leq \frac{1}{2} (\|f\|_{L^2}^2 + \|\xi|^2 f\|_{L^2}^2). \end{aligned}$$

Using (4.16) and the fact that f satisfies the bound (4.1), we deduce from (4.15) that

$$\begin{aligned} & \partial_\tau E_0(\tau) + \left(\frac{1}{4} - \mu_0\right) \|F\|_{L^2}^2 + \left(1 + \frac{3\bar{\alpha}}{4}e^{-\tau}\right) \|\nabla F\|_{L^2}^2 + \bar{\epsilon}e^{-2\tau}(1 - \mu_0) \|\Delta F\|_{L^2}^2 \\ & \leq C_{\mu_0} |\beta|^2 (\bar{\alpha}^2 + \bar{\epsilon})e^{-2\tau} + C_{\mu_0} |\beta|^2 \|\nabla f\|_{L^2}^2 \\ & \quad + C_{\mu_0}(\delta + |\beta|^2)(\|f\|_{L^2}^2 + \|\xi|^2 f\|_{L^2}^2) \\ & \quad + C_{\mu_0}(\delta + |\beta|^2)\bar{\alpha}^2 e^{-2\tau}(\|\Delta f\|_{L^2}^2 + \|\xi|^2 \Delta f\|_{L^2}^2) \end{aligned}$$

Now, let $0 < \mu_0 < \frac{1}{4}$ and $\frac{\theta}{2} = \frac{1}{4} - \mu_0 < \frac{1}{4}$. The above inequality becomes

$$\begin{aligned} & \partial_\tau E_0(\tau) + \theta E_0(\tau) + \left(1 + \frac{3\bar{\alpha}}{4}e^{-\tau} - \frac{\theta\bar{\alpha}}{2}e^{-\tau}\right) \|\nabla F\|_{L^2}^2 + \bar{\epsilon}\left(\frac{3}{4} + \frac{\theta}{2}\right)e^{-2\tau} \|\Delta F\|_{L^2}^2 \\ & \leq C_0 |\beta|^2 (\bar{\alpha}^2 + \bar{\epsilon})e^{-2\tau} + C_0 |\beta|^2 \|\nabla f\|_{L^2}^2 \\ & \quad + C_0(\delta + |\beta|^2)(\|f\|_{L^2}^2 + \|\xi|^2 f\|_{L^2}^2) \\ & \quad + C_0(\delta + |\beta|^2)\bar{\alpha}^2 e^{-2\tau}(\|\Delta f\|_{L^2}^2 + \|\xi|^2 \Delta f\|_{L^2}^2) \end{aligned}$$

□

Next, we will give estimates of f and Δf .

4.1.2. *Estimates of f and ∇f .* In order to estimate $\|f\|_{L^2}$ and $\|\nabla f\|_{L^2}$, we introduce the functional $E_1(\tau)$ given by

$$(4.17) \quad E_1(\tau) = \frac{1}{2}(\|f(\tau)\|_{L^2}^2 + \bar{\alpha}e^{-\tau} \|\nabla f(\tau)\|_{L^2}^2)$$

We have the following lemma.

LEMMA 4.2. *Assume that $f \in L^\infty([\tau_0, \tau_1], H^2(2))$ is a solution of (3.14) satisfying the bound (4.1). Then, there exists a positive constant C_1 such that, for all $\tau \in [\tau_0, \tau_1]$,*

$$\begin{aligned} & \partial_\tau E_1(\tau) + E_1(\tau) + \left(\frac{1}{6} - \frac{\bar{\alpha}}{2}e^{-\tau}\right) \|\nabla f\|_{L^2}^2 + \frac{\bar{\epsilon}}{2}e^{-2\tau} \|\Delta f\|_{L^2}^2 \\ & \leq C_1 |\beta|^2 (\bar{\alpha}^2 + \bar{\epsilon})e^{-2\tau} + \left(\frac{2}{3} + C_1 |\beta|^2\right) \|\nabla F\|_{L^2}^2 \\ & \quad + C_1 |\beta|^2 \|\xi|^2 f\|_{L^2}^2 + C_1(\delta + |\beta|^2)\bar{\alpha}^2 e^{-2\tau} \|\Delta f\|_{L^2}^2 \end{aligned}$$

Proof : Taking the scalar product in $L^2(\mathbb{R}^2)$ of (3.14) with f , we obtain

$$\begin{aligned} & \partial_\tau E_1(\tau) + \|\nabla f\|_{L^2}^2 - \frac{1}{2}\|f\|_{L^2}^2 + \bar{\epsilon}e^{-2\tau} \|\Delta f\|_{L^2}^2 \\ (4.18) \quad & + \beta\frac{\bar{\alpha}}{2}e^{-\tau}(\xi \cdot \nabla \Delta G, f) + \beta\bar{\epsilon}e^{-2\tau}(\Delta^2 G, f) + \beta\bar{\alpha}e^{-\tau}(\Delta G, f) \\ & + J_1 + \beta J_2 + \beta J_3 = 0 \end{aligned}$$

where

$$J_1 = (K_f \cdot \nabla(f - \bar{\alpha} e^{-\tau} \Delta f), f)$$

$$J_2 = (V^G \cdot \nabla(f - \bar{\alpha} e^{-\tau} \Delta f), f)$$

$$J_3 = (K_f \cdot \nabla(G - \bar{\alpha} e^{-\tau} \Delta G), f).$$

Integrating by parts and applying the Hölder inequality, we have the following bounds

$$(4.19) \quad |(\xi \cdot \nabla \Delta G, f)| \leq (2 \|\Delta G\|_{L^2} + \|\xi\| \|\Delta G\|_{L^2}) \|\nabla f\|_{L^2} \leq C \|\nabla f\|_{L^2}$$

$$(4.20) \quad |(\Delta^2 G, f)| \leq \|\Delta G\|_{L^2} \|\Delta f\|_{L^2} \leq C \|\Delta f\|_{L^2}$$

$$(4.21) \quad |(\Delta G, f)| \leq \|\nabla G\|_{L^2} \|\nabla f\|_{L^2} \leq C \|\nabla f\|_{L^2}$$

Next, we bound the terms J_i , $i = 1, 2, 3$. Integrating by parts and using the fact that $\operatorname{div} K_f = 0$, we can write J_1 as

$$J_1 = -\bar{\alpha} e^{-\tau} (K_f \cdot \nabla f, \Delta f)$$

Thus, applying Hölder's inequality and using Lemma 2.2 part (a), we obtain the following bound

$$(4.22) \quad |J_1| \leq \bar{\alpha} e^{-\tau} \|K_f\|_{L^\infty} \|\nabla f\|_{L^2} \|\Delta f\|_{L^2} \\ \leq C \bar{\alpha} e^{-\tau} \|f\|_{H^1}^{\frac{1}{2}} \|f\|_{L^2(2)}^{\frac{1}{2}} \|\nabla f\|_{L^2} \|\Delta f\|_{L^2} \leq C \sqrt{\delta} \bar{\alpha} e^{-\tau} \|\nabla f\|_{L^2} \|\Delta f\|_{L^2}$$

since f satisfies the bound (4.1).

On the other hand, since $\operatorname{div} V^G = 0$, the term J_2 can be estimated as above and we have

$$(4.23) \quad |J_2| \leq \bar{\alpha} e^{-\tau} \|V^G\|_{L^\infty} \|\nabla f\|_{L^2} \|\Delta f\|_{L^2} \leq C \bar{\alpha} e^{-\tau} \|\nabla f\|_{L^2} \|\Delta f\|_{L^2}$$

Finally, integrating by parts, using Lemma 2.2 part (b), we obtain the following bound on J_3

$$(4.24) \quad |J_3| \leq \|K_f\|_{L^4} \|G - \bar{\alpha} e^{-\tau} \Delta G\|_{L^4} \|\nabla f\|_{L^2} \leq C(1 + \bar{\alpha} e^{-\tau}) \|f\|_{L^2(2)} \|\nabla f\|_{L^2}$$

Collecting the bounds (4.19) to (4.24) and applying Young's inequality on (4.18), we show that, for all $\mu_1 > 0$, there exists a constant $C_{\mu_1} > 0$ such that

$$\partial_\tau E_1(\tau) + (1 - \mu_1) \|\nabla f\|_{L^2}^2 - \frac{1}{2} \|f\|_{L^2}^2 + \bar{\epsilon} e^{-2\tau} (1 - \mu_1) \|\Delta f\|_{L^2}^2 \\ \leq C_{\mu_1} |\beta|^2 (\bar{\alpha}^2 + \bar{\epsilon}) e^{-2\tau} + C_{\mu_1} |\beta|^2 (1 + \bar{\alpha}^2 e^{-2\tau}) \|f\|_{L^2(2)}^2 \\ + C_{\mu_1} (\delta + |\beta|^2) \bar{\alpha}^2 e^{-2\tau} \|\Delta f\|_{L^2}^2$$

Choosing $\mu_1 = \frac{1}{2}$ and remarking that

$$(4.25) \quad \|f\|_{L^2(2)}^2 \leq 2(\|f\|_{L^2}^2 + \|\xi\|^2 \|f\|_{L^2}^2),$$

we deduce from the above inequality that

$$\begin{aligned}
(4.26) \quad & \partial_\tau E_1(\tau) + E_1(\tau) + \left(\frac{1}{2} - \frac{\bar{\alpha}}{2}e^{-\tau}\right) \|\nabla f\|_{L^2}^2 + \frac{\bar{\epsilon}}{2}e^{-2\tau} \|\Delta f\|_{L^2}^2 \\
& \leq C_1 |\beta|^2 (\bar{\alpha}^2 + \bar{\epsilon})e^{-2\tau} + (1 + C_1 |\beta|^2 (1 + \bar{\alpha}^2 e^{-2\tau})) \|f\|_{L^2}^2 \\
& + C_1 |\beta|^2 (1 + \bar{\alpha}^2 e^{-2\tau}) \|\xi|^2 f\|_{L^2}^2 + C_1(\delta + |\beta|^2) \bar{\alpha}^2 e^{-2\tau} \|\Delta f\|_{L^2}^2
\end{aligned}$$

Using (3.19), we can write Inequality (4.26) as

$$\begin{aligned}
(4.27) \quad & \partial_\tau E_1(\tau) + E_1(\tau) + \left(\frac{1}{6} - \frac{\bar{\alpha}}{2}e^{-\tau}\right) \|\nabla f\|_{L^2}^2 + \frac{\bar{\epsilon}}{2}e^{-2\tau} \|\Delta f\|_{L^2}^2 \\
& \leq C_1 |\beta|^2 (\bar{\alpha}^2 + \bar{\epsilon})e^{-2\tau} + \left(\frac{2}{3} + C_1 |\beta|^2\right) \|\nabla f\|_{L^2}^2 \\
& + C_1 |\beta|^2 \|\xi|^2 f\|_{L^2}^2 + C_1(\delta + |\beta|^2) \bar{\alpha}^2 e^{-2\tau} \|\Delta f\|_{L^2}^2.
\end{aligned}$$

□

4.1.3. *Estimates of ∇f and Δf .* In order to estimate $\|\nabla f\|_{L^2}$ and $\|\Delta f\|_{L^2}$, we introduce the functional is

$$(4.28) \quad E_2(\tau) = \frac{1}{2}(\|\nabla f(\tau)\|_{L^2}^2 + \bar{\alpha}e^{-\tau} \|\Delta f(\tau)\|_{L^2}^2)$$

LEMMA 4.3. *Assume that $f \in L^\infty([\tau_0, \tau_1], H^2(2))$ is a solution of (3.14) satisfying the bound (4.1). Then, there exists a positive constant C_2 such that for all $\tau \in [\tau_0, \tau_1]$, we have*

$$\begin{aligned}
& \partial_\tau E_2(\tau) + E_2(\tau) + \left(\frac{1}{2} - \bar{\alpha}e^{-\tau}\right) \|\Delta f\|_{L^2}^2 + \frac{\bar{\epsilon}}{2}e^{-2\tau} \|\nabla \Delta f\|_{L^2}^2 \\
& \leq C_2 |\beta|^2 (\bar{\alpha}^2 + \bar{\epsilon})e^{-2\tau} + \left(\frac{3}{2} + C_2(\delta + |\beta|^2)\right) \|\nabla f\|_{L^2}^2 \\
& + C_2 |\beta|^2 (\|\xi|^2 f\|_{L^2}^2 + \|f\|_{L^2}^2)
\end{aligned}$$

Proof : In order to obtain estimates of the L^2 -norm of Δf , we take the scalar product in $L^2(\mathbb{R}^2)$ of (3.14) with $-\Delta f$. We obtain

$$\begin{aligned}
(4.29) \quad & \partial_\tau E_2(\tau) + (\mathcal{L}f, \Delta f) + \bar{\epsilon}e^{-2\tau} \|\nabla \Delta f\|_{L^2}^2 - \frac{\bar{\alpha}}{2}e^{-\tau} \|\Delta f\|_{L^2}^2 \\
& \leq |\beta| \bar{\alpha}e^{-\tau} \left(\frac{1}{2} \|\xi\| \|\nabla \Delta G\|_{L^2} + \|\Delta G\|_{L^2}\right) \|\Delta f\|_{L^2} \\
& + \bar{\epsilon}\beta e^{-2\tau} \|\Delta G\|_{L^2} \|\Delta f\|_{L^2} + K_1 + \beta K_2 + \beta K_3
\end{aligned}$$

where

$$\begin{aligned}
K_1 &= (K_f \cdot \nabla(f - \bar{\alpha}e^{-\tau} \Delta f), \Delta f) \\
K_2 &= (V^G \cdot \nabla(f - \bar{\alpha}e^{-\tau} \Delta f), \Delta f) \\
K_3 &= (K_f \cdot \nabla(G - \bar{\alpha}e^{-\tau} \Delta G), \Delta f)
\end{aligned}$$

A simple integration by parts implies that $(\xi \cdot \nabla f, \Delta f) = 0$. Thus,

$$(\mathcal{L}f, \Delta f) = \|\Delta f\|_{L^2}^2 - \|\nabla f\|_{L^2}^2.$$

Since $\operatorname{div} V^G = \operatorname{div} K_f = 0$, we remark that

$$(K_f \cdot \nabla \Delta f, \Delta f) = (V^G \cdot \nabla \Delta f, \Delta f) = 0.$$

Therefore, using Lemma 2.2 part (a), we can write
(4.30)

$$\begin{aligned} |K_1| &\leq \|K_f\|_{L^\infty} \|\nabla f\|_{L^2} \|\Delta f\|_{L^2} \leq C \|f\|_{H^1}^{\frac{1}{2}} \|f\|_{L^2(2)}^{\frac{1}{2}} \|\nabla f\|_{L^2} \|\Delta f\|_{L^2} \\ &\leq C\sqrt{\delta} \|\nabla f\|_{L^2} \|\Delta f\|_{L^2}. \end{aligned}$$

We also have

$$(4.31) \quad |K_2| \leq \|V^G\|_{L^\infty} \|\nabla f\|_{L^2} \|\Delta f\|_{L^2} \leq C \|\nabla f\|_{L^2} \|\Delta f\|_{L^2}$$

Finally, using Lemma 2.2 part (b), we can write

$$(4.32) \quad |K_3| \leq \|K_f\|_{L^4} \|\nabla(G - \bar{\alpha}e^{-\tau}\Delta G)\|_{L^4} \|\Delta f\|_{L^2} \leq C(1 + \bar{\alpha}e^{-\tau}) \|f\|_{L^2(2)} \|\Delta f\|_{L^2}$$

Thus, using the bounds (4.30), (4.31) and (4.32) and applying the Cauchy-Schwarz inequality to the estimate (4.29), we obtain that, for all $\mu_2 > 0$, there exists a constant $C_{\mu_2} > 0$ such that

$$\begin{aligned} \partial_\tau E_2(\tau) + (1 - \frac{\bar{\alpha}}{2}e^{-\tau} - \mu_2) \|\Delta f\|_{L^2}^2 - \|\nabla f\|_{L^2}^2 + \bar{\epsilon}e^{-2\tau}(1 - \mu_2) \|\nabla \Delta f\|_{L^2}^2 \\ \leq C_{\mu_2} |\beta|^2 (\bar{\alpha}^2 + \bar{\epsilon})e^{-2\tau} + C_{\mu_2}(\delta + |\beta|^2) \|\nabla f\|_{L^2}^2 \\ + C_{\mu_2} |\beta|^2 (\|\xi\|^2 \|f\|_{L^2}^2 + \|f\|_{L^2}^2) \end{aligned}$$

Choosing $\mu_2 = \frac{1}{2}$, we get

$$\begin{aligned} \partial_\tau E_2(\tau) + E_2(\tau) + (\frac{1}{2} - \bar{\alpha}e^{-\tau}) \|\Delta f\|_{L^2}^2 + \frac{\bar{\epsilon}}{2}e^{-2\tau} \|\nabla \Delta f\|_{L^2}^2 \\ \leq C_2 |\beta|^2 (\bar{\alpha}^2 + \bar{\epsilon})e^{-2\tau} + (\frac{3}{2} + C_2(\delta + |\beta|^2)) \|\nabla f\|_{L^2}^2 \\ + C_2 |\beta|^2 (\|\xi\|^2 \|f\|_{L^2}^2 + \|f\|_{L^2}^2) \end{aligned}$$

Thus, Lemma 4.3 is proved. \square

In order to obtain an estimate of $\|f\|_{H^1}^2 + \bar{\alpha}e^{-\tau} \|\Delta f\|_{L^2}^2$, we introduce the functional E_3 given by

$$(4.33) \quad E_3(\tau) = 5E_0(\tau) + 5E_1(\tau) + \frac{1}{2}E_2(\tau)$$

Indeed, we have the following inequality

$$\|f\|_{H^1}^2 + \bar{\alpha}e^{-\tau} \|\Delta f\|_{L^2}^2 \leq CE_3(\tau),$$

where $C > 0$ is a constant independent of $\bar{\alpha}$.

Lemmas 4.1, 4.2, 4.3 and Inequality (3.19) imply that there exists a constant $C_3 > 0$

such that for all $\tau \in [\tau_0, \tau_1]$, we have

$$\begin{aligned}
(4.34) \quad & \partial_\tau E_3(\tau) + \theta E_3(\tau) + \bar{\epsilon} e^{-\tau} \left(\left(\frac{15}{4} + \frac{5\theta}{2} \right) \|\Delta F\|_{L^2}^2 + \frac{5}{2} \|\Delta f\|_{L^2}^2 + \frac{1}{4} \|\nabla \Delta f\|_{L^2}^2 \right) \\
& + \left(\frac{5}{3} + \frac{5\bar{\alpha}}{4} e^{-\tau} - \frac{5\theta\bar{\alpha}}{2} - C_3(|\beta|^2 + \delta) \right) \|\nabla F\|_{L^2}^2 \\
& + \left(\frac{1}{12} - \frac{5\bar{\alpha}}{2} - C_3(|\beta|^2 + \delta) \right) \|\nabla f\|_{L^2}^2 + \left(\frac{1}{4} - \frac{\bar{\alpha}}{2} e^{-\tau} - C_3\bar{\alpha}^2(|\beta|^2 + \delta) \right) \|\Delta f\|_{L^2}^2 \\
& \leq C_3 |\beta|^2 (\bar{\alpha}^2 + \bar{\epsilon}) e^{-\tau} + C_3(|\beta|^2 + \delta) \|\xi\|^2 \|f\|_{L^2}^2 \\
& \quad + C_3(|\beta|^2 + \delta) \bar{\alpha}^2 e^{-2\tau} \|\xi\|^2 \|\Delta f\|_{L^2}^2
\end{aligned}$$

where $0 < \theta < \frac{1}{2}$.

4.2. Energy estimates in $L^2(2)$. In order to bound the H^2 weighted norm of f , it remains to estimate the term $\|\xi\|^2 \|f(\tau) - \bar{\alpha} e^{-\tau} \Delta f(\tau)\|_{L^2}$. For this purpose, we introduce the weighted functional

$$(4.35) \quad E_4(\tau) = \frac{1}{2} \|\xi\|^2 \|f(\tau) - \bar{\alpha} e^{-\tau} \Delta f(\tau)\|_{L^2}^2.$$

We have the following lemma.

LEMMA 4.4. *Assume that $f \in L^\infty([\tau_0, \tau_1], H^2(2))$ is a solution of (3.14) satisfying the bound (4.1). Then, there exists a constant $C_4 > 0$ such that for all $\tau \in [\tau_0, \tau_1]$,*

$$\begin{aligned}
& \partial_\tau E_4(\tau) + \frac{1}{2} E_4(\tau) + \left(\frac{1}{12} - C_4(\sqrt{\delta} + \bar{\alpha} e^{-\tau} + \delta) \right) \|\xi\|^2 \|f\|_{L^2}^2 \\
& + \left(1 + \frac{\bar{\alpha}}{2} e^{-\tau} - \bar{\epsilon} e^{-2\tau} C_4 \right) \|\xi\|^2 \|\nabla f\|_{L^2}^2 \\
& + \bar{\alpha} e^{-\tau} \left(1 + \frac{\bar{\alpha}}{4} e^{-\tau} - \bar{\alpha} e^{-\tau} (\sqrt{\delta} + \frac{1}{12} + C_4 \bar{\epsilon} e^{-2\tau}) \right) \|\xi\|^2 \|\Delta f\|_{L^2}^2 \\
& + \bar{\epsilon} e^{-2\tau} \left(\|\xi\|^2 \|\Delta f\|_{L^2}^2 + 32 \|f\|_{L^2}^2 + \bar{\alpha} e^{-\tau} \|\xi\|^2 \|\nabla \Delta f\|_{L^2}^2 \right) \\
& \leq C_4 \delta (\bar{\epsilon}^2 + \bar{\alpha}^2) e^{-2\tau} + (48 + C_4(\bar{\alpha} e^{-\tau} + \sqrt{\delta})) \|f\|_{L^2}^2 \\
& + C_4 \bar{\epsilon} e^{-2\tau} \|\nabla f\|_{L^2}^2 + (C_4 \bar{\epsilon} \bar{\alpha} e^{-3\tau} + \bar{\alpha}^2 e^{-2\tau} C_4 \sqrt{\delta}) \|\Delta f\|_{L^2}^2
\end{aligned}$$

Proof : In order to estimate $E_4(\tau)$, we take the scalar product of Equation (3.14) with $|\xi|^4 (f - \bar{\alpha} e^{-\tau} \Delta f)$.

We obtain

$$\begin{aligned}
(4.36) \quad & \partial_\tau E_4(\tau) - (\mathcal{L}f, |\xi|^4 (f - \bar{\alpha}e^{-\tau}\Delta f)) + \bar{\epsilon}e^{-2\tau}(\Delta^2 f, |\xi|^4 (f - \bar{\alpha}e^{-\tau}\Delta f)) \\
& + \frac{\bar{\alpha}}{2}e^{-\tau}(\xi \cdot \nabla \Delta f, |\xi|^4 (f - \bar{\alpha}e^{-\tau}\Delta f)) + \bar{\alpha}e^{-\tau}(\Delta f, |\xi|^4 (f - \bar{\alpha}e^{-\tau}\Delta f)) \\
& \leq |M_1| + |M_2| + |M_3| \\
& + |\beta| e^{-\tau} \| |\xi|^2 (f - \bar{\alpha}e^{-\tau}\Delta f) \|_{L^2} \left(\bar{\epsilon}e^{-\tau} \| |\xi|^2 \Delta^2 G \|_{L^2} + \bar{\alpha} \| |\xi|^2 \Delta G \|_{L^2} \right. \\
& \quad \left. + \frac{\bar{\alpha}}{2} \| |\xi|^3 \nabla \Delta G \|_{L^2} \right)
\end{aligned}$$

where

$$\begin{aligned}
M_1 &= \beta(V^G \cdot \nabla(f - \bar{\alpha}e^{-\tau}\Delta f), |\xi|^4 (f - \bar{\alpha}e^{-\tau}\Delta f)), \\
M_2 &= \beta(K_f \cdot \nabla(G - \bar{\alpha}e^{-\tau}\Delta G), |\xi|^4 (f - \bar{\alpha}e^{-\tau}\Delta f)), \\
M_3 &= (K_f \cdot \nabla(f - \bar{\alpha}e^{-\tau}\Delta f), |\xi|^4 (f - \bar{\alpha}e^{-\tau}\Delta f)).
\end{aligned}$$

We begin by computing the term $(\mathcal{L}f, |\xi|^4 (f - \bar{\alpha}e^{-\tau}\Delta f))$. Using an integrating by parts, we obtain

$$\begin{aligned}
(4.37) \quad & (\Delta f, |\xi|^4 f) = - \| |\xi|^2 \nabla f \|_{L^2}^2 + 8 \| |\xi| f \|_{L^2}^2 \\
& \frac{1}{2}(\xi \cdot \nabla f, |\xi|^4 f) = -\frac{3}{2} \| |\xi|^2 f \|_{L^2}^2
\end{aligned}$$

Thus,

$$(4.38) \quad -(\mathcal{L}f, |\xi|^4 f) = \| |\xi|^2 \nabla f \|_{L^2}^2 - 8 \| |\xi| f \|_{L^2}^2 + \frac{1}{2} \| |\xi|^2 f \|_{L^2}^2.$$

Next, we compute the term $\frac{\bar{\alpha}}{2}e^{-\tau}(\mathcal{L}f, |\xi|^4 \Delta f)$. Integrating by parts yields

$$\begin{aligned}
(4.39) \quad & \frac{1}{2}(\xi \cdot \nabla f, |\xi|^4 \Delta f) = -\frac{1}{2}(\xi \cdot \nabla \Delta f, |\xi|^4 f) - 3(f, |\xi|^4 \Delta f) \\
& = -\frac{1}{2}(\xi \cdot \nabla \Delta f, |\xi|^4 f) + 3 \| |\xi|^2 \nabla f \|_{L^2}^2 - 24 \| |\xi| f \|_{L^2}^2
\end{aligned}$$

Thus, using the equalities (4.37) and (4.39), we get

$$\begin{aligned}
(4.40) \quad & \bar{\alpha}e^{-\tau}(\mathcal{L}f, |\xi|^4 \Delta f) = \bar{\alpha}e^{-\tau} \left(\| |\xi|^2 \Delta f \|_{L^2}^2 + 2 \| |\xi|^2 \nabla f \|_{L^2}^2 \right. \\
& \quad \left. - 16 \| |\xi| f \|_{L^2}^2 - \frac{1}{2}(\xi \cdot \nabla \Delta f, |\xi|^4 f) \right)
\end{aligned}$$

Equalities (4.38) and (4.40) imply that

$$\begin{aligned}
(4.41) \quad & -(\mathcal{L}f, |\xi|^4 (f - \bar{\alpha}e^{-\tau}\Delta f)) = \\
& -\frac{\bar{\alpha}}{2}e^{-\tau}(\xi \cdot \nabla \Delta f, |\xi|^4 f) - 8(1 + 2\bar{\alpha}e^{-\tau}) \| |\xi| f \|_{L^2}^2 \\
& + \frac{1}{2} \| |\xi|^2 f \|_{L^2}^2 + (1 + 2\bar{\alpha}e^{-\tau}) \| |\xi|^2 \nabla f \|_{L^2}^2 + \bar{\alpha}e^{-\tau} \| |\xi|^2 \Delta f \|_{L^2}^2
\end{aligned}$$

On the other hand,

$$-\bar{\alpha}^2 e^{-2\tau} \left(\frac{1}{2} \xi \cdot \nabla \Delta f + \Delta f, |\xi|^4 \Delta f \right) = \frac{\bar{\alpha}^2}{2} e^{-2\tau} \| |\xi|^2 \Delta f \|_{L^2}^2,$$

and

$$\begin{aligned}
& \bar{\epsilon}e^{-2\tau}(\Delta^2 f, |\xi|^4 f) \\
&= \bar{\epsilon}e^{-2\tau}(\| |\xi|^2 \Delta f \|_{L^2}^2 + 16(\Delta f, |\xi|^2 f) + 8(\xi \cdot \nabla f, |\xi|^2 \Delta f)) \\
&= \frac{\epsilon}{\bar{\nu}^2}e^{-2\tau}(\| |\xi|^2 \Delta f \|_{L^2}^2 - 16 \| \xi \cdot \nabla f \|_{L^2}^2 + 32 \| f \|_{L^2}^2 + 8(\xi \cdot \nabla f, |\xi|^2 \Delta f)).
\end{aligned}$$

Again, integrating by parts, we obtain

$$\begin{aligned}
8(\xi \cdot \nabla f, |\xi|^2 \Delta f) &= 8 \| \xi \cdot \nabla f \|_{L^2}^2 - 16(\xi \cdot \nabla f, \xi \cdot \nabla f) \\
&\geq 8 \| \xi \cdot \nabla f \|_{L^2}^2 - 16 \| \xi \cdot \nabla f \|_{L^2}^2 = -8 \| \xi \cdot \nabla f \|_{L^2}^2.
\end{aligned}$$

Therefore,

$$(4.42) \quad \bar{\epsilon}e^{-2\tau}(\Delta^2 f, |\xi|^4 f) \geq \bar{\epsilon}e^{-2\tau}(\| |\xi|^2 \Delta f \|_{L^2}^2 - 24 \| \xi \cdot \nabla f \|_{L^2}^2 + 32 \| f \|_{L^2}^2).$$

Finally,

$$(4.43) \quad -\bar{\epsilon}\bar{\alpha}e^{-3\tau}(\Delta^2 f, |\xi|^4 \Delta f) = \bar{\epsilon}\bar{\alpha}e^{-3\tau}(\| |\xi|^2 \nabla \Delta f \|_{L^2}^2 - 8 \| \xi \cdot \Delta f \|_{L^2}^2)$$

Putting together the estimates (4.41), (4.42) and (4.43), we obtain the following inequality for the left-hand side of (4.36), that is,

$$\begin{aligned}
& \partial_\tau E_4(\tau) + \frac{1}{2} \| |\xi|^2 f \|_{L^2}^2 + (1 + \bar{\alpha}e^{-\tau}) \| |\xi|^2 \nabla f \|_{L^2}^2 \\
&+ \bar{\alpha}e^{-\tau}(1 + \frac{\bar{\alpha}}{2}e^{-\tau}) \| |\xi|^2 \Delta f \|_{L^2}^2 \\
&+ \bar{\epsilon}e^{-2\tau}(\| |\xi|^2 \Delta f \|_{L^2}^2 + 32 \| f \|_{L^2}^2 + \bar{\alpha}e^{-\tau} \| |\xi|^2 \nabla \Delta f \|_{L^2}^2) \\
&- (8 + 8\bar{\alpha}e^{-\tau}) \| \xi \cdot f \|_{L^2}^2 - \bar{\epsilon}e^{-2\tau}(24 \| \xi \cdot \nabla f \|_{L^2}^2 + 8\bar{\alpha}e^{-\tau} \| \xi \cdot \Delta f \|_{L^2}^2) \\
&\leq |M_1| + |M_2| + |M_3| \\
&+ |\beta| e^{-\tau} \| |\xi|^2 (f - \bar{\alpha}e^{-\tau} \Delta f) \|_{L^2} \left(\bar{\epsilon}e^{-\tau} \| |\xi|^2 \Delta^2 G \|_{L^2} + \bar{\alpha} \| |\xi|^2 \Delta G \|_{L^2} \right. \\
&\quad \left. + \frac{\bar{\alpha}}{2} \| |\xi|^3 \nabla \Delta G \|_{L^2} \right)
\end{aligned}$$

It remains to bound the terms M_i ; $i = 1, 2, 3$.

Integrating by parts and using the fact that $\operatorname{div} V_G = 0$, we obtain

$$M_1 = -2 \int_{\mathbb{R}^2} (V_G \cdot \xi) |\xi|^2 |f - \bar{\alpha}e^{-\tau} \Delta f|^2 d\xi$$

Using remark 3.1, we deduce that $M_1 = 0$.

In order to bound M_2 , we use Lemma 2.2 part (b). We obtain

$$\begin{aligned}
|M_2| &\leq |\beta| \|K_f\|_{L^4} \| |\xi|^2 (G - \bar{\alpha}e^{-\tau} \Delta G) \|_{L^4} \| |\xi|^2 (f - \bar{\alpha}e^{-\tau} \Delta f) \|_{L^2} \\
&\leq C |\beta| \|f\|_{L^2(2)} \| |\xi|^2 (f - \bar{\alpha}e^{-\tau} \Delta f) \|_{L^2}
\end{aligned}$$

Then, the Cauchy-Schwarz inequality implies that for all $\lambda > 0$, there exists a constant $C_\lambda > 0$ such that

$$(4.44) \quad \begin{aligned} |M_2| &\leq C_\lambda |\beta|^2 \|f\|_{L^2(2)}^2 + \lambda \|\xi|^2 (f - \bar{\alpha}e^{-\tau}\Delta f)\|_{L^2}^2 \\ &\leq C_\lambda |\beta|^2 \|f\|_{L^2}^2 + (\lambda + C_\lambda |\beta|^2) \|\xi|^2 f\|_{L^2}^2 + \lambda \bar{\alpha}^2 e^{-2\tau} \|\xi|^2 \Delta f\|_{L^2}^2 \end{aligned}$$

Finally, integrating by parts the term M_3 and remarking that, for all $\mu > 0$, there exists $C_\mu > 0$ such that

$$(4.45) \quad |\xi|^3 \leq \mu |\xi|^4 + C_\mu,$$

we can write

$$|M_3| \leq \|K_f\|_{L^\infty} (\mu \|\xi|^2 (f - \bar{\alpha}e^{-\tau}\Delta f)\|_{L^2}^2 + C_\mu \|f - \bar{\alpha}e^{-\tau}\Delta f\|_{L^2}^2)$$

Then, applying Lemma 2.2 part (a), we have

$$\begin{aligned} |M_3| &\leq \mu \|f\|_{H^1}^{\frac{1}{2}} \|f\|_{L^2(2)}^{\frac{1}{2}} \|\xi|^2 (f - \bar{\alpha}e^{-\tau}\Delta f)\|_{L^2}^2 \\ &\quad + C_\mu \|f\|_{H^1}^{\frac{1}{2}} \|f\|_{L^2(2)}^{\frac{1}{2}} \|f - \bar{\alpha}e^{-\tau}\Delta f\|_{L^2}^2 \\ &\leq \mu\sqrt{\delta} (\|\xi|^2 f\|_{L^2}^2 + \bar{\alpha}^2 e^{-2\tau} \|\xi|^2 \Delta f\|_{L^2}^2) \\ &\quad + C_\mu\sqrt{\delta} (\|f\|_{L^2}^2 + \bar{\alpha}^2 e^{-2\tau} \|\Delta f\|_{L^2}^2) \end{aligned}$$

since f satisfies the bound (4.1).

Taking into account the estimates (4.44) and (4.46), using the fact that $|\beta|^2 \leq \delta$ and applying the Cauchy-Schwarz inequality yield that, for all $\mu_4 > 0$, there exists a constant $C_{\mu_4} > 0$ such that

$$(4.46) \quad \begin{aligned} &\partial_\tau E_4(\tau) + \left(\frac{1}{2} - \mu_4 - C_{\mu_4}(\mu_4\sqrt{\delta} + \delta)\right) \|\xi|^2 f\|_{L^2}^2 \\ &+ \left(1 + \bar{\alpha}e^{-\tau}\right) \|\xi|^2 \nabla f\|_{L^2}^2 \\ &+ \bar{\alpha}e^{-\tau} \left(1 + \frac{\bar{\alpha}}{2}e^{-\tau} - \bar{\alpha}e^{-\tau}(\mu_4\sqrt{\delta} + \mu_4)\right) \|\xi|^2 \Delta f\|_{L^2}^2 \\ &+ \bar{\epsilon}e^{-2\tau} \left(\|\xi|^2 \Delta f\|_{L^2}^2 + 32\|f\|_{L^2}^2 + \bar{\alpha}e^{-\tau} \|\xi|^2 \nabla \Delta f\|_{L^2}^2\right) \\ &- \left(8 + 8\bar{\alpha}e^{-\tau}\right) \|\xi| f\|_{L^2}^2 - \bar{\epsilon}e^{-2\tau} \left(24 \|\xi| \nabla f\|_{L^2}^2 + 8\bar{\alpha}e^{-\tau} \|\xi| \Delta f\|_{L^2}^2\right) \\ &\leq C_{\mu_4} \frac{|\beta|^2}{\nu^2} (\bar{\epsilon}^2 + \bar{\alpha}^2) e^{-2\tau} + C_{\mu_4} (|\beta|^2 + \sqrt{\delta}) \|f\|_{L^2}^2 \\ &+ \bar{\alpha}^2 e^{-2\tau} C_{\mu_4} \sqrt{\delta} \|\Delta f\|_{L^2}^2 \end{aligned}$$

For any $\lambda > 0$, we can write

$$\|\xi| f\|_{L^2}^2 \leq \frac{\lambda}{2} \|\xi|^2 f\|_{L^2}^2 + \frac{1}{2\lambda} \|f\|_{L^2}^2$$

Likewise, for any $\eta > 0$, there exists a constant $C_\eta > 0$ such that

$$\bar{\epsilon}e^{-2\tau} \|\xi | \nabla f\|_{L^2}^2 \leq \bar{\epsilon}e^{-2\tau} (\eta \|\xi |^2 \nabla f\|_{L^2}^2 + C_\eta \|\nabla f\|_{L^2}^2)$$

$$\bar{\epsilon}\bar{\alpha}e^{-3\tau} \|\xi | \Delta f\|_{L^2}^2 \leq \bar{\epsilon}\bar{\alpha}e^{-3\tau} (\eta \|\xi |^2 \Delta f\|_{L^2}^2 + C_\eta \|\Delta f\|_{L^2}^2)$$

Thus, for any $\mu > 0$ and any $\lambda > 0$, there exists a constant $C_\mu > 0$ such that Inequality (4.46) becomes

$$\begin{aligned} & \partial_\tau E_4(\tau) + \left(\frac{1}{2} - \mu - C_\mu(\mu\sqrt{\delta} + \delta) - 4\lambda(1 + \bar{\alpha}e^{-\tau})\right) \|\xi |^2 f\|_{L^2}^2 \\ & + \left(1 + \bar{\alpha}e^{-\tau} - \bar{\epsilon}e^{-2\tau}C_\mu\right) \|\xi |^2 \nabla f\|_{L^2}^2 \\ & + \bar{\alpha}e^{-\tau} \left(1 + \frac{\bar{\alpha}}{2}e^{-\tau} - \bar{\alpha}e^{-\tau}(\mu\sqrt{\delta} + \mu + C_\mu\bar{\epsilon}e^{-2\tau})\right) \|\xi |^2 \Delta f\|_{L^2}^2 \\ (4.47) \quad & + \bar{\epsilon}e^{-2\tau} \left(\|\xi |^2 \Delta f\|_{L^2}^2 + 32\|f\|_{L^2}^2 + \bar{\alpha}e^{-\tau} \|\xi |^2 \nabla \Delta f\|_{L^2}^2\right) \\ & \leq C_\mu \frac{|\beta|^2}{\nu^2} (\bar{\epsilon}^2 + \bar{\alpha}^2)e^{-2\tau} + \left(\frac{4}{\lambda}(1 + \bar{\alpha}) + C_\mu(|\beta|^2 + \sqrt{\delta})\right) \|f\|_{L^2}^2 \\ & + C_\mu\bar{\epsilon}e^{-2\tau} \|\nabla f\|_{L^2}^2 + (C_\mu\bar{\epsilon}\bar{\alpha}e^{-3\tau} + \bar{\alpha}^2e^{-2\tau}C_\mu\sqrt{\delta}) \|\Delta f\|_{L^2}^2 \end{aligned}$$

We finally remark that

$$\begin{aligned} \|\xi |^2 (f - \bar{\alpha}e^{-\tau}\Delta f)\|_{L^2}^2 &= \|\xi |^2 f\|_{L^2}^2 + 2\bar{\alpha}e^{-\tau} \|\xi |^2 \nabla f\|_{L^2}^2 \\ &+ \bar{\alpha}^2e^{-2\tau} \|\xi |^2 \Delta f\|_{L^2}^2 - 16\bar{\alpha}e^{-\tau} \|\xi | f\|_{L^2}^2, \end{aligned}$$

and thus that

$$\begin{aligned} \|\xi |^2 (f - \bar{\alpha}e^{-\tau}\Delta f)\|_{L^2}^2 &\leq \|\xi |^2 f\|_{L^2}^2 + 2\bar{\alpha}e^{-\tau} \|\xi |^2 \nabla f\|_{L^2}^2 \\ (4.48) \quad &+ \bar{\alpha}^2e^{-2\tau} \|\xi |^2 \Delta f\|_{L^2}^2. \end{aligned}$$

Next, we set $\mu = 4\lambda = \frac{1}{12}$, for example. Thus, (4.47), together with (4.48), implies that

$$\begin{aligned} & \partial_\tau E_4(\tau) + \frac{1}{2}E_4(\tau) + \left(\frac{1}{12} - C_4(\sqrt{\delta} + \bar{\alpha}e^{-\tau} + \delta)\right) \|\xi |^2 f\|_{L^2}^2 \\ & + \left(1 + \frac{\bar{\alpha}}{2}e^{-\tau} - \bar{\epsilon}e^{-2\tau}C_4\right) \|\xi |^2 \nabla f\|_{L^2}^2 \\ & + \bar{\alpha}e^{-\tau} \left(1 + \frac{\bar{\alpha}}{4}e^{-\tau} - \bar{\alpha}e^{-\tau}(\sqrt{\delta} + \frac{1}{12} + C_4\bar{\epsilon}e^{-2\tau})\right) \|\xi |^2 \Delta f\|_{L^2}^2 \\ (4.49) \quad & + \bar{\epsilon}e^{-2\tau} \left(\|\xi |^2 \Delta f\|_{L^2}^2 + 32\|f\|_{L^2}^2 + \bar{\alpha}e^{-\tau} \|\xi |^2 \nabla \Delta f\|_{L^2}^2\right) \\ & \leq C_4\delta(\bar{\epsilon}^2 + \bar{\alpha}^2)e^{-2\tau} + (48 + C_4(\bar{\alpha}e^{-\tau} + \sqrt{\delta})) \|f\|_{L^2}^2 \\ & + C_4\bar{\epsilon}e^{-2\tau} \|\nabla f\|_{L^2}^2 + (C_4\bar{\epsilon}\bar{\alpha}e^{-3\tau} + \bar{\alpha}^2e^{-2\tau}C_4\sqrt{\delta}) \|\Delta f\|_{L^2}^2 \end{aligned}$$

The lemma 4.4 is thus proved. \square

We have obtained energy estimates of the functionals E_3 and E_4 . In order to obtain an energy estimate of f in the space $H^2(2)$, we introduce a final functional, which is a linear combination of E_3 and E_4 . In order to choose appropriate coefficients, we begin by remarking that

$$3 \|f\|_{L^2}^2 \leq 2 \|\nabla F\|_{L^2}^2 + \|\nabla f\|_{L^2}^2.$$

Thus, choosing $b > 12 \times 16 = 192$, we introduce the functional

$$(4.50) \quad E_5(\tau) = bE_3(\tau) + E_4(\tau).$$

Then, we have the following lemma.

LEMMA 4.5. *Let $f \in L^\infty([\tau_0, \tau_1], H^2(2))$ be a solution of (3.14) satisfying the bound (4.1). There exist three constants $K_0 > 0$, $K_1 > 0$ and $K_2 > 0$ such that*

$$(4.51) \quad \|f\|_{H^1}^2 + \bar{\alpha}e^{-\tau} \|\Delta f\|_{L^2}^2 + \|\|\xi\|^2 (f - \bar{\alpha}e^{-\tau} \Delta f)\|_{L^2}^2 \leq K_1 E_5(\tau)$$

and

$$(4.52) \quad E_5(\tau) \leq K_2 (\|f\|_{H^1}^2 + \bar{\alpha}e^{-\tau} \|\Delta f\|_{L^2}^2 + \|\|\xi\|^2 f\|_{L^2}^2 + \bar{\alpha}^2 e^{-2\tau} \|\|\xi\|^2 \Delta f\|_{L^2}^2)$$

Moreover, $E_5(\tau)$ satisfies the following inequality for all $\tau \in [\tau_0, \tau_1]$,

$$(4.53) \quad E_5(\tau) \leq e^{-\theta(\tau-\tau_0)} E_5(\tau_0) + \frac{K_0 \delta}{2-\theta} (\bar{\alpha}^2 + \bar{\epsilon}) e^{-\theta\tau}$$

with $0 < \theta < \frac{1}{2}$.

Proof : Using the definition of E_5 , it is easy to see that Inequality (4.51) is verified. The estimate (4.52) is a direct consequence of the definition (4.50) of E_5 and the lemmas 3.4 and 2.4.

It remains to prove Inequality (4.53). Using (4.34), (4.49) and choosing the constants $\bar{\epsilon}$, δ and $\bar{\alpha}$ sufficiently small, we show that there exists a constant $K_0 > 0$ such that E_5 satisfies the following inequality

$$\begin{aligned} & \partial_\tau E_5(\tau) + \theta E_5(\tau) + \bar{\epsilon} e^{-2\tau} \left(b \left(\frac{15}{4} + \frac{5\theta}{2} \right) \|\Delta F\|_{L^2}^2 + \frac{5b}{2} \|\Delta f\|_{L^2}^2 + \frac{b}{4} \|\nabla \Delta f\|_{L^2}^2 \right) \\ & + \bar{\epsilon} e^{-2\tau} \left(\|\|\xi\|^2 \Delta f\|_{L^2}^2 + 32 \|f\|_{L^2}^2 + \bar{\alpha} e^{-\tau} \|\|\xi\|^2 \nabla \Delta f\|_{L^2}^2 \right) \\ & \leq K_0 \delta (\bar{\alpha}^2 + \bar{\epsilon}) e^{-2\tau} \end{aligned}$$

where $0 < \theta < \frac{1}{2}$.

Integrating the above inequality between τ_0 and $\tau > \tau_0$ and applying the Gronwall inequality, we obtain

$$\begin{aligned} E_5(\tau) & \leq e^{-\theta(\tau-\tau_0)} E_5(\tau_0) + \frac{K_0 \delta}{2-\theta} (\bar{\alpha}^2 + \bar{\epsilon}) e^{-\theta\tau} (e^{-\tau_0(2-\theta)} - e^{-\tau(2-\theta)}) \\ & \leq e^{-\theta(\tau-\tau_0)} E_5(\tau_0) + \frac{K_0 \delta}{2-\theta} (\bar{\alpha}^2 + \bar{\epsilon}) e^{-\theta\tau} \end{aligned}$$

with $0 < \theta < \frac{1}{2}$. □

5. Proof of Theorem 3.3 and convergence when ϵ tends to zero

In this section, we first prove Theorem 3.3. Next, passing to the limit, when ϵ tends to zero, we prove Theorem 1.1 and Corollary 1.2.

5.1. Proof of Theorem 3.3. Let γ be a small positive constant and let W_0 belong to $H^2(2)$. Theorem 2.6 implies that there exists a solution $W \in C([\tau_0, \hat{\tau}], H^2(2))$ of Equation (3.3) with $W(0) = W_0$, where $\hat{\tau} = \log(T + t_{\max})$.

We recall that $W_\epsilon(\xi, \tau) = \beta G(\xi) + f_\epsilon(\xi, \tau)$.

Thus, the global existence of W_ϵ is a direct consequence of the global existence of f_ϵ .

We also know that the solution f_ϵ of Equation (3.14) exists on $[\tau_0, \hat{\tau}]$ and belongs to $C([\tau_0, \hat{\tau}], H^2(2))$.

We suppose that W_0 satisfies the bound (3.11).

Using the continuous injection of $L^2(2)$ into $L^1(\mathbb{R}^2)$, we can write that

$$|\beta| \leq C\gamma_0$$

where β is given by (3.13) and $C > 0$ is a constant.

Therefore, we have the following bound

$$(5.1) \quad \begin{aligned} & |\beta|^2 + \|f_\epsilon(\tau_0)\|_{H^1}^2 + \bar{\alpha} \|\Delta f_\epsilon(\tau_0)\|_{L^2}^2 \\ & + \|\xi|^2 f_\epsilon(\tau_0)\|_{L^2}^2 + \bar{\alpha} \|\xi|^2 \Delta f_\epsilon(\tau_0)\|_{L^2}^2 \leq \tilde{C}\gamma_0, \end{aligned}$$

where $\tilde{C} > 0$ is a constant.

Let $\delta = \frac{\tilde{C}\gamma_0}{\kappa}$, where $0 < \kappa < \frac{1}{4}$ is a constant that will be made more precise later.

By continuity of the solutions, there exists a time τ_1 , with $\tau_0 < \tau_1 \leq \hat{\tau}$, such that, for all $\tau \leq \tau_1$, f_ϵ satisfies the bound (4.1). Then, according to (4.53), we have, for $\tau_0 \leq \tau \leq \tau_1$,

$$E_5(\tau) \leq e^{-\theta(\tau-\tau_0)} E_5(0) + \frac{K_0\delta}{2-\theta} (\bar{\alpha}^2 + \bar{\epsilon}) e^{-\theta\tau}$$

where $0 < \theta < \frac{1}{2}$.

Let

$$A(\tau) = \|f_\epsilon(\tau)\|_{H^1}^2 + \|\xi|^2 f_\epsilon(\tau)\|_{L^2}^2.$$

In order to complete the proof of the global existence of f_ϵ , it remains to show that $A(\tau) < \delta$, for all τ , $\tau_0 \leq \tau \leq \tau_1$.

We recall that

$$\begin{aligned} \|\xi|^2 (f_\epsilon - \bar{\alpha}e^{-\tau} \Delta f_\epsilon)\|_{L^2}^2 &= \|\xi|^2 f_\epsilon\|_{L^2}^2 - 16\bar{\alpha}e^{-\tau} \|\xi| f_\epsilon\|_{L^2}^2 \\ &+ 2\bar{\alpha}e^{-\tau} \|\xi|^2 \nabla f_\epsilon\|_{L^2}^2 + \bar{\alpha}^2 e^{-2\tau} \|\xi|^2 \Delta f_\epsilon\|_{L^2}^2 \end{aligned}$$

Thus,

$$\|\xi|^2 f_\epsilon\|_{L^2}^2 \leq \|\xi|^2 (f_\epsilon - \bar{\alpha}e^{-\tau} \Delta f_\epsilon)\|_{L^2}^2 + 16\bar{\alpha}e^{-\tau} \|\xi| f_\epsilon\|_{L^2}^2$$

We also have, for all $\mu > 0$,

$$\|\xi| f_\epsilon\|_{L^2}^2 \leq \frac{\mu}{2} \|\xi|^2 f_\epsilon\|_{L^2}^2 + \frac{1}{2\mu} \|f_\epsilon\|_{L^2}^2$$

Choosing $\mu = \frac{1}{16}$, we can write

$$\frac{1}{2} \|\xi|^2 f_\epsilon\|_{L^2}^2 \leq \|\xi|^2 (f_\epsilon - \bar{\alpha}e^{-\tau} \Delta f_\epsilon)\|_{L^2}^2 + 128\bar{\alpha}e^{-\tau} \|f_\epsilon\|_{L^2}^2$$

Therefore, using Inequality (4.51) of Lemma 4.5, we obtain that there exists a constant $\tilde{K}_1 > K_1$ such that

$$(5.2) \quad A(\tau) \leq \tilde{K}_1 E_5(\tau)$$

On the other hand, we have, by Inequality (4.52) of Lemma 4.5,

$$(5.3) \quad E_5(\tau) \leq K_2(A(\tau) + \bar{\alpha}e^{-\tau} \|\Delta f_\epsilon(\tau)\|_{L^2}^2 + \bar{\alpha}^2 e^{-2\tau} \|\xi\|^2 \|\Delta f_\epsilon(\tau)\|_{L^2}^2)$$

Now, let

$$(5.4) \quad K = \tilde{K}_1 \max(K_0, K_2)$$

and choose

$$(5.5) \quad \kappa = \frac{1}{4} \min(1, K)$$

where K_0 is the constant given in Inequality (4.53). Suppose that T is large enough (which is equivalent to saying that $\bar{\epsilon}$ and $\bar{\alpha}$ are small enough) such that

$$K(\bar{\alpha}^2 + \bar{\epsilon}) \leq \frac{1}{8}, \text{ and } \bar{\alpha} \leq \frac{1}{4}.$$

Then, using Estimate (4.53) and Inequalities (5.2) (5.3), we obtain

$$\begin{aligned} A(\tau) &\leq K_1 E_5(\tau) \\ &\leq K_1 e^{-\theta(\tau-\tau_0)} E_5(\tau_0) + K_1 K_0 \frac{\delta}{2-\theta} (\bar{\alpha}^2 + \bar{\epsilon}) e^{-\theta\tau} \\ &\leq K e^{-\theta(\tau-\tau_0)} (A(\tau_0) + \bar{\alpha} \|\Delta f_\epsilon(\tau_0)\|_{L^2}^2 + \bar{\alpha}^2 \|\xi\|^2 \|\Delta f_\epsilon(\tau_0)\|_{L^2}^2) + \frac{\delta}{4} e^{-\theta\tau} \\ &< \delta \end{aligned}$$

Therefore, $A(\tau)$ remains small on $[\tau_0, \tau_1]$. We conclude that $\tau_1 = \hat{\tau}$. On the other hand, Inequalities (4.51) and (4.53) imply that the solution f_ϵ of Equation (3.14) satisfies the following bound $\forall \tau_0 \leq \tau \leq \hat{\tau}$,

$$(5.6) \quad \begin{aligned} &\|f_\epsilon(\tau)\|_{H^1}^2 + \bar{\alpha} e^{-\tau} \|\Delta f_\epsilon(\tau)\|_{L^2}^2 + \|\xi\|^2 (f_\epsilon(\tau) - \bar{\alpha} e^{-\tau} \Delta f_\epsilon)^2_{L^2} \\ &\leq K_1 e^{-\theta(\tau-\tau_0)} E_5(\tau_0) + \frac{K_1 K_0 \delta}{2-\theta} (\bar{\alpha}^2 + \bar{\epsilon}) e^{-\theta\tau}, \end{aligned}$$

where $0 < \theta < \frac{1}{2}$. Therefore,

$$(5.7) \quad \|f_\epsilon(\tau) - \bar{\alpha} e^{-\tau} \Delta f_\epsilon\|_{L^2(2)}^2 \leq C e^{-\theta\tau},$$

where C is a positive constant.

The above inequality implies that the $H^2(2)$ -norm of f_ϵ remains bounded for all $\tau \in [\tau_0, \hat{\tau}]$. Thus, $\hat{\tau} = +\infty$ and f_ϵ belongs to the space $L^\infty([\tau_0, +\infty[, H^2(2))$.

5.2. Convergence when ϵ tends to zero. Before we begin the proof of Theorem 1.1, we give the following lemmas, which will be useful later.

LEMMA 5.1. *Let $w \in L^2(2)$ and let $z = (I - \alpha\Delta)^{-1}w$. Then, there exists a positive constant C such that we have the following inequalities:*

- a) $\|z\|_{L^2}^2 + 2\alpha \|\nabla z\|_{L^2}^2 + \alpha^2 \|\Delta z\|_{L^2}^2 \leq C \|w\|_{L^2}^2.$
- b) $\| |x|^2 z \|_{L^2}^2 + 2\alpha \| |x|^2 \nabla z \|_{L^2}^2 + \alpha^2 \| |x|^2 \Delta z \|_{L^2}^2 \leq C \|w\|_{L^2(2)}^2.$

Proof : We have

$$(5.8) \quad z - \alpha \Delta z = w.$$

Thus, in order to prove Inequalities a) and b), it is sufficient to take the scalar product of (5.8) with $|x|^4 (z - \alpha \Delta z)$ respectively. \square

LEMMA 5.2. 1) Let f and g be two functions such that $g \in L^2(1) \cap H^1(\mathbb{R}^2)$, $\nabla f \in L^4(\mathbb{R}^2) \cap L^\infty(\mathbb{R}^2)$ and $\Delta f \in L^2(\mathbb{R}^2) \cap L^4(\mathbb{R}^2)$. Also let $h = (I - \alpha \Delta)^{-1}(f \cdot (I - \alpha \Delta)g) - fg$. Then, there exists a positive constant C such that we have the following inequalities:

$$a) \quad \|h\|_{L^2}^2 + \alpha \|\nabla h\|_{L^2}^2 \leq C_\alpha (\|\Delta f\|_{L^2}^2 \|g\|_{H^1}^2 + \|\nabla f\|_{L^4}^2 \|\nabla g\|_{L^2}^2).$$

$$b) \quad \begin{aligned} & \| |x| h \|_{L^2}^2 + \alpha \| |x| \nabla h \|_{L^2}^2 \leq C_\alpha (\|h\|_{L^2}^2 + \|\Delta f\|_{L^4}^2 \| |x| g \|_{L^2}^2 \\ & + \|\nabla f\|_{L^\infty}^2 (\|g\|_{L^2}^2 + \| |x| g \|_{L^2}^2)), \end{aligned}$$

where $C_\alpha = C(\alpha + \alpha^2)$.

2) Let \bar{f} and \bar{g} be two functions such that $\bar{f} \in L^\infty(\mathbb{R}^2)$, $\nabla \bar{g} \in L^2(2)$ and $\Delta \bar{g} \in L^2(2)$. Also let $k = (I - \alpha \Delta)^{-1}(\bar{f} \cdot \nabla(I - \alpha \Delta)\bar{g})$. Then, we have the following inequalities:

$$c) \quad \|k\|_{L^2}^2 + \alpha \|\nabla k\|_{L^2}^2 \leq C \|\bar{f}\|_{L^\infty}^2 (\|\nabla \bar{g}\|_{L^2}^2 + \alpha \|\Delta \bar{g}\|_{L^2}^2).$$

$$d) \quad \begin{aligned} & \| |x|^2 k \|_{L^2}^2 + \alpha \| |x|^2 \nabla k \|_{L^2}^2 \leq C_\alpha (\|k\|_{L^2}^2 \\ & + \|\bar{f}\|_{L^\infty}^2 (\| |x|^2 \nabla \bar{g} \|_{L^2}^2 + \| |x|^2 \Delta \bar{g} \|_{L^2}^2)). \end{aligned}$$

Proof : Using the expression of h , we can write

$$(5.9) \quad h - \alpha \Delta h = \alpha \Delta f \cdot g + 2\alpha \nabla f \cdot \nabla g$$

Taking the scalar product of Equation (5.9) with h and integrating by parts, we can write the following inequality

$$(5.10) \quad \|h\|_{L^2}^2 + \alpha \|\nabla h\|_{L^2}^2 \leq C_\alpha \|h\|_{L^4} (\|\Delta f\|_{L^2} \|g\|_{L^4} + \|\nabla f\|_{L^4} \|\nabla g\|_{L^2})$$

Then, applying the Cauchy-Schwarz inequality, we obtain Inequality a).

In order to obtain Inequality b), it is sufficient to take the scalar product of Equation (5.9) with $|x|^2 h$.

Inequalities c) and d) can be shown by the same way. \square

Now, we prove the Theorem 1.1. In the previous section, we have showed that the solution f_ϵ of Equation (3.14) belongs to the space $C^0([\tau_0, +\infty), H^2(2))$ and that Estimate (5.6) is satisfied, $\forall \tau \geq \tau_0$. In particular, $\|f_\epsilon(\tau) - \bar{\alpha} e^{-\tau} \Delta f_\epsilon(\tau)\|_{L^2(2)}$ is bounded uniformly in ϵ and decays exponentially to 0.

On the other hand, one can show, according to Equation (3.14), that $\partial_\tau (f_\epsilon - \bar{\alpha} e^{-\tau} \Delta f_\epsilon)$ is uniformly bounded in ϵ in the space $L^\infty([\tau_0, \tau], H^{-2}(\mathbb{R}^2))$.

Therefore,

$$(5.11) \quad \partial_\tau f_\epsilon \in L^\infty([\tau_0, \tau], L^2(\mathbb{R}^2))$$

Let O be a bounded open set in \mathbb{R}^2 . Property (5.11) implies that the family (f_ϵ) , $\epsilon > 0$, is equicontinuous in $C^0([\tau_0, \tau], L^2(O))$.

Ascoli's theorem allows us to extract a subsequence still denoted by f_ϵ such that

f_ϵ converges strongly to f in $C^0([\tau_0, \tau], H^{-1}(O))$. Next, the interpolation between $H^{-1}(O)$ and $H^2(O)$ allows us to deduce that

$$(5.12) \quad f_\epsilon \longrightarrow f \text{ strongly in } C^0([\tau_0, \tau], H^s(O)), \quad \forall s < 2.$$

Let us note that, by the Hölder inequality, we have

$$(5.13) \quad \left\| |\xi|^{\frac{3}{2}} f_\epsilon \right\|_{L^2} \leq \|f_\epsilon\|_{L^2}^{\frac{1}{4}} \left\| |\xi|^2 f_\epsilon \right\|_{L^2}^{\frac{3}{4}}$$

Then, using property (5.12) and the fact that f_ϵ is uniformly bounded in

$$L^\infty([\tau_0, +\infty], L^2(2))$$

, we deduce that, for any $\tau > 0$,

$$(5.14) \quad |\xi|^{\frac{3}{2}} f_\epsilon \longrightarrow |\xi|^{\frac{3}{2}} f \text{ strongly in } C^0([0, \tau], L^2(O)).$$

Using Lemma 2.1 part b), together with the properties (5.12) and (5.14), we deduce that

$$(5.15) \quad K_{f_\epsilon} \longrightarrow K_f \text{ strongly in } L^\infty([\tau_0, \tau], L^\infty(O)).$$

Also, using Lemma 2.1 part b) and Property (5.12), we deduce that

$$(5.16) \quad \nabla K_{f_\epsilon} \longrightarrow \nabla K_f \text{ strongly in } L^\infty([\tau_0, \tau], L^4(O)).$$

These convergences allow us to show that f satisfies the equation (3.14) in the weak sense for $\epsilon = 0$. To this end, we take the L^2 -product of (3.14) with any function $\phi \in C_0^\infty(\mathbb{R}^+ \times \mathbb{R}^2, \mathbb{R}^2)$ such that $\text{supp}(\phi) \subset [\tau_0, \tau] \times O$.

We will only prove the convergence of the nonlinear term

$\int_{\tau_0}^\tau \int_O K_{f_\epsilon} \cdot \nabla (f_\epsilon - \bar{\alpha} e^{-\tau} \Delta f_\epsilon) \cdot \phi d\xi d\tau$ since, for the other terms, the convergence is easier to prove.

Let $\phi \in C_0^\infty(\mathbb{R}^+ \times \mathbb{R}^2, \mathbb{R}^2)$ such that $\text{supp}(\phi) \subset [\tau_0, \tau] \times O$.

Then, integrating by parts, we obtain

$$(5.17) \quad \begin{aligned} & \int_{\tau_0}^\tau \int_O K_{f_\epsilon} \cdot \nabla (f_\epsilon - \bar{\alpha} e^{-\tau} \Delta f_\epsilon) \phi d\xi d\tau = \int_0^\tau \int_O K_{f_\epsilon} \cdot \nabla \phi (f_\epsilon - \bar{\alpha} e^{-\tau} \Delta f_\epsilon) d\xi d\tau \\ & = \int_{\tau_0}^\tau \int_O K_{f_\epsilon} \cdot \nabla \phi f_\epsilon \\ & \quad + \bar{\alpha} e^{-\tau} \int_0^\tau \int_O \sum_{k=1}^2 (\partial_k K_{f_\epsilon} \cdot \nabla \phi \partial_k f_\epsilon + K_{f_\epsilon} \cdot \nabla \partial_k \phi \partial_k f_\epsilon) d\xi d\tau \end{aligned}$$

Using Properties (5.15), (5.16) and (5.12), we deduce that

$$\int_{\tau_0}^\tau \int_O K_{f_\epsilon} \cdot \nabla \phi (f_\epsilon - \bar{\alpha} e^{-\tau} \Delta f_\epsilon) d\xi d\tau \rightarrow \int_{\tau_0}^\tau \int_O K_f \cdot \nabla \phi (f - \bar{\alpha} e^{-\tau} \Delta f) d\xi d\tau.$$

Therefore, f satisfies the equation (3.14) in the weak sense for $\epsilon = 0$.

On the other hand, remarking that the estimates proved in the Section 4 are uniform with respect to ϵ , we can then obtain the same estimates for the limiting solution f with $\epsilon = 0$. We thus have shown that f satisfies the same decay rate in time as f_ϵ and we have

$$\|f(\tau)\|_{H^1}^2 + \bar{\alpha} \|\Delta f(\tau)\|_{L^2}^2 + \left\| |\xi|^2 (f(\tau) - \bar{\alpha} e^{-\tau} \Delta f) \right\|_{L^2(2)}^2 \leq \delta e^{-\theta\tau}$$

where $0 < \theta < \frac{1}{2}$ and $C > 0$ is a constant.

Now, we prove the uniqueness of solutions of Equation (1.6). For this purpose, we return to Equation (1.1) written in the original variables (x, t) .

Suppose that w_1 and w_2 are two solutions of Equation (1.1) such that $w_1(0, x) = w_2(0, x) = w_0(x)$ and let u_1 and u_2 be the velocity fields associated to the vorticities w_1 and w_2 respectively.

Then, $w = w_1 - w_2$ satisfies the following equation

$$(5.18) \quad \begin{aligned} \partial_t(w - \alpha\Delta w) - \nu\Delta w + u_1 \cdot \nabla(w - \alpha\Delta w) + (u_1 - u_2) \cdot \nabla(w_2 - \alpha\Delta w_2) &= 0 \\ w(0, x) &= 0 \end{aligned}$$

According to Lemma 2.3, we have that

$$\|u_1 - u_2\|_{L^2} \leq C \| |x| w \|_{L^2}.$$

This indicated that the uniqueness of solutions should be proved by using a weighted norm.

Before we start the proof of the uniqueness of solutions, we will give the following bounds, which will be useful later.

Using the Fourier transform of u and the continuous injection of $L^2(2)$ into $L^1(\mathbb{R}^2)$, we can write

$$(5.19) \quad \begin{aligned} \|\nabla u_1\|_{L^\infty} &\leq C \|\widehat{\nabla u_1}\|_{L^1} \leq C \|\widehat{w_1}\|_{L^1} \\ &\leq C \|\widehat{w_1}\|_{L^2(2)} \leq C(\|w_1\|_{L^2} + \|\Delta w_1\|_{L^2}) \leq C, \end{aligned}$$

where $C > 0$ is a constant.

We also have by Lemma 2.1 part(d) that

$$(5.20) \quad \begin{aligned} \|\Delta u_1\|_{L^4} &\leq C \|\Delta u_1\|_{H^1} \leq C(\|\Delta u_1\|_{L^2} + \|\nabla \Delta u_1\|_{L^2}) \\ &\leq C(\|\nabla w_1\|_{L^2} + \|\Delta w_1\|_{L^2}) \leq C. \end{aligned}$$

As we have explained before, in order to prove that $w = 0$, we will write an energy estimation of w in the space $L^2(2)$. As a first step, we begin by performing an estimation of $\|w\|_{L^2} + \sqrt{\alpha}\|\nabla w\|_{L^2}$. For this purpose, we take the scalar product of Equation (5.18) with w . We obtain, after some integrations by parts,

$$\begin{aligned} &\frac{1}{2}\partial_t(\|w\|_{L^2}^2 + \alpha\|\nabla w\|_{L^2}^2) + \nu\|\nabla w\|_{L^2}^2 \\ &\leq C\|\nabla u_1\|_{L^\infty}\|\nabla w\|_{L^2}^2 + C\|u_1 - u_2\|_{L^\infty}\|\Delta w_2\|_{L^2}\|\nabla w\|_{L^2} \end{aligned}$$

Therefore, using (5.19) and Lemma 2.2 part a), then applying the Cauchy-Schwarz inequality, we obtain

$$(5.21) \quad \begin{aligned} &\frac{1}{2}\partial_t(\|w\|_{L^2}^2 + \alpha\|\nabla w\|_{L^2}^2) + \nu\|\nabla w\|_{L^2}^2 \\ &\leq C\|\nabla w\|_{L^2}^2 + C\|w\|_{L^2(2)}^{\frac{1}{2}}\|w\|_{H^1}^{\frac{1}{2}}\|\nabla w\|_{L^2} \\ &\leq C\|\nabla w\|_{L^2}^2 + C\|w\|_{L^2(2)}\|w\|_{H^1} \end{aligned}$$

In order to obtain an estimation of w in $L^2(2)$, it remains to bound the L^2 -norm of $|x|^2 w$. For this purpose, we write Equation (5.18) in another form:

$$(5.22) \quad \begin{aligned} &\partial_t w - \nu(I - \alpha\Delta)^{-1}\Delta w + (I - \alpha\Delta)^{-1}(u_1 \cdot \nabla(w - \alpha\Delta w)) \\ &+ (I - \alpha\Delta)^{-1}((u_1 - u_2) \cdot \nabla(w_2 - \alpha\Delta w_2)) = 0 \end{aligned}$$

Now, taking the scalar product of the above equation with $|x|^4 w$, we get

$$\begin{aligned}
& \frac{1}{2} \partial_t \| |x|^2 w \|_{L^2}^2 - \nu ((I - \alpha \Delta)^{-1} \Delta w, |x|^4 w) \\
(5.23) \quad & + ((I - \alpha \Delta)^{-1} (u_1 \cdot \nabla (w - \alpha \Delta w)), |x|^4 w) \\
& + ((I - \alpha \Delta)^{-1} ((u_1 - u_2) \cdot \nabla (w_2 - \alpha \Delta w_2)), |x|^4 w) = 0
\end{aligned}$$

We begin by computing the term $I_1 = -((I - \alpha \Delta)^{-1} \Delta w, |x|^4 w)$.

Let $z = (I - \alpha \Delta)^{-1} w$. Integrating by parts, we can write

$$\begin{aligned}
I_1 &= - \int_{\mathbb{R}^2} \Delta z \cdot |x|^4 z \, dx + \alpha \int_{\mathbb{R}^2} \Delta z \cdot |x|^4 \Delta z \, dx \\
(5.24) \quad &= \| |x|^2 \nabla z \|_{L^2}^2 - 8 \| |x| z \|_{L^2}^2 + \alpha \| |x|^2 \Delta z \|_{L^2}^2 \\
&= \| |x|^2 \nabla (I - \alpha \Delta)^{-1} w \|_{L^2}^2 - 8 \| |x| (I - \alpha \Delta)^{-1} w \|_{L^2}^2 \\
&\quad + \alpha \| |x|^2 \Delta (I - \alpha \Delta)^{-1} w \|_{L^2}^2
\end{aligned}$$

Next, we estimate the term $I_2 = ((I - \alpha \Delta)^{-1} (u_1 \cdot \nabla (w - \alpha \Delta w)), |x|^4 w)$. We have

$$\begin{aligned}
I_2 &= \int_{\mathbb{R}^2} u_1 \cdot \nabla (I - \alpha \Delta)^2 z \cdot (I - \alpha \Delta)^{-1} |x|^4 (z - \alpha \Delta z) \, dx \\
&= \int_{\mathbb{R}^2} u_1 \cdot \nabla (I - \alpha \Delta)^2 z \cdot (I - \alpha \Delta)^{-1} [(I - \alpha \Delta)(|x|^4 z) \\
&\quad + \alpha \Delta(|x|^4 z) + 2\alpha \nabla(|x|^4) \cdot \nabla z] \, dx \\
&= \int_{\mathbb{R}^2} u_1 \cdot \nabla (I - \alpha \Delta)^2 z \cdot |x|^4 z \, dx \\
&\quad + \alpha \int_{\mathbb{R}^2} (I - \alpha \Delta)^{-1} (u_1 \cdot \nabla (I - \alpha \Delta)^2 z) \cdot (16 |x|^2 z + 8 |x|^2 x \cdot \nabla z) \, dx
\end{aligned}$$

Let

$$\begin{aligned}
J_1 &= \int_{\mathbb{R}^2} u_1 \cdot \nabla (I - \alpha \Delta)^2 z \cdot |x|^4 z \, dx \\
&= \int_{\mathbb{R}^2} (u_1 \cdot \nabla z - 2\alpha u_1 \cdot \nabla \Delta z + \alpha^2 u_1 \cdot \nabla \Delta^2 z) \cdot |x|^4 z \, dx
\end{aligned}$$

Integrating by parts and using (4.45) and Lemma 2.2 part a), we obtain

$$\begin{aligned}
(5.25) \quad & \left| \int_{\mathbb{R}^2} u_1 \cdot \nabla z \cdot |x|^4 z \, dx \right| = \left| -2 \int_{\mathbb{R}^2} u_1 \cdot x \cdot |x|^2 |z|^2 \, dx \right| \\
& \leq C \|u_1\|_{L^\infty} \|z\|_{L^2(2)}^2 \leq C \|z\|_{L^2(2)}^2
\end{aligned}$$

We also have

$$\begin{aligned}
(5.26) \quad & \left| \int_{\mathbb{R}^2} u_1 \cdot \nabla \Delta z \cdot |x|^4 z \, dx \right| \\
&= \left| - \int_{\mathbb{R}^2} u_1 \cdot \nabla z \cdot |x|^4 \Delta z \, dx - 4 \int_{\mathbb{R}^2} u_1 \cdot x \Delta z \cdot |x|^2 z \, dx \right| \\
&\leq C \|u_1\|_{L^\infty} \| |x|^2 \Delta z \|_{L^2} (\| |x|^2 \nabla z \|_{L^2} + \| |x| z \|_{L^2}) \\
&\leq C \| |x|^2 \Delta z \|_{L^2} (\| |x|^2 \nabla z \|_{L^2} + \|z\|_{L^2(2)})
\end{aligned}$$

Finally, integrating by parts several times, we get

$$\begin{aligned}
& \int_{\mathbb{R}^2} u_1 \cdot \nabla \Delta^2 z \cdot |x|^4 z \, dx = \int_{\mathbb{R}^2} \Delta u_1 \cdot \nabla \Delta z \cdot |x|^4 z \, dx \\
& \quad + \int_{\mathbb{R}^2} u_1 \cdot \nabla \Delta z \cdot \Delta(|x|^4 z) \, dx + 2 \sum_k \int_{\mathbb{R}^2} \partial_k u_1 \cdot \nabla \Delta z \cdot \partial_k(|x|^4 z) \, dx \\
& = - \int_{\mathbb{R}^2} \Delta u_1 \cdot \nabla(|x|^4 z) \Delta z \, dx - \int_{\mathbb{R}^2} u_1 \cdot \nabla \Delta(|x|^4 z) \Delta z \, dx \\
& \quad - 2 \sum_k \int_{\mathbb{R}^2} \partial_k u_1 \cdot \nabla \partial_k(|x|^4 z) \Delta z \, dx
\end{aligned}$$

A simple computation and the application of the Hölder inequality allow us to write that

$$\begin{aligned}
& \left| \int_{\mathbb{R}^2} u_1 \cdot \nabla \Delta^2 z \cdot |x|^4 z \, dx \right| \\
& \leq C \|\Delta u_1\|_{L^4} \| |x|^2 \Delta z \|_{L^2} (\| |x|^2 \nabla z \|_{L^4} + \| |x| z \|_{L^4}) \\
& \quad + C \|u_1\|_{L^\infty} \left[\|\Delta z\|_{L^2} (\| |x| z \|_{L^2} + \| |x|^2 \nabla z \|_{L^2}) + \| |x|^2 \Delta z \|_{L^2} \| |x| \Delta z \|_{L^2} \right] \\
& \quad + C \|\nabla u_1\|_{L^\infty} \| |x|^2 \Delta z \|_{L^2} (\|z\|_{L^2} + \| |x| \nabla z \|_{L^2} + \| |x|^2 \Delta z \|_{L^2})
\end{aligned}$$

Thus, inequalities (5.19) and (5.20) imply that

$$\begin{aligned}
(5.27) \quad & \left| \int_{\mathbb{R}^2} u_1 \cdot \nabla \Delta^2 z \cdot |x|^4 z \, dx \right| \\
& \leq C \| |x|^2 \Delta z \|_{L^2} (\| |x|^2 \nabla z \|_{H^1} + \| |x| z \|_{H^1}) \\
& \quad + C \left[\|\Delta z\|_{L^2} (\|z\|_{L^2(2)} + \| |x|^2 \nabla z \|_{L^2}) + \| |x|^2 \Delta z \|_{L^2} \|\Delta z\|_{L^2(2)} \right] \\
& \quad + C \| |x|^2 \Delta z \|_{L^2} (\|z\|_{L^2} + \|\nabla z\|_{L^2(2)} + \| |x|^2 \Delta z \|_{L^2}) \\
& \leq C \| |x|^2 \Delta z \|_{L^2} (\|z\|_{L^2(2)} + \|\nabla z\|_{L^2(2)} + \|\Delta z\|_{L^2(2)}) \\
& \quad + C \|\Delta z\|_{L^2} (\|z\|_{L^2(2)} + \| |x|^2 \nabla z \|_{L^2}).
\end{aligned}$$

Then, adding the inequalities (5.25), (5.26) and (5.27), we can write the following bound on J_1

$$\begin{aligned}
|J_1| & \leq \\
& C \|z\|_{L^2(2)}^2 + \alpha C \| |x|^2 \Delta z \|_{L^2} (\|z\|_{L^2(2)} + (1 + \alpha) \|\nabla z\|_{L^2(2)} + \alpha \|\Delta z\|_{L^2(2)}) \\
& \quad + \alpha^2 C \|\Delta z\|_{L^2} (\|z\|_{L^2(2)} + \| |x|^2 \nabla z \|_{L^2})
\end{aligned}$$

Therefore, Lemma 5.1 implies that

$$(5.28) \quad |J_1| \leq \tilde{C}_\alpha \|w\|_{L^2(2)}^2,$$

where $\tilde{C}_\alpha = C(1 + \sqrt{\alpha} + \alpha + \frac{1+\alpha}{\sqrt{\alpha}})$ and C is a positive constant.

Now, let $J_2 = \alpha \int_{\mathbb{R}^2} (I - \alpha \Delta)^{-1} (u_1 \cdot \nabla (I - \alpha \Delta)^2 z) \cdot (16 |x|^2 z + 8 |x|^2 x \cdot \nabla z) \, dx$.

Integrating by parts and applying the Hölder inequality, we can write

$$\begin{aligned}
|J_2| &= \alpha \left| \sum_i \int_{\mathbb{R}^2} (I - \alpha\Delta)^{-1} (u_{1i}(I - \alpha\Delta)^2 z) \cdot (32x_i z + 24|x|^2 \partial_i z \right. \\
&\quad \left. + 16x_i x \cdot \nabla z + 8|x|^2 x \cdot \nabla \partial_i z) dx \right| \\
&\leq \alpha C (\| |x| z \|_{L^2} + \| |x|^2 \nabla z \|_{L^2}) \sum_i \| (I - \alpha\Delta)^{-1} (u_{1i}(I - \alpha\Delta)^2 z) \|_{L^2} \\
&\quad + \alpha C (\| |x| \nabla z \|_{L^2} + \| |x|^2 \Delta z \|_{L^2}) \sum_i \| |x| (I - \alpha\Delta)^{-1} (u_{1i}(I - \alpha\Delta)^2 z) \|_{L^2}
\end{aligned}$$

Using Lemma 5.2 parts a), we can write

$$\begin{aligned}
&\| (I - \alpha\Delta)^{-1} (u_{1i}(I - \alpha\Delta)^2 z) \|_{L^2} \\
(5.29) \quad &\leq \| (I - \alpha\Delta)^{-1} (u_{1i}(I - \alpha\Delta)^2 z) - u_{1i} w \|_{L^2} + \| u_{1i} w \|_{L^2} \\
&\leq C_\alpha (\| \Delta u_1 \|_{L^2} \| w \|_{H^1} + \| \nabla u_1 \|_{L^4} \| \nabla w \|_{L^2}) + C \| u_1 \|_{L^\infty} \| w \|_{L^2} \\
&\leq C_\alpha \| w \|_{H^1}
\end{aligned}$$

On the other hand, Lemma 5.2 parts b) allows us to write

$$\begin{aligned}
&\| |x| (I - \alpha\Delta)^{-1} (u_{1i}(I - \alpha\Delta)^2 z) \|_{L^2} \\
&\leq \| |x| [(I - \alpha\Delta)^{-1} (u_{1i}(I - \alpha\Delta)^2 z) - u_{1i} w] \|_{L^2} + \| |x| u_{1i} w \|_{L^2} \\
(5.30) \quad &\leq C_\alpha \| w \|_{H^1} + C_\alpha (\| \Delta u_1 \|_{L^4} \| |x| w \|_{L^2} + \| \nabla u_1 \|_{L^\infty} \| w \|_{L^2(2)}) \\
&\quad + C \| u_1 \|_{L^\infty} \| |x| w \|_{L^2} \\
&\leq C_\alpha (\| w \|_{H^1} + \| w \|_{L^2(2)})
\end{aligned}$$

Thus, Inequalities (5.29) and (5.30), together with Lemma 5.1 imply that

$$(5.31) \quad |J_2| \leq C_\alpha (\| w \|_{L^2(2)} \| w \|_{H^1} + \| w \|_{L^2(2)}^2)$$

Finally, we estimate the term

$$I_3 = ((I - \alpha\Delta)^{-1} ((u_1 - u_2) \cdot \nabla (w_2 - \alpha\Delta w_2)), |x|^4 w).$$

Applying the Hölder inequality and using Lemma 5.2 parts c) and d), we can write

$$\begin{aligned}
|I_3| &\leq \| |x|^2 (I - \alpha\Delta)^{-1} ((u_1 - u_2) \cdot \nabla (w_2 - \alpha\Delta w_2)) \|_{L^2} \| |x|^2 w \|_{L^2} \\
(5.32) \quad &\leq C_\alpha \| u_1 - u_2 \|_{L^\infty} \| |x|^2 w \|_{L^2} (\| \nabla w_2 \|_{L^2(2)} + \| \Delta w_2 \|_{L^2(2)}) \\
&\leq C_\alpha \| w \|_{L^2(2)}^{\frac{1}{2}} \| w \|_{H^1}^{\frac{1}{2}} \| |x|^2 w \|_{L^2}
\end{aligned}$$

Therefore, collecting the inequalities (5.24), (5.28), (5.31) and (5.32), we can write Equality (5.23) as follows

$$\begin{aligned}
(5.33) \quad &\frac{1}{2} \partial_t \| |x|^2 w \|_{L^2}^2 + \nu \| |x|^2 \nabla (I - \alpha\Delta)^{-1} w \|_{L^2}^2 + \alpha \nu \| |x|^2 \Delta (I - \alpha\Delta)^{-1} w \|_{L^2}^2 \\
&\leq C_\alpha (\| w \|_{L^2(2)} \| w \|_{H^1} + \| w \|_{L^2(2)}^2) + C_\alpha \| w \|_{L^2(2)}^{\frac{1}{2}} \| w \|_{H^1}^{\frac{1}{2}} \| |x|^2 w \|_{L^2}
\end{aligned}$$

Taking the sum of Inequalities (5.21) and (5.33) and applying the Cauchy-Schwarz inequality, we obtain

$$\begin{aligned} & \frac{1}{2} \partial_t (\|w\|_{L^2(2)}^2 + \alpha \|\nabla w\|_{L^2}^2) + \nu \|\nabla w\|_{L^2}^2 + \nu \| |x|^2 \nabla (I - \alpha \Delta)^{-1} w \|_{L^2}^2 \\ & + \alpha \nu \| |x|^2 \Delta (I - \alpha \Delta)^{-1} w \|_{L^2}^2 \leq (C_\alpha + \tilde{C}_\alpha) \|w\|_{L^2(2)}^2 + C_\alpha \|w\|_{H^1}^2 \end{aligned}$$

Finally, integrating the above inequality between 0 and $t > 0$ and using the Gronwall lemma, we deduce that $w = 0$ and thus, the solution of Equation (1.1) is unique.

5.3. Proof of Corollary 1.2. In the proof of Corollary 1.2, we use the proposition B.1 of [16], that we recall here.

PROPOSITION 5.3. *Let $w \in L^2(m^*)$ for some $m^* > 0$ and denote by v the velocity field obtained from w via the Biot-Savart law. Assume that either 1) $0 < m^* \leq 1$, or*

2) $1 < m^* \leq 2$, and $\int_{\mathbb{R}^2} w(\xi) d\xi = 0$

If $m^* \notin \mathbb{N}$, then for all $2 < q < \infty$, there exists $C > 0$ such that

$$\left\| (1 + |\xi|^2)^{\frac{m^*}{2} - \frac{1}{q}} v \right\|_{L^q} \leq C \left\| (1 + |\xi|^2)^{\frac{m^*}{2}} w \right\|_{L^2}.$$

For the proof of the above proposition, see [16].

Now, let $w(x, t)$ be the solution of (1.1) with $w(x, 0) = w_0(x)$ and let $W(\xi, \tau)$ be the solution of (1.6) with $W_0(\xi) = T w_0(x)$ as initial data. We recall that $L^2(2)$ is continuously embedded into $L^p(\mathbb{R}^2)$, for all $1 \leq p \leq 2$.

Then, using (1.3) and Theorem 1.1, we obtain

$$\begin{aligned} & \left\| (1 - \frac{\alpha}{T} \Delta)(w(t) - \beta \Omega(t)) \right\|_{L^p} \\ & = \nu^{\frac{1}{p}} (T + t)^{-1 + \frac{1}{p}} \left\| (1 - \bar{\alpha} e^{-\tau} \Delta)(W(\log(T + t)) - \beta G) \right\|_{L^p} \\ (5.34) \quad & \leq C (T + t)^{-1 + \frac{1}{p}} \left\| (1 - \bar{\alpha} e^{-\tau} \Delta)(W(\log(T + t)) - \beta G) \right\|_{L^2(2)} \\ & \leq C (T + t)^{-1 - \theta + \frac{1}{p}} \end{aligned}$$

Using Lemma 2.1 part a), we see that (1.13) holds for all $2 < q < \infty$.

In order to show that (1.13) holds also for all $1 < q \leq 2$, we use Proposition 5.3.

Now, assume that $1 < q \leq 2$ and fix $m^* \in (\frac{2}{q}, 2)$.

Therefore, using Proposition 5.3 and the Hölder inequality, we obtain

$$\begin{aligned} & \left\| (1 - \bar{\alpha} e^{-\tau} \Delta)(V(\tau) - \beta V^G(\tau)) \right\|_{L^q} \\ & \leq \left\| (1 + |\xi|^2)^{\frac{m^*}{2} - \frac{1}{4}} (1 - \bar{\alpha} e^{-\tau} \Delta)(V(\tau) - \beta V^G(\tau)) \right\|_{L^4} \\ (5.35) \quad & \leq C \left\| (1 + |\xi|^2)^{\frac{m^*}{2}} (1 - \bar{\alpha} e^{-\tau} \Delta)(W(\tau) - \beta G(\tau)) \right\|_{L^2} \\ & \leq \left\| (1 - \bar{\alpha} e^{-\tau})(W(\tau) - \beta G(\tau)) \right\|_{L^2(2)} \leq C e^{-\theta \tau} \end{aligned}$$

Finally, using the change of variables (1.4), we obtain (1.13) for all $1 < q \leq 2$.

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