

Complete submanifolds of \mathbb{R}^n with finite topology

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We show that a complete m -dimensional immersed submanifold M of \mathbb{R}^n with $a(M) < 1$ is properly immersed and have finite topology, where $a(M) \in [0, \infty]$ is a scaling invariant number that gives the rate that the norm of the second fundamental form decays to zero at infinity. The class of submanifolds $M \subset \mathbb{R}^n$ with $a(M) < 1$ contains all complete minimal surfaces with finite total curvature, all m -dimensional minimal submanifolds with finite total scalar curvature $\int_M |\alpha|^m dV < \infty$ and all complete 2-dimensional surfaces with $\int_M |\alpha|^2 dV < \infty$ and non-positive curvature with respect to every normal direction.

1. Introduction

Let M be a complete surface minimally immersed in \mathbb{R}^n and let K be its Gaussian curvature. Osserman [6] for $n = 3$ and Chern–Osserman [2] for $n \geq 3$ proved that $\int_M |K| dV < \infty$ if and only if M is conformally equivalent to a compact Riemann surface \overline{M} punctured at a finite number of points $\{p_1, \dots, p_r\}$ and the Gauss map $\Phi : M \rightarrow \mathbb{G}_{2,n}$ extends to a holomorphic map $\overline{\Phi} : \overline{M} \rightarrow \mathbb{G}_{2,n}$, (see [4] for a clear exposition). Anderson [1] proved a higher-dimension version of Chern–Osserman finite total curvature theorem, i.e., a complete m -dimensional minimally immersed submanifold M of \mathbb{R}^n has finite total scalar curvature $\int_M |\alpha|^m dV < \infty$ if and only if M is C^∞ -diffeomorphic to a compact smooth Riemannian manifold \overline{M} punctured at a finite number of points $\{p_1, \dots, p_r\}$ and the Gauss map Φ on M extends to a C^∞ -map $\overline{\Phi}$ on \overline{M} , where $|\alpha|$ is the norm of the second fundamental form of M .

These results above have appropriate versions in the non-minimal setting. White [7], proved that a complete 2-dimensional surface M immersed in \mathbb{R}^n with $\int_M |\alpha|^2 dV < \infty$ and non-positive curvature with respect to every normal direction¹ is homeomorphic to a compact Riemann surface \overline{M} punctured at finite number of points $\{p_1, \dots, p_r\}$, its Gauss map Φ extends continuously

¹A submanifold $M \subset \mathbb{R}^n$ is non-positively curved with respect to each normal direction at x if $\det(\eta \cdot \alpha(\cdot, \cdot)) \leq 0$ for all normals η to M at x ; see [7].

to all of \overline{M} and M is properly immersed. It should be observed that the properness of M in White's theorem is a consequence of the first two statements about the immersion, i.e., Jorge and Meeks [3], proved that a complete m -dimensional immersed submanifold M of \mathbb{R}^n , homeomorphic to a compact Riemann manifold \overline{M} punctured at finite number of points $\{p_1, \dots, p_r\}$ and such that the Gauss map Φ extends continuously to all of \overline{M} is properly immersed.

Muller and Sverak [5], answering a question of White, proved that a complete 2-dimensional surface M immersed in \mathbb{R}^n with $\int_M |\alpha|^2 dV < \infty$ is properly immersed.

The purpose of this paper is to put another piece on this puzzle showing that a complete m -dimensional submanifold of \mathbb{R}^n with the norm of the second fundamental form uniformly decaying to zero $|\alpha(x)| \rightarrow 0$ as $x \rightarrow \infty$ in a certain rate is proper and has finite topological type. The decaying rate of $|\alpha(x)| \rightarrow 0$ we considered is not fast enough to make $\int_M |\alpha(x)|^m dV < \infty$.

To be more precise, let M be a complete m -dimensional submanifold of \mathbb{R}^n and let $K_1 \subset K_2 \subset \dots$ be an exhaustion sequence of M by compact sets. Fix a point $p \in K_1$ and set $a_i = \sup\{\rho(x) \cdot |\alpha(x)|, x \in M \setminus K_i\}$, where $\rho(x) = \text{dist}_M(p, x)$ and $|\alpha(x)|$ is the norm of the second fundamental form of M at x . The a_i s form a non-increasing sequence $\infty \geq a_1 \geq a_2 \geq \dots \geq 0$ with $a_1 = \infty$ if and only if $a_l = \infty$ for all $l \geq 1$. Define the (possibly extended) scaling invariant number $a(M) = \lim_{i \rightarrow \infty} a_i \in [0, \infty]$. It can be shown that $a(M)$ does not depend on the exhaustion sequence nor on the point p . It follows from the work of Jorge–Meeks [3] that complete m -dimensional submanifolds M of \mathbb{R}^n homeomorphic to a compact Riemannian manifold \overline{M} punctured at finite number of points $\{p_1, \dots, p_r\}$ and having a well-defined normal vector at infinity have $a(M) = 0$. In particular, complete minimal surfaces in \mathbb{R}^n with finite total curvature, complete 2-dimensional complete surfaces with $\int_M |\alpha|^2 dV < \infty$ and non-positive curvature with respect to every normal direction considered by White or the m -dimensional minimal submanifolds M of \mathbb{R}^n with finite total scalar curvature considered by Anderson have $a(M) = 0$. In our main result, we prove that the larger class of complete m -dimensional immersed submanifolds of \mathbb{R}^n with $a(M) < 1$ share some properties with these submanifolds with $a(M) = 0$. We prove the following theorem.

Theorem 1.1. *Let M be a complete m -dimensional submanifold of \mathbb{R}^n with $a(M) < 1$. Then M is properly immersed and it is C^∞ -diffeomorphic to a compact smooth manifold \overline{M} with boundary.*

Observe that $\int_M |\alpha|^m dV < \infty$ is not equivalent to $a(M) < 1$. However, one might ask if Theorem 1.1 holds under finite total scalar curvature $\int_M |\alpha|^m dV < \infty$.

For complete m -dimensional minimal submanifolds M of \mathbb{R}^n we define the increasing sequence $b_i = \inf\{\rho^2(x) \cdot \text{Ric}(x)(\nu, \nu), |\nu| = 1, x \in M \setminus K_i\}$ with $b_1 = -\infty$ if and only if $b_l = -\infty$ for all $l \geq 1$. Define the scaling invariant number $b(M) = \lim_{i \rightarrow \infty} b_i \in [-\infty, 0]$. Again, it can be shown that $b(M)$ does not depend on the exhaustion sequence nor on the point p . The proof of Theorem 1.1 can be slightly modified to prove the following version for minimal submanifolds.

Theorem 1.2. *Let M be a complete m -dimensional minimal submanifold of \mathbb{R}^n with $b(M) > -1$. Then M is properly immersed and it is C^∞ -diffeomorphic to a compact smooth manifold \overline{M} with boundary.*

2. Proof of Theorem 1.1

2.1. M is properly immersed

Let $\varphi : M^m \hookrightarrow \mathbb{R}^n$ be a complete submanifold with $a(M) < 1$ and let $p \in M$ be a fixed point such that $\varphi(p) = 0 \in \mathbb{R}^n$. There exists a geodesic ball $B_M(p, R_0)$ centered at p with radius R_0 such that for all $x \in M \setminus B_M(p, R_0)$ we have that $\rho(x)|\alpha(x)| \leq c < 1$. Let $f : M^m \rightarrow \mathbb{R}$ given by $f(x) = |\varphi(x)|^2$. Fix a point $x \in M \setminus B_M(p, R_0)$ then for $\nu \in T_x M, |\nu| = 1$ we have that

$$\begin{aligned}
 \frac{1}{2} \text{Hess } f(x)(\nu, \nu) &= 1 + \langle \varphi(x), \alpha(x)(\nu, \nu) \rangle \\
 &\geq 1 - |\varphi(x)| \cdot |\alpha(x)| \\
 &\geq 1 - \rho(x)|\alpha(x)| \\
 &\geq 1 - c.
 \end{aligned}
 \tag{2.1}$$

Let $\sigma : [0, \rho(x)] \rightarrow M^m$ be a minimal geodesic from p to x . From (2.1) we have for all $t \geq R_0$ that $(f \circ \sigma)''(t) = \text{Hess } f(\sigma(t))(\sigma', \sigma') \geq 2(1 - c)$ and for $t < R_0$ that $(f \circ \sigma)''(t) \geq b, b = \inf_{x \in B_M(p, R_0)} \{\text{Hess } f(x)(\nu, \nu), |\nu| = 1\}$. Thus

$$\begin{aligned}
 (f \circ \sigma)'(s) &= \int_0^s (f \circ \sigma)''(\tau) d\tau \\
 &\geq \int_0^{R_0} b d\tau + \int_{R_0}^s (1 - c) d\tau \\
 &\geq b R_0 + (1 - c)(s - R_0)
 \end{aligned}
 \tag{2.2}$$

$$\begin{aligned}
 f(x) &= \int_0^{\rho(x)} (f \circ \sigma)'(s) ds \\
 (2.3) \quad &\geq \int_0^{\rho(x)} b R_0 + (1 - c)(s - R_0) ds \\
 &= b R_0 \rho(x) + (1 - c) \left(\frac{\rho(x)^2}{2} - R_0 \rho(x) \right).
 \end{aligned}$$

Thus $|\varphi(x)|^2 \geq (b - 1 + c)R_0\rho(x) + (1 - c)\rho(x)^2/2$ for all $x \in M \setminus B_M(p, R)$. In fact, this proves that following proposition.

Proposition 2.1. *Let $f : M \rightarrow \mathbb{R}$ be a C^2 -function defined on a complete Riemannian manifold such that $\text{Hess } f(x) \geq g(\rho(x))$, where ρ is the distance function to x_0 and $g : [0, \infty) \rightarrow \mathbb{R}$ is a piecewise continuous function. Setting $G(t) = f(x_0) - |\text{grad } f(x_0)|t + \int_0^t \int_0^s g(u) du ds$, $t \in [0, \infty)$ we have that if G is proper and bounded from below then f is proper.*

2.2. M has finite topology

Let $\varphi : M^m \hookrightarrow \mathbb{R}^n$ be a complete immersed submanifold with $a(M) < 1$. To show that M is diffeomorphic to a compact manifold \overline{M} with boundary it suffices to show that R has finitely many critical points. Let $p \in M$ be such that $\varphi(p) = 0 \in \mathbb{R}^n$. We may suppose that $R(x) = |\varphi(x)|$, $x \in M$ is a Morse function. Let $r_0 > 0$ be such that $\Gamma_{r_0} = \varphi(M) \cap \mathbb{S}^{n-1}(r_0)$ is a compact submanifold of $\mathbb{S}^{n-1}(r_0)$ and $\rho(x) \cdot |\alpha(x)| \leq c < 1$ for all $x \in M \setminus \varphi^{-1}(B_{\mathbb{R}^n}(r_0))$. Set $\Lambda_{r_0} = \varphi^{-1}(\Gamma_{r_0})$. For each $x \in \Lambda_{r_0}$ there is an open set $x \in U_x \subset M$ such that $\varphi|_{U_x}$ is an embedding and $\varphi(U_x) \pitchfork \mathbb{S}^{n-1}(r)$, $r \in (r_0 - \delta, r_0 + \delta)$, $\delta > 0$ small. For each $y \in \Gamma_r \cap \varphi(U_x)$, there is only one unit vector $\nu(y) \in T_{\varphi^{-1}(y)}U_x$ such that $T_y\varphi(U_x) = T_y(\varphi(U_x) \cap \Gamma_r) \oplus [[\varphi_*\nu(y)]]$ and $\langle \varphi_*\nu(y), \eta(y) \rangle > 0$, where $\eta(y) = y/r$ is the unit vector perpendicular to $T_y\mathbb{S}^{n-1}(r)$. Since Λ_{r_0} is compact we find a finite sequence $\{x_1, \dots, x_k\} \subset \Lambda_{r_0}$ and $\delta = \min\{\delta_1, \dots, \delta_k\}$ such that using partition of unit we construct by this procedure a smooth vector field ν in $V = \varphi^{-1}(B_{\mathbb{R}^n}(r_0 + \delta) \setminus B_{\mathbb{R}^n}(r_0 - \delta))$. Identify $\nu(x)$ with $\varphi_*\nu(y)$, $y = \varphi(x)$. Consider the function ψ defined in V given by

$$\psi(x) = \langle \nu(y), \eta(y) \rangle = \cos \theta(y).$$

For each $x \in \Lambda_{r_0}$, let $\xi(t, x)$ be the solution of the following problem on M

$$(2.4) \quad \begin{aligned} \xi_t &= \frac{1}{\psi} \nu(\xi(t, x)), \\ \xi(0, x) &= x. \end{aligned}$$

Recall that $R(x) = |\varphi(x)|$. For $X \in TM$ we have that $X(R) = \langle X, \eta \rangle$ and writing $\eta(y) = \sin \theta(y) \nu^*(y) + \cos \theta(y) \nu(y)$, $\nu^*(y) \perp \nu(y)$, we have that $\text{grad } R = \psi \nu$. Set the notation $R(t, x) = |\varphi \circ \xi(t, x)|$. We have that

$$R_t = \left\langle \text{grad } R, \frac{1}{\psi} \nu \right\rangle = \left\langle \psi \nu, \frac{1}{\psi} \nu \right\rangle = 1 \iff R = R(t, y) = t + r.$$

We will derive a differential equation that the function $\psi \circ \xi(t, y)$ satisfies.

$$\begin{aligned} \psi_t &= \xi_t \langle \nu, \eta \rangle = \langle D_{(1/\psi)\nu} \nu, \eta \rangle + \langle \nu, D_{\xi_t} \eta \rangle \\ &= \langle \nabla_\nu \nu + \alpha(\nu, \nu), \eta \rangle + \left\langle \nu, D_{\xi_t} \left(\frac{\xi}{R} \right) \right\rangle \end{aligned}$$

But $\langle \nu, \nu \rangle = 1 \Rightarrow \langle \nu, \nabla_\nu \nu \rangle = 0$ and $\nabla_\nu \nu \in T_x M \Rightarrow \nabla_\nu \nu \in (T_x M \cap T_x S_R^n) \Rightarrow \langle \nabla_\nu \nu, \eta \rangle = 0$. On the other hand

$$D_{\xi_t} \left(\frac{\xi}{R} \right) = \frac{(1/\psi)\nu}{R} - \frac{R_t}{R^2} \varphi = \frac{1}{R\psi} \nu - \frac{1}{R} \eta$$

then

$$(2.5) \quad \psi_t = \frac{1}{\psi} \langle \alpha(\nu, \nu), \eta \rangle + \frac{1}{\psi R} - \frac{\psi}{R} = \frac{\sqrt{1-\psi^2}}{\psi} \langle \alpha(\nu, \nu), \nu^* \rangle + \frac{1-\psi^2}{\psi R}$$

To determine a differential equation satisfied by $\sin \theta(t, x) = \sqrt{1-\psi^2}$, we proceed as follows. By (2.5) we have

$$(2.6) \quad \frac{\psi \psi_t}{\sqrt{1-\psi^2}} = \langle \alpha(\nu, \nu), \nu^* \rangle + \frac{\sqrt{1-\psi^2}}{R}$$

Observing that $R(t, x) = t + r$, Equation (2.6) can be written as

$$(2.7) \quad -(t+r)(\sqrt{1-\psi^2})_t = (t+r) \langle \alpha(\nu, \nu), \nu^* \rangle + \sqrt{1-\psi^2}$$

and rewritten as

$$(2.8) \quad \left[(t+r)\sqrt{1-\psi^2} \right]_t + (t+r) \langle \alpha(\nu, \nu), \nu^* \rangle = 0.$$

Integrating Equation (2.8), we have the following equation

$$(2.9) \quad \sqrt{1 - \psi^2} = \frac{r}{t+r} \sqrt{1 - \psi_0^2} - \frac{1}{t+r} \int_0^t (s+r) \langle \alpha(\nu, \nu), \nu^* \rangle ds,$$

where $\psi_0 = \psi(\xi(0, x))$. Since $\sin \theta(\xi(t, x)) = \sqrt{1 - \psi^2}$ we rewrite (2.9) in the following form

$$(2.10) \quad \sin \theta(\xi(t, x)) = \frac{r}{t+r} \sin \theta(\xi(0, x)) - \frac{1}{t+r} \int_0^t (s+r) \langle \alpha(\nu, \nu), \nu^* \rangle ds$$

Now,

$$-\langle \alpha(\nu, \nu), \nu^* \rangle(\xi(s, x)) \leq |\alpha|(\xi(s, x)) \leq c/\rho(\xi(s, x)) \leq c/R(s, x).$$

Substituting in (2.10) and recalling that $R(s, x) = s + r$ we have that

$$(2.11) \quad \begin{aligned} \sin \theta(\xi(t, x)) &\leq \frac{r}{t+r} \sin \theta(\xi(0, y)) + \frac{1}{t+r} \int_0^t (s+r) \frac{c}{s+r} ds \\ &= \frac{ct + r \sin \theta(\xi(0, x))}{t+r} < 1, \quad \forall t \geq 0. \end{aligned}$$

The critical points of R are those x such that $\psi(x) = 0$, or those points where $\sin \theta(x) = 1$. Thus, along the integral curves $\xi(t, y)$, $y \in \Gamma_r$, there is no critical point for the function $R(x) = |\varphi(x)|$. This shows that outside the compact set $M \setminus B_M(p, r_0)$ there are no critical points for R . Since R is a Morse function, its critical points are isolated thus there are finitely many of them. Therefore M has finite topology.

3. Sketch of proof for Theorem 1.2

Let $\varphi : M^m \hookrightarrow \mathbb{R}^n$ be a complete minimal submanifold and let $x \in M$, $\nu \in T_x M$ and $\{e_1, \dots, e_m = \nu\}$ an orthonormal basis for $T_x M$. Using the Gauss equation we can compute the Ricci curvature in the direction ν by

$$(3.1) \quad \begin{aligned} Ric(x)(\nu) &= \left\langle \sum_{i=1}^m \alpha_{ii}, \alpha_{mm} \right\rangle - \sum_{i=1}^{m-1} |\alpha_{im}|^2 \\ &= \langle mH - \alpha_{mm}, \alpha_{mm} \rangle - \sum_{i=1}^{m-1} |\alpha_{im}|^2 \\ &= - \sum_{i=1}^m |\alpha_{im}|^2, \end{aligned}$$

where $\alpha_{ij} = \alpha(e_i, e_j)$. Let $f : M^m \rightarrow \mathbb{R}$ given by $f(x) = |\varphi(x)|^2$. The Hessian of f at $x \in M$ and $\nu \in T_x M$, $|\nu| = 1$ satisfies

$$\begin{aligned}
 (3.2) \quad \frac{1}{2} \text{Hess } f(x)(\nu, \nu) &= +\langle \varphi(x), \alpha(\nu, \nu) \rangle \\
 &\geq [1 - |\varphi(x)| \cdot |\alpha_{mm}|] \\
 &\geq \left[1 - |\varphi(x)| \sqrt{-\text{Ric}(x)(\nu)} \right] \\
 &\geq \left[1 - \rho(x) \sqrt{-\text{Ric}(x)(\nu)} \right] \\
 &\geq 1 - c.
 \end{aligned}$$

The proof of Theorem 1.1 from Equation (2.1) shows that M is properly immersed in Theorem 1.2. To show that M has finite topological type, observe that

$$|\alpha|(\xi(s, x)) \leq \sqrt{-\text{Ric}(\xi(s, x))(\nu, \nu)} \leq c/\rho(\xi(s, x)) \leq c/R(s, x),$$

and follow the proof of Theorem 1.1 after (2.10) and we still have (2.11).

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