

Symplectic Topology as the Geometry of Action Functional, II – pants product and cohomological invariants

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1. Introduction and the main results.

This is a sequel to our paper [O4] in which we defined the Floer homology of submanifolds $HF_*(H, S, J : M) = HF_*^\sigma(H, S, J : M)$ for given compact submanifold $S \subset M$ and for each given coherent orientation $\sigma \in \text{Or}([S] : M)$, and applied them to the geometry of Lagrangian submanifolds by constructing some homotopy theoretic invariants. Obviously, one can also define the Floer cohomology $HF_\sigma^*(H, S, J : M)$ by the functorial construction. We will mostly follow the notations we used in [O4]. In this paper we further analyze the case in which $S = M$ and σ is the *canonical* coherent orientation in the sense of Theorem 5.5 [O4] and Theorem 12 [FH1]. Using the Floer theory for this case, we construct some cohomological invariants and study their basic properties in terms of the product structure of Floer cohomology. We refer readers to [O4] for the details of the construction of orientation, grading, and filtration for the Floer (co)homology we use in this paper.

One important new ingredient of our Floer theory in [O4] is the incorporation of some geometric calculations involving the geometry of Lagrangian submanifolds and Hamiltonian systems. Hence our Floer theory can be considered as “geometry of action functional” while Floer’s original (global) theory in the literature as “topology of action functional”. This optimal calculation has been crucial for applications to problems in symplectic topology, and indeed provides a systematic way of studying symplectic rigidity (See [O6] for a simple proof of non-degeneracy of Hofer’s norm in this spirit).

The heart of the present paper is in Section 6 and 7 where we further develop this calculation in a more elaborate way, this time involving pants product and filtrations in Floer cohomology. Our presentation of pants product is given in a way so that an optimal form of this calculation can be carried out, which is crucial for the applications in these sections. In this

sense, our presentation of the pants product contains new features that have not been addressed in the literature.

In the case $S = M$ from [O4], we have $N^*S = o_M$. Therefore as far as the *global* Floer theory is concerned, this case reduces to the standard Floer theory in the *dynamical version*. Using the symmetry present in this special case,

$$\begin{aligned} \gamma &\mapsto \tilde{\gamma} = \gamma(1-t), & u &\mapsto \tilde{u} = u(-\tau, 1-t), & \sigma &\mapsto \tilde{\sigma}, \\ H &\mapsto \tilde{H} = -H(x, 1-t), & J &\mapsto \tilde{J}_t = J_{1-t} \end{aligned}$$

one can define a natural homomorphism between $HF_{n-*}^{\tilde{\sigma}}(\tilde{H}, \tilde{J} : M)$ and $HF_{\sigma}^*(H, J : M) := HF_{\sigma}^*(H, M, J : M)$ which becomes an isomorphism with respect to arbitrary coefficients. This isomorphism enables us to define the semi-infinite version of the cup-product, the so called *pants product*, on $HF^*(H, J : M)$. In general, however, the two Floer homologies $HF_{*}^{\tilde{\sigma}}(\tilde{H}, \tilde{J} : M)$ and $HF_{*}^{\sigma}(\tilde{H}, \tilde{J} : M)$ are not isomorphic for general coefficients (see Section 2.2 below). We prove in Theorem 2.3 that if we use the canonical coherent orientation defined in Theorem 5.5 [O4], the two become isomorphic with arbitrary coefficients (resp. \mathbb{Z}_2 -coefficients) when M is orientable (resp. non-orientable). With respect to this canonical coherent orientation, combining the above two isomorphisms and the isomorphism

$$HF_{n-k}^{\sigma}(H, J : M) \rightarrow HF_{n-k}^{\sigma}(\tilde{H}, \tilde{J} : M),$$

we obtain the *Poincaré duality* isomorphism

$$PD_{(H,J)} : HF_{n-k}^{\sigma}(H, J : M) \rightarrow HF_{\sigma}^k(H, J : M).$$

From now on, we will fix the canonical coherent orientation and suppress the σ from the notations below in this introduction.

We first recall the group operation on the space of Hamiltonians $H : P \times [0, 1] \rightarrow \mathbb{R}$,

$$(1.1) \quad H \# K(x, t) = H(x, t) + K((\phi_H^t)^{-1}(x), t).$$

We also denote by \overline{H} the *inverse* of H that is given by the formula

$$\overline{H}(x, t) := -H((\phi_H^t)(x), t).$$

Our pants product is closely related to this group operation.

Theorem I. *Let $H^{\alpha}, H^{\beta}, K^{\alpha}, K^{\beta}$ and $H^{\alpha} \# K^{\alpha}, H^{\beta} \# K^{\beta}$ be generic and J^{α}, J^{β} are regular for all three Hamiltonians respectively.*

- (1) *There exists a natural bi-linear map, denoted by \cup_F which is called the pants product*

$$(1.2) \quad HF^*(H, J : M) \otimes HF^*(K, J : M) \xrightarrow{\cup_F} HF^*(H\#K, J : M)$$

that respects the filtration induced by values of the corresponding action functional (see [O4]) in the sense that \cup_F restricts to

$$(1.3) \quad HF_{(\lambda_1, \infty)}^*(H, J : M) \otimes HF_{(\lambda_2, \infty)}^*(K, J : M) \xrightarrow{\cup_F} HF_{(\lambda_1 + \lambda_2 + \epsilon(K), \infty)}^*(H\#K, J : M)$$

where $\epsilon(K)$ is a constant, which vanishes for autonomous Hamiltonians K , and it satisfies the inequality

$$|\epsilon(K)| \leq \|K\|$$

in general.

- (2) *The above pants product commutes with the natural isomorphism*

$$h^{\alpha\beta} : HF^*(H^\beta, J^\beta : M) \rightarrow HF^*(H^\alpha, J^\alpha : M)$$

in that the following diagram commutes

$$HF^*(H^\alpha, J^\alpha : M) \otimes HF^*(K^\alpha, J^\alpha : M) \xrightarrow{\cup_F} HF^*(H^\alpha\#K^\alpha, J^\alpha : M)$$

$$\begin{array}{ccc} \uparrow h_H^{\alpha\beta} \otimes h_K^{\alpha\beta} & & \uparrow h_{H\#K}^{\alpha\beta} \end{array}$$

$$HF^*(H^\beta, J^\beta : M) \otimes HF^*(K^\beta, J^\beta : M) \xrightarrow{\cup_F} HF^*(H^\beta\#K^\beta, J^\beta : M).$$

- (3) *There exists a natural isomorphism, which we call the (semi-infinite version) of the Thom isomorphism*

$$F_H = F_{(H, J)} : H^*(M, \mathbb{Z}) \rightarrow HF^*(H, J : M)$$

that commutes with \cup_F : the diagram

$$HF^*(H, J : M) \otimes HF^*(K, J : M) \xrightarrow{\cup_F} HF^*(H\#K, J : M)$$

$$\begin{array}{ccc} \uparrow F_H \otimes F_K & & \uparrow F_{H\#K} \end{array}$$

$$H^*(M, \mathbb{Z}) \otimes H^*(M, \mathbb{Z}) \xrightarrow{\cup} H^*(M, \mathbb{Z})$$

commutes.

- (4) *There exists an action (which we call the cup action by $u \in H^*(M, \mathbb{Z})$) on $HF^*(H, J : M)$ $u \mapsto (\cdot) \cup_F u$ which satisfies*

$$(1.4) \quad F_H(v) \cup_F u = F_H(v \cup u)$$

and which restricts to an action on $HF_{(\lambda, \infty)}^(H, J : M)$ for all $\lambda \in \mathbb{R}$.*

There have been several articles (see [BzR], [Sc2] and [PSS]) which describe the pants product as we do in this paper. In fact, they describe more general results in the point of view of the symplectic version of relative Donaldson invariants in the context of Hamiltonian diffeomorphisms. Fukaya [Fu1] also dealt with the Lagrangian intersections in a rather brief way. Floer [F3] first studied a product of the type (1.4) in the cup-length estimate of Lagrangian intersections.

However, *for the first time, in this paper the filtration is taken into account as in Theorem I (1) and (4) in the study of pants product. For this purpose, it is crucial to put $H \# K$ on the right hand side of the above diagrams for the pants product \cup_F when we restrict to the relative cohomology as in (1.3), although the global version (1.2) will still hold for arbitrary Hamiltonian L not just for $H \# K$. Furthermore, we would like to emphasize that in the proof of the statement (3) (see [FO] for the relevant result), it is again crucial to have $H \# K$ on the right hand side. We call this phenomenon the conservation law for the pants product. This important feature has not appeared so far in the literature partly because almost all of the literatures on the Floer homology deal with Hamiltonian diffeomorphisms not Lagrangian submanifolds. For the Hamiltonian diffeomorphism, there are very few cases for the above filtration to occur or to be useful. These are the cases where the closed symplectic manifold (P, ω) satisfies $\omega|_{\pi_2(P)} \equiv 0$. One could also study the exact symplectic manifold with contact type boundary in the spirit of the present paper, which will be a subject of future study.*

Unlike Floer's definition [F3] of the action (1.4) which uses a complicated intersection theoretic method, we will define this action using *degenerate pants* which enables us to prove the commutativity (4) and the statement on the filtration easily from an obvious modification of the analysis in [FO]. This simple definition of the cup action \cup_F *satisfying (1.4)* has been possible due to our previous analytical work done with Fukaya in [FO], where we carefully studied degeneration of the moduli space of marked J_g -holomorphic discs with Lagrangian boundary conditions of the graphs of df_j 's and proved that this moduli space is diffeomorphic to that of graph flow moduli space of f_j 's defined in [BC] and [Fu1]. One important point we would like to address is that *because we use the functorial definition of the Floer cohomology, we*

never consider taking the Poincaré dual to the cohomology class u in the definition of this action which most literature do and which forces them to mod out the torsion classes in the definition.

Using the Floer's isomorphism, which we call the *semi-infinite version of the Thom isomorphism for the fibration* $p : \Omega \rightarrow M$, and imitating Viterbo's construction in [V],

$$F_{(H,J)} : H^*(M, \mathbb{Z}) \rightarrow HF^*(H, J : M)$$

we define the real number

$$\rho(H, u) = \inf_{\lambda} \{ \lambda \mid j_{\lambda}^* F_{(H,J)}(u) \neq 0 \}$$

for each $u \in H^*(M, \mathbb{Z})$, and prove that it does not depend on J , where $j_{\lambda}^* : HF^* \rightarrow HF^*_{(-\infty, \lambda]}$ is the natural homomorphism. We summarize basic properties of $\rho(H, u)$ in the following

Theorem II (Compare with Theorem II [O4]). *Let $u \in H^*(M, \mathbb{Z})$ and $\rho(H, u)$ as above. Then*

- (1) *All of $\rho(H, u)$ are critical values of \mathcal{A}_H on Ω and satisfies that for two H^{α}, H^{β} with $\phi_{H^{\alpha}}^1(o_M) = \phi_{H^{\beta}}^1(o_M)$, we have*

$$\rho(H^{\beta}, u) - \rho(H^{\alpha}, u) = c(H^{\alpha}, H^{\beta})$$

where $c(H^{\alpha}, H^{\beta})$ does not depend on $u \in H^(M, \mathbb{Z})$.*

- (2) *When $H \equiv 0$, $\rho(H, u) = 0$ for all $u \in H^*(M, \mathbb{Z})$.*

- (3) *For any $u \in H^*(M, \mathbb{Z})$,*

$$\int_0^1 -\max(H^{\beta} - H^{\alpha}) dt \leq \rho(H^{\beta}, u) - \rho(H^{\alpha}, u) \leq \int_0^1 -\min(H^{\beta} - H^{\alpha}) dt.$$

In particular, combined with (2), we have

$$\int_0^1 -\max H dt \leq \rho(H, u) \leq \int_0^1 -\min H dt.$$

- (4) *$|\rho(H^{\beta}, u) - \rho(H^{\alpha}, u)| \leq \|H^{\beta} - H^{\alpha}\|_{C^0}$ and so $H \mapsto \rho(H, u)$ can be extended to a continuous function of H with respect to the C^0 -norm of H .*

(5) For any $u, v \in H^*(M, \mathbb{Z})$, we have

$$\rho(H \# K, u \cup v) \geq \rho(H, u) + \rho(K, v) + \epsilon(K)$$

where $\epsilon(K)$ is the same constant as in (1.3). In particular, one has

$$\rho(H, u \cup v) \geq \rho(H, u).$$

We would like to compare Theorem II with similar results on the Viterbo's invariants $c(L, u)$ defined in [V]: Our invariant has a *direct* relation to Hofer's geometry while $c(L, u)$ has only *indirect* one. However, we prove with D. Milinković (see [MO], [Mk] for details) that up to suitable normalizations, our invariants $\rho(L, u)$ coincide with Viterbo's $c(L, u)$. As in [V], one can define a capacity of L as follows

$$\gamma(L) := \rho(H, \mu_M) - \rho(H, 1) \geq 0$$

which will not depend on H generating L i.e., such that $L = \phi_H^1(o_M)$. Now we relate $\gamma(L)$ with Hofer's distance. Define Hofer's distance between Lagrangian submanifolds (Hamiltonian isotopic to each other) by

$$d(L_1, L_2) = \inf_{H: \phi_H(L_1) = L_2} \|H\|.$$

The following theorem is the analogue of Corollary 2.3 [V] but with the estimate in relation to Hofer's distance.

Theorem III. (1) $\gamma(L) = 0$ if and only if $L = o_M$.

(2) $\gamma(L) \leq d(L, o_M)$ and in particular combined with (1), Hofer's distance is nondegenerate.

In Theorem III and [O4], we have introduced two natural *capacities* (or sizes) of L , $\text{osc}(f_L)$ and $\gamma(L)$ respectively. Here f_L is the *basic phase function* of L defined in [O4]. We have shown by some example in [O4] that

$$\text{osc}(f_L) \neq \gamma(L)$$

in general. It seems plausible to us that the inequality

$$(1.5) \quad \text{osc}(f_L) \leq \gamma(L)$$

holds in general. In fact when L is the graph of an exact one-form, we can prove

$$(1.6) \quad \text{osc}(f_L) = \gamma(L) = d(o_M, L)$$

(see [MO] for its proof). This immediately implies

Corollary. *For any smooth function f on M , the path*

$$t \mapsto \text{graph}(t df)$$

is a (globally) distance minimizing path with respect to Hofer's distance d .

Once we have Theorem II and III, we can apply the above to the compactification of the graphs of Hamiltonian diffeomorphisms ϕ_H on \mathbb{R}^{2n} . As we mentioned above, another way of studying diffeomorphisms on \mathbb{R}^{2n} or more generally on any (P, ω) with $\omega|_{\pi_2(P)} \equiv 0$ is directly constructing analogues of our invariants for Hamiltonian diffeomorphisms considering their Floer homology, which we will pursue in the future. In a recent preprint "On the action spectrum for closed symplectically aspherical manifolds", M. Schwartz carried out this construction for Hamiltonian diffeomorphisms. Combining the construction in the present paper with P. Seidel's result, he, among other things, proved a triangle inequality for the diffeomorphisms which sharpens Theorem II (5) by eliminating the error term $E(K)$ in Theorem II (5) for the case of diffeomorphisms. We will also postpone more elaborate applications of the theory developed in this paper and [O4] to the future works so that this paper does not become too long and its appearance is not delayed by much. We advise that readers who feel uncomfortable about the coherent orientation question safely take \mathbb{Z}_2 -coefficients to follow the main stream of the ideas developed in this paper and refer them to our future work on the orientation problem in the more general context.

The organization of the paper is in order: Section 2 explains Poincaré duality and Floer's isomorphism with orientation in a precise manner. Section 3 provides a functorial construction of pants product which carefully exploits the symmetry mentioned in the beginning. As a result, we prove Theorem I (1) and (2) except the statement on the filtration. Section 4 contains the proof of Theorem I (3). Section 5 provides a new construction, using degenerate pants, of the cup action defined by Floer [F2] and prove Theorem I (4). Section 6 studies interaction of pants product with filtration and Hofer's geometry, and proves Theorem II and all the statements involving filtrations in Theorem I. Section 7 proves Theorem III. In the appendix, we provide a proof of an index formula on a semi-infinite strip which will be needed in the construction of pants product.

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Notations.

- (1) $H \# K(x, t) = H(x, t) + K((\phi_H^t)^{-1}(x), t)$
- (2) $\bar{H}(x, t) = -H(\phi_H^t(x), t)$
- (3) $\tilde{H}(x, t) = -H(x, 1 - t)$
- (4) $\mathcal{H} = \mathcal{H}^{ac}(P) =$ the set of asymptotically constant Hamiltonians on P
- (5) $\mathcal{H}_0 = \{H \in \mathcal{H} \mid \phi_H(o_M) \pitchfork o_M\}$
- (6) $\mathcal{D}_\omega^{ac}(P) =$ the set of Hamiltonian diffeomorphisms generated by \mathcal{H}^{ac}
- (7) $\phi_H =$ the time-one map of the equation $\dot{z} = X_H(z)$
- (8) $H \mapsto \phi$ if and only if $\phi = \phi_H$
- (9) $o_M =$ the zero section of T^*M
- (10) $H \mapsto L$ if and only if $L = \phi_H(o_M)$
- (11) $z_H^p : [0, 1] \rightarrow T^*M; \quad z_H^p(t) = \phi_H^t((\phi_H^1)^{-1}(p))$
- (12) $\Omega = \{z : [0, 1] \rightarrow T^*M \mid z(0) \in o_M\}$
- (13) $\Omega(M) = \{z : [0, 1] \rightarrow T^*M \mid z(0), z(1) \in o_M\}$

Conventions.

- (1) The Hamiltonian vector field X_H is defined by $X_H \lrcorner \omega = dH$.
- (2) An almost complex structure J is said to be compatible to ω , if the bilinear form $\langle \cdot, \cdot \rangle_J = \omega(\cdot, J\cdot)$ defines a Riemannian metric.

2. Floer cohomology.

Let $CF(H, M)$ be the set of solutions

$$\begin{cases} \dot{z} = X_H(z) \\ z(0), z(1) \in o_M \subset T^*M. \end{cases}$$

which is the set of critical points of \mathcal{A}_H on $\Omega(M)$ (see $CF(H, M : M)$ in [O4]). This convention will apply to various other objects we have defined in [O4]. Using the grading and the coherent orientation we provided in [O4], we define a \mathbb{Z} -module $CF_k(H, M)$, for each $k \in \mathbb{Z}$, by the free \mathbb{Z} -module over the set of $z \in CF(H, M)$ with

$$(2.1) \quad \mu_M(z) + \frac{1}{2} \dim M = k.$$

We will omit the subscript M from μ_M and just denote $\mu = \mu_M$.

Let σ be the canonical coherent orientation given in Theorem 5.5 [O4]. We form

$$(2.2) \quad \begin{aligned} CF^k(H, M) &:= \text{Hom}(CF_k(H, M), \mathbb{Z}) \\ \delta_{(H, J)}^\sigma &:= \text{Hom}(\partial_{(H, J)}^\sigma) : CF^k(H, M) \rightarrow CF^{k+1}(H, M). \end{aligned}$$

Then we define for each $k \in \mathbb{Z}$, the k -th Floer cohomology group of $(H, J : M)$ by

$$HF_\sigma^k(H, J : M) = \text{Ker } \delta_{(H, J)}^\sigma / \text{Im } \delta_{(H, J)}^\sigma.$$

It also follows from the naturality of construction of the cohomology that we have the isomorphism

$$h^{\alpha\beta} : HF_\sigma^*(H^\beta, J^\beta : M) \rightarrow HF_\sigma^*(H^\alpha, J^\alpha : M)$$

for two generic (H^α, J^α) and (H^β, J^β) . This map is induced from the cochain map $h_\sigma^{\alpha\beta} : CF^*(H^\beta, J^\beta : M) \rightarrow CF^*(H^\alpha, J^\alpha : M)$ which is dual to the chain map $h_{\sigma}^{\alpha\beta} : CF_*(H^\alpha, J^\alpha : M) \rightarrow CF_*(H^\beta, J^\beta : M)$ (see [O4] for more explanation on this map).

2.1. Thom isomorphism.

Theorem 5.5 in [O4], applied to the cohomological version of the case $S = M$ immediately gives rise to the natural isomorphism

$$(2.3) \quad F_{(H, J)} : H^*(M, \mathbb{Z}) \rightarrow HF_\sigma^*(H, J : M)$$

that preserves the grading. This isomorphism is natural in the sense that

$$F_{(H^\alpha, J^\alpha)} = h_\sigma^{\alpha\beta} \circ F_{(H^\beta, J^\beta)}$$

defined in (2.2). We regard (2.3) as *the semi-infinite version of the Thom isomorphism* for the fibration $p : \Omega(M) \rightarrow M$. We would like to emphasize that this isomorphism holds *with arbitrary coefficients* whether or not the manifold M is orientable. Recall that the classical Thom isomorphism requires only that the vector bundle has an orientation, not the base manifold itself. The coherent orientation provided by Theorem 5.2 [O4] can be interpreted as the “orientation” of the fibration $p|_{\Omega(M)} : \Omega(M) \rightarrow M$.

2.2. Poincaré duality.

We first note that the “semi-infinite fundamental cycle”

$$\Omega(M) = \{\gamma : [0, 1] \rightarrow T^*M \mid \gamma(0), \gamma(1) \in o_M\}$$

has a natural \mathbb{Z}_2 -action that is induced from the time reversal map: $t \mapsto 1-t$. The \mathbb{Z}_2 -action is given by

$$\gamma \mapsto \tilde{\gamma}, \quad \tilde{\gamma}(t) := \gamma(1-t).$$

This action is compatible with the action on \mathcal{H} ,

$$H \mapsto \tilde{H}, \quad \tilde{H}(x, t) = -H(x, 1-t)$$

and also with the action on \mathcal{J} = the set of almost complex structures,

$$(2.4) \quad J \mapsto \tilde{J}, \quad \tilde{J}(x, t) = J(x, 1-t)$$

in the following sense: If z is a solution of

$$\begin{cases} \dot{z} = X_H(z) \\ z(0), z(1) \in o_M, \end{cases}$$

then $\tilde{z} \in CF_*(\tilde{H} : M)$, i.e., \tilde{z} satisfies

$$\begin{cases} \dot{\tilde{z}} = X_{\tilde{H}}(\tilde{z}) \\ \tilde{z}(0), \tilde{z}(1) \in o_M. \end{cases}$$

Furthermore, if $u : \mathbb{R} \times [0, 1] \rightarrow T^*M$ is a solution of

$$(2.5) \quad \begin{cases} \frac{\partial u}{\partial \tau} + J \left(\frac{\partial u}{\partial t} - X_H(u) \right) = 0 \\ u(\tau, 0), u(\tau, 1) \in o_M \\ \lim_{\tau \rightarrow -\infty} u(\tau) = z^\alpha, \quad \lim_{\tau \rightarrow +\infty} u(\tau) = z^\beta, \end{cases}$$

then $\tilde{u} : \mathbb{R} \times [0, 1] \rightarrow T^*M$ is a solution of

$$(2.6) \quad \begin{cases} \frac{\partial \tilde{u}}{\partial \tau} + \tilde{J} \left(\frac{\partial \tilde{u}}{\partial t} - X_{\tilde{H}}(\tilde{u}) \right) = 0 \\ \tilde{u}(\tau, 0), \tilde{u}(\tau, 1) \in o_M \\ \lim_{\tau \rightarrow -\infty} \tilde{u}(\tau) = \tilde{z}^\beta, \quad \lim_{\tau \rightarrow +\infty} \tilde{u}(\tau) = \tilde{z}^\alpha, \end{cases}$$

where

$$(2.7) \quad \tilde{u}(\tau, t) := u(-\tau, 1 - t).$$

In other words, the map $u \mapsto \tilde{u}$ (2.7) defines a natural one-to-one correspondence between $\mathcal{M}_J(H, M : z^\alpha, z^\beta)$ and $\mathcal{M}_{\tilde{J}}(\tilde{H}, M : \tilde{z}^\beta, \tilde{z}^\alpha)$. (2.6) should be considered as the “upward” gradient flow of the action functional \mathcal{A}_H . By (2.1), the assignment

$$z \mapsto \tilde{z}$$

defines a natural isomorphism between $CF_k(H, M)$ and $CF_{n-k}(\tilde{H}, M)$, where $n = \dim M$. This is because we have the following lemma which immediately follows from the definition of the Maslov index (see [RS] and [O4]), and from the identity

$$\mu(\tilde{z}) + \frac{1}{2} \dim M = -\mu(z) + \frac{1}{2} \dim M = \dim M - \left(\mu(z) + \frac{1}{2} \dim M \right).$$

Lemma 2.1. *Let $\mu(z)$ be $\mu_M(z)$ as defined in Theorem 5.1 [O4] for $S = M$. Then we have*

$$\mu(\tilde{z}) = -\mu(z).$$

Using (2.2)–(2.4) and Lemma 2.1, we define the natural homomorphism

$$\sigma_H : CF_{n-k}(\tilde{H} : M) \rightarrow CF^k(H : M)$$

as follows. For each generator $\tilde{z} \in CF_{n-k}(\tilde{H} : M)$ i.e., $z \in \text{Crit } \mathcal{A}_H$ with $\mu(z) + \frac{1}{2}n = k$, we define $\sigma_H(\tilde{z}) \in CF^k(H : M) = \text{Hom}(CF_k(H : M), \mathbb{Z})$ by

$$(2.8) \quad \begin{aligned} \sigma_H(\tilde{z})(w) &= 1 && \text{if } w = z \\ &= 0 && \text{otherwise} \end{aligned}$$

where w 's are generators of $CF_k(H : M)$. We then extend this definition linearly to the whole module $CF_{n-k}(\tilde{H} : M)$. Now, the map (2.5) naturally push-forwards the coherent orientation σ on $\mathcal{M}_J(H, M : z^\alpha, z^\beta)$ to the orientation $\tilde{\sigma}$ on $\mathcal{M}_J(\tilde{H}, M : \tilde{z}^\beta, \tilde{z}^\alpha)$. We would like to emphasize that *a priori, this orientation $\tilde{\sigma}$ on $\mathcal{M}_J(\tilde{H}, M : \tilde{z}^\beta, \tilde{z}^\alpha)$, is not connected to the one induced there by σ .*

Proposition 2.2. *Let $\partial_{(\tilde{H}, J)}^{\tilde{\sigma}}$ ($\delta_{(H, J)}^\sigma$) be the canonical boundary (coboundary) maps. Then the following diagram*

$$(2.9) \quad \begin{array}{ccc} CF_{n-k}(\tilde{H} : M) & \xrightarrow{\sigma_H} & CF^k(H : M) \\ \downarrow \partial_{(\tilde{H}, J)}^{\tilde{\sigma}} & & \downarrow \delta_{(H, J)}^\sigma \\ CF_{n-k-1}(\tilde{H} : M) & \xrightarrow{\sigma_H} & CF^{(k+1)}(H : M) \end{array}$$

commutes. Hence σ_H induces a chain-isomorphism and so induces a natural isomorphism

$$(2.10) \quad \sigma_{(H, J)} : HF_{n-k}^{\tilde{\sigma}}(\tilde{H}, \tilde{J} : M) \rightarrow HF_\sigma^k(H, J : M).$$

Proof. It is enough to check

$$\delta_{(H, J)}^\sigma \circ \sigma_H(\tilde{z}) = \sigma_{(H, J)} \circ \partial_{(\tilde{H}, J)}^{\tilde{\sigma}}(\tilde{z})$$

for any generator $\tilde{z} \in CF_{n-k}(\tilde{H} : M)$. To prove this, we compute $\delta_{(H, J)}^\sigma \circ \sigma_H(\tilde{z})(w)$ and $\sigma_{(H, J)} \circ \partial_{(\tilde{H}, J)}^{\tilde{\sigma}}(\tilde{z})(w)$ for each generator $w \in CF_{k+1}(H : M)$. First,

$$\begin{aligned} \delta_{(H, J)}^\sigma \circ \sigma_H(\tilde{z})(w) &= \sigma_H(\tilde{z})(\partial_{(H, J)}^\sigma w) \\ &= \sigma_H(\tilde{z}) \left(\sum_y n_{(H, J)}^\sigma(w, y)y \right) \\ &= \sum_y n_{(H, J)}^\sigma(w, y)\delta_{yz} \\ &= n_{(H, J)}^\sigma(w, z). \end{aligned}$$

Secondly, we have

$$\begin{aligned} \sigma_H \circ \partial_{(\tilde{H}, \tilde{J})}^{\tilde{\sigma}}(\tilde{z})(w) &= \sigma_H \left(\sum_{\tilde{y}} n_{(\tilde{H}, \tilde{J})}^{\tilde{\sigma}}(\tilde{z}, \tilde{y}) \tilde{y} \right) (w) \\ &= \sum_{\tilde{y}} n_{(\tilde{H}, \tilde{J})}^{\tilde{\sigma}}(\tilde{z}, \tilde{y}) \delta_{yw} \\ &= n_{(\tilde{H}, \tilde{J})}^{\tilde{\sigma}}(\tilde{z}, \tilde{w}). \end{aligned}$$

On the other hand, by the definition of $\tilde{\sigma}$ and $n(\cdot, \cdot)$, we have

$$n_{(H, J)}^{\sigma}(w, z) = n_{(\tilde{H}, \tilde{J})}^{\tilde{\sigma}}(\tilde{z}, \tilde{w}),$$

which finishes the proof. \square

Remark 2.3. As we pointed out, the two orientations provided by σ and $\tilde{\sigma}$ may not be related in a natural way in general and so the two Floer homology $HF_{n-k}^{\tilde{\sigma}}(\tilde{H}, \tilde{J} : M)$ and $HF_{n-k}^{\sigma}(\tilde{H}, \tilde{J} : M)$ may not be isomorphic. In fact, when M is connected and not orientable, we know that by the isomorphisms

$$F_{(H, J)} : H_*(M, \mathbb{Z}) \rightarrow HF_*^{\sigma}(H, J : M)$$

and

$$h_{\alpha\beta}^{\sigma} : HF_*^{\sigma}(H^{\beta}, J^{\beta} : M) \rightarrow HF_*^{\sigma}(H^{\alpha}, J^{\alpha} : M),$$

we have

$$HF_0^{\sigma}(\tilde{H}, \tilde{J} : M) \cong HF_0^{\sigma}(H, J : M) \cong H_0(M, \mathbb{Z}) = \text{free abelian}$$

while by the isomorphisms (2.2) and (2.8), we have

$$HF_0^{\tilde{\sigma}}(\tilde{H}, \tilde{J} : M) \cong HF_0^{\tilde{\sigma}}(H, J : M) \cong H^0(M, \mathbb{Z}) = \text{torsion}.$$

This shows that the Floer cohomologies with respect to different coherent orientations can actually be different.

However, we have the following theorem.

Theorem 2.4. *Let (K, J) be any generic parameter. There exists an isomorphism between $HF_*^{\sigma}(K, J : M)$ and $HF_*^{\tilde{\sigma}}(K, J : M)$ that preserves the grading with \mathbb{Z} -coefficients when M is orientable (and so with respect to arbitrary coefficients) and does so with \mathbb{Z}_2 -coefficients when it is non-orientable.*

Proof. We first consider the case when M is orientable. With the natural isomorphism, it will be enough to consider the case when $K = f \circ \pi$ for sufficiently C^2 -small f on M where $\pi : T^*M \rightarrow M$ is the canonical projection. Consider the diagram

$$\begin{array}{ccc} HF_{n-k}^{\tilde{\sigma}}(K, J : M) & \xrightarrow{\tau_K} & HF_{n-k}^{\sigma}(K, J : M) \\ \uparrow F_{(K,J)} & & \uparrow F_{(K,J)} \\ H_{n-k}^{\tilde{\sigma}}(f, \mathbb{Z}) & \xrightarrow{\tau_f} & H_{n-k}^{\sigma}(f, \mathbb{Z}) \end{array}$$

where $\tau_K : HF_{n-k}^{\tilde{\sigma}}(K, J : M) \rightarrow HF_{n-k}^{\sigma}(K, J : M)$ and $\tau_f : H_{n-k}(f, \mathbb{Z}) \rightarrow H_{n-k}^{\sigma}(f, \mathbb{Z})$ are the homomorphisms induced from the identity homomorphism

$$id : CF_{n-k}(K, J : M) \rightarrow CF_{n-k}(K, J : M)$$

and

$$id : C_{n-k}(f, \mathbb{Z}) \rightarrow C_{n-k}(f, \mathbb{Z}).$$

The definition of the boundary map $\partial_f^{\tilde{\sigma}}$ uses the orientation of the Morse complex given by orienting the stable manifolds instead of unstable manifolds, while ∂_f^{σ} does the one given by the unstable manifolds (see [Section 7, Mi]). It is also a routine exercise to check that this geometric orientation coincides (maybe upto simultaneous change of sign) with the analytically defined canonical coherent orientation σ defined in [FH1, Sc1]. The boundary map $\partial_K^{\tilde{\sigma}}$ uses the analogue to that of $\partial_f^{\tilde{\sigma}}$ for the Floer complex.

Note that for $K = f \circ \pi$ sufficiently small and of Morse-Smale type, it has been known (see [Appendix, O5] for the proof) that the kernels of the linearizations of the corresponding trajectories in the Morse complex of f and the Floer complex of K have natural one-to-one correspondence. Therefore we can also naturally identify the two maps

$$\partial_K^{\tilde{\sigma}} \cong \partial_f^{\tilde{\sigma}}, \quad \partial_K^{\sigma} \cong \partial_f^{\sigma}.$$

When M is orientable, it is proven in Section 7 [Mi] that

$$(2.12) \quad \partial_f^{\tilde{\sigma}}|_{C_k(f)} = (-1)^{k-1} \partial_f^{\sigma}|_{C_k(f)}$$

which proves that

$$\tau_f : H_{n-k}^{\tilde{\sigma}}(f, \mathbb{Z}) \rightarrow H_{n-k}^{\sigma}(f, \mathbb{Z})$$

becomes an isomorphism. Then by the way how the vertical homomorphisms are defined (see Theorem 5.5 [O4]), the above diagram commutes.

Furthermore, both vertical arrows are isomorphisms. Therefore the arrow in the top becomes an isomorphism. When M is non-orientable, (2.12) holds mod 2. So τ_f is an isomorphism in \mathbb{Z}_2 -coefficient. \square

Remark 2.5. We would like to emphasize that the isomorphism in Theorem 2.4 does not follow from the standard continuity argument as in (2.3). This continuity fails because it is not generally possible to connect the two coherent orientations σ and $\tilde{\sigma}$, as shown in Remark 2.3. The isomorphism in Theorem 2.4 is essentially the classical Poincaré duality of the underlying manifold M . The (classical) Poincaré duality depends on the orientability of the manifold and so holds only for the cohomology with appropriate coefficients, when M is not orientable. For the non-relative Floer theory Theorem 2.4 is always true simply *because the symplectic manifold has the canonical orientation*. This point has not been addressed carefully in the literature as in [PSS].

Combining (2.10) and Theorem 2.4 applied to (\tilde{H}, \tilde{J}) , we obtain an isomorphism

$$(2.13) \quad PD_{(H,J)} : HF_k^\sigma(H, J : M) \rightarrow HF_{\sigma}^{n-k}(H, J : M)$$

which is called the *Poincaré duality of the Floer theory* in literature. However this isomorphism is not *natural* while the homomorphism (2.10) is so, when one considers the filtration later. In fact, we will use (2.10) in a crucial way in the definition of the pants product but will never use the isomorphism (2.13) in the rest of the paper.

The identity

$$(2.14) \quad \mathcal{A}_{\tilde{H}}(\tilde{z}) = -\mathcal{A}_H(z)$$

and the map defined in (2.5) are important ingredients in the study of filtrations in Section 5 and 6.

3. Pants product.

We will fix the canonical coherent orientation σ and suppress σ from the notations in the rest of the paper. We will take \mathbb{Z} as coefficients unless otherwise specified.

In this section, we study the product properties of $HF^*(H, J : M)$ using the so called *pants-product*. A version of pants-product has been described in several literature (see [BzR], [PSS], [RT] and [Sc2] for example) mostly in

non-relative Floer theory. Some aspects of the relative point of view were also described in [Fu1,2]. In fact, they described a more general version of the *pants-product* in the context of the *symplectic version of relative Donaldson invariants*. Fukaya and the author [FO] studied, degeneration of the Floer moduli space to the Morse moduli space (or graph flow moduli space in the terminology of [BzC]) in full analytic details, which is essential to relate the pants products defined in the Morse theory and Floer theory. [FO] also defines and proves the graph flow moduli space in a precise way.

One novelty of our approach to the pants product in this paper is to use the most functorial version for two different reasons:

- (1) *In applications to the construction of symplectic invariants, it is crucial to analyze how the filtration in the Floer complex is affected under the pants-product, and to estimate the optimal change of the filtrations.*
- (2) *When one tries to relate the pants-product on HF^* and ordinary cup-product on $H^*(M, \mathbb{Z})$, the functorial version of the pants-product is essential in some analytical reason (see [FO]).*

Both of these two aspects will be crucial in deriving the *product inequality* (6.1) of the symplectic invariants we will construct in Section 6.

We first recall how the classical cup product in the cohomology can be defined

$$H^*(M, \mathbb{Z}) \otimes H^*(M, \mathbb{Z}) \xrightarrow{\cup} H^*(M, \mathbb{Z})$$

in the point of view of the Witten's *Morse homology* (see [Sc1] for a detailed exposition on Morse homology and [BzC] or [Fu1] for the product operation): One chooses a suitable triple of functions (g_1, g_2, g_3) on M and consider the gradient flows of g_i 's, $i = 1, 2, 3$. Floer's construction will define the Morse homology denoted by $H_*(M : g_i)$ for $i = 1, 2, 3$ each of them is isomorphic to $H_*(M, \mathbb{Z})$ the singular homology of M . By the dual construction, one can also define the Morse cohomology $H^*(M : g_i)$. Now for a given tree T with 3 edges, we identify (or give coordinates) the edges e_1, e_2 with $[0, \infty)$ (*incoming edges*) and the edge e_3 with $(-\infty, 0]$ (*outgoing edge*). We then consider the map

$$I : T \rightarrow M$$

such that the restriction $\chi_i = I|_{e_i}$ to each edge e_i satisfies

$$(3.1) \quad \begin{cases} \frac{d\chi_i}{dt} = -\text{grad}_g g_i(\chi_i) \\ \lim_{\tau \rightarrow +\infty} \chi_i(\tau) = p_i & \text{for } i=1,2 \\ \lim_{\tau \rightarrow -\infty} \chi_i(\tau) = p_3 \end{cases}$$

where $p_i \in \text{Crit}(g_i)$. We define by $\mathcal{M}(M : \vec{g}, \vec{p})$ for $\vec{g} = (g_1, g_2, g_3)$ and

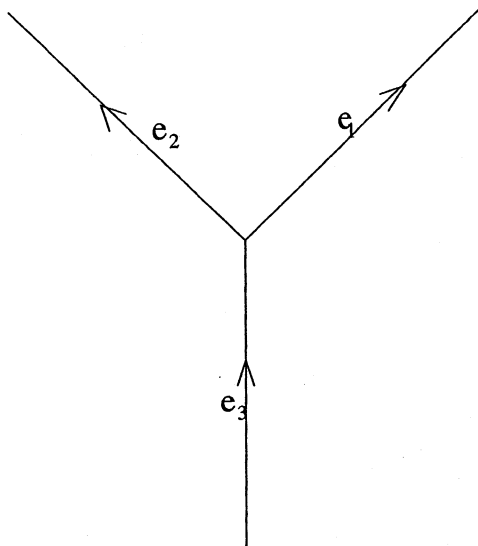


Figure 1

$\vec{p} = (p_1, p_2, p_3)$ the set of all such maps I as above. Geometrically, one can also identify this set with

$$(\cap_{i=1}^2 W_{p_i}^+(g_i)) \cap W_{p_3}^-(g_3)$$

where $W_p^+(h)$ (resp. $W_p^-(h)$) is the stable (resp. unstable) manifold of the gradient flow of the function h at the critical point $p \in M$. Under a suitable transversality hypothesis [Theorem 3.1,FO] (see Theorem 4.1 below), the set $\mathcal{M}(M : \vec{g}, \vec{p})$ becomes a smooth manifold of dimension given by

$$\begin{aligned} D = D(\vec{p}) &:= (n - \mu(p_1)) + (n - \mu(p_2)) + \mu(p_3) + n - 3n, \\ &= \mu(p_3) - \mu(p_1) - \mu(p_2) \\ &= (n - (n - \mu(p_3))) - \mu(p_1) - \mu(p_2) \end{aligned}$$

where $\mu(p_j)$ is the Morse index of g_j at p_j . When $D = 0$, one can prove for a generic choice of g_j 's (see [O2] and [FO] for details) that $\mathcal{M}(M :$

\vec{g}, \vec{p}) becomes a compact zero-dimensional manifold and so we can count the algebraic number of the elements in $\mathcal{M}(M : \vec{g}, \vec{p})$. We denote this number by $n(M : \vec{g}, \vec{p})$ and define a chain, denoted by $\Psi_T(\vec{g}) \in C_*(M, g_1) \otimes C_*(M, g_2) \otimes C_*(M, -g_3)$,

$$(3.2) \quad \Psi_T(\vec{g}) := \sum_{\vec{p}} n(M : \vec{g}, \vec{p}) \langle \vec{p} \rangle, \quad \langle \vec{p} \rangle = p_1 \otimes p_2 \otimes p_3,$$

where we define $n(M : \vec{g}, \vec{p}) = 0$ if $D \neq 0$. One can prove by the standard cobordism argument that $\Psi_T(\vec{g})$ defines a cycle and so induces an element in $H_*(M, g_1) \otimes H_*(M, g_2) \otimes H_*(M, -g_3)$ which we also denote by $\Psi_T(\vec{g})$. Now, we define a bilinear map which we call the *pants-product*

$$H^*(M, g_1) \otimes H^*(M, g_2) \rightarrow H^*(M, g_3)$$

by the dual to the homology class $\Psi_T(\vec{g})$. More precisely, for each given $a_1 \in H^k(M, g_1)$, $a_2 \in H^\ell(M, g_2)$, choose their representative cocycles, which we ambiguously denote also by a_1 and a_2 . Then we consider the contraction cycle

$$(3.3) \quad \langle a_1 \otimes a_2, \Psi_T(\vec{g}) \rangle \in C_{n-(k+\ell)}(M, -g_3)$$

and the cocycle

$$\sigma_f(\langle a_1 \otimes a_2, \Psi_T(\vec{g}) \rangle) \in C^{k+\ell}(M, g_3).$$

We define the third element $a_1 \cup a_2 \in H^{k+\ell}(M, g_3) = H_\sigma^{k+\ell}(M, g_3)$ by the cohomology class represented by the cocycle $\sigma_f(\langle a_1 \otimes a_2, \Psi_T(\vec{g}) \rangle)$. Here we used the isomorphism σ_f between $H_{n-(k+\ell)}^\sigma(M, -g_3)$ and $H_\sigma^{k+\ell}(M, g_3)$ that is defined similarly as (2.8). One can again check by the standard arguments that this class is independent of the choice of the cocycles a_1 and a_2 . The above construction can be applied to *any* (g_1, g_2, g_3) that satisfies suitable transversality hypothesis. However, it was first noted by Fukaya [Fu1] that in relation to the quantized Morse homology, i.e., Floer homology (for the Lagrangian intersections on the cotangent bundle), it is natural to consider the triple (g_1, g_2, g_3) such that

$$(3.4) \quad g_3 = g_1 + g_2.$$

It turns out that this *conservation law* is crucial in the analysis needed to establish the equivalence between the Fukaya's A^∞ structures in the Morse theory and in its quantization, the Floer theory (see [FO] for detailed proofs).

The analogue of the conservation law to (3.4) is a crucial ingredient in studying the filtration under the pants-product later in this paper. We recall the operation $\#$ defined in (1.1):

$$H\#K(x, t) = H(x, t) + K((\phi_H^t)^{-1}(x), t)$$

We note that if we apply (1.1) to the time independent Hamiltonians of the form

$$g \circ \pi : T^*M \rightarrow \mathbb{R}$$

for $g : M \rightarrow \mathbb{R}$, (1.1) reduces to (3.4) because of the following simple formula, which can be easily proved,

$$(3.5) \quad (h \circ \pi)\#(k \circ \pi) = (h + k) \circ \pi.$$

The following is the main theorem we prove throughout the rest of this section, Section 4 and 5. This is the content of Theorem I without taking filtrations into account. We will study its relation to filtrations in Section 6.

Theorem 3.1. *Assume that $H^\alpha, H^\beta, K^\alpha, K^\beta$ and $H^\alpha\#K^\alpha, H^\beta\#K^\beta$ are in \mathcal{H}_0 and J^α, J^β are regular with respect to the Hamiltonians respectively of α and β .*

- (1) *Then there exists a natural bilinear map denoted by \cup_F which we call the pants-product and which satisfies the following commutative diagram*

$$(3.6) \quad \begin{array}{ccc} HF^*(H^\alpha, J^\alpha : M) \otimes HF^*(K^\alpha, J^\alpha : M) & \xrightarrow{\cup_F} & HF^*(H^\alpha\#K^\alpha, J^\alpha : M) \\ \uparrow & & \uparrow \\ HF^*(H^\beta, J^\beta : M) \otimes HF^*(K^\beta, J^\beta : M) & \xrightarrow{\cup_F} & HF^*(H^\beta\#K^\beta, J^\beta : M) \end{array}$$

where the vertical isomorphisms are the ones defined in Theorem 5.4 [O4].

- (2) *Furthermore \cup_F respects the diagram*

$$(3.7) \quad \begin{array}{ccc} HF^*(H, J : M) \otimes HF^*(K, J : M) & \xrightarrow{\cup_F} & HF^*(H\#K, J : M) \\ \uparrow F_H \otimes F_K & & \uparrow F_{H\#K} \\ H^*(M, \mathbb{Z}) \otimes H^*(M, \mathbb{Z}) & \xrightarrow{\cup} & H^*(M, \mathbb{Z}). \end{array}$$

- (3) There exists a (right) action by $H^*(M, \mathbb{Z})$ on $HF^*(H, J : M)$, denoted again by \cup_F , which respects the diagram

$$(3.8) \quad \begin{array}{ccc} HF^*(H, J : M) \otimes H^*(M, \mathbb{Z}) & \xrightarrow{\cup_F} & HF^*(H, J : M) \\ \uparrow F_H \otimes id & & \uparrow F_H \\ H^*(M, \mathbb{Z}) \otimes H^*(M, \mathbb{Z}) & \xrightarrow{\cup} & H^*(M, \mathbb{Z}). \end{array}$$

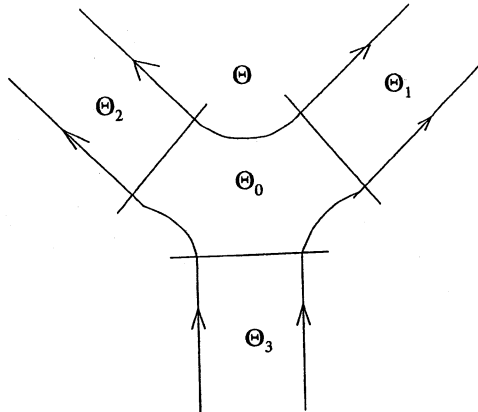
Remark 3.2. (1) In the literature, the above product has been described for fixed Hamiltonian or for arbitrary triples without imposing any restriction (in the *non-relative* Floer theory). [PSS] and [RT] also announced that this product is compatible with the various versions of other products (e.g., the Floer's product [F3] or the quantum cup product).

- (2) In Section 6, we will prove a refined version of Theorem 3.1 which takes the filtration into account and use this to prove some product inequality of the symplectic invariants that we will construct.

In the remaining section, we construct the pants-product \cup_F and outline the proofs of the statements (1), (2) and (3) in Theorem 3.1.

We will consider the quantized version of the space $\mathcal{M}(M : \vec{g}, \vec{p})$ in the Floer theory. Let $\Theta = \Theta_{0,3}$ be a domain of genus 0 in \mathbb{C} with 3 cylindrical ends. In general, we denote by $\Theta_{g,j}$ the domain in \mathbb{C} with genus g and with j marked points in the boundary. $\bar{\Theta}$ is conformally equivalent to the unit disc with 3 marked points on the boundary $\partial\Theta$. We denote

$$\begin{aligned} \Theta_i &= \phi_i([0, \infty) \times [0, 1]) \subset \Theta \quad \text{for } i = 1, 2 \\ \Theta_3 &= \phi_3((-\infty, 0] \times [0, 1]) \subset \Theta \end{aligned}$$



where ϕ_i 's are one-one holomorphic maps from the corresponding semi-strips into \mathbb{C} respectively. For notational convenience, we also denote

$$H^1 = H, H^2 = K, H^3 = H\#K, \quad \text{and} \quad \vec{H} = (H^1, H^2, H^3).$$

Given $\vec{z} = (z_1, z_2, z_3), z_j \in CF_*(H^j : M)$, we consider the space

$$\mathcal{M}_\Theta(\vec{z}) = \mathcal{M}_\Theta(\vec{H}, J : \vec{z})$$

of all smooth maps $u : \Theta \rightarrow T^*M$ that satisfy the conditions:

- (1) *The maps $u_i = u \circ \phi_i$ satisfy*

$$(3.9) \quad \begin{cases} \frac{\partial u}{\partial \tau} + J \left(\frac{\partial u}{\partial t} - X_{H^i}(u) \right) = 0 \\ \lim_{\tau \rightarrow +\infty} u_i(\tau) = z_i \\ \lim_{\tau \rightarrow -\infty} u_3(\tau) = z_3 \end{cases} \quad \text{for } i = 1, 2,$$

- (2) *u satisfies the boundary condition*

$$(3.10) \quad u(\partial\Theta) \subset o_M \subset T^*M$$

- (3) *u satisfies "some equation" on the complement*

$$\Theta_0 = \Theta - \bigcup_i \Theta_i$$

*that is 0-th order compact perturbation of J -holomorphic equation: Overall on Θ , this defining equation should come from a suitable smooth section of some smooth vector bundle over the space of maps $u : \Theta \rightarrow T^*M$ satisfying the boundary condition (2). In (6.7) of Section 6, we will give the precise formula for this equation.*

For defining the product, the choice of perturbations over Θ_0 is not essential but is essential for studying its relation to filtrations (see Section 6 for the optimal choice). We have the following theorem for the index of $u \in \mathcal{M}_\Theta(\vec{H}, J : \vec{z})$.

Theorem 3.3. *For a generic choice of (\vec{H}, J) , $\mathcal{M}_\Theta(\vec{H}, J : \vec{z})$ becomes an orientable smooth manifold of dimension*

$$(3.11) \quad \begin{aligned} D_{(\vec{H}, \vec{J})}(\vec{z}) &:= n - \left(\mu(z_1) + \frac{n}{2}\right) - \left(\mu(z_2) + \frac{n}{2}\right) - \left(-\mu(z_3) + \frac{n}{2}\right) \\ &= \left(\mu(z_3) + \frac{n}{2}\right) - \left(\mu(z_1) + \frac{n}{2}\right) - \left(\mu(z_2) + \frac{n}{2}\right) \end{aligned}$$

where $n = \dim M$.

Proof. The orientation problem can be solved similarly as in Theorem 5.2 [O4] and so we will omit the details except that we would like to emphasize that again our dynamical version of the Floer theory makes it easier to prove that $\mathcal{M}_\Theta(\vec{H}, J : \vec{z})$ is orientable. It will be enough to compute the Fredholm index of the linearization operator at $u \in \mathcal{M}_\Theta(\vec{H}, J : \vec{z})$. The formula can then be obtained by the gluing formula (or excision formula) by considering the following picture: Cap each z_j as drawn in the picture.

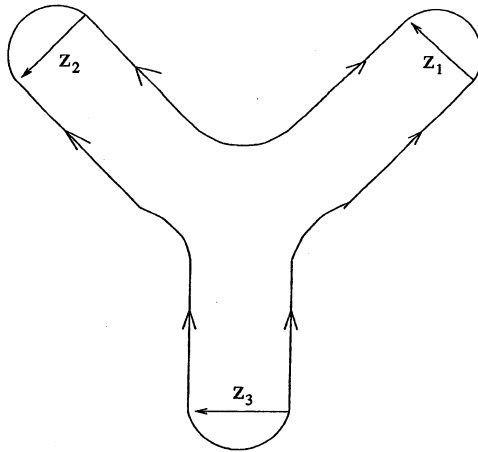


Figure 3

We will prove in the appendix that each cap has the index given by $-\mu(z) + \frac{n}{2}$ when z is an *incoming* asymptotic limit in the cap. Note that

the glued operator of the linearized operators over the four regions, under the trivializations of the type satisfying an analogue to (5.19) in [O4] on Θ , is homotopic to the Cauchy-Riemann operator on the unit disc with boundary condition on $\mathbb{R}^n \subset \mathbb{C}^n$. It is well-known that the latter operator has the Fredholm index n . Now by the excision formula for the Fredholm operator (this can be easily checked by modifying arguments in [BzR] or [Sc2] that were used for similar applications of the excision formula for the non-relative Floer theory), we have

$$D_{(\vec{H}, J)}(\vec{z}) + \left(\mu(z_1) + \frac{n}{2}\right) + \left(\mu(z_2) + \frac{n}{2}\right) + \left(-\mu(z_3) + \frac{n}{2}\right) = n$$

which is equivalent to (3.11). This finishes the proof. □

Remark 3.4. One can apply the same argument to find the dimension formula for general $\mathcal{M}_{\Theta_{g,k}}(\vec{H}, J : \vec{z}^-, \vec{z}^+)$, which is the space of solutions of the perturbed Cauchy-Riemann equation that is the generalization of (6.7) for arbitrary (g, k) . In fact, for a generic choice of \vec{H} , one can prove the following general dimension formula

$$\dim \mathcal{M}_{\Theta_{g,k}}(\vec{H}, J : \vec{z}^-, \vec{z}^+) = n(1-g) - \sum_{j=1}^{k_-} \left(-\mu(z_j^-) + \frac{n}{2}\right) - \sum_{j=1}^{k_+} \left(\mu(z_j^+) + \frac{n}{2}\right)$$

where $k = k_- + k_+$, and k_- and k_+ are the number of outgoing and incoming edges respectively (Similar formula was given in [BzC], [BzR] and [Sc2] and others in different contexts). Since we do not need this general formula in this paper, we will not discuss more about this generalization.

Furthermore when $D_{(\vec{H}, J)}(\vec{z}) = 0$, i.e., $\mathcal{M}_{\Theta}(\vec{H}, J : \vec{z})$ has dimension zero, it follows by the standard dimension counting argument that it is compact and so has only finitely many elements, provided we establish the following a priori area estimate. We will prove this in Section 6.

Theorem 3.5. *For all $u \in \mathcal{M}_{\Theta}(\vec{H}, J : \vec{z})$ that is defined by the equation (6.7), we have*

$$\int_{\Theta} \tilde{u}^* \omega = -\mathcal{A}_{H\#K} \left(z_{H\#K}^{p_3} \right) + \mathcal{A}_{H\#K} \left(z_{H\#K}^{\phi_H(p_1)} \right) - \mathcal{A}_H \left(z_H^{\phi_H(p_1)} \right) + \mathcal{A}_H \left(z_H^{p_2} \right)$$

where $\tilde{u} = \phi_{\vec{z}} \circ u$ is defined in (6.7) below. In particular, we have a priori area bound for $\int_{\Theta} \tilde{u}^* \omega$ that is independent of u .

Then we define an integer

$$n_{\Theta}(\vec{H}, J : \vec{z}) = \#(\mathcal{M}_{\Theta}(\vec{H}, J : \vec{z})),$$

and the chain in $CF_*(H, J : M) \otimes CF_*(K, J : M) \otimes CF_*(\widetilde{H\#K}, \tilde{J} : M)$ by

$$(3.12) \quad \Psi_{\Theta}(\vec{H}, J) = \sum n_{\Theta}(\vec{H}, J : \vec{z}) \langle \vec{z} \rangle, \quad \langle \vec{z} \rangle = z_1 \otimes z_2 \otimes z_3.$$

Again we can prove by the cobordism argument (see [BzR]) that this becomes a cycle and so induces a Floer homology class in $HF_*(H, J : M) \otimes HF_*(K, J : M) \otimes HF_*(\widetilde{H\#K}, \tilde{J} : M)$, which we also denote by $\Psi_{\Theta}(\vec{H}, J)$.

Similarly to the case of Morse cohomology, as in (3.3), for each

$$\alpha_1 \in HF^k(H, J : M), \alpha_2 \in HF^{\ell}(K, J : M)$$

we define

$$\alpha_1 \cup_F \alpha_2 \in HF^{k+\ell}(\widetilde{H\#K}, \tilde{J} : M)$$

by the cohomology class represented by the dual to the contraction cycle

$$\langle \alpha_1 \otimes \alpha_2, \Psi_{\Theta}(\vec{H}, J) \rangle \in CF_{n-(k+\ell)}(\widetilde{H\#K}, \tilde{J} : M)$$

i.e., by the cocycle

$$(3.13) \quad \sigma_{(H\#K, J)} \langle \alpha_1 \otimes \alpha_2, \Psi_{\Theta}(\vec{H}, J) \rangle \in CF^{k+\ell}(H\#K, J : M).$$

Theorem 3.1 (1) can be proven by now standard arguments considering the boundary of the one-dimensional component of $\mathcal{M}_{\Theta}(\vec{H}, J)$ as in [BzR]. Note that our case is easier because the bubbling does not occur. The existence of an action of $H^*(M, \mathbb{Z})$ without the commutative diagram (3.8) was first proven by Floer in [F3] in the context of the geometric version of the Floer theory for Lagrangian intersections. The proofs of Theorem 3.1 (2) and (3) can be reduced to the main result from [FO] (for $k = 3$). We will explain this reduction in detail in Section 4 and 5 partly because the setting in [FO] is different from that of the present paper and no explicit statement like Theorem 3.1 is given there. Furthermore, our construction in Section 5 *using degenerate pants* of the cup action (3.8) is new and useful for the proof of commutativity in Theorem 3.1 (3): Our construction can be considered as the limiting case of (3.7) as ϵ goes to zero for the special Hamiltonian K of the form $F = \epsilon f \circ \pi$ for a suitable Morse function f . The commutativity of the diagram (3.8) will follow from the definition of F_H and from the result

in [FO]. This will finish the proof of Theorem I except the statements on the filtration.

The statement about filtration in Theorem I (4) will also immediately follow from this construction.

4. Proof of Theorem 3.1 (2).

We would like to briefly recall how one can prove that $HF^*(H, J : M)$ is isomorphic to $H^*(M, \mathbb{Z})$. A version of this in the Floer's geometric setting $HF_J^*(L_0, L_1 : T^*M)$

$$(4.1) \quad \begin{cases} \frac{\partial u}{\partial \tau} + J \frac{\partial u}{\partial t} = 0 \\ u(\tau, 0) \in o_M, u(\tau, 1) \in \phi^1(o_M) \end{cases}$$

was proven by Floer [F2]. Using the invariance property of $HF_J^*(L_0, L_1 : T^*M)$ under the change of L_0, L_1 and J , Floer chooses a special choice of H and J to compute the group:

$$(4.2) \quad H_0 = \pi \circ f, \quad J_{H_0} = (\phi_{H_0}^t)^* J_g$$

and considers the map

$$u \mapsto (\phi_{H_0}^t)^{-1} u(\tau, t) =: \tilde{\chi}(\tau, t)$$

for each solution u of (4.1). Then he proves that if $|f|_{C^2}$ is sufficiently small, the above $\tilde{\chi}$ is t -independent and satisfies the equation

$$(4.3) \quad \dot{\chi} = -\text{grad}_g f(\chi).$$

Conversely, it is easy to check that if $\chi : \mathbb{R} \rightarrow M$ is a solution of (4.3), then

$$u(\tau, t) = \phi_{H_0}^t(\chi(\tau))$$

will be a solution of (4.1) for J_{H_0} defined as above. All the solutions of (4.1) will be regular if f is a Morse-Smale function with respect to the given metric g on M and if $|f|_{C^2}$ is sufficiently small (See [Appendix, O5]). Therefore by comparing the Morse homology and the Floer homology, we conclude that $HF^*(H_0, J_{H_0} : M)$ is naturally isomorphic to $H^*(M, \mathbb{Z})$. In fact, the above isomorphism holds in the chain level for the choice

$$H = H_0 \quad \text{and} \quad J = J_0.$$

In the proof of Theorem 3.1 (2), we will follow the similar idea to establish the diffeomorphism between the moduli spaces $\mathcal{M}(M : \vec{g}, \vec{p})$ and $\mathcal{M}_\Theta(\vec{H}, J : \vec{z})$ for suitable choice of (\vec{H}, J) and the perturbation of the J -holomorphic equation. However unlike the case of maps from the strip $\mathbb{R} \times [0, 1]$, it would not be possible to make the corresponding choice J as J_{H_0} for the domain Θ , since the definition of J_{H_0} in (4.2) involves the coordinates of $\mathbb{R} \times [0, 1]$. Therefore it would be important to prove the above equivalence theorem for the canonical almost complex structure J_g itself. In [FO], Fukaya and the author analytically constructed a diffeomorphism between $\mathcal{M}(M : \vec{g}, \vec{p})$ and $\mathcal{M}_\Theta(T^*M, J_g : \vec{\Lambda}^\epsilon, \vec{x}^\epsilon)$ on arbitrary discs with any finite number of marked points by a version of gluing construction. In particular, the main result for $k = 2$ proves that there exists a diffeomorphism between the moduli space $\mathcal{M}_g(f)$ and the moduli space $\mathcal{M}_{J_g}(o_M, \text{graph } df)$ when $|f|_{C^2}$ is sufficiently small. By comparing the relative indices and orientations, this diffeomorphism gives a chain isomorphism between the Morse complex and the Floer complex.

We state the main theorem for $k = 3$ from [FO] for the reader's convenience.

Theorem 4.1 [Theorem 3.1, FO]. *Suppose that $f_{i+1} - f_i$ are Morse functions and that the unstable manifolds $W_p^-(f_{i+1} - f_i)$ for $i = 1, 2, 3 \pmod{3}$ intersect transversely, i.e., we have*

$$\prod_{i=1}^3 (W_{p_i}^-(f_{i+1} - f_i)) \pitchfork \Delta \quad \text{in} \quad M \times M \times M$$

where $\Delta \subset M \times M \times M$ is the diagonal $\Delta = \{(q, q, q) \mid q \in M\}$. Then there exists some $\epsilon_0 > 0$ such that for any $0 < \epsilon < \epsilon_0$, we have a diffeomorphism

$$\Phi^\epsilon : \mathcal{M}_g(M : \vec{g}, \vec{p}) \rightarrow \mathcal{M}_{J_g}(T^*M : \vec{\Lambda}^\epsilon, \vec{x}^\epsilon)$$

where $g_i = f_{i+1} - f_i$, $\vec{\Lambda}^\epsilon = (\Lambda_1^\epsilon, \Lambda_2^\epsilon, \Lambda_3^\epsilon)$, $\vec{x}^\epsilon = (x_1^\epsilon, x_2^\epsilon, x_3^\epsilon)$ and

$$\Lambda_i^\epsilon = \text{Graph } \epsilon df_i, \quad x_i^\epsilon = (p_i, \epsilon df_i(p_i)).$$

Note that the three functions $g_i = f_{i+1} - f_i$ satisfies the conservation law

$$g_1 + g_2 + g_3 = 0$$

where the sign of change from (3.4) in front of g_3 is due to the way how [FO] defined the moduli space $\mathcal{M}_g(M : \vec{f}, \vec{p})$: In [FO], we give the coordinates to the tree T so that all the edges are *outgoing*.

Now, we would like to establish a similar diffeomorphism between $\mathcal{M}_g(M : \vec{g}, \vec{p})$ and our moduli space $\mathcal{M}_\Theta(\vec{H}, J_g : \vec{z})$ where $g_3 = g_1 + g_2$ and $H^i = \pi \circ g^i$ and the Hamiltonian path z_i is the solution of the equation

$$\begin{cases} \dot{z}_i = X_{H^i}(z_i) \\ z_i(1) = p_i \in o_M \cap \phi_H(o_M) \subset T^*M \quad \text{for } i = 1, 2, 3 \end{cases}$$

We remind readers of the identity (3.5). By imitating the proof in [FO] for the equation (6.7) which we introduce in Section 6, we can prove the following theorem which is the analogue to Theorem 4.1 in our setting. Since the modification from the proof in [FO] will be straightforward, we omit the details.

Theorem 4.2. *Let $J \equiv J_g$ and suppose that g_1, g_2 and $g_3 = g_1 + g_2$ are Morse functions and that the stable manifolds $W_{p_1}^+(g_1), W_{p_2}^+(g_2)$ and the unstable manifold $W_{p_3}^-(g_3)$ intersect transversely. Denote $G_i = g_i \circ \pi$. Then there exists some $\epsilon_0 > 0$ such that for any $0 < \epsilon < \epsilon_0$, we have a diffeomorphism*

$$\Psi_\epsilon : \mathcal{M}_g(M : \vec{g}, \vec{p}) \rightarrow \mathcal{M}_\Theta(\vec{G}^\epsilon, J_g : \vec{z}^\epsilon)$$

where $\vec{G}^\epsilon = (\epsilon G_1, \epsilon G_2, \epsilon G_3)$, $\vec{z}^\epsilon = (z_1^\epsilon, z_2^\epsilon, z_3^\epsilon)$ and z_i^ϵ are the solutions of

$$\begin{cases} \dot{z}_i^\epsilon = X_{\epsilon G_i}(z_i^\epsilon) \\ z_i^\epsilon(1) = p_i \in o_M \end{cases}$$

Furthermore, the images of this map Ψ_ϵ approximate the $\mathcal{M}_g(M : \vec{g}, \vec{p})$ in the Hausdorff topology.

Once we have proven Theorem 4.2, the proof of Theorem 3.1 (2) will follow from the definition of the pants-product in the Morse cohomology and our Floor cohomology $HF^*(H, J : M)$. The commutativity, Theorem 3.1 (2) (Theorem I (3)) will follow by comparing the boundaries of the one-dimensional component of $\mathcal{M}_\Theta(\vec{G}^\epsilon, J_g : \vec{z}^\epsilon)$ and $\mathcal{M}_g(M : \vec{g}, \vec{p})$. This finally finishes the proof of Theorem 3.1 (2) (Theorem I (3)).

5. Cup action and the proof of Theorem 3.1 (3).

Roughly saying, we will define the cup action

$$HF^*(H, J : M) \otimes H^*(M, \mathbb{Z}) \rightarrow HF^*(H, J : M)$$

as the dual to a cycle in $HF_*(H, J : M) \otimes H_*(M, \mathbb{Z}) \otimes HF_*(\tilde{H}, J : M)$. This cycle is defined by counting the elements in $\mathcal{M}_J(H, M)$ that intersect with the stable manifolds of critical points of a given Morse function f on M . More precisely, for each given $z_2, z_3 \in CF_*(H, J : M)$ and $p_1 \in C_*(f : M)$, we consider the following “degenerate pants”.

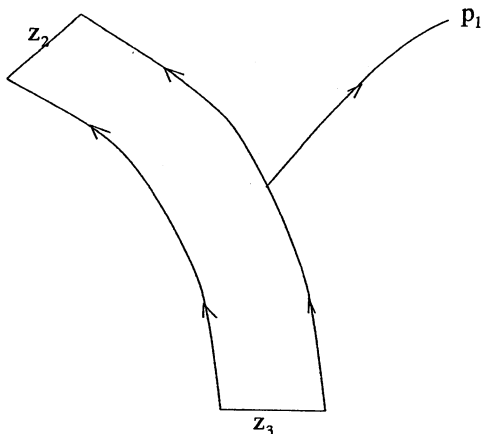


Figure 4

One should regard the current set up as the limit case as $\epsilon \rightarrow 0$ of that in the definition of the pants product in which $K = \epsilon f \circ \pi$. We denote by $\mathcal{M}_p^+(f)$ the set of gradient trajectories of f that has p as the ω -limit and consider the evaluation map

$$ev_{(f:p)} : \mathcal{M}_f^+(p) \rightarrow M; \quad ev(\chi) = \chi(0).$$

Of course the image of this map is exactly the stable manifold of p . Now we define the map

$$\begin{aligned} ev_{(f:p_1)} \times Ev : \mathcal{M}_f^+(p_1) \times \mathcal{M}_J(H, M : z_3, z_2) &\rightarrow M \times M \\ (\chi, u) &\mapsto (\chi(0), u(0, 0)) \end{aligned}$$

We denote the pre-image $(ev \times Ev)^{-1}(\Delta)$ by $\mathcal{M}_J(z_3, z_2 | p_1) = \mathcal{M}_J(H : z_3, z_2 | f : p_1)$ where $\Delta \subset M \times M$ is the diagonal. Except the orientation, the following proposition can be proven by the standard transversality argument. The proof of the orientation statement in a much more general

context will be given elsewhere and so the proof of the following proposition will be omitted. In the mean time, we refer to [BzR] for some relevant explanation of this orientation question in the non-relative context.

Proposition 5.1. *For generic choice of f and H , the set $\mathcal{M}_J(z_3, z_2|p_1)$ becomes a smooth manifold of dimension given by*

$$\left(\mu(z_3) + \frac{n}{2}\right) - \left(\mu(z_2) + \frac{n}{2}\right) - \mu_f(p_1).$$

One can also give orientations to these sets which are compatible to the gluing procedure.

Again by a dimension counting argument, one can prove that the zero dimensional component of $\mathcal{M}_J(H|f) = \cup_{(z_3, z_2|p_1)} \mathcal{M}_J(z_3, z_2|p_1)$ will be compact and so we can define an integer

$$n(z_3, z_2|p_1) = n_{(H, J|f)}(z_3, z_2|p_1) := \#(\mathcal{M}_J(z_3, z_2|p_1)).$$

We define a chain in $CF_*(H, J : M) \otimes C_*(f : M) \otimes CF_*(\tilde{H}, \tilde{J} : M)$ by

$$\Psi(z_3, z_2|p_1) = \Psi(H, J : z_3, z_2|f : p_1) := \sum_{z_3, p_1|z_2} n(z_3, z_2|p_1) z_2 \otimes p_1 \otimes \tilde{z}_3.$$

For each given $a \in CF^k(H, J : M)$ and $\beta \in C^\ell(f : M)$, we consider the contraction cycle

$$\langle a \otimes \beta, \Psi(z_3, z_2|p_1) \rangle = \sum_{z_3, z_2|p_1} n(z_3, z_2|p_1) a(z_2) \beta(p_1) \tilde{z}_3 \in CF_{n-(k+\ell)}(\tilde{H}, \tilde{J} : M)$$

and then the cocycle

$$\sigma_{(H, J)} \langle a \otimes \beta, \Psi(z_3, z_2|p_1) \rangle \in CF^{k+\ell}(H, J : M)$$

which defines an element in $HF^{k+\ell}(H, J : M)$.

Definition 5.2. For each given $[a] \in HF^*(H, J : M)$ and $u \in H^*(M, \mathbb{Z})$, we define the cup action of $H^*(M, \mathbb{Z})$ on $HF^*(H, J : M)$ by

$$a \cup_F u := [\sigma_{(H, J)} \langle a \otimes \beta, \Psi(z_3, z_2|p_1) \rangle]$$

where $[\beta] = u$.

It remains to prove the commutativity of the diagram (3.8). By the cobordism argument, it will be enough to prove the case when $H = h \circ \pi$ for a Morse function h . The following lemma is the analogue of Floer's theorem in [F2].

Lemma 5.3. *Let $H = h \circ \pi$ where h is a function of Morse-Smale type. Then there exists some $\epsilon > 0$ such that if $|h|_{C^2} < \epsilon$, all the solutions u with finite energy of the equation*

$$\begin{cases} \frac{\partial u}{\partial \tau} + J_g \left(\frac{\partial u}{\partial t} - X_H(u) \right) = 0 \\ u(\tau, 0), u(\tau, 1) \in o_M \end{cases}$$

are t -independent and $\chi(\tau) = u(\tau, 0)$ is a trajectory of $-\text{grad } f$.

Now, it is not difficult to see (see [BzC] for some explanation) that in the Morse-Witten homology setup, the cup action (or product) can be also described as follows: For each $p_2, p_3 \in C_*(h : M)$ and $p_1 \in C_*(f : M)$, we study the pair $(\chi, \nu) \in \mathcal{M}_{p_1}^+ \times \mathcal{M}(h : p_3, p_2)$ such that

$$\chi(0) = \nu(0).$$

If we define the set of such pairs by $\mathcal{M}(h : p_3, p_2 | f : p_1)$, then Lemma 5.3 implies that there exists an orientation preserving diffeomorphism between the space $\mathcal{M}_{J_g}(H : z_3, z_2 | f : p_1)$ and $\mathcal{M}_g(h : p_3, p_2 | f : p_1)$, where $z_3 \equiv p_3$, $z_2 \equiv p_2$ are the constant Hamiltonian orbits of $X_{h \circ \pi}$. Then the commutativity (3) immediately follows from the definitions of the cup action. This finishes the proof of Theorem 3.1 (3).

6. Pants product and cohomological invariants.

So far, we have proven all the statements in Theorem I except ones involving filtrations in (1).

In this section, we use the (semi-infinite) Thom isomorphism established in Section 2 to construct some cohomological invariants of Viterbo type [V] and prove Theorem II. In the course of doing these, we will also prove Theorem I (1). All the properties of our invariants will be directly related to the Hamiltonian H 's and so to *Hofer's geometry*.

Using the filtration given by the values of \mathcal{A}_H and the canonical grading by (2.1) on $CF_*(H, M)$, we define

$$CF_a^k = \text{Hom}(CF_k^a, \mathbb{Z})$$

and

$$CF_k^a = CF_k^a(H, J : M) = \{z \in CF_k(H, J : M) \mid \mathcal{A}_H(z) < a\}$$

as defined in [O4]. Then for $b > a$, we have the homomorphism

$$j_{ba}^* : CF_b^k \rightarrow CF_a^k$$

defined by the restriction, which becomes surjective. Then we define

$$CF_{(a,b)}^k := \text{Ker } j_{ba}^*$$

The coboundary map $\delta_{(H,J)} : CF^k(H : M) \rightarrow CF^{k+1}(H : M)$ induces the homomorphism

$$\delta_{(H,J)} : CF_{(a,b)}^k \rightarrow CF_{(a,b)}^{k+1}$$

and so one can define the relative Floer cohomology group

$$HF_{(a,b)}^k(H, J : M) = \text{Ker } \delta_{(H,J)} / \text{Im } \delta_{(H,J)}.$$

It is easy to check from the definition that there exists a canonical homomorphism

$$j^* : HF_{(c,d)}^k \rightarrow HF_{(a,b)}^k$$

whenever $c \geq a, d \geq b$. In particular, there exists the natural homomorphism

$$j_\lambda^* : HF^k \rightarrow HF_{(-\infty, \lambda]}^k.$$

We are now ready to define, for each $u \in H^*(M, \mathbb{Z})$, the cohomological invariants. First, we define

$$\begin{aligned} \rho(H, J : u) &= \inf\{\lambda \mid j_\lambda^* F_{(H,J)}(u) \neq 0 \text{ in } HF_{(-\infty, \lambda]}^*(H, J : M)\} \\ &= \sup\{\lambda \mid j_\lambda^* F_{(H,J)}(u) = 0 \text{ in } HF_{(-\infty, \lambda]}^*(H, J : M)\}. \end{aligned}$$

Lemma 6.1. *For (H, J) such that $\phi_H(o_M) \pitchfork o_M$ and $J \in \mathcal{J}_H$, $\rho(H, J : u)$ is a critical value of \mathcal{A}_H and independent of $J \in \mathcal{J}_H$.*

Proof. The proof is an obvious modification of Lemma 7.2 in [O4]. We leave the details to readers. \square

Definition 6.2. For each $u \neq 0 \in H^*(M, \mathbb{Z})$ and $H \in \mathcal{H}_0$, we define

$$\rho(H, u) := \rho(H, J : u)$$

for some $J \in \mathcal{J}_H$ (and so for all J). We set $\rho(H, 0) = +\infty$ for the zero class $0 \in H^*(M, \mathbb{Z})$.

Now, we study the H -dependence of $\rho(H, u)$. The following is again easy to prove as Lemma 8.1 in [O4].

Lemma 6.3. *When $H \in \mathcal{H}_0$ and as $\|H\|_{C^1} \rightarrow 0$, then $\rho(H, u) \rightarrow 0$.*

The following theorem summarizes the basic properties of $\rho(H, u)$, which are Theorem II (3)–(5). Note that Theorem II (2) is an immediate consequence of (3).

Theorem 6.4. *We assume that H, H^α and $H^\beta \in \mathcal{H}_0 \subset \mathcal{H}$. Then*

(1) *For any $u \neq 0 \in H^*(M, \mathbb{Z})$, we have*

$$\int_0^1 -\max_x (H^\beta - H^\alpha) dt \leq \rho(H^\beta, u) - \rho(H^\alpha, u) \leq \int_0^1 -\min_x (H^\beta - H^\alpha) dt$$

In particular when combined with Lemma 6.3, we have

$$(6.1) \quad \int_0^1 -\max_x H dt \leq \rho(H, u) \leq \int_0^1 -\min_x H dt.$$

(2) *We have*

$$|\rho(H^\beta, u) - \rho(H^\alpha, u)| \leq \|H^\beta - H^\alpha\|_{C^0}$$

and so the map $H \mapsto \rho(H, u)$ can be extended to a continuous function of H on \mathcal{H}_{C^0} . We still denote this extension by $\rho(H, u)$ for $u \in H^(M, \mathbb{Z})$.*

(3) *For any $u, v \in H^*(M, \mathbb{Z})$ and $H, K \in \mathcal{H}$, we have*

$$(6.2) \quad \rho(H \# K, u \cup v) \geq \rho(H, u) + \rho(K, v) + \epsilon(K)$$

where $\epsilon(K)$ depends only on K which vanishes for any autonomous K and $\epsilon(K) \leq \|K\|$. In particular, we have

$$(6.3) \quad \rho(H, u \cup v) \geq \rho(H, u).$$

Proof. (2) immediately follows from (1). To prove (1), we follow the argument of the proof of Theorem 7.2 (7.2) in [O4]. By the same argument as therein, if we set $\epsilon^{\alpha\beta} = \int_0^1 -\min_x (H^\beta - H^\alpha) dt$, then the natural map (with respect to the “linear homotopy”) $h_{\alpha\beta} : CF_*(H^\alpha, J : M) \rightarrow CF_*(H^\beta, J : M)$ restricts to a map

$$h_{\alpha\beta} : CF_*^{(-\infty, \lambda]}(H^\alpha, J : M) \rightarrow CF_*^{(-\infty, \lambda + \epsilon^{\alpha\beta})}(H^\beta, J : M)$$

and so induces the homomorphism

$$h^{\alpha\beta} : CF_{(-\infty, \lambda + \epsilon^{\alpha\beta})}^*(H^\beta, J : M) \rightarrow CF_{(-\infty, \lambda]}^*(H^\alpha, J : M).$$

Therefore for any λ , we have the following commutative diagram

$$\begin{array}{ccc} HF^*(H^\alpha, J : M) & \xrightarrow{j_\lambda^*} & HF_{(-\infty, \lambda]}^*(H^\alpha, J : M) \\ \uparrow h^{\alpha\beta} & & \uparrow h^{\alpha\beta} \\ HF^*(H^\beta, J : M) & \xrightarrow{j_{\lambda + \epsilon^{\alpha\beta}}^*} & HF_{(-\infty, \lambda + \epsilon^{\alpha\beta})}^*(H^\beta, J : M) \end{array}$$

where the left hand side arrow is an isomorphism. By naturality of the Floer-Thom isomorphism (2.2) with respect to $h^{\alpha\beta}$ and from the above commutative diagram, for any $u \in H^*(M, \mathbb{Z})$, we derive

$$\rho(H^\beta, u) \leq \rho(H^\alpha, u) + \epsilon^{\alpha\beta},$$

which finishes the proof of the right half of (1). By changing the role of α and β and using the identity

$$\max f = -\min(-f),$$

we have finished the proof of the other half of (1). We refer to [O4] for more details in this argument. Now, it remains to prove (3). We first recall the formula from (3.7)

$$F_{(H\#K)}(u \cup v) = F_H(u) \cup_F F_K(v)$$

and so one can rewrite $\rho(H\#K, u \cup v)$ as

$$(6.4) \quad \rho(H\#K, u \cup v) = \sup_\lambda \{ \lambda \mid j_\lambda^*(F_H(u) \cup_F F_K(v)) = 0 \text{ in } HF_{(-\infty, \lambda]}^*(H\#K, J : M) \}$$

To motivate what we are going to do, we recall how we prove the optimal inequality (8.2) [O4]. We used the *linear* homotopy

$$(1-s)H^\alpha + sH^\beta$$

connecting H^α and H^β . This linear homotopy may not be generic in general but can be approximated by generic paths of Hamiltonians (see [O4]). And all the inequalities we prove are based on the negativity of the kind of term

$$-\int \left| \frac{\partial u}{\partial t} - X_H(u) \right|_J^2 \leq 0.$$

This sort of philosophy is exactly what we need to prove the inequality (6.1).

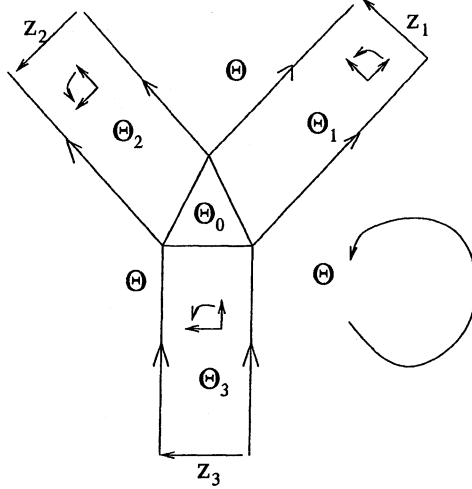


Figure 6

We identify Θ with the piecewise linear domain drawn as above. We recall that the equation on $\mathbb{R} \times [0, 1]$

$$\begin{cases} \frac{\partial u}{\partial \tau} + J \left(\frac{\partial u}{\partial t} - X_H(u) \right) = 0 \\ u(\tau, 0), u(\tau, 1) \in o_M \\ u(-\infty) = z^\alpha \end{cases}$$

is equivalent to

$$(6.5) \quad \begin{cases} \frac{\partial \tilde{u}}{\partial \tau} + J^H \frac{\partial \tilde{u}}{\partial t} = 0 \\ \tilde{u}(\tau, 0) \in \phi_H(o_M), \tilde{u}(\tau, 1) \in o_M \\ \tilde{u}(-\infty) = z^\alpha(1) \in \phi_H(o_M) \cap o_M \end{cases}$$

where

$$\begin{aligned} \tilde{u}(\tau, t) &:= \phi_H^1(\phi_H^t)^{-1} u(\tau, t) \\ J^H(x, t) &:= (\phi_H^1(\phi_H^t)^{-1})_* J(x, t). \end{aligned}$$

Moreover (6.5) can be re-written as

$$(6.6) \quad \bar{\partial}_{J^H} \tilde{u} = 0$$

where

$$\bar{\partial}_{J^H}(\tilde{u})(z) := \frac{T_z \tilde{u} + J^H(\tilde{u}(z), z) \cdot T \tilde{u} \circ i}{2}, \quad z = (\tau, t)$$

An advantage of the equation (6.6) is that it can be written in a coordinate-free form and so can be written on a general domain Θ . Motivated by these discussions, we will choose the perturbed J -holomorphic equation needed in the definition of the pants-product defined in Theorem 3.1, in the following way. We first choose a “smooth” map

$$\phi : \Theta \rightarrow \mathcal{D}_\omega^{ac}(T^*M),$$

that satisfies

- (1) $\phi|_{\partial_1 \Theta} = (\phi_H^1)^{-1}$, $\phi|_{\partial_2 \Theta} = \phi_K^1$ and $\phi|_{\partial_3 \Theta} = id$,
- (2) $\phi|_{\Theta_1}(\tau, t) = \phi_K^1 \circ (\phi_K^t)^{-1}$, $\phi|_{\Theta_2}(\tau, t) = (\phi_H^t)^{-1} = \phi_K^1 \circ (\phi_H^t \circ \phi_K^1)^{-1}$,
 $\phi|_{\Theta_3}(\tau, t) = \phi_K^1 (\phi_H^t \circ \phi_K^t)^{-1}$
- (3) On the center triangle, we define

$$\phi_{\vec{z}} := \phi_K^1 \circ (\phi_H^t \circ \phi_K^s)^{-1}$$

where $\vec{z} \in \Theta_0$ is the point pictured as below. Here $\mathcal{D}_\omega^{ac}(T^*M)$ is as in the notation (6) in the introduction. It is easy to check that the family of almost complex structures $(\phi_{\vec{z}})_* J$ naturally extends J_H , J_K and $J^{H\#K}$ on $\Theta \setminus \Theta_0$ to the whole Θ .

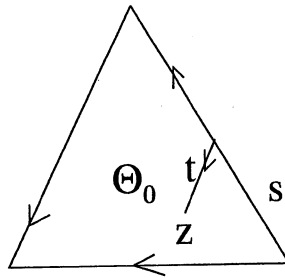


Figure 7

Now, we impose on u that u satisfy the equation

$$(6.7) \quad \begin{cases} \bar{\partial}_{(\phi_{\bar{z}})_* J} \tilde{u} = 0, & \tilde{u} = \phi_{\bar{z}} \circ u \\ \tilde{u}(\partial_1 \Theta) \subset (\phi_H)^{-1}(o_M) = \phi_{\bar{H}}(o_M) \\ \tilde{u}(\partial_2 \Theta) \subset \phi_K(o_M), & \tilde{u}(\partial_3 \Theta) \subset o_M \end{cases}$$

(6.7) is the equation we use in the definition of our pants product given in Section 4. Note that if we restrict (6.7) to each Θ_i , it is equivalent to the equation (6.4). Furthermore, we have

$$\begin{aligned} \tilde{u}_1(+\infty) &= z_1(1) \in \phi_K(o_M) \cap o_M \\ \tilde{u}_2(+\infty) &= \phi_H^{-1}(z_2(1)) \in \phi_H^{-1}(o_M) \cap o_M \\ \tilde{u}_3(-\infty) &= \phi_H^{-1}(z_3(1)) \in \phi_H^{-1}(o_M) \cap \phi_K(o_M). \end{aligned}$$

all of which are *constant* paths. We also note that since \tilde{u} satisfies (6.7), we have

$$(6.8) \quad \int_{\Theta} \tilde{u}^* \omega = \int |\partial_{(\phi_{\bar{z}})_* J} \tilde{u}|_{(\phi_{\bar{z}})_* J}^2 \geq 0.$$

This is exactly the reason why we choose (6.7) as the required equation in the pants-product. On the other hand, since $\omega = -d\theta$ where θ is the canonical one form on T^*M , we have by Stokes' theorem,

$$\int_{\Theta} \tilde{u}^* \omega = \int_{\Theta} (\phi_H \circ \tilde{u})^* \omega = - \int_{\partial \Theta} (\phi_H \circ \tilde{u}|_{\partial \Theta})^* \theta$$

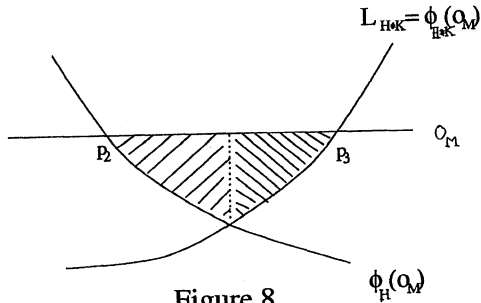


Figure 8

which becomes symplectic area of the shaded region in the picture. Since each $\tilde{u}(\partial_i \Theta)$ lies in a *fixed* Lagrangian submanifold, we apply (2.25) in [O4]

$$d\mathcal{A}_H(z_H^p)(\xi_H^v) = \theta(p)(v)$$

and re-write the above area (after taking the orientation into consideration) as

$$(6.9) \quad \int_{\Theta} \tilde{u}^* \omega = \mathcal{A}_{H\#K} \left(z_{H\#K}^{p_3} \right) - \mathcal{A}_{H\#K} \left(z_{H\#K}^{\phi_H(p_1)} \right) \\ + \mathcal{A}_H \left(z_H^{\phi_H(p_1)} \right) - \mathcal{A}_H \left(z_H^{p_2} \right).$$

This proves Theorem 3.5 which we promised to prove in this section. In fact, the identity (6.9) can be generalized to the domains Θ with arbitrary number of ends which will imply some generalized version of the inequality (6.2) under the higher order Massey product. Since we will not need this general identity in this paper, we will not discuss further about this generalization.

Now, we further analyze the two middle terms in (6.9).

Lemma 6.5. *We have*

$$(6.10) \quad \mathcal{A}_{H\#K} \left(z_{H\#K}^{\phi_H(p_1)} \right) - \mathcal{A}_H \left(z_H^{\phi_H(p_1)} \right) = \mathcal{A}_K \left(z_K^{p_1} \right) + \epsilon(K, p_1)$$

where

$$\epsilon(K, p_1) = \int_0^1 \int_0^1 K \left(z_{(1-s)K}^{p_1}(t), t \right) ds dt - \int_0^1 K \left(z_K^{p_1}(t), t \right) dt.$$

In particular when K is autonomous, we have $\epsilon(K, p_1) \equiv 0$ for all $p_1 \in \phi_K(o_M) \cap o_M$.

Assuming this lemma for the moment, we proceed with the proof. Combining (6.8)–(6.10), we have proven that

$$\mathcal{A}_{H\#K} \left(z_{H\#K}^{p_3} \right) - \mathcal{A}_K \left(z_K^{p_1} \right) - \mathcal{A}_H \left(z_H^{p_2} \right) - \epsilon(K, p_1) \geq 0$$

i.e.

$$(6.11) \quad \mathcal{A}_{H\#K} \left(z_{H\#K}^{p_3} \right) \geq \mathcal{A}_K \left(z_K^{p_1} \right) + \mathcal{A}_H \left(z_H^{p_2} \right) + \epsilon(K, p_1)$$

whenever (6.7) has a solution with the asymptotic condition given. We denote

$$\epsilon(K) = \inf_{p \in \phi_K(o_M) \cap o_M} \epsilon(K, p).$$

Then it follows from the definition

$$|\epsilon(K)| \leq \|K\|,$$

and that for the autonomous K 's, $\epsilon(K) = 0$.

Now, we have to interpret the inequality (6.11) in terms of the wanted inequality (6.1). We consider the diagram (3.7)

$$\begin{array}{ccc}
HF^*(H, J : M) \otimes HF^*(K, J : M) & \xrightarrow{\cup_F} & HF^*(H\#K, J : M) \\
\uparrow F_H \otimes F_K & & \uparrow F_{H\#K} \\
H^*(M, \mathbb{Z}) \otimes H^*(M, \mathbb{Z}) & \xrightarrow{\cup} & H^*(M, \mathbb{Z})
\end{array}$$

First if $u \cup v = 0$, then $\rho(u \cup v, H) = \infty$ by definition, the inequality is obviously true. Therefore, we assume that $u \cup v \neq 0$ and so $F_{(H,J)}(u \cup v) \neq 0$ since $F_{(H,J)}$ is an isomorphism. To prove (6.1) and Theorem I (1), it will be enough to prove from (6.3) that *whenever*

$$\lambda < \rho(H, u) + \rho(K, v) + \epsilon(K),$$

then

$$j_\lambda^*(F_H(u) \cup_F F_K(v)) = 0.$$

For such λ , there exists some λ_1 and λ_2 such that $\lambda_1 < \rho(H, u)$, $\lambda_2 < \rho(K, v)$ or $\lambda_2 < \rho(H, u)$, $\lambda_1 < \rho(K, v)$, and $\lambda < \lambda_1 + \lambda_2 + \epsilon(K)$. We only consider the first case since the other case will be proved in the same way by switching the role of λ_1 and λ_2 . By definition of ρ , we have

$$(6.12) \quad j_{\lambda_1}^*(F_H(u)) = 0 \quad \text{and} \quad j_{\lambda_2}^*(F_K(v)) = 0$$

Now let $a \in CF^*(H, J : M)$, $b \in CF^*(K, J : M)$ be the cocycles with $[a] = F_H(u)$, $[b] = F_H(v)$ respectively and consider the contraction cycle

$$(6.13) \quad \langle a \otimes b, \Psi_\Theta(\vec{H}, J) \rangle = \sum n_\Theta(\vec{H}, J; \vec{z}) a(z_1) b(z_2) \tilde{z}_3.$$

(6.12) implies that we can choose the representative cocycles a and b satisfying

$$a(z_1) = 0 \quad \text{and} \quad b(z_2) = 0$$

whenever $\mathcal{A}_H(z_1) < \lambda_1$ and $\mathcal{A}_H(z_2) < \lambda_2$ respectively. Therefore only those z_1, z_2 with $\mathcal{A}_H(z_1) > \lambda_1$ and $\mathcal{A}_H(z_2) > \lambda_2$ can give non-trivial contribution in (6.13). Furthermore if $n_\Theta(\vec{H}, J; \vec{z}) \neq 0$, then by (6.11)

$$\begin{aligned}
\mathcal{A}_{H\#K}(z_3) &\geq \mathcal{A}_K(z_1) + \mathcal{A}_H(z_2) + \epsilon(K) \\
&> \lambda_1 + \lambda_2 + \epsilon(K)
\end{aligned}$$

and so

$$\mathcal{A}_{H\#K}(\tilde{z}_3) < -\lambda_1 - \lambda_2 - \epsilon(K).$$

And hence

$$\langle a \otimes b, \Psi_\Theta(\vec{H}, J) \rangle \in CF_{n-(k+\ell)}^{(-\infty, -\lambda_1 - \lambda_2 - \epsilon(K))}(\widetilde{H\#K} : M).$$

Therefore we have from the definition of $\sigma_{(H,J)}$ that the cocycle

$$\sigma_{(H\#K,J)}\langle a \otimes b, \Psi_\Theta(\vec{H}, J) \rangle$$

becomes zero when restricted to

$$CF_{(k+\ell)}^{(-\infty, \lambda_1 + \lambda_2 + \epsilon(K))}(H\#K : M)$$

This implies

$$j_{(\lambda_1 + \lambda_2 + \epsilon(K))}^*(F_H(u) \cup F_H(v)) = 0 \quad \text{in} \quad HF_{(-\infty, \lambda_1 + \lambda_2 + \epsilon(K))}^{(k+\ell)}(H\#K : M).$$

and so $j_\lambda^*(F_H(u) \cup F_H(v)) = 0$ since we assumed $\lambda < \lambda_1 + \lambda_2 + \epsilon(K)$. This finally finishes the proof of Theorem 6.4 (Theorem II (5)). Note that we have also proven Theorem I (1) as well.

Proof of Lemma 6.5. We connect the Hamiltonians $H\#K$ and H by the path $s \mapsto H^s$ by

$$H^s(x, t) := H\#((1-s)K)(x, t) = H(x, t) + (1-s)K((\phi_H^t)^{-1}(x), t)$$

and the curves $z_{H\#K}^{\phi_H(p_1)}$ and $z_H^{\phi_H(p_1)}$ by the path $s \mapsto \gamma^s$,

$$\gamma^s := z_{H\#(1-s)K}^{\phi_H(p_1)}.$$

More explicitly, we can write

$$\begin{aligned} \gamma^s(t) &= \phi_H^t \circ \phi_{(1-s)K}^t((\phi_{(1-s)K}^1)^{-1} \circ (\phi_H^1)^{-1}(\phi_H^1(p_1))) \\ &= \phi_H^t \circ \phi_{(1-s)K}^t((\phi_{(1-s)K}^{-1}(p_1))). \end{aligned}$$

Note that γ^s is a Hamiltonian path of H^s and

$$\gamma^s(1) = \phi_H^1(p_1), \quad \gamma^s(0) = (\phi_{(1-s)K}^{-1}(p_1)) = z_K^{p_1}(s).$$

Here the second identity easily follows from the identity

$$K\#s\bar{K} = (1-s)K$$

which can be proven by a simple computation. Note that $\gamma^s(1)$ is fixed for all $0 \leq s \leq 1$. Now we have

$$(6.14) \quad \mathcal{A}_H \left(z_H^{\phi_H(p_1)} \right) - \mathcal{A}_{H\#K} \left(z_{H\#K}^{\phi_H(p_1)} \right) = \int_0^1 \frac{d}{ds} \mathcal{A}_{H^s}(\gamma^s) ds$$

where we compute

$$(6.15) \quad \frac{d}{ds} \mathcal{A}_{H^s}(\gamma^s) = d\mathcal{A}_{H^s}(\gamma^s) \frac{\partial \gamma^s}{\partial s} + \int_0^1 K \left((\phi_H^t)^{-1}(\gamma^s(t)), t \right) dt.$$

Applying the general variation formula (2.17) in [O4],

$$d\mathcal{A}_H(\gamma)\xi = \int_0^1 (w(\dot{\gamma}, \xi) - dH(\gamma)\xi) - \langle \xi(0), \theta(\gamma(0)) \rangle + \langle \xi(1), \theta(\gamma(1)) \rangle,$$

we get

$$\begin{aligned} d\mathcal{A}_{H^s}(\gamma^s) \frac{\partial \gamma}{\partial s} &= -\left\langle \frac{\partial \gamma^s}{\partial s}(0), \theta(\gamma^s(0)) \right\rangle = -\langle z_K^{p_1}, \theta(z_K^{p_1}) \rangle(s) \\ &= -(z_K^{p_1})^* \theta(s). \end{aligned}$$

And

$$\begin{aligned} \int_0^1 K \left(\phi_H^t \right)^{-1} \gamma^s(t), t \right) dt &= \int_0^1 K \left(\phi_{(1-s)}^t (\phi_{(1-s)K}^1)^{-1}(p), t \right) dt \\ &= \int_0^1 K \left(z_{(1-s)K}^{p_1}(t), t \right) dt. \end{aligned}$$

Therefore, we get by integrating (6.15)

$$\begin{aligned} \int_0^1 \frac{d}{ds} \mathcal{A}_{H^s}(\gamma^s) ds &= -\int_0^1 (z_K^{p_1})^* \theta(s) + \int_0^1 \int_0^1 K \left(z_{(1-s)K}^{p_1}(t), t \right) dt ds \\ &= -\mathcal{A}_K(z_K^{p_1}) + \epsilon(K, p_1) \end{aligned}$$

where for each $p \in \phi_K(o_M) \cap o_M$, $\epsilon(K, p)$ is defined as

$$\epsilon(K, p) = \int_0^1 \int_0^1 K \left(z_{(1-s)K}^p(t), t \right) ds dt - \int_0^1 K \left(z_K^p(t), t \right) dt.$$

Now substituting this into (6.14), we have finished the proof of Lemma 6.5.

□

7. Non-triviality of the invariants.

Note that an immediate consequence of (6.2) applied to $u = 1$ and $v = \mu_M$ is

$$\rho(H, \mu_M) \geq \rho(H, 1).$$

Now as in [V], we define a capacity of L as follows, which is the analogue of Viterbo's in [V].

Definition 7.1 [ρ -capacity]. For any L that is Hamiltonian isotopic to o_M i.e., $L = \phi(o_M)$ for $\phi \in \mathcal{D}_\omega^{ac}(M)$, we define the ρ -capacity of L by

$$\gamma(L) := \rho(H, \mu_M) - \rho(H, 1)$$

for any $H \mapsto L$.

The following is Theorem III (1) which is the analogue of Corollary 2.3 in [V].

Theorem 7.2. *We have*

$$\gamma(L) = 0 \quad \text{if and only if } L = o_M.$$

One can also easily derive from Theorem 6.4 and Theorem 7.2 that the Hofer's distance in (2.10) [O4] is nondegenerate. In fact, we have the inequality

$$(7.1) \quad \gamma(L) \leq d(L, o_M),$$

since we have

$$\rho(H, \mu_M) \leq \int_0^1 -\min H_t dt \quad \text{and} \quad \rho(H, 1) \geq \int_0^1 -\max H_t dt$$

by Theorem 6.4 (1).

Using γ applied to the compactification of the graph of Hamiltonian diffeomorphisms on \mathbb{R}^{2n} as in [V], one can define an invariant $\gamma(\phi)$ of Hamiltonian diffeomorphisms ϕ of \mathbb{R}^{2n} . Then (7.1) has the implication

$$\gamma(\phi) \leq \|\phi\| = \text{Hofer's norm of } \phi,$$

which is the analogue to Corollary 1.2.C. [BP] i.e., the inequality between Hofer's and Viterbo's norm. Here we prove this inequality directly without proving the local flatness.

The rest of this section will be spent to prove Theorem 7.2. It turns out easier to work with the geometric version of the Floer homology to prove Theorem 7.2. We consider the equation

$$(7.2) \quad \begin{cases} \frac{\partial u}{\partial \tau} + J \frac{\partial u}{\partial t} = 0 \\ u(\tau, 0) \in \phi_H(o_M), u(\tau, 1) \in o_M \end{cases}$$

which is the gradient flow of \underline{a}_H normalized as in Section 8 [O4] so that $\mathcal{A}_H(z_H^p) = \underline{a}_H(p)$ for all $p \in \phi_H(o_M) \cap o_M$. Then we have $\tilde{\rho}(H, u) = \rho(H, u)$ for all $u \in H^*(M, \mathbb{Z})$ and in particular

$$\tilde{\rho}(H, \mu_M) - \tilde{\rho}(H, 1) = \rho(H, \mu_M) - \rho(H, 1).$$

Therefore to prove the theorem, it will be enough to prove

$$(7.3) \quad \tilde{\rho}(H, \mu_M) - \tilde{\rho}(H, 1) > 0$$

when $\phi_H(o_M) \neq o_M$. Let $\phi_H(o_M) \neq o_M$ and define

$$d_H := \max\{ |p|_g \mid p \in \phi_H(o_M) \subset T^*M \}$$

which then will be strictly positive. Here $|p|_g$ denotes the induced norm of $p \in T_{\pi(p)}^*M$ with respect to the metric g on M (as a linear functional on $T_{\pi(p)}M$).

By making a C^1 -small perturbation of H into H' , we may assume

$$(7.4) \quad d_{H'} > d_H - \epsilon > 0$$

and

$$(7.5) \quad |\tilde{\rho}(H', u) - \tilde{\rho}(H, u)| \leq \epsilon$$

for all $u \in H^*(M, \mathbb{Z})$, where ϵ can be made arbitrarily small. In fact, (7.5) follows from Theorem 6.4 (2). The following lemma can be proven by a standard argument by contradiction.

Lemma 7.3. *Denote by $B_{\delta_0}(p_0)$ the δ_0 -ball centered at p_0 in T^*M where $p_0 \in \phi_H(o_M)$ is a point with $|p_0| = d_H$. Then there exists constants $c = c(H, J)$ and $\epsilon_0 > 0$ such that for any H' with $\|H' - H\|_{C^1} < \epsilon_0$, we have*

$$(7.6) \quad \mathcal{A}_{H'}(u(-\infty)) - \mathcal{A}_{H'}(u(\infty)) \geq c > 0$$

for any solution u of

$$(7.7) \quad \begin{cases} \frac{\partial u}{\partial \tau} + J \frac{\partial u}{\partial t} = 0 \\ u(\tau, 0) \in \phi_{H'}(o_M), u(\tau, 1) \in o_M \end{cases}$$

such that

$$(7.8) \quad u(0, 0) \in B_{\delta_0}(p_0) \cap \phi_{H'}(o_M).$$

We now recall the definition of the *cap action* by μ_M on $HF_*(\phi_{H'}(o_M), o_M)$ (see [BzR] or [PSS]). This action is the dual version of the cup action $(\cdot) \cup \mu_M$ which we define in Section 5: Pick a generic point $p \in \phi_{H'}(o_M)$ and count the number, denoted by $n_{\{p\}}(z^\alpha, z^\beta)$ of solutions of (7.7) that passes through the point p via the evaluation map from $\mathcal{M}_J(z^\alpha, z^\beta)$. Because of the dimensional reason, we could have $n_{\{p\}}(z^\alpha, z^\beta) \neq 0$ only when

$$\mu(z^\alpha) - \mu(z^\beta) = n.$$

Then we consider the assignment

$$z^\alpha \mapsto \sum_{z^\alpha, z^\beta} n_{\{p\}}(z^\alpha, z^\beta) z^\beta$$

and extend linearly to $CF_*(\phi_{H'}(o_M), o_M)$. The cap action by μ_M on

$$HF_n(\phi_{H'}(o_M), o_M)$$

is then defined by

$$\mu_M \cap_F [z^\alpha] = \sum_{z^\alpha, z^\beta} n_{\{p\}}(z^\alpha, z^\beta) [z^\beta]$$

for $z^\alpha \in CF_n(\phi_{H'}(o_M), o_M)$ and by proving that it descends to

$$HF_n(\phi_{H'}(o_M), o_M).$$

The following lemma can be proven by a straightforward modification of the main theorem of [F3]. We refer to [PSS] or [BzR] for further explanation on the cap action.

Lemma 7.4. *Let K be a generic choice of Hamiltonian. Consider the cap action by $\mu_M \in H^n(M, \mathbb{Z})$ on $HF_n(\phi_K(o_M), o_M)$*

$$\mu_M \cap_F (\cdot) : HF_n(\phi_K(o_M), o_M) \rightarrow HF_0(\phi_K(o_M), o_M).$$

This action becomes an isomorphism with \mathbb{Z} -coefficients (resp. \mathbb{Z}_2 -coefficients) when M is orientable (resp. when M is non-orientable) and restricts to a homomorphism

$$(7.9) \quad \mu_M \cap_F (\cdot) : HF_n^{(-\infty, \lambda)}(\phi_K(o_M), o_M) \rightarrow HF_0^{(-\infty, \lambda)}(\phi_K(o_M), o_M)$$

for any $\lambda \in \mathbb{R}$.

To prove Theorem 7.2, we need to refine (7.9), i.e, we need to decrease the filtration level by a positive amount. Let $a \in CF_n(\phi_{H'}(o_M), o_M)$ and $b \in CF_0(\phi_{H'}(o_M), o_M)$ whose Floer homology class $[a] \in HF_n(\phi_{H'}(o_M), o_M)$ and $[b] \in HF_0(\phi_{H'}(o_M), o_M)$ become the generators respectively. Then we write

$$(7.10) \quad \begin{aligned} [a] &= \left[\sum_{\ell} a_{\ell} z_{\ell} \right] \\ [b] &= \left[\sum_k a_k z_k \right] \end{aligned}$$

where $z_{\ell}, z_k \in \text{Crit}(\underline{a}_H)$ and we assume that $[z_{\ell}] \neq 0 \neq [z_k]$. We define

$$\begin{aligned} C_a &:= \{z_{\ell} \in \text{Crit}(\underline{a}_H) \mid a_{\ell} \neq 0\} \\ C_b &:= \{z_k \in \text{Crit}(\underline{a}_H) \mid a_k \neq 0\} \end{aligned}$$

and the subset of $\phi_{H'}(o_M)$

$$N_{ab} := \{p \in \phi_{H'}(o_M) \mid p = u(0, 0) \text{ for some } u \in \bigcup_{(z_{\ell}, z_k) \in C_{\ell} \times C_k} \mathcal{M}_J(z_{\ell}, z_k)\}.$$

Then from the definition of the cap action, the first statement of Lemma 7.4 implies

$$(7.11) \quad \overline{N_{ab}} = \phi_{H'}(o_M).$$

(See [F3]). Otherwise it is easy to see by choosing a generic point in $\phi_{H'}(o_M) \setminus \overline{N_{ab}}$ that the cap action will be trivial. If we choose the point p from $B_{\delta_0}(p_0) \cap \phi_{H'}(o_M)$, we have

$$\mathcal{A}_{H'}(u(-\infty)) - \mathcal{A}_{H'}(u(+\infty)) \geq c$$

by Lemma 7.3. Therefore it follows that the cap action induces a homomorphism

$$(7.12) \quad \mu_M \cap_F (\cdot) : HF_n^{(-\infty, \lambda)}(\phi_{H'}(o_M), o_M) \rightarrow HF_0^{(-\infty, \lambda - c)}(\phi_{H'}(o_M), o_M)$$

for any $\lambda \in \mathbb{R}$.

Proof of Theorem 7.2. Suppose the contrary, i.e., assume that

$$\rho(H, \mu_M) - \rho(H, 1) = 0.$$

We choose a generic H' that satisfy (7.6) and Lemma 7.3, we have

$$(7.13) \quad 0 \leq \rho(H', \mu_M) - \rho(H', 1) < \epsilon < \frac{c}{2}.$$

We now consider the following commutative diagram

$$\begin{array}{ccc} HF_0^{(-\infty, \lambda - c)}(\phi_{H'}(o_M), o_M) & \xrightarrow{j_*^{(\lambda - c)}} & HF_0(\phi_{H'}(o_M), o_M) \\ \uparrow \mu_M \cap_F (\cdot) & & \uparrow \mu_M \cap_F (\cdot) \\ HF_n^{(-\infty, \lambda)}(\phi_{H'}(o_M), o_M) & \xrightarrow{j_*^\lambda} & HF_n(\phi_{H'}(o_M), o_M) \end{array}$$

The right vertical arrow is an isomorphism by (7.9). From this, we see that whenever the bottom arrow becomes non-zero, the top arrow becomes non-zero. However $\tilde{F}_{H'}(1)$ or $\tilde{F}_{H'}(\mu_M)$ is the generator of HF^0 or HF^n respectively by the Floer-Thom isomorphism and it is easy to check that the non-zerosness of these homomorphisms are equivalent to $j_\lambda^* \tilde{F}_{H'}(1) \neq 0$ or $j_{\lambda - c}^* \tilde{F}_{H'}(\mu_M) \neq 0$ respectively. Here we denote by \tilde{F}_H the Floer-Thom isomorphism for the geometric version of the Floer cohomology

$$\tilde{F}_H : H^*(M, \mathbb{Z}) \rightarrow HF^*(\phi_{H'}(o_M), o_M).$$

Combining these, we have derived

$$\rho(H', \mu_M) \geq \rho(H', 1) + c.$$

This gives rise to a contradiction to (7.13). Therefore the result follows. \square

Appendix: Index computation on $\Theta_{0,1}$.

First, note that the operator glued in the cap in the proof of Theorem 3.3 is of the following type: Consider the domain $\Theta_{0,1} \subset \mathbb{C}$ as drawn in the picture which is conformally a disc with one marked point.

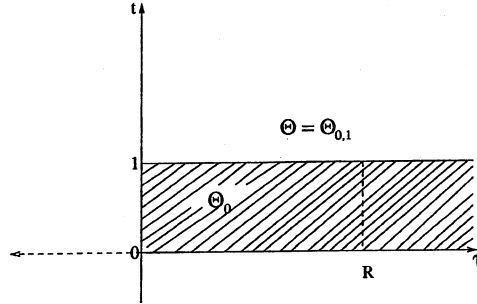


Figure 9

We consider the operator

$$\bar{\partial}_{J,T} = \frac{\partial}{\partial \tau} + J \frac{\partial}{\partial t} + T : W_n^{1,p}(\Theta_{0,1}) \rightarrow L^p(\Theta_{0,1}), \quad p > 2$$

on the space

$$W_n^{1,p} = W_n^{1,p}(\Theta_{0,1}) := \{\zeta \in W^{1,p}(\Theta_{0,1}, \mathbb{C}^n) \mid \zeta(\theta) \in \mathbb{R}^n \text{ for all } \theta \in \partial\Theta_{0,1}\}$$

where J and T satisfy (1)–(4) in Section 5 [O4] as $\tau \rightarrow \infty$. Such an operator $\bar{\partial}_{J,T}$ is a Fredholm operator and so has the Fredholm index. The following index formula is the main theorem we will prove in this appendix.

Theorem A.1. *Let T and J be as above and Ψ_∞ be the solution of*

$$\begin{cases} \frac{\partial \Psi}{\partial t} - J(\infty, t)T(\infty, t)\Psi = 0 \\ \Psi(0) = id. \end{cases}$$

Then we have

$$\text{Index } \bar{\partial}_{J,T} = \mu(\Psi_\infty(t) \cdot \mathbb{R}^n, \mathbb{R}^n) + \frac{n}{2}.$$

One immediate corollary is the following index formula. This can be proved by considering the linearized operator which will have the form of the operator considered as in Theorem A.1 under the trivialization of the type we used in Section 5.1 [O4].

Corollary A.2. *Let $R > 0$ be a real number. Consider the perturbed Cauchy-Riemann equation of the map $u : \Theta_{0,1} \rightarrow T^*M$*

$$\begin{cases} \frac{\partial u}{\partial \tau} + J \left(\frac{\partial u}{\partial t} - X_H(u) \right) = 0, & \text{on } \tau > R + 1 \\ u \text{ satisfying appropriate zero-order perturbation} \\ \text{of the equation } \frac{\partial u}{\partial \tau} + J \frac{\partial u}{\partial t} = 0, & \text{for } \tau \leq R + 1 \end{cases}$$

Then if the Hamiltonian path $z(t) = z_H^p(t)$ for $p \in \phi_H(o_M) \cap o_M$ is regular (i.e., $\phi_H(o_M) \pitchfork o_M$ at p) and so the linearization at u becomes a Fredholm operator, then we have

$$\text{Index } u = -\mu(z) + \frac{n}{2}.$$

The remaining section will be spent to prove Theorem A.1.

By deforming the operators without changing the Fredholm index, we may further assume that for sufficiently large $R > 0$

$$J(\tau, \cdot) = \begin{cases} J(\infty, \cdot) & \text{for } \tau \geq R + 1 \\ i & \text{for } \tau \leq R \end{cases}$$

and

$$T(\tau, \cdot) = \begin{cases} T(\infty, \cdot) & \text{for } \tau \geq R + 1 \\ 0 & \text{for } \tau \leq R \end{cases}$$

We now transform the above operator on $W_{\tilde{\Lambda}}^{1,p}$ to another operator defined on the space

$$W_{\tilde{\Lambda}}^{1,p} = \{ \zeta \in W^{1,p}(\Theta_{0,1}, \mathbb{C}^n) \mid \zeta(\theta) \in \tilde{\Lambda}(\theta) \}$$

where $\tilde{\Lambda} : \partial\Theta_{0,1} \rightarrow \tilde{\Lambda}(n)$ is the path defined as

$$\tilde{\Lambda}(\theta) = \begin{cases} \mathbb{R}^n & \text{if } \theta \in \partial_0\Theta_{0,1} \\ \mathbb{R}^n & \text{if } \theta = (\tau, 0) \text{ for } \tau \leq R + 1 \\ \tilde{\Lambda}_1(\theta) & \text{if } \theta = (\tau, 1) \text{ for } R + 1 \leq \tau \leq R + 2 \\ \Psi(1) \cdot \mathbb{R}^n & \text{if } \theta = (\tau, 1) \text{ for } \tau \geq R + 2. \end{cases}$$

Here $\partial_0\Theta_{0,1}$ is the portion of the boundary of the compact part Θ_0 in $\partial\Theta_{0,1}$ as pictured in Figure 9 and $\tilde{\Lambda}_1 : [R + 1, R + 2] \rightarrow \tilde{\Lambda}(n)$ is a path defined by

$$\tilde{\Lambda}_1(\tau, 1) := \Psi_{\infty}(\rho(\tau - R - 1)) \cdot \mathbb{R}^n \quad \text{for } \tau \geq R - 1$$

and by extending this definition to the whole Θ by setting

$$\tilde{\Lambda}(\theta) \equiv \mathbb{R}^n \quad \text{for } \tau \leq R-1.$$

Here the function $\rho : \mathbb{R} \rightarrow [0, 1]$ is the cut-off function we used before in the main part of this paper.

Note that since we assume that $T \equiv 0$ on $\tau \leq R$, the map $\Psi : [R, \infty) \times [0, 1] \rightarrow Sp(2n)$ defined by

$$\Psi(\tau, t) := \Psi(\rho(\tau - R - 1)t) \quad \text{for } \tau \geq R$$

can be smoothly extended to the whole Θ by setting $\Psi \equiv \text{id}$ for $\tau \leq R$. Therefore we can now define the push-forward operator

$$\Psi_*(\bar{\partial}_{J,T}) = \Psi \circ \bar{\partial}_{J,T} \circ \Psi^{-1} : W_{\tilde{\Lambda}}^{1,p} \rightarrow L^p.$$

Then this push-forward will have the form

$$\bar{\partial}_{J,T,\tilde{\Lambda}} = \frac{\partial}{\partial \tau} + \tilde{J} \frac{\partial}{\partial t} + \tilde{T} : W_{\tilde{\Lambda}}^{1,p} \rightarrow L^p.$$

such that

$$\begin{aligned} \tilde{T} &\equiv 0 && \text{if } \tau \geq R+1 \quad \text{or} \quad \tau \leq R \\ \tilde{J} &\equiv i && \text{if } \tau \leq R \end{aligned}$$

It is obvious that the two operators $\bar{\partial}_{J,T}$ and $\bar{\partial}_{J,T,\tilde{\Lambda}}$ will have the same Fredholm indices and so it is enough to compute the index of $\bar{\partial}_{J,T,\tilde{\Lambda}}$. We recall that we imposed the transversality $\Psi(1) \cdot \mathbb{R}^n \pitchfork \mathbb{R}^n$ and so

$$\tilde{\Lambda}_1(\theta) \pitchfork \mathbb{R}^n \quad \text{for } \theta = (\tau, 1), \quad \tau \geq R+2$$

If we denote

$$\infty_+ = \lim_{\tau \rightarrow \infty} (\tau, 1) \quad \text{and} \quad \infty_- = \lim_{\tau \rightarrow \infty} (\tau, 0)$$

the map $\tilde{\Lambda} : \partial\Theta_{0,1} \rightarrow \tilde{\Lambda}(n)$ satisfies

$$\begin{aligned} \tilde{\Lambda}(\infty_-) &= \tilde{\Lambda}(\tau, R+1) = \mathbb{R}^n && \text{and} && \tilde{\Lambda}(\infty_+) = \Psi(1) \cdot \mathbb{R}^n = \tilde{\Lambda}_1(R+1) \\ \tilde{\Lambda}(\tau, 1) &= \Psi(\rho(\tau - R - 1)) \cdot \mathbb{R}^n && \text{for } R+1 \leq \tau. \end{aligned}$$

By construction, the two paths $t \mapsto \Psi(t) \cdot \mathbb{R}^n$ and $\tau \mapsto \tilde{\Lambda}_1$ are homotopic with the same fixed end points and so have the same Maslov indices, i.e.,

$$(A.1) \quad \mu(\tilde{\Lambda}_1, \mathbb{R}^n) = \mu(\Psi \cdot \mathbb{R}^n, \mathbb{R}^n).$$

Using the stratum-homotopy invariance of the Maslov index, Theorem 2.4 [RS1], we can deform the operator $\bar{\partial}_{J,T,\Lambda}$ without changing the Fredholm property and without changing the Maslov indices of $\tilde{\Lambda}$ into

$$\bar{\partial}_{i,0,\Lambda} = \frac{\partial}{\partial \tau} + i \frac{\partial}{\partial t} = \bar{\partial} : W_{\Lambda}^{1,p} \rightarrow L^p$$

where $\Lambda : \partial\Theta_{0,1} \rightarrow \Lambda(n)$ is defined as

$$\Lambda(\theta) = \begin{cases} \mathbb{R}^n & \text{if } \theta = (\tau, 0) \\ D(t) \cdot \mathbb{R}^n & \text{if } \theta = (t, 0) \\ i \cdot \mathbb{R}^n & \text{if } \theta = (\tau, 1) \end{cases}$$

with

$$D(t) = \begin{pmatrix} e^{-(\ell + \frac{1}{2})\pi it} & & & 0 \\ & e^{-\frac{1}{2}\pi it} & & \\ & & \ddots & \\ 0 & & & e^{-\frac{1}{2}\pi it} \end{pmatrix}$$

for some integer ℓ . Here we identify $\Theta_{0,1}$ with the semi-strip as drawn below.

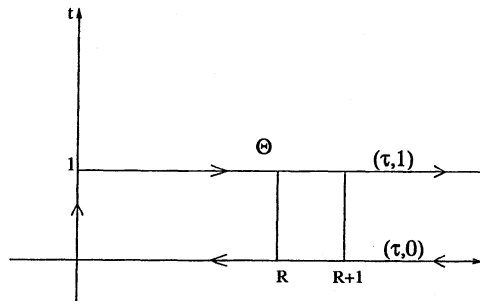


Figure 10

Noting that both the operator $\bar{\partial}$ and the boundary condition Λ both are *separable*, we have reduced the computation of the index into the one-dimensional problem below. Recall that both Fredholm index of $\bar{\partial}_{i,0,\Lambda}$ and the Maslov index of Λ are additive under the direct sum.

We now study the following equation in one-dimension

$$(*) \quad \begin{cases} \bar{\partial}\zeta = 0 & (A.2) \\ \zeta(\tau, 0) \in \mathbb{R}, \quad \zeta(\tau, 1) \in i\mathbb{R} & (A.3) \\ \zeta(0, t) \in e^{-(\ell + \frac{1}{2})\pi it} \mathbb{R} & (A.4) \end{cases}$$

Note that ζ satisfying (A.2), (A.3) and $\int |D\zeta|^2 < \infty$ must have the form

$$\zeta(z) = \sum_{k=1}^{\infty} a_k e^{-(k-\frac{1}{2})\pi z}, \quad a_k \in \mathbb{R} \quad \text{and } z \in \Theta_{0,1}.$$

This becomes

$$\zeta(0, t) = \sum_{k=1}^{\infty} a_k e^{-(k-\frac{1}{2})\pi i t}$$

on $\{0\} \times [0, 1]$. Since (A.4) implies

$$e^{(\ell+\frac{1}{2})\pi i t} \zeta(0, t) \in \mathbb{R},$$

we have

$$\sum_{k=1}^{\infty} a_k e^{-(k-\ell-1)\pi i t} \in \mathbb{R}.$$

Equivalently, we have

$$(A.5) \quad \sum_{k=-\ell}^{\infty} a_{k+\ell+1} e^{-k\pi i t} \in \mathbb{R}.$$

We consider two cases where $\ell \geq 0$ and $\ell \leq -1$ separately. First, let us assume that $\ell \geq 0$. Then from (A.5), we derive

$$\begin{aligned} a_{k+\ell+1} &= 0 & \text{if } k &\geq \ell + 2 \\ a_{\ell+1} & & \text{arbitrary} \\ a_{k+\ell+1} &= a_{-k+\ell+1} & \text{if } -\ell &\leq k \leq -1 \end{aligned}$$

i.e.,

$$\begin{aligned} a_k &= 0 & \text{if } k &\geq \ell + 2 \\ a_{\ell+1} & & \text{arbitrary} \\ a_k &= a_{-k+2(\ell+1)} & \text{if } 1 &\leq k \leq \ell \end{aligned}$$

On the other hand if $\ell \leq -1$, it immediately follows from (A.5) that (*) has no non-trivial solution. Hence if we denote by $\text{Ker}[*]$ the solution space of the equation (*), then we have

$$(A.6) \quad \dim \text{Ker}[*] = \begin{cases} \ell + 1 & \text{if } \ell \geq 0 \\ 0 & \text{if } \ell \leq -1 \end{cases}$$

Now let us study the L^2 -adjoint problem of (*);

$$(**) \quad \begin{cases} \partial\eta = 0, & (A.7) \\ \eta(\tau, 0) \in \mathbb{R}, \quad \eta(\tau, 1) \in i\mathbb{R} & (A.8) \\ i\eta(0, t) \in e^{-(\ell + \frac{1}{2})\pi it} \cdot \mathbb{R} & (A.9) \end{cases}$$

and denote by $\text{Coker}[*]$ the solution space of (**). This equation can be derived by taking the L^2 -inner product (*) with η and then by integrating by parts. It follows from (A.7), (A.8) and $\int |D\eta|^2 < \infty$ that η must have the form

$$\eta(z) = \sum_{j=1}^{\infty} b_j e^{-(j - \frac{1}{2})\pi \bar{z}}, \quad b_j \in \mathbb{R}.$$

By substituting $z = (0, t)$ into this, we get

$$\eta(0, t) = \sum_{j=1}^{\infty} b_j e^{(j - \frac{1}{2})\pi it}, \quad b_j \in \mathbb{R}.$$

Condition (A.9) is equivalent to

$$ie^{(\ell + \frac{1}{2})\pi it} \eta(0, t) \in \mathbb{R} \quad \text{i.e.,} \quad \sum_{j=1}^{\infty} ib_j e^{(j+\ell)\pi it} \in \mathbb{R}$$

and hence we have derived

$$(A.10) \quad \sum_{j=\ell+1}^{\infty} ib_{j-\ell} e^{j\pi it} \in \mathbb{R}.$$

From this, we immediately conclude that if $\ell \geq 0$, then (**) has no non-trivial solution. When $\ell \leq -1$, we derive from (A.10)

$$\begin{aligned} b_{j-\ell} &= 0 & \text{if } j &\geq -\ell \\ b_{-\ell} &= 0 \\ b_{j-\ell} &= -b_{-j-\ell} & \text{if } 1 \leq j &\leq -\ell - 1 \end{aligned}$$

From this, we conclude that

$$(A.11) \quad \dim \text{Coker}[*] = \begin{cases} 0 & \text{if } \ell \geq 0 \\ -\ell - 1 & \text{if } \ell \leq -1 \end{cases}$$

Combining (A.6) and (A.11), we have proven

$$(A.12) \quad \text{Index}[*] = \dim \text{Ker}[*] - \dim \text{Coker}[*] = \ell + 1$$

for all ℓ . By applying (A.12) for $\ell = 0$ and adding the contributions from other components of $D(t)$, we get

$$(A.13) \quad \text{Index} \bar{\partial}_{i,0,\Lambda} = \ell + 1 + (n - 1) = \ell + n$$

We now compute the Maslov index $\mu(D(t) \cdot \mathbb{R}^n, \mathbb{R}^n)$ of the path

$$t \mapsto D(t) \cdot \mathbb{R}^n.$$

By the additivity of the Maslov index under the direct sum operation, we have

$$(A.14) \quad \mu(D(t) \cdot \mathbb{R}^n, \mathbb{R}^n) = \mu\left(e^{-i(\ell + \frac{1}{2})\pi t} \cdot \mathbb{R}, \mathbb{R}\right) + (n - 1)\mu\left(e^{-\frac{\pi}{2}it} \cdot \mathbb{R}, \mathbb{R}\right).$$

However, it is easy to check from the definition of the Maslov index from [RS1], we have

$$\mu\left(e^{-i(\ell + \frac{1}{2})\pi t} \cdot \mathbb{R}, \mathbb{R}\right) = \ell + \frac{1}{2}.$$

By applying this to $\ell = 0$ for the second term in (A.14) as well, we conclude that

$$(A.15) \quad \mu(D \cdot \mathbb{R}^n, \mathbb{R}^n) = \ell + \frac{n}{2}.$$

However from (A.1) and from the way how we deform the operators afterwards, we have

$$\mu(\Psi \cdot \mathbb{R}^n, \mathbb{R}^n) = \mu(D \cdot \mathbb{R}^n, \mathbb{R}^n)$$

which finally finishes Theorem A.1.

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