Flat connections, the Alexander invariant, and Casson's invariant

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This paper explores the relationship between the flat moduli space of a homology knot complement and other topological invariants of the knot. We define an invariant by counting the flat orbits with trace of the meridinal holonomy fixed and give a formula for the invariant in terms of the Tristam-Levine equivariant knot signature and the Casson invariant of the homology 3-sphere in which the knot lives.

Casson defined a topological invariant, now known as the Casson invariant, for closed oriented homology 3-spheres which, roughly speaking, counts (one half) the number of irreducible representations from the fundamental group of the 3-manifold into SU(2) modulo conjugation (see [AM]). Shortly thereafter, Taubes provided an analytic definition of the same invariant, counting instead flat SU(2) connections modulo gauge equivalence (see [T]). These papers, along with related ones by Walker [Wa] and Floer [F], have inspired a long list of papers both from the topological viewpoint and from the gauge theoretic one.

In 1992, Lin defined an S^3 knot invariant by counting the number of trace-free irreducible representations of the knot group into SU(2) modulo conjugation (see [Li]). Here trace-free means that all knot meridians are taken to trace-free matrices. He then showed by a clever topological argument that this invariant equals one half of the knot signature. Ruberman suggested a generalization of this result involving equivariant knot signature which removed the trace-free condition. For the case of 2-bridge knots, a similar formula was conjectured by Heusener in [He].

The aim of this article is to establish a general formula for arbitrary knots in homology 3-spheres. In the special case of knots in S^3 , this proves the formula suggested by Ruberman. Our main result states that if $\kappa: S^1 \to X$ is a smooth knot in an oriented homology 3-sphere then (under certain transversality assumptions) the number of conjugacy classes of nonabelian representations $\rho: \pi_1(X \setminus \kappa) \to SU(2)$ taking the meridians to matrices of trace $2\cos\alpha$ equals minus four times the Casson invariant of X minus one

half the Tristam-Levine knot signature $\operatorname{Sign} B_{\kappa}(e^{i2\alpha})$. The conjugacy classes are counted with signs corresponding to oriented intersection numbers.

The techniques used in this paper are gauge theoretic rather than topological. In particular, we consider flat SU(2) connections modulo gauge equivalence, rather than fundamental group representations to SU(2) modulo conjugation. The association taking each flat connection to its holonomy representation gives an identification of the flat moduli space with the space of representations modulo conjugation.

The general picture is as follows. Let Y be the complement of an open tubular neighborhood of a smooth knot κ in an oriented homology sphere X. Let \mathcal{M} denote the space of flat connections on Y modulo gauge equivalence, and let \mathcal{M}^* denote the subset consisting of equivalence classes of *irreducible* connections. My work in [H1] and [H2] shows that after a small perturbation of the flatness equation, if necessary, \mathcal{M}^* is a smooth 1-manifold, compact except for open ends which limit to interior points in the abelian moduli space $\mathcal{M} \setminus \mathcal{M}^*$, which is an arc.

There is a natural restriction map r from \mathcal{M} to \mathcal{M}_{T^2} , the flat moduli space for the boundary torus. This moduli space is the "pillowcase" orbifold T^2/\mathbb{Z}_2 , which is topologically a 2-sphere. Equivalence classes of irreducible flat connections on Y whose holonomy representations take knot meridians to matrices of trace $2\cos\alpha$ correspond to points in $r^{-1}(S_\alpha)$ for a certain circle $S_\alpha \subset \mathcal{M}_{T^2}$. Thus the points to be counted are intersections between the immersion $r: \mathcal{M}^* \to \mathcal{M}_{T^2}$ and the circle S_α .

The signs of the intersections are determined by considering the double cover $\tilde{\mathcal{M}}^*$ of \mathcal{M}^* . In the second section we describe a method by which $\tilde{\mathcal{M}}^*$ is given a natural orientation, once one is chosen on $H^1(Y;\mathbf{R})$. There is a corresponding restriction map $\tilde{r}: \tilde{\mathcal{M}} \to \tilde{\mathcal{M}}_{T^2} = T^2$. The intersection points to be counted correspond in a one-to-one fashion with $\tilde{r}^{-1}(\tilde{S}_{\alpha}) \cap \tilde{\mathcal{M}}^*$, where \tilde{S}_{α} is one component in the double cover of S_{α} . An orientation on \tilde{S}_{α} is also determined by the ones on $H^1(Y;\mathbf{R})$. The last piece of information we need is an orientation on $\tilde{\mathcal{M}}_{T^2}$. Its tangent space is canonically isomorphic to $H^1(\partial Y;\mathbf{R})$ and so receives an orientation from Poincaré duality on ∂Y , oriented as the boundary of $Y \subset X$. We adopt the convention that an oriented basis for $T_x \partial Y$ followed by an outward normal vector gives an oriented basis for $T_x Y$.

Several more pieces of notation are necessary to state our main theorem. Choose a Seifert surface F for κ and fix an oriented normal vector field on F. Choose a basis of curves $\{x_i\}_{1\leq i\leq 2g}$ for $H_1(F;\mathbf{R})$ and let x_i^+ denote the pushoff of x_i in the positive normal direction. We then define the Seifert pairing V to be the matrix with entries $V_{ij} = \operatorname{link}(x_i, x_i^+)$. We use this to define, for

each unit complex number t, a matrix $B_{\kappa}(t) = (1-t)V + (1-t^{-1})V^{T}$. The signature of this Hermitian matrix is called the Tristam-Levine signature of the knot and is a function from U(1) to \mathbf{Z} . The matrix $B_{\kappa}(t)$ is related to the symmetrized Alexander matrix $A_{\kappa}(t) = t^{\frac{1}{2}}V - t^{-\frac{1}{2}}V^{T}$ by

$$(t^{-\frac{1}{2}}-t^{\frac{1}{2}})A_{\kappa}(t)=B_{\kappa}(t),$$

and the Alexander polynomial of the knot is

$$\Delta_{\kappa}(t) = \det(V^T - tV) = (1 - t^{-1})^{-2g} \det(B_{\kappa}(t)).$$

Our main theorem is the following, where $\lambda(X)$ denotes the Casson invariant of X (see [AM] and [T]).

Theorem 0.1. For any $0 < \alpha < \pi$ with $\Delta_{\kappa}(e^{i2\alpha}) \neq 0$, if \mathcal{M} is nondegenerate, then

$$\tilde{r}(\tilde{\mathcal{M}}^*) \cdot \tilde{S}_{\alpha} = -4\lambda(X) - \frac{1}{2} \mathrm{Sign} B_k(e^{i2\alpha}).$$

If \mathcal{M} is degenerate, then after a small perturbation of the flatness equation this formula holds.

Remark: The intersection number on the left side of the formula is the number of flat orbits in \mathcal{M}_h^* with $\operatorname{tr}(\operatorname{hol}_\mu(A)) = 2\cos\alpha$, counted with signs. We only state the formula in terms of the double cover because doing so allows us to interpret the correct signs as oriented intersection numbers. We will also see that the Casson invariant has an interpretation as an oriented intersection number, namely, $-\frac{1}{4}\tilde{r}(\tilde{\mathcal{M}}^*)\cdot \tilde{S}_0$. This collection of intersections corresponds to the double cover of the set of orbits of connections on Y which may be extended to flat connections on X.

As a special case, when κ is a knot in S^3 , we get the generalization of Lin's theorem suggested by Ruberman.

Corollary 0.2. Let Y be the complement of a knot κ in S^3 . Then for any $0 < \alpha < \pi$ with $B_{\kappa}(e^{i2\alpha})$ invertible, if M is nondegenerate, $\tilde{r}(\tilde{\mathcal{M}}^*) \cdot \tilde{S}_{\alpha} = -\frac{1}{2}\mathrm{Sign}B_{\kappa}(e^{i2\alpha})$. If M is degenerate, then after a small perturbation this formula holds.

We have learned from David Austin that he has independently found a proof of a result similar to Corollary 3, but his proof is more along the lines of Akbulut and McCarthy's treatment of the Casson invariant (see [AM]). **Acknowledgements:** I would like to express my gratitude to my thesis advisor Tom Mrowka, who first suggested this problem to me and with

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1. Background and Notation.

In this section we review the basic gauge theory setup and the generic structure of the flat (or perturbed flat) moduli space for a knot complement. This material is described in full detail in [H1] and [H2].

Let κ be a smooth knot in an oriented homology sphere X with open tubular neighborhood $\nu(\kappa)$. Set $Y = X \setminus \nu(\kappa)$, with the orientation inherited from X. We fix a Riemannian metric on Y, and let $*: \Omega^p(Y; su(2)) \to \Omega^{3-p}(Y; su(2))$ be the Hodge star operator.

We consider the trivial SU(2) bundle $P=Y\times SU(2)$. By fixing a trivialization of P we obtain an identification of the space of SU(2) connections on Y with $\Omega^1(Y;su(2))$, the space of 1-forms on Y with su(2) values. Let \mathcal{A} denote the completion of this space with respect to the L^2_2 Soboloev norm. The gauge group in this context is $\mathcal{G}=\operatorname{Map}(Y,SU(2))$, completed with the L^2_3 norm. \mathcal{A}_{T^2} , and \mathcal{G}_{T^2} are defined similarly, using the $L^2_{\frac{3}{2}}$ and $L^2_{\frac{5}{2}}$ norms, respectively. In this paper we will not be explicit about Sobolev norms.

SU(2) connections may be divided into classes according to the size of their stabilizer, which is isomorphic to \mathbf{Z}_2 , U(1), or SU(2). Such connections are called irreducible, abelian, and central, respectively. (Note that according to this definition, abelian and central are mutually exclusive.) It is useful to divide \mathcal{A} into $\mathcal{A} = \mathcal{A}^* \cup \mathcal{A}^{U(1)}$ where \mathcal{A}^* denotes the set of irreducible connections and $\mathcal{A}^{U(1)}$ denotes the set of reducible (that is, abelian or central) connections. Similarly we divide the space of gauge equivalence classes $\mathcal{B} = \mathcal{A}/\mathcal{G}$ into $\mathcal{B} = \mathcal{B}^* \cup \mathcal{B}^{U(1)}$.

To each connection A is associated its curvature 2-form, $F(A) = dA + A \wedge A \in \Omega^2(Y; su(2))$, and the connection A is said to be flat if its curvature is zero. The flat moduli space $\mathcal{M} = \{A \in \mathcal{A} | F(A) = 0\}/\mathcal{G}$ of Y is the object of primary interest in this paper. It has a topological interpretation as $\text{Hom}(\pi_1(Y), SU(2))/SU(2)$, the set of fundamental group representations modulo conjugation.

The flat moduli space of a knot complement is in general a very singular space and hence is difficult to work with (although interesting results have been proven using the its real algebraic structure, for example in [He]). For this reason, we define a class of admissible perturbations of the flatness equation as follows.

Let $\{\gamma_i: S^1 \times D^2 \to Y\}_{1 \leq i \leq n}$ be a collection of embeddings of the solid torus into Y whose images are disjoint. Let η be the product of a nonnegative bump function on D^2 with support in the interior and the standard volume form on D^2 . Let $\{\overline{h}_i: \mathbf{R} \to \mathbf{R}\}_{1 \leq i \leq n}$ be a collection of C^2 functions. Let $\mathrm{tr} \ \mathrm{hol}_{\gamma_i}(x,A)$ be the trace of the holonomy of the connection A around the curve $\gamma_i(S^1 \times \{x\})$. We define a function $h: \mathcal{A} \to \mathbf{R}$ by the formula

$$h(A) = \sum_{i=1}^n \int_{D^2} \overline{h}_i(\operatorname{tr} \, \operatorname{hol}_{\gamma_i}(x,A)) \eta(x).$$

Definition 1. A function h constructed in this way is called an **admissible** perturbation function.

Given an admissible perturbation $h: \mathcal{A} \to \mathbf{R}$, we define a function $\zeta_h(A): \mathcal{A} \to \Omega^1(Y; su(2))$ by

$$\zeta_h(A) = -\frac{1}{2\pi} * F(A) + \nabla h(A).$$

Definition 2. We say that a connection A is **perturbed flat** (with respect to a perturbation h) if it satisfies the equation $\zeta_h(A) = 0$. The **perturbed flat moduli space** is the quotient $\mathcal{M}_h = \zeta_h^{-1}(0)/\mathcal{G}$. We also decompose this into the set of irreducible orbits $\mathcal{M}_h^* = \mathcal{M}_h \cap \mathcal{B}^*$ and the reducible orbits $\mathcal{M}_h^{U(1)} = \mathcal{M}_h \cap \mathcal{B}^{U(1)}$.

One point should be made about the notation. The flat moduli space of Y or its strata will generally be denoted by \mathcal{M}_h , \mathcal{M}_h^* , and $\mathcal{M}_h^{U(1)}$, with no further adornment. We will denote the corresponding moduli spaces of a 3-manifold M which is different from Y by $\mathcal{M}_h(M)$, $\mathcal{M}_h^*(M)$, and $\mathcal{M}_h^{U(1)}(M)$.

We will denote the flat moduli space for the torus by \mathcal{M}_{T^2} . The holonomy representation of any flat connection on T^2 is abelian, so its image lies in a maximal torus $U(1) \subset SU(2)$. Any such maximal torus in SU(2) can be conjugated to itself with the reverse orientation. Thus,

$$\mathcal{M}_{T^2} = \operatorname{Hom}(\pi_1(T^2), SU(2))/Ad = \operatorname{Hom}(\mathbf{Z} \oplus \mathbf{Z}, U(1))/\mathbf{Z}_2 = T^2/\mathbf{Z}_2.$$

This flat moduli space is topologically a 2-sphere with four distinguished points, namely the fixed points of the involution (the central orbits).

Given a connection A which is perturbed flat with respect to an admissible perturbation h, we will define associated absolute and relative cohomology groups, denoted by $\mathcal{H}^1_{A,h}(Y;su(2))$ and $\mathcal{H}^1_{A,h}(Y,\partial Y;su(2))$, in Section

3. Roughly, they arise as the kernel and cokernel of the linearization of the perturbed flatness equation. When h = 0, these correspond to cohomology with coefficients in the twisted su(2) bundle of the flat connection.

Definition 3. We will say that \mathcal{M}_h is **nondegenerate** if it satisfies the following 5 properties (and otherwise **degenerate**):

- (a) The only orbits in \mathcal{M}_h which are central when restricted to ∂Y are central on Y.
- (b) For each central connection A, $\mathcal{H}^1_{A,h}(Y,\partial Y;su(2))=0$.
- (c) For finitely many noncentral orbits $[A] \in \mathcal{M}_h^{U(1)}$, $\dim \mathcal{H}_{A,h}^1(Y, \partial Y; su(2)) = 2$ and Stab A acts nontrivially on $\mathcal{H}_{A,h}^1(Y, \partial Y; su(2))$. For all remaining noncentral abelian orbits $\dim \mathcal{H}_{A,h}^1(Y, \partial Y; su(2)) = 0$.
- (d) At each abelian orbit where there is nontrivial relative first cohomology the family of symmetric matrices H_t (defined below) has transverse spectral flow.
- (e) For each $[A] \in \mathcal{M}_h^*$, dim $\mathcal{H}_{A,h}^1(Y,\partial Y;su(2)) = 1$.

Conditions (a) and (b) clearly hold for h=0, and they continue to hold for small h. Condition (c) insures that $\mathcal{M}_h^{U(1)}$ is a smooth 1-manifold, even at the points where the cohomology jumps. In fact, for h small, $\mathcal{M}_h^{U(1)}$ consists of a single component connecting the two central orbits.

To define the matrix H_t in condition (d) we first choose a family of connections A_t whose orbits parametrize an open set in $\mathcal{M}_h^{U(1)}$ and with $\dim(\mathcal{H}_{A_0,h}^1(Y;\partial Y;su(2)))=2$. Let V denote the orthogonal complement of $T_{[A_0]}\mathcal{M}_h^{U(1)}$ in $\mathcal{H}_{A_0,h}^1(Y;su(2))$. Then we define a 1-parameter family of bilinear forms on V by the formula

$$H_t(\alpha, \beta) = \langle *d_{A_t,h}\alpha, \beta \rangle.$$

 H_t is symmetric and $Stab(A_0) = U(1)$ invariant.

When h=0, a jump in $\mathcal{H}_A^1(Y;su(2))$ occurs (for abelian connections) at connections where, up to gauge, $\mathrm{hol}_{\mu}A=\exp(\mathbf{i}\theta)$ and $\mathrm{hol}_{\lambda}A=1$ where $B_{\kappa}(e^{i2\theta})$ is degenerate.

The structure of \mathcal{M}_h was described in [H1]. It is summarized in the next theorem. Let $\overline{\mathcal{M}_h^*}$ denote the closure of \mathcal{M}_h^* in \mathcal{M}_h .

Theorem 1.1. (Theorem 15 and Corollary 24, [H1]; also, see Theorem 12, [H2]) For generic admissible perturbations h, $\overline{\mathcal{M}_h^*}$ and $\mathcal{M}_h^{U(1)}$ are compact smooth 1-manifolds. $\partial \overline{\mathcal{M}_h^*}$ consists of orbits in the interior of $\mathcal{M}_h^{U(1)}$. $\partial \mathcal{M}_h^{U(1)}$ consists of exactly two orbits, the central orbits. Furthermore, $r: \mathcal{M}_h \to \mathcal{M}_{T^2}$ is an immersion on each stratum taking only the central orbits of \mathcal{M}_h to the central orbits of \mathcal{M}_{T^2}

Definition 4. The orbits in $\overline{\mathcal{M}_h^*} \cap \mathcal{M}_h^{U(1)}$ are called **bifurcation points**.

Remark: The proof of Theorem 1.1 amounts to showing that the set of perturbations for which \mathcal{M}_h is degenerate has codimension 1, and then using local implicit function theorem arguments to show that these cohomological conditions guarantee that \mathcal{M}_h has the structure in the theorem.

2. The Double Cover of the Moduli Space.

In this section we will discuss the double cover of the moduli space (without the central orbits). This double cover has the same type of bifurcation point singularities where the different strata meet, but we will see that its 1-dimensional strata receive natural orientations from an orientation on $H^1(Y)$ or, equivalently, a choice of generator $[\mu] \in H_1(Y; \mathbf{Z})$.

We begin by fixing a maximal torus in $\{\exp(i\theta)\} \hookrightarrow SU(2)$. Here we identify su(2) with the space of purely imaginary quaternions, with standard basis elements \mathbf{i} , \mathbf{j} , and \mathbf{k} . We will abuse the notation and refer to this maximal torus as U(1). The adjoint representation of U(1) on su(2) reduces to a trivial representation on span $\{\mathbf{i}\}$, which we will identify with \mathbf{R} , and a weight two representation on span $\{\mathbf{j},\mathbf{k}\}$, which we will identify with \mathbf{C} .

First note that by considering flat connections on the torus with holonomy values in $U(1) \subset SU(2)$ we obtain a natural double cover $\tilde{\mathcal{M}}_{T^2}$ of \mathcal{M}_{T^2} , branched at the central points. Specifically, $\tilde{\mathcal{M}}_{T^2}$ is the space of flat u(1) valued connection 1-forms divided by the group of U(1) valued gauge transformations.

We define

$$\hat{\mathcal{A}} = \{ A \in \mathcal{A} | A|_{\partial Y} \in \Omega^1(\partial Y; \mathbf{R}) \}$$

and

$$\hat{\mathcal{G}} = \{ g \in \mathcal{G} | g|_{\partial Y} \in \operatorname{Map}(\partial Y, U(1)) \}.$$

Let $d_{A,h} = \frac{1}{2\pi} d_A - *\operatorname{Hess} h(A)$. Then $-*d_{A,h}$ is the linearization of ζ_h . Define

$$\Omega^p_\tau(Y;su(2))=\{a\in\Omega^p(Y;su(2))|\ a|_{\partial Y}=0\}$$

and

$$\Omega^p_{\nu}(Y; su(2)) = \{ a \in \Omega^p(Y; su(2)) | *a|_{\partial Y} = 0 \}.$$

Let U be a contractible family of admissible perturbation functions. We consider the family of elliptic operators

$$K_h(A): \Omega^0_{\tau}(Y; su(2)) \oplus \Omega^1_{\nu}(Y; su(2)) \to \Omega^0(Y; su(2)) \oplus \Omega^1(Y; su(2)),$$

parametrized by $(A, h) \in \hat{\mathcal{A}} \times U$, given by

$$K_h(A)(\sigma,\tau) = (d_A^*\tau, d_A\sigma + *d_{A,h}\tau).$$

If $\zeta_h(A) = 0$, then

$$\ker K_h(A) = \mathcal{H}_A^0(Y, \partial Y; su(2)) \oplus \mathcal{H}_{A,h}^1(Y; su(2))$$

and

$$\operatorname{coker} K_h(A) = \mathcal{H}^0_A(Y; su(2)) \oplus \mathcal{H}^1_{A,h}(Y, \partial Y; su(2)).$$

Here $\mathcal{H}_{A}^{0}(Y;su(2))$, $\mathcal{H}_{A,h}^{1}(Y;su(2))$, $\mathcal{H}_{A,h}^{1}(Y;\partial Y;su(2))$, and $\mathcal{H}_{A}^{0}(Y;\partial Y;su(2))$ are the harmonic spaces representing the cohomology groups of the Fredholm elliptic complex

$$\Omega^0 \stackrel{d_A}{\to} \Omega^1 \stackrel{*d_{A,h}}{\to} \Omega^1 \stackrel{d_A^*}{\to} \Omega^0.$$

The last cohomology group is always trivial when h = 0, these cohomology groups correspond to the cohomology with coefficients in the twisted flat su(2) bundle determined by the flat connection.

Notice that if $A \in \hat{\mathcal{A}}$ is a perturbed flat connection and $A|_{\partial Y}$ is noncentral then all the harmonic forms have boundary values in u(1). The virtual bundle $\operatorname{Ind} K_h = \ker K_h - \operatorname{coker} K_h$ is orientable since $\hat{\mathcal{A}}$ is an affine space. We will refer to an orientation on $\operatorname{Ind} K_h(A)$ by specifying one on $\ker K_h(A) \oplus \operatorname{coker} K_h(A)$.

Lemma 2.1. (Lemma 53 of [H1])

The action of $\hat{\mathcal{G}}$ on the index bundle $\operatorname{Ind}K_h$ is orientation preserving.

For the remainder of this section, let h be a fixed nondegenerate admissible perturbation function. For any noncentral $A \in \zeta_h^{-1}(0) \cap \hat{\mathcal{A}}$,

$$\mathcal{H}_A^0(\partial Y; su(2)) = T_{\operatorname{id}}\operatorname{Stab}(A|_{\partial Y}) \cong u(1),$$

which is canonically oriented. The kernel ker $K_h(A)$ contains the tangent space to the stratum $(\tilde{\mathcal{M}}_h^* \text{ or } \tilde{\mathcal{M}}_h^{U(1)})$ containing [A]. If [A] is a bifurcation

point, however, the kernel contains more. In the latter case, a space complementary to the tangent space of the stratum receives a canonical orientation from $\mathcal{H}_{A}^{0}(\partial Y; su(2))$. Furthermore, $\operatorname{coker} K_{h}(A)$ (which always has positive dimension) also receives a canonical orientation from $\mathcal{H}_{A}^{0}(\partial Y; su(2))$. This can be seen as follows. There are several cases to consider.

If $[A] \in \tilde{\mathcal{M}}_h^{U(1)}$ is not a bifurcation point, then the restriction map $\mathcal{H}_A^0(Y;su(2)) \to \mathcal{H}_A^0(\partial Y;su(2))$ is an isomorphism and $\mathcal{H}_{A,h}^1(Y,\partial Y;su(2))=0$. If $[A] \in \tilde{\mathcal{M}}_h^*$ then $\mathcal{H}_A^0(Y;su(2))=0$ and $\mathcal{H}^1(Y;su(2))$ and $\mathcal{H}^1(Y;su(2))$ are both 1-dimensional. In this case, the coboundary map in the long exact sequence of the pair $(Y,\partial Y)$ gives a canonical isomorphism from $\mathcal{H}_A^0(Y;su(2))$ to $\mathcal{H}_{A,h}^1(Y,\partial Y;su(2))$.

If $[A] \in \tilde{\mathcal{M}}_h^{U(1)}$ is a bifurcation point, then the restriction map $\mathcal{H}_A^0(Y;su(2)) \to \mathcal{H}_A^0(\partial Y;su(2))$ is injective, but $\mathcal{H}_{A,h}^1(Y,\partial Y;su(2))$ and the kernel of the restriction map $r:\mathcal{H}_{A,h}^1(Y;su(2)) \to \mathcal{H}_A^1(\partial Y;su(2))$ are both real 2-dimensional, with $\operatorname{Stab}(A)$ acting with weight 2 to give a complex structure on each. If $[A] \in \tilde{\mathcal{M}}_h^*$ then $\mathcal{H}_A^0(Y;su(2)) = 0$ and $\mathcal{H}^1(Y;su(2))$ and $\mathcal{H}^1(Y;su(2))$ are both 1-dimensional. In this case, the coboundary map in the long exact sequence of the pair $(Y,\partial Y)$ gives a canonical isomorphism from $\mathcal{H}_A^0(Y;su(2))$ to $\mathcal{H}_{A,h}^1(Y,\partial Y;su(2))$.

It follows that an orientation on the virtual index bundle determines one on the 1-dimensional strata of $\tilde{\mathcal{M}}_h$ for each nondegenerate h. We fix an orientation on this index bundle by specifying it on one fiber; namely, we orient $\ker K_0(\Theta) \oplus \operatorname{coker} K_0(\Theta)$, where Θ denotes the trivial connection.

Our orientation will depend on an orientation of $H^1(Y; \mathbf{R})$ or, equivalently, a choice of primitive generator $[\mu] \in H^1(Y; \mathbf{Z})$. Let μ^* denote the harmonic 1-form on Y with Neumann boundary conditions and satisfying $\int_{\mu} \mu^* = 1$. Then we take the orientation on $\ker K_0(\Theta) \oplus \operatorname{coker} K_0(\Theta)$ determined by the basis

$$\{\mu^* \otimes \mathbf{i}, \mu^* \otimes \mathbf{j}, \mu^* \otimes \mathbf{k}, \mathbf{i}, \mathbf{j}, \mathbf{k}\}.$$

We end this section by noting that the \mathbb{Z}_2 action on the double cover does not preserve this orientation on $\tilde{\mathcal{M}}_h$.

3. Perturbing.

In order to obtain nondegenerate moduli spaces in general, it is necessary to perturb the flatness equations. In this section we describe the admissible perturbation functions and prove that it is possible to find small perturbations such that the moduli spaces satisfy certain technical conditions that will be needed in Lemma 5.1.

The standard class of admissible perturbation functions h in this context (see, for example, [T], [F], [H1]) is defined as follows. Let x be a pair of coordinates on the disk D^2 . Let $\eta(x)$ be a radially symmetric bump function on D^2 which vanishes near the boundary and let dx be the standard measure on D^2 . Given a finite collection of disjoint embeddings $\{\gamma_i: S^1 \times D^2 \to Y\}_{i=1,\dots,n}$ and a collection of C^2 adjoint invariant functions $\{h_i: SU(2) \to \mathbf{R}\}_{i=1,\dots,n}$, we define a gauge invariant function on \mathcal{A} given by

$$h(A) = \sum_{i=1}^n \int_{D^2} h_i(\text{hol}_{\gamma_i}(x,A)) \eta(x) dx.$$

Functions constructed in this way are said to be admissible.

For our purposes it will be sufficient to fix a single collection of thickened loops $\{\gamma_i\}_{i=1,\dots,n}$. The collection is required to be sufficiently large in the sense of [H1], Section 6, Theorem 15. We allow ourselves to vary the functions h_i to achieve nondegeneracy, transversality, etc. Let $\mathcal{H} = [C_{SU(2)}^2(SU(2), \mathbf{R})]^n$, the product of n copies of the space of Adinvariant C^2 functions from SU(2) to \mathbf{R} .

Theorem 3.1. Fix $0 < \alpha < \pi$ with $\Delta_{\kappa}(e^{2i\alpha}) \neq 0$. Then there exist arbitrarily small perturbations $h \in \mathcal{H}$ for which \mathcal{M}_h satisfies (1)-(5) of Lemma 5.1.

Proof. By the proof of Theorem 15 in [H1] there is a neighborhood $V \subset \mathcal{H}$ of 0 such that the set $V_0 \subset V$ of perturbations for which \mathcal{M}_h is degenerate has codimension ≥ 1 . Furthermore, Proposition 34 in [H1] implies that V may be chosen small enough that the set $V_1 \subset V$ of perturbations for which $r(\mathcal{M}_h^*)$ does not intersect S_{α} transversely also has codimension 1.

Choose a path $h_t: (-1,1) \to V$, with $h_0 = 0$, which meets V_0 and V_1 transversely. This will ensure that there is an $\epsilon > 0$ such that \mathcal{M}_{h_t} satisfies conditions (1) and (2) for each $0 < t < \epsilon$.

To meet condition (4), note that for t small enough, the map $tr(\operatorname{hol}_{\mu}): \mathcal{M}_{h_t}^{U(1)} \to [-2,2]$ given by $[A] \mapsto \operatorname{tr}(\operatorname{hol}_{\mu}(A))$ is a diffeomorphism on the interior and continuous on the whole space. By another (t-dependent) perturbation using a curve near ∂Y parallel to μ , $r(\mu_{h_t}^{U(1)})$ can be realigned with the unperturbed abelian stratum. See Lemma 61 and Example 1, p. 64, of [H1], for details.

That condition (3) holds for t sufficiently small may be seen as follows. Suppose \tilde{S}_{α} intersects $\tilde{r}(\tilde{\mathcal{M}}_{h_t}^{U(1)})$ at a bifurcation point for arbitrarily small t>0. Then there are Fredholm operators arbitrarily close to $K_{A^{\alpha}}(Y)$ (namely $K_{A^{\alpha},h_t}(Y)$) with larger kernel than $\ker K_{A^{\alpha}}(Y)$. This contradicts the fact that dim $\ker K$ is an upper semi-continuous function on the space of Fredholm operators from one separable Hilbert space to another.

The path h_t , $0 \le t \le \frac{\epsilon}{2}$, constructed in this manner, automatically satisfies condition (5).

4. The Local Picture Near a Bifurcation Point.

In this section we fix a primitive $[\mu] \in H_1(Y; \mathbf{Z})$ to specify an orientation on the 1-dimensional strata of $\tilde{\mathcal{M}}_h$ as in the previous section. We assume furthermore that \mathcal{M}_h is nondegenerate and fix $A_0 \in \zeta_h^{-1}(0) \cap \hat{\mathcal{A}}$ such that $[A_0]$ is a bifurcation point on the U(1)-stratum. For concreteness say that $\operatorname{hol}_{\mu}(A_0) = \exp(\sigma \mathbf{i})$ where $\sigma \in (0, \pi)$ (thereby specifying in which half of the double cover of the moduli space $[A_0]$ lies). We will explore the Kuranishi picture for the moduli space near $[A_0]$.

Let Π_0 denote the orthogonal projection

$$\Pi_0: \Omega^0(Y; su(2)) \oplus \Omega^1(Y; su(2)) \to \mathcal{H}^0_{A_0}(Y; su(2)) \oplus \mathcal{H}^1_{A_0,h}(Y; \partial Y; su(2)).$$

We shall obtain a description of the restriction

$$\Pi_0 \circ K_h(A) : \mathcal{H}^1_{A_0,h}(Y; su(2)) \to \mathcal{H}^0_{A_0}(Y; su(2)) \oplus \mathcal{H}^1_{A_0,h}(Y; \partial Y; su(2)),$$

for A near A_0 . This will enable us to sort out the orientations induced on the irreducible and abelian strata near $[A_0]$ from the one on $\mathcal{H}_A^0(\partial Y; su(2))$, in terms of the direction of the spectral flow of H_t at t=0.

We begin by studying a part of this operator, namely, its restriction to the orthogonal complement in $\mathcal{H}^1_{A_0,h}(Y;su(2))$ of the U(1) stratum tangent space. As pointed out above, $\operatorname{Stab}(A_0)$ is naturally identified with the fixed (oriented) $U(1) \subset SU(2)$. The action of $\operatorname{Stab}(A_0)$ on $\Omega^1(Y;su(2))$ gives a natural complex structure on this orthogonal complement, denoted by $\mathcal{H}^1_{A_0,h}(Y;\mathbf{C})$, and on $\mathcal{H}^1_{A_0,h}(Y,\partial Y;su(2))$. We denote both of these complex structures by J.

Let $\vec{u} \in \mathcal{H}^0_{A_0}(Y; su(2)) = T_{\text{id}} \text{Stab}(A_0)$ point in the positive direction. Recall that the map $j : \mathcal{H}^1_{A_0,h}(Y,\partial Y; su(2)) \to \mathcal{H}^1_{A_0,h}(Y; su(2))$ in the long exact sequence of the pair is in fact L^2 orthogonal projection between the harmonic spaces representing the cohomology groups. Choose nonzero cohomology classes \vec{a} , \vec{b} , and \vec{c} , as follows. Choose $\vec{c} \in \mathcal{H}^1_{A_0,h}(Y,\partial Y; \mathbf{C})$ and let $\vec{b} = j\vec{c} \in \mathcal{H}^1_{A_0,h}(Y; \mathbf{C})$. Note that \vec{b} and \vec{c} differ by an exact form. Let $\vec{a} \in \mathcal{H}^1_{A_0}(Y; \mathbf{R})$ be a vector such that the orientation coming from the basis $\{\vec{a}, \vec{b}, J\vec{b}, \vec{u}, \vec{c}, J\vec{c}\}$ agrees with the orientation on $\ker K_h(A_0) \oplus \operatorname{coker} K_h(A_0) = \mathcal{H}^1_{A_0,h}(Y; su(2)) \oplus \mathcal{H}^0_{A_0}(Y; su(2)) \oplus \mathcal{H}^1_{A_0,h}(Y; su(2))$. Let A_t be a 1-parameter family of connections through A_0 such that

Let A_t be a 1-parameter family of connections through A_0 such that $[A_t]$ gives a smooth parameterization of $\mathcal{M}_h^{U(1)}$ We further require that the parameterization be chosen so that $\frac{d}{dt}A_t|_{t=0}=\vec{a}$. Define H_t to be the cohomological pairing $H_t(z,z')=\langle *d_{A_t,h}z,z'\rangle$ on the orthogonal complement of $T_{|A_0|}\mathcal{M}_h^{U(1)}$ in $\mathcal{H}_{A_0,h}^1(Y;su(2))$.

Proposition 4.1. The pairing has the form $H_t = \lambda(t) \text{Id}$ for some real valued function $\lambda(t)$ with $\lambda(0) = 0$ and $\lambda'(0) \neq 0$.

Proof. $H_t: \mathbf{C} \to \mathbf{C}$ is a U(1) equivariant map and hence has the form $\lambda(t)e^{i\theta(t)}$ for some real valued functions λ and θ . We first show that H_t is symmetric, which shows that $\theta(t) = 0$.

The Hessian of h is symmetric. To see that $*d_{A_t}$ is also symmetric, let z and z' be harmonic forms in $\mathcal{H}^1_{A_0}(Y; \mathbb{C})$. These forms are necessarily exact when restricted to ∂Y ; say, $z|_{\partial Y} = d_{A_0}\xi$ and $z'|_{\partial Y} = d_{A_0}\xi'$. Then,

$$\langle *d_{A_t}z, z' \rangle - \langle *d_{A_t}z', z \rangle = -\int_Y \operatorname{tr}(d_{A_t}z \wedge z' - z \wedge d_{A_t}z')$$

$$= -\int_{\partial Y} \operatorname{tr}(z \wedge z')$$

$$= -\int_{\partial Y} \operatorname{tr}(d_{A_0}\xi \wedge d_{A_0}\xi')$$

$$= -\int_{\partial Y} \operatorname{tr}(\xi[F_{A_0}, \xi']) = 0.$$

The last integral equals zero because A_0 is flat on ∂Y . Our nondegeneracy assumptions guarantee that $\lambda'(0) \neq 0$.

Finally, we relate the sign of the spectral flow $\frac{\lambda'(0)}{|\lambda'(0)|}$ to the orientation of the irreducible arc limiting to the bifurcation point. A slice to the gauge group action through A_0 is

$$X_{A_0} = \{A_0 + a | d_{A_0}^* a = 0, a \in \Omega_{\nu}^1(Y; su(2))\}.$$

Let $\Pi_{\ker d_{A_0}^*}$ denote the orthogonal projection from $\Omega^1(Y; su(2))$ onto $\ker d_{A_0}^*$. By standard arguments involving the Kuranishi map, the connections in X_{A_0} near A_0 for which $\Pi_{\ker d_{A_0}^*}(\zeta_h(A)) \in \mathcal{H}^1_{A_0,h}(Y,\partial Y; su(2))$ make up a smooth 3-dimensional submanifold, parametrized by

$$A(t,x,y) = A_0 + t\vec{a} + x\vec{b} + yJ\vec{c} + \phi(t,x,y),$$

where $\phi: \mathbf{R}^3 \to *d_{A_0,h}\Omega^1_{\tau}(Y;su(2))$ satisfies $\phi(0,0,0) = 0$. See [H1], for example, for details.

To first order in t, x, and y, in terms of the bases $\{\vec{a}, \vec{b}, J\vec{b}\}$ and $\{\vec{u}, \vec{c}, J\vec{c}\}$ for $\mathcal{H}^1_{A_0,h}(Y; su(2))$ and $\mathcal{H}^0_{A_0}(Y; su(2)) \oplus \mathcal{H}^1_{A_0,h}(Y, \partial Y; su(2))$, the restricted operator has the form

$$\Pi_0\circ K_h(A(t,x,y))=\left[egin{array}{ccc} 0&2y&-2x\ \lambda'(0)x&\lambda'(0)t&0\ \lambda'(0)y&0&\lambda'(0)t \end{array}
ight].$$

The lower right hand 2×2 block in the above matrix is equal to H_t . The second and third entries in the first column must have the values given because of the fact that the bottom two rows form the derivative matrix for a map from $\mathcal{H}^1_{A_0,h}(Y;su(2))$ to $\mathcal{H}^1_{A_0,h}(Y,\partial Y;su(2))$. The top row entries are clear from the fact that $\operatorname{Stab}(A_0)$ acts with weight two on the complex coefficients.

For the purposes of keeping track of orientations this first order approximation is sufficient. By Theorem 12 of [H2], the irreducible perturbed flat connections in the slice near A_0 , together with A_0 (which is reducible), form a 2-dimensional submanifold through A_0 , invariant under the $Stab(A_0)$ action, described to first order by A(0, x, y). What remains for us to do is to identify the induced orientation on the radial direction in this tangent space from the orientation on the index of K_h .

We will say that two bases for a vector space are equivalent if they induce the same orientation on the vector space, and we denote this equivalence by \sim . Recall that by assumption, a correctly oriented basis for $\ker K_h(A_0) \oplus \operatorname{coker} K_h(A_0)$ is

$$\{\vec{a}, \vec{b}, J\vec{b}, \vec{u}, \vec{c}, J\vec{c}\}.$$

The corresponding basis for $\operatorname{Ind} K_h(A(0,x,0))$ is $\{\epsilon \vec{b}, J\vec{c}\}$ where $\epsilon \in \{\pm 1\}$ makes

$$\{\epsilon \vec{b}, \vec{a}, J \vec{b}, J \vec{c}, \Pi_0 \circ K_h(A(0, x, 0)) \vec{a}, \Pi_0 \circ K_h(A(0, x, 0)) J \vec{b}\}$$

$$\sim \{\epsilon \vec{b}, \vec{a}, J \vec{b}, J \vec{c}, \lambda'(0) x \vec{c}, 2x \vec{u}\}$$

$$\sim \{\vec{a}, \lambda'(0) \epsilon \vec{b}, J \vec{b}, \vec{u}, \vec{c}, J \vec{c}\}$$

equivalent to

$$\{\vec{a},\vec{b},J\vec{b},\vec{u},\vec{c},J\vec{c}\}.$$

In other words, $\epsilon = \frac{\lambda'(0)}{|\lambda'(0)|}$, so the sign coincides with the spectral flow direction of H_t . This is summarized in the following proposition.

Proposition 4.2. The orientation on the irreducible arc limiting to a bifurcation point points away from or towards the bifurcation point according to whether the spectral flow of H_t is positive or negative.

Remark: By Corollary 3 of [H2], the direction in \mathcal{M}_{T^2} in which $r(\mathcal{M}_h^*)$ leaves the image of the bifurcation point is also determined by this sign. Thus the orientation on the non-closed components of $\tilde{\mathcal{M}}_h^*$ is determined by their image in $\tilde{\mathcal{M}}_{T^2}$.

5. An Intersection Formula.

Choose a 0-framed longitude λ for the knot, i.e., an embedded circle in ∂Y which is null homologous in Y. Also, choose a meridian curve μ , the boundary of a normal disk in $\nu(\kappa)$. We require that λ and μ are oriented so that their intersection is $\mu \cdot \lambda = 1$, using the boundary orientation on T^2 . Note that this orients the index bundles from Section 2 on both Y and $S^1 \times D^2$, since λ and μ generate $H^1(S^1 \times D^2; \mathbf{R})$ and $H^1(Y; \mathbf{R})$, respectively.

For each $0 \le \alpha < \pi$, define

$$\tilde{S}_{\alpha} = \{ [A] \in \tilde{\mathcal{M}}_{T^2} | \operatorname{hol}_{\mu}(A)) = \exp(\mathbf{i}\alpha) \}.$$

Orient this circle so that $\tilde{r}(\tilde{\mathcal{M}}^{U(1)}) \cdot \tilde{S}_{\alpha} = 1$. For $\alpha = 0$, $\tilde{S}_0 = r(\tilde{\mathcal{M}}_{S^1 \times D^2})$, and this orientation on \tilde{S}_0 is corresponds to the one on $\tilde{\mathcal{M}}_{S^1 \times D^2}$ coming from the choice of first homology generator λ .

Assume that the map

$$\phi: \tilde{\mathcal{M}}_h^{U(1)} \to U(1)$$

given by $\phi([A]) = \operatorname{hol}_{\mu}(A)$ is a diffeomorphism. (Large perturbations can violate this requirement, but small ones cannot.) For each bifurcation point $[A] \in \tilde{\mathcal{M}}_h^{U(1)}$, let $\sigma([A]) = \pm 1$ depending on whether the eigenvalue $\lambda(t)$ of H_t has positive or negative derivative when it crosses zero.

Define $S:(0,\pi)\to \mathbf{Z}$ to be $S(\alpha)=\sum \sigma([A])$ where the sum is taken over all bifurcation points in $\phi^{-1}(0,\alpha)$.

For each $0 \le \alpha < \pi$, let A^{α} denote a flat abelian connection on Y with meridinal holonomy equal to $\exp(i\alpha) \in SU(2)$. Such a connection is unique up to gauge equivalence.

Lemma 5.1. Let $0 < \alpha < \pi$ be a number such that $\mathcal{H}^1_{A^{\alpha}}(Y, \partial Y; su(2)) = 0$. Let h be a perturbation such that the following conditions hold.

- (1) \mathcal{M}_h is nondegenerate.
- (2) \tilde{S}_{α} meets $\tilde{r}(\tilde{\mathcal{M}}_{h}^{*})$ transversely.
- (3) \tilde{S}_{α} misses the bifurcation points of $\tilde{r}(\tilde{\mathcal{M}}_{h}^{U(1)})$.
- (4) r maps $\mathcal{M}_{h}^{U(1)}$ onto $r(\mathcal{M}_{h_0}^{U(1)})$.
- (5) There is a path h_t of perturbations from 0 to h such that \mathcal{M}_{h_t} satisfies (1), (3) and (4) for all $0 < t \le 1$.

Then

$$r(\tilde{\mathcal{M}}_h^*) \cdot \tilde{S}_{\alpha} - r(\tilde{\mathcal{M}}_h^*) \cdot \tilde{S}_0 = \mathcal{S}(\alpha).$$

Remark: We will show in Section 3 that it is always possible to find a small perturbation satisfying (1) - (5).

Proof. of Lemma 5.1 This reduces to the following elementary topological fact. Let $\Sigma \subset \tilde{\mathcal{M}}_{T^2}$ denote the smaller annulus between \tilde{S}_0 and \tilde{S}_{α} , i.e., $\Sigma = \bigcup_{0 < \beta < \alpha} \tilde{S}_{\beta}$. The induced orientation makes $\partial \Sigma = \tilde{S}_{\alpha} - \tilde{S}_{0}$.

For any immersion $f: C \to \tilde{\mathcal{M}}_{T^2}$ of a compact, oriented, 1-dimensional submanifold C with $f(\partial C) \cap \partial \Sigma = \emptyset$ and f(C) transverse to $\partial \Sigma$, $f(C) \cdot \partial \Sigma$ equals the number of endpoints (counted with orientation) of C whose images lie in Σ .

6. $S(\alpha)$ and the Equivariant Knot Signature.

We next relate $S(\alpha)$ to the spectral flow of the twisted signature operator on the 0-surgery on κ . We then relate this spectral flow to the signature of the matrix $B_k(e^{i2\alpha})$. We begin by recalling the definition of spectral flow for a family of self-adjoint Fredholm operators.

Let K_t , $0 \le t \le 1$, be a continuous 1-parameter family of self-adjoint Fredholm operators on a separable Hilbert space. The eigenvalues of K_t are real and vary continuously in t. We consider their graphs in $[0,1] \times \mathbf{R}$. The nonzero eigenvalues of K_0 and K_1 are bounded away from zero. Let

 $\delta > 0$ be smaller than the absolute value of the nonzero eigenvalue closest to zero. A small homotopy of the family of operators, fixing the endpoints, will insure that the eigenvalues cross this line transversely. Then we define the spectral flow $SF(K_0, K_1)$ to be the number of eigenvalues, counted with multiplicities, which cross the line segment connecting $(0, -\delta)$ to $(1, \delta)$; an eigenvalue counts with a plus or minus sign depending on whether it crosses from below to above or from above to below. Equivalently, the spectral flow from K_0 to K_1 is the number of eigenvalues that change from non-negative to non-positive. Note that with this convention, $SF(K_0, K_1) + SF(K_1, K_2) = SF(K_0, K_2) - \dim \ker(K_1)$.

Let $\overline{Y} = Y \cup_{\partial Y} S^1 \times D^2$ be the closed manifold obtained by 0-surgery on κ . We will denote connections on \overline{Y} by \overline{A} . In this section we assume that h is a perturbation such that $\mathcal{M}_h(Y)$ satisfies (1) - (5). We are considering h as a perturbation for both Y and \overline{Y} . Condition (4) insures that the abelian portion of $\mathcal{M}_h(\overline{Y})$ is a 1-dimensional arc parametrized by $\operatorname{tr}(\operatorname{hol}_{\mu}(\overline{A}))$. (This is not the case for generic perturbations on \overline{Y} , but it can be arranged by choosing the perturbations in Y as prescribed above.)

Let $K_{\overline{A},h}: \Omega^0(\overline{Y}; su(2)) \oplus \Omega^1(\overline{Y}; su(2)) \to \Omega^0(\overline{Y}; su(2)) \oplus \Omega^1(\overline{Y}; su(2))$ be the twisted signature operator for \overline{A} on \overline{Y} , given by

$$K_{\overline{A},h}(\sigma,\tau)=(d_{\overline{A}}^*\tau,d_{\overline{A}}\sigma+*d_{\overline{A},h}\tau).$$

Let A_t be a path of abelian connections on Y such that $[A_t]$ passes through a bifurcation point when t=0, as in Section 4. Let \overline{A}_t be a family of abelian connections on \overline{Y} such that $\overline{A}_t|_Y = A_t$ and $\overline{A}_t|_{S^1 \times D^2}$ is flat. Let \overline{a} denote the tangent vector $\frac{d}{dt}\overline{A}_t|_{t=0}$. The next proposition relates the spectral flow of the finite dimensional self-adjoint operator H_t defined in Section 1 to the spectral flow of the operator $K_{\overline{A}_t,h}$.

Proposition 6.1. As t passes through 0, exactly one eigenvalue of $K_{\overline{A}_{t},h}$, having multiplicity two, changes sign, and it changes in the same direction as $\lambda(t)$.

Proof. The Mayer Vietoris sequence implies that \overline{Y} has a jump in (twisted) first cohomology at exactly those abelian connections which restrict to be bifurcation points on Y. The only problem is to relate the sign of the spectral flows at these points.

The Mayer Vietoris sequence along with our assumption about $\mathcal{M}_h^{U(1)}$ together imply that the restriction map from $\mathcal{H}_{\overline{A},h}^1(\overline{Y};su(2))$ to $\mathcal{H}_{A,h}^1(Y;su(2))$ is an isomorphism.

Let $\overline{\lambda}(t)$ be the eigenvalue of $K_{\overline{A}_{t},h}$ which passes through 0 when t=0, and let $\overline{\phi}(t)$ be a corresponding eigenvector. Then $\overline{\phi}(0) \in \mathcal{H}^{1}_{\overline{A},h}(\overline{Y}; \mathbb{C})$, and in fact $\overline{\phi}(t)$ can be chosen so that $\overline{\phi}(0)|_{Y} = \vec{b}$.

$$\langle K_{\overline{A}_t,h}\overline{\phi}(t),\overline{\phi}(t)
angle = \overline{\lambda}(t)\|\overline{\phi}(t)\|_{L^2(\overline{Y})}^2.$$

Differentiating in t and evaluating when t = 0 gives

$$\overline{\lambda}(t)'(0)\|\overline{\phi}(0)\|_{L^2(\overline{Y})}^2=\langle *[\overline{a}\wedge\overline{\phi}(0)],\overline{\phi}(0)\rangle=-\int_{\overline{Y}}\mathrm{tr}([\overline{a}\wedge\overline{\phi}(0)]\wedge\overline{\phi}(0)).$$

(Note: this pairing only depends on the cohomology classes of $\overline{\phi}(0)$ and \overline{a} .) Breaking up the integral we obtain

$$\begin{split} -\int_{\overline{Y}} \operatorname{tr}([\overline{a} \wedge \overline{\phi}(0)] \wedge \overline{\phi}(0)) &= -\int_{Y} \operatorname{tr}([\overline{a} \wedge \overline{\phi}(0)] \wedge \overline{\phi}(0)) \\ &- \int_{S^{1} \times D^{2}} \operatorname{tr}([\overline{a} \wedge \overline{\phi}(0)] \wedge \overline{\phi}(0)) \\ &= -\int_{Y} \operatorname{tr}([\overline{a} \wedge \overline{b}] \wedge \overline{b}). \end{split}$$

The integral over the solid torus vanishes because there $\overline{\phi}_0$ is exact and \overline{a} is closed. The integral over Y has the same sign as $\lambda'(0)$.

Corollary 6.2.
$$2S(\alpha) - 4 = SF(K_{\overline{A}^0,h}, K_{\overline{A}^{\alpha},h})(\overline{Y}).$$

Proof. The image of the set of bifurcation points in \mathcal{M}_{h_t} , $0 < t \le 1$, in \mathcal{M}_{T^2} is bounded away from the trivial orbit. It follows that dim $\ker K_{\overline{A}^0,h_t}(\overline{Y})$ is constantly equal to 6, and that for $\beta > 0$ very small dim $\ker K_{\overline{A}^0,h_t}$ is constantly equal to 2 for $0 \le t \le 1$. Therefore $SF(K_{\overline{A}^0,h},K_{\overline{A}^0,h})(\overline{Y}) = SF(K_{\overline{A}^0},K_{\overline{A}^0})(\overline{Y})$ which is easily calculated to be -4 by explicitly computing $K_{\overline{A}^0|\ker K_{\overline{A}^0}}$. The proposition implies that $2\mathcal{S}(\alpha) = SF(K_{\overline{A}^0,h},K_{\overline{A}^\alpha,h})(\overline{Y}) + 2$, which equals $SF(K_{\overline{A}^0},K_{\overline{A}^\alpha})(\overline{Y}) + 4$ by the above argument.

We now relate the spectral flow of the twisted signature operator on \overline{Y} to the signature of the matrix $B_{\kappa}(e^{i2\alpha}) = (1 - e^{i2\alpha})V + (1 - e^{-i2\alpha})V^T$, where V is the Seifert pairing of a Seifert surface for κ . The following modification of the argument in [KKR], Section 4, was suggested to the author by Paul Kirk.

Proposition 6.3. $SF(K_{A^0}, K_{A^{\alpha}})(\overline{Y}) = -\operatorname{Sign} B_{\kappa}(e^{i2\alpha}) - 4.$

Proof. We will use a formula relating the spectral flow of K_A on \overline{Y} to the Chern-Simons function and rho invariants of the flat connections at the ends of the path. A derivation of this formula may be found in [KKR].

Let A^{α} and A^{β} be any flat connections on a 3-manifold Z with holonomy representations $\alpha, \beta: \pi_1 Z \to SU(2)$. The formula is the following:

$$\begin{split} SF(K_{A^{\alpha}}, K_{A^{\beta}})(Z) &= 8(cs(A^{\beta})(Z) - cs(A^{\alpha})(Z)) \\ &+ \frac{1}{2}(\rho_{ad\beta}(Z) - \rho_{ad\alpha}(Z)) \\ &- \frac{1}{2}(\dim \ker K_{A^{\alpha}} + \dim \ker K_{A^{\beta}}). \end{split}$$

Suppose that M is an oriented 4-manifold with oriented boundary Z. Suppose furthermore that $\tilde{\alpha}: \pi_1 M \to SU(2)$ is an extension of the complexified adjoint representations $ad\alpha$. Then the rho invariant of $ad\alpha$ may be calculated with the formula

$$\rho_{ad\alpha}(Z) = 3 \operatorname{Sign} M - \operatorname{Sign}_{\tilde{\alpha}} M,$$

where the latter term is the equivariant signature of M.

We begin by describing a 4-manifold to which we will apply the above spectral flow formula. Let U be the union of $X \times [0,1]$ with a 2-handle attached to $X \times \{1\}$ along $N(\kappa)$ with the 0-framing. Orient U so that $\partial U = \overline{Y} - X$.

Let F be a Seifert surface for $\kappa \times \{1\}$, the interior of which is pushed into $X \times [0,1]$. Let \overline{F} denote the closed surface obtained by capping F off with the core of the 2-handle. \overline{F} has trivial normal bundle in U, so we may remove $N(\overline{F})$ and replace it by $S^1 \times H$ where H is a handlebody of genus equal to that of \overline{F} . Call the resulting manifold M.

Proposition 6.4. 1. $H_1(M) = \mathbf{Z}$.

- 2. The map $H_1(Y) \to H_1(M)$ induced by the inclusion map is an isomorphism.
- 3. $\operatorname{Sign}(M) = 0$.

This proposition is just a homology calculation, so it suffices to show it for the case of κ equal to the unknot in S^3 , with F equal to a disk. The claims are easily checked in this case.

The important property of M is that $\partial M = \overline{Y} - X$ and any abelian representation $\alpha: \pi_1 \overline{Y} \to SU(2)$ extends uniquely to an abelian representation $\tilde{\alpha}$ of $\pi_1 M$ which is trivial on $\pi_1 X$. Thus $\rho_{ad\alpha}(\overline{Y}) - \rho_{\text{trivial}}(X) = 3\text{Sign}M - \text{Sign}_{\tilde{\alpha}}M$. Since the Chern-Simons function is a flat cobordism invariant, $cs(A^{\alpha})(\overline{Y}) = cs(A^{0})(X) = 0$, and the Chern-Simons function terms in the spectral flow formula contribute zero.

The formula then implies

$$SF(K_{A^0},K_{A^{m{lpha}}})(\overline{Y}) = -rac{1}{2}\mathrm{Sign}_{ ilde{m{lpha}}}M-4.$$

Proposition 6.3 is now a consequence of the following fact.

Proposition 6.5. $\operatorname{Sign}_{\tilde{\alpha}} M = 2\operatorname{Sign} B_{\kappa}(e^{i2\alpha}).$

Proof. of Proposition 6.5 Since $S^1 \times H$ has a deformation retract $S^1 \times (\vee_i S^1)$ in its boundary, $\operatorname{Sign}_{\tilde{\alpha}} S^1 \times H$ and $\operatorname{Sign}_{\tilde{\alpha}} S^1 \times H$ are both zero. By Novikov additivity $\operatorname{Sign}_{\tilde{\alpha}} M = \operatorname{Sign}_{\tilde{\alpha}} U \setminus N(F)$.

Let $N = U \setminus N(F)$, and let \tilde{N} be the universal abelian cover of N. Let $B: H_2(\tilde{N}; \mathbf{Z}) \times H_2(\tilde{N}; \mathbf{Z}) \to \mathbf{Z}[t, t^{-1}]$ denote the equivariant intersection form.

Theorem 6.6. (Theorem 4.2 of [KKR]) $H_2(\tilde{N}; \mathbf{Z}) = (\mathbf{Z}[t, t^{-1}])^{2g} \oplus \mathbf{Z}$ where $\mathbf{Z}[t, t^{-1}]$ acts trivially on the \mathbf{Z} summand. The matrix for the equivariant intersection form, B, on the free summand is given by

$$(1-t)V + (1-t^{-1})V^T$$

where V is the Seifert matrix for the Seifert surface F, $V_{ij} = \ell k(x_i, x_j^+)$. The **Z** summand is in the kernel of B.

The proof of this theorem is a standard argument which may be found in Chapter VII of [K] and in [KKR]. The idea is to construct \tilde{N} as the union of the universal cover of the 2-handle minus its core and the universal cover of $X \times [0,1] \setminus F$. In both of the above references, the calculation is done for the case when $X = S^3$ (and the trivial X end of the cobordism U is capped off with a 4-ball). It works the same for the present situation, however. The

important feature is that $(X \times [0,1]) \setminus N(F)$ cut open along the trace of a homotopy from F to a Seifert surface in $X \times \{1\}$ has no 1-dimensional or 2-dimensional cohomology.

All that remains to prove Proposition 6.5 is to understand the adjoint action of $\exp(i\alpha)$ on the complexified Lie algebra $su(2) \otimes \mathbf{C}$. The representation of $H_1(M) = \mathbf{Z}$ reduces to a direct sum of 3 U(1) representations, taking the generator to $e^{i2\alpha}$, $e^{-i2\alpha}$, and 1. Thus

$$\operatorname{Sign}_{\tilde{\alpha}} N = \operatorname{Sign} B_{\kappa}(e^{i2\alpha}) + \operatorname{Sign} B_{\kappa}(e^{-i2\alpha}) + \operatorname{Sign} B_{\kappa}(1) = +2\operatorname{Sign} B_{\kappa}(e^{i2\alpha}).$$

7. Casson's Invariant.

In this section we relate the intersection number $\tilde{r}(\tilde{\mathcal{M}}_h^*) \cdot \tilde{S}_0$ to the Casson invariant. We will make use of the fact that Taubes showed $\lambda(X) = -\frac{1}{2} \sum_{[A] \in \mathcal{M}^*(X)} (-1)^{SF(K_{\Theta},K_A)}$ in [T]; see also [KKR], Section 2, for clarification of the sign.

Theorem 7.1.
$$\tilde{r}(\tilde{\mathcal{M}}_h^*) \cdot \tilde{S}_0 = -4\lambda(X)$$
.

We first prove this equality up to an overall sign. That is, we show that the oriented intersection number $\tilde{r}(\tilde{\mathcal{M}}_h^*) \cdot \tilde{S}_0$ has the same absolute value as 4 times Casson's invariant for X.

Proposition 7.2. Let [A] and [A'] be orbits in $\tilde{\mathcal{M}}_h^* \cap \tilde{r}^{-1}(\tilde{S}_0)$. Then the local intersection numbers of $\tilde{r}(\tilde{\mathcal{M}}_h^*(Y)) \cdot \tilde{S}_0$ at [A] and [A'] agree if and only if $SF(K_{A,h},K_{A',h})$ equals zero modulo 2.

Remark: Both of the quantities are unchanged when A' is replaced by g(A') for any gauge transformation. Thus it is sufficient to prove the proposition for one for arbitrary $A \in \zeta_h^{-1}(0)$ and for any representative A' of an arbitrary orbit in the intersection. In fact, it is enough to do so for pairs [A], [A'] in the same component of $\tilde{r}^{-1}(\tilde{S}_0 \setminus \{\text{centrals}\})$.

Proposition 7.2 is analogous with Proposition 5.2 of [T], with the following difference. Taubes was concerned with intersecting the two irreducible strata of the flat moduli spaces for the solid handlebodies in a Heegard decomposition for X in the irreducible stratum of the flat moduli space for the splitting surface. Because our connections are abelian on the torus ∂Y ,

and on the tubular neighborhood of the knot, the Fredholm operators which for Taubes were surjective have cokernel in our case. We have already dealt with this problem Section 2 and we now modify Taubes' argument to include the identifications of these two cokernels with $\mathcal{H}^0(\partial Y; su(2))$.

We begin by establishing some notation that will parallel that in [T]. Recall that X is a homology 3-sphere, in which Y sits as complement of an open tubular neighborhood of a knot. Let $X_1 = Y$ and let $X_2 = S^1 \times D^2$ be the closure of a slightly larger tubular neighborhood, so that $X_0 = X_1 \cap X_2$ is diffeomorphic to a product $T^2 \times [0, 1]$. We may assume that the perturbation curves do not intersect X_0 .

We make the following definition

$$\mathcal{A}^{\diamond} = \{ A \in \mathcal{A}(X) | A|_{X_2} \in \Omega^1(X_2; u(1)), A|_{X_2} \text{ is not central} \}.$$

For each $A \in \mathcal{A}^{\diamond}$, let $\mathcal{T}_{\alpha}(A) = \ker d_A^* \cap \Omega^1_{\nu}(X_{\alpha})$. These fit together to form bundles \mathcal{T}_{α} over \mathcal{A}^{\diamond} . For $\alpha = 0, 2$, this requires a straightforward modification of the usual argument, taking advantage of the fact that $\ker d_A \cap \Omega^0$ is always the span of the constant 0-form **i**.

The bundles fit into an exact, acyclic Fredholm complex

$$0 \to \mathcal{T} \xrightarrow{\Phi} \mathcal{T}_1 \oplus \mathcal{T}_2 \xrightarrow{\Psi} \mathcal{T}_0 \to 0.$$

The map Φ is defined by

$$\Phi(a) = (a|_{X_1} - d_A b_1, a|_{X_2} - d_A b_2)$$

where $b_{1,2}$ is the unique 0-form satisfying

$$d_A^* d_A b_{1,2} = 0, *d_A b_{1,2}|_{\partial X_{1,2}} = *a|_{\partial X_{1,2}}$$

and $b_2 \perp \mathbf{i}$.

The map Ψ is defined by

$$\Psi(a_1, a_2) = a_1|_{X_0} - a_2|_{X_0} - d_A b_0$$

where b_0 is the unique 0-form satisfying

$$d_A^* d_A b_0 = 0, \ *d_A b_0|_{\partial X_0} = *(a_1 - a_2)|_{\partial X_0}$$

and $b_0 \perp \mathbf{i}$.

Next, define $\mathcal{L}_{\alpha} = \ker d_A^* \cap \Omega^1(X_{\alpha}; su(2))$ for $\alpha = \emptyset, 0, 1, 2$. Again we have an exact, acyclic, Fredholm complex

$$0 \to \mathcal{L} \xrightarrow{\overline{\Phi}} \mathcal{L}_1 \oplus \mathcal{L}_2 \xrightarrow{\overline{\Psi}} \mathcal{L}_0 \to 0,$$

where the maps are $\overline{\Phi}(a)=(a|_{X_1},a|_{X_2})$ and $\overline{\Psi}(a_1,a_2)=a_1|_{X_0}-a_2|_{X_0}$.

Proof of Proposition 7.2: Let $A, A' \in \mathcal{A}^{\circ}$ be two perturbed flat irreducible connections on X. We will use the same notation for their restrictions to the pieces X_{α} . Without loss of generality, we can assume that A and A' are connected by a path $A_t, t \in [0,1]$ for which $A_t|_{X_2}$ is flat and which is mapped 1-1 onto the arc in \tilde{S}_0 connecting $[A|_{\partial X_1}]$ to $[A'|_{\partial X_1}]$ which does not include any central orbits.

To conserve notation, let $\mathcal{T}_{\alpha}(t)$ and $\mathcal{L}_{\alpha}(t)$ denote the fibers of these bundles over A_t . We will let $B_{\alpha}(t)$ denote $*d_{A_t,h}|_{\mathcal{T}_{\alpha}(t)}$ composed with orthogonal projection onto $\mathcal{L}_{\alpha}(t)$. We begin by considering the diagram of maps

$$0 \longrightarrow \mathcal{T}(t) \stackrel{\Phi}{\longrightarrow} \mathcal{T}_{1}(t) \oplus \mathcal{T}_{2}(t) \stackrel{\Psi}{\longrightarrow} \mathcal{T}_{0}(t) \longrightarrow 0$$

$$\downarrow \qquad \qquad \downarrow B(t) \downarrow \qquad \qquad \downarrow B_{1}(t) \oplus B_{2}(t) \qquad \downarrow B_{0}(t) \qquad \downarrow$$

$$0 \longrightarrow \mathcal{L}(t) \stackrel{\overline{\Phi}}{\longrightarrow} \mathcal{L}_{1}(t) \oplus \mathcal{L}_{2}(t) \stackrel{\overline{\Psi}}{\longrightarrow} \mathcal{L}_{0}(t) \longrightarrow 0.$$

Next we adjust the complex to compensate for the extra cokernel at the perturbed flat connections. $B_2(t)$ is surjective for all t. When t=0,1, B_1 has cokernel equal to $\mathcal{H}^1_{A_t,h}(X_1,\partial X_1;su(2))$. To eliminate this, we let $B_1'(t):\mathcal{T}_1(t)\oplus\mathbf{R}\to\mathcal{L}_1(t)$ be the map $(a,s)\mapsto (B_1(a),s\Pi_{\mathcal{L}_1}d_{A_t}\mathbf{i})$. Then, given our nondegeneracy assumptions on $h,B_1'\oplus B_2$ is surjective for t=0,1. Similarly, for t=0,1, B is an isomorphism but B_0 has cokernel equal to $\mathcal{H}^1_{A_t,h}(X_0,\partial X_0;su(2))\cong\mathcal{H}^2_{A_t}(\partial X_1;su(2))$. Let $B_0':\mathcal{T}_0\oplus\mathbf{R}\to\mathcal{L}_0$ be the map $(a,s)\mapsto (B_0(a),s\mathbf{i}du)$ where u is the [0,1] variable.

Proposition 7.3. There exists a pair of nonzero numbers $\lambda(0)$ and $\lambda(1)$ of the same sign such that for t = 0, 1 the following diagram commutes:

$$0 \longrightarrow \mathcal{T}(t) \stackrel{\Phi}{\longrightarrow} \mathcal{T}_{1}(t) \oplus \mathbf{R} \oplus \mathcal{T}_{2}(t) \stackrel{\Psi \oplus \lambda(t)}{\longrightarrow} \mathcal{T}_{0}(t) \oplus \mathbf{R} \longrightarrow 0$$

$$\downarrow \qquad \qquad \downarrow B(t) \downarrow \qquad \qquad \downarrow B'_{1}(t) \oplus B_{2}(t) \qquad \qquad \downarrow B'_{0}(t) \qquad \qquad \downarrow$$

$$0 \longrightarrow \mathcal{L}(t) \stackrel{\overline{\Phi}}{\longrightarrow} \mathcal{L}_{1}(t) \oplus \mathcal{L}_{2}(t) \stackrel{\overline{\Psi}}{\longrightarrow} \mathcal{L}_{0}(t) \longrightarrow 0.$$

Proof. We will prove this by showing that for each $t \in [0,1]$, $\overline{\Psi}(\Pi_{\mathcal{L}_1}(d_A\mathbf{i}))$ is a nonzero multiple of $\mathbf{i} du$. Let $A \in \mathcal{A}^{\diamond}(X)$ be a connection with $A|_{X_2}$ flat.

Let $b \in \Omega^0(X_1; su(2))$ be the unique solution to the equations

$$d_A^* d_A b = 0, \ b|_{\partial X_1} = 0.$$

Then $\Pi_{\mathcal{L}_1} d_A \mathbf{i} = d_A (\mathbf{i} - b)$.

Suppose that $\Pi_{\mathcal{L}_1}d_A\mathbf{i}|_{X_0}=0$. Then $b|_{X_0}$ is a constant multiple of \mathbf{i} . But then the boundary conditions on b imply that $b|_{X_0}=0$, which implies that b=0 on X_1 . This contradicts the fact that $d_A^*d_A\mathbf{i}\neq 0$ on X_1 . Therefore $\Pi_{\mathcal{L}_1}d_A\mathbf{i}|_{X_0}\neq 0$.

The preceding observation rules out the possibility that $(\Pi_{\mathcal{L}_1}d_A\mathbf{i},0)=\overline{\Phi}(a)$ for some $a\in\mathcal{L}$. By exactness, $\overline{\Psi}(\Pi_{\mathcal{L}_1}d_A\mathbf{i},0)\neq 0$. We conclude the proof of Proposition 7.3 by showing that $\Pi_{\mathcal{L}_1}d_A\mathbf{i}|_{X_0}\perp *d_A\Omega^1(X_0;su(2))$. Here we are making use of the Hodge decomposition theorem, justified by the fact that A is flat on X_0 , and the fact that $\mathcal{H}_A^1(X_0;su(2))$ is generated by $\mathbf{i}du$.

Let $z \in \Omega^1(X_0; su(2))$.

$$egin{array}{lll} \langle d_A(\mathbf{i}-b),*d_Az
angle &=& -\int_{X_0} \mathrm{tr}(d_A(\mathbf{i}-b)\wedge d_Az) \ &=& -\int_{\partial X_0} \mathrm{tr}((\mathbf{i}-b)\wedge d_Az) \ &=& -\int_{\partial X_0} \mathrm{tr}(\mathbf{i}d_Az) = \int_{X_0} \mathrm{tr}(d_A\mathbf{i}\wedge z) = 0. \end{array}$$

Now extend $\lambda: \{0,1\} \to \mathbf{R} \setminus \{0\}$ to a continuous function; for example, we can choose $\lambda(t)$ to be the number which satisfies $\overline{\Psi}(\Pi_{\mathcal{L}_1(t)}d_{A_t}\mathbf{i},0) = \lambda(t)\mathbf{i}du$. We can now form the diagram in 7.3 for all $t \in [0,1]$. The rows are exact (since $\lambda(t)$ never vanishes) and the diagram commutes at the endpoints.

Choose a splitting $\overline{\Theta}(t): \mathcal{L}_0(t) \to \mathcal{L}_1(t) \oplus \mathcal{L}_2(t)$ with the property that $\overline{\Psi}(t) \circ \overline{\Theta}(t) = 1$. Since the vertical maps in the diagram are surjective for t = 0, 1, one can easily construct splittings $\Theta(t): \mathcal{T}_0(t) \oplus \mathbf{R} \to \mathcal{T}_1(t) \oplus \mathbf{R} \oplus \mathcal{T}_2$ such that $(B_1'(t) \oplus B_2(t)) \circ \Theta(t) = \overline{\Theta} \circ B_0'(t)$ for t = 0, 1. Since the set of all splittings of this short exact sequence may be identified with the space of bounded maps from $\mathcal{T}_0 \oplus \mathbf{R}$ to \mathcal{T} , which is connected, these may be connected by a path of splittings $\Theta(t): \mathcal{T}_0(t) \oplus \mathbf{R} \to \mathcal{T}_1(t) \oplus \mathbf{R} \oplus \mathcal{T}_2(t)$ satisfying $(\Psi \oplus \lambda(t)) \circ \Theta(t) = 1$.

We shift our attention to the folded over diagram given below.

$$\mathcal{T}(t) \oplus \mathcal{T}_0(t) \oplus \mathbf{R} \xrightarrow{\Phi \oplus \Theta(t)} \mathcal{T}_1(t) \oplus \mathbf{R} \oplus \mathcal{T}_2(t)$$
 $B(t) \oplus B_0'(t) \downarrow \qquad \qquad \downarrow B_1'(t) \oplus B_2(t)$
 $\mathcal{L}(t) \oplus \mathcal{L}_0(t) \xrightarrow{\overline{\Phi} \oplus \overline{\Theta}} \mathcal{L}_1(t) \oplus \mathcal{L}_2(t).$

Its rows are isomorphisms. Furthermore, the diagram commutes at perturbed flat connections (i.e., for t=0,1). The columns are operators of index 2, and when t=0,1 they are surjective. The operator $B_0'(t)$ has is always surjective, with kernel equal to $\mathcal{H}^1_{A_t}(X_0; su(2))$, which we may identify with \mathbf{R}^2 . Let $\Pi_1: \mathcal{T}_0(t) \to \mathbf{R}^2$ denote the orthogonal projection onto this subspace.

We use this to make one final diagram from the previous one, as follows.

$$\mathcal{T}(t) \oplus \mathcal{T}_0(t) \oplus \mathbf{R} \xrightarrow{\Phi \oplus \Theta(t)} \mathcal{T}_1(t) \oplus \mathbf{R} \oplus \mathcal{T}_2(t)$$

$$\downarrow B(t) \oplus B'_0(t) \oplus \Pi_1 \downarrow \qquad \qquad \downarrow B'_1(t) \oplus B_2(t) \oplus (\Pi_1 \circ \Psi(t))$$

$$\mathcal{L}(t) \oplus \mathcal{L}_0(t) \oplus \mathbf{R}^2 \xrightarrow{\overline{\Phi} \oplus \overline{\Theta} \oplus 1} \mathcal{L}_1(t) \oplus \mathcal{L}_2(t) \oplus \mathbf{R}^2.$$

The rows of this diagram are again isomorphisms, and the columns are when t=0,1. Furthermore, when t=0,1, it commutes.

Following [T], we let \mathcal{F}_n denote the set of real, bounded, Fredholm operators on a separable Hilbert space which have index n, and let \mathcal{F}_n^1 denote the subset which has nonempty cokernel. \mathcal{F}_0^1 has codimension 1 in \mathcal{F}^1 . Given two operators $F_0, F_1 \in \mathcal{F}_0$, we define $\delta(F_0, F_1)$ to be the mod (2) cardinality of the set $\{F_t\} \cap \mathcal{F}_0^1$ for a generic path F_t between them. This number is well defined and independent of the path F_t .

Applying this to the current situation, we get that the delta invariants of

$$(B_1'(t) \oplus B_2(t) \oplus \Pi_1) \circ \Psi(t),$$

$$(\overline{\Phi}(t) \oplus \overline{\Theta}(t) \oplus 1) \circ (B(t) \oplus B_0'(t) \oplus \Pi_1 \circ \Psi(t)) \circ (\Phi(t) \oplus \Theta(t))^{-1},$$

$$B(t) \oplus B_0'(t) \oplus \Pi_1 \text{ and } B(t)$$

are all equal. The last delta invariant is equal to $SF(K_{A_0}, K_{A_1})(X)$ modulo 2.

Finally, we relate the delta invariant of $B_1'(t) \oplus B_2(t) \oplus \Pi_{\mathbf{R}^2}$ to the relative intersections numbers at $[A_0]$ and $[A_1]$.

Proposition 7.4.

- 1. $B_1'(t)$ is homotopic rel endpoints to a path $B_1''(t)$ which misses \mathcal{F}_1^1 .
- 2. With $B_1''(t)$ chosen as above, $B_1''(t) \oplus B_2(t)$ is surjective for all t.

Proof. of Proposition 7.4: The first assertion follows immediately from Lemma 5.7 in [T]. The second follows from the fact that $B_2(t)$ is surjective (recall that $A_t|_{X_2}$ are flat u(1) connections).

Now we conclude the proof of Proposition 7.2. Let $V_t = \ker(B_1''(t) \oplus B_2(t))$. These 2-dimensional subspaces fit together to form a vector bundle V over [0,1]. The virtual vector bundle $\operatorname{Index} B_1'(t)$ is oriented in such a way that the orientation on $\ker B_1'(t)$ agrees with that on $T_{[A_t]}\tilde{\mathcal{M}}_h$ for t=0,1 (compare with Section 2). Therefore $\ker B_1''(t)$, a 1-dimensional vector bundle over [0,1], has the same property.

Let $\phi(t): V \to \mathbf{R}^2$ be the map $\phi(t) = \Pi_1 \circ \Psi(t)|_{V_t}$. Perturb $\phi(t)$ relative to the endpoints to get a $\phi'(t): V \to \mathbf{R}^2$ with the section det $\phi'(t)$ transverse to the zero section of $\Lambda^2(\mathbf{R}^2) \otimes \Lambda^2(V^*)$. Then the relative orientations of $T_{[A_t]}\tilde{\mathcal{M}}_h^*(X_1) \oplus \tilde{S}_0$ with \mathbf{R}^2 at t = 0, 1 differ by the cardinality of $\det(\phi')^{-1}(0)$ modulo 2.

Proposition 7.2 proves Theorem 7.1 up to an overall sign. The remainder of this section is devoted to determining that sign.

Lemma 7.5. If A is a perturbed flat connection on X with $\mathcal{H}^1_{A,h}(X; su(2))$ trivial, and if Θ denotes the trivial connection, then $\tilde{r}(\tilde{\mathcal{M}}^*(Y))$ intersects positively with $\tilde{r}(\tilde{\mathcal{M}}(S^1 \times D^2))$ if and only if the spectral flow from K_{Θ} to K_A is even.

Proof. In the case where there are non-closed components in \mathcal{M}_h^* , we can perturb to deform $r(\mathcal{M}(S^1 \times D^2))$ until it intersects the image of an non-closed arc such that $r(\mathcal{M}^*(Y))$, $r(\mathcal{M}^{U(1)}(Y))$ and $r(\mathcal{M}(S^1 \times D^2))$ form a small triangle in \mathcal{M}_{T^2} . Then a direct spectral flow calculation (see [H3]) gives the allows the determination of the spectral flow from the trivial connection to the irreducible perturbed flat connection which is a corner of the triangle, which proves the theorem. If there is no such arc, we can produce one as follows.

On pp. 410-411 of [H1], we described a particular perturbation which gave rise to an irreducible arc in the perturbed flat moduli space of the solid torus. Performing the same perturbation using a pair of curves which are

parallel to μ in Y and have framing 1 does the same thing to the moduli space of Y (adds a new non-closed component to \mathcal{M}^*). It also, however, creates singularities along each part of \mathcal{M}_h^* which maps under r into a neighborhood of $r(\mathcal{M}(S^1 \times D^2))$. By doing the construction from [H1] very close to the trivial orbit, however, and then by perturbing slightly on the Dehn filling, we can arrange that $r(\mathcal{M}(S^1 \times D^2))$ misses these new singularities. Furthermore, with a little care, we can arrange that the new intersections, except for two intersections with the new arc, correspond under a one-to-one, orientation preserving map to the old intersections. Then, once again, the direct spectral flow calculation implies Lemma 7.5.

8. Proof of Main Theorem.

The proof of the main result of this paper now follows easily.

Theorem 8.1. For any $0 < \alpha < \pi$ with $B_{\kappa}(e^{i2\alpha})$ invertible, if \mathcal{M} is non-degenerate then

$$ilde{r}(ilde{\mathcal{M}}^*)\cdot ilde{S}_lpha - ilde{r}(ilde{\mathcal{M}}^*)\cdot ilde{S}_0 = -rac{1}{2} ext{Sign} B_\kappa(e^{i2lpha}).$$

If \mathcal{M} is degenerate, then after a small perturbation this formula holds.

Proof. The assumption about $B_{\kappa}(e^{i2\alpha})$ implies that $\mathcal{H}^1_{A^{\alpha}}(Y, \partial Y; su(2)) = 0$. By Theorem 3.1 we can find a perturbation h satisfying the hypotheses of Lemma 5.1. This lemma, combined with Corollary 6.2 and Proposition 6.3, proves the theorem.

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