

A variational principle for Kaluza–Klein type theories

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For any positive integer n and any Lie group \mathfrak{G} , given a definite symmetric bilinear form on \mathbb{R}^n and an Ad-invariant scalar product on the Lie algebra of \mathfrak{G} , we construct a variational problem on fields defined on an arbitrary oriented $(n + \dim\mathfrak{G})$ -dimensional manifold \mathcal{Y} . We show that, if \mathfrak{G} is compact and simply connected, any global solution of the Euler–Lagrange equations leads, through a spontaneous symmetry breaking, to identify \mathcal{Y} with the total space of a principal bundle over an n -dimensional manifold \mathcal{X} . Moreover \mathcal{X} is then endowed with a (pseudo-)Riemannian metric and a connection which are solutions of the Einstein–Yang–Mills system of equations with a cosmological constant.

1. Introduction

1.1. Motivations

In 1919 T. Kaluza [10] (after an earlier attempt by G. Nordström [14] in 1914) discovered that solutions of the Einstein equations of gravity in vacuum on a 5-dimensional manifold could modelize Einstein equations coupled with Maxwell equations on a 4-dimensional space-time manifold, provided one assumes that the 5-dimensional manifold is a circle fiber bundle over space-time and that the metric is constant along these fibers. This was re-discovered more or less independently by O. Klein [12] in 1926 (and also by H. Mandel [13]), who proposed to assume that the size of the extra fifth dimension is sufficiently tiny in order to explain why this dimension is not directly observed. Since then this fascinating observation has been an important source of inspiration and questioning (see e.g. [5]). It has been extended to include non Abelian gauge theories [2–4, 11], in order to unify the Einstein equations with the Yang–Mills equations on a curved space-time and,

in particular, it becomes an important ingredient of the 11-dimensional supergravity and the superstrings theories. It remains today a subject of questioning (see e.g. [1, 16]).

However some difficulties plag this beautiful idea:

The Kaluza–Klein ansatz is indeed based on the assumption that the metric is covariantly constant along the fibers. But this raises the question of finding physical reasons for that. Moreover the initial proposal by Kaluza and Klein led to inconsistency. This point was raised by P. Jordan [9] and Y. Thiry [15], who allowed the coefficient of the metric along the fifth dimension to be an extra scalar field. However this scalar field is a source of difficulties as to its physical interpretation.

A way to avoid the assumption that the metric is covariantly constant along the fibers is, as proposed by Klein, to assume that the extra dimension is tiny. Then by expanding the fields in harmonic modes on each fiber one finds that, as a consequence of the Heisenberg uncertainty principle, all modes excepted the zero one should be extremely massive. This would hence explain why we cannot observe their quantum excitations. This idea is at the origin of the current hypothesis.

But this does not answer the fundamental question of understanding why these extra dimensions are fibered and compact (and tiny if we want to support the above hypothesis or, alternatively, if the smallness assumption is not true, why the metric is constant along the fiber): could a dynamical mechanism explain these assumptions ?

In the following we address these questions and we present a variational principle which satisfies the following properties: provided that the involved structure Lie group is compact and simply connected, the Euler–Lagrange equations satisfied by the critical points lead to a mechanism which forces a spontaneous fibration of the higher dimensional manifold over an emerging space-time, forces the metric to be covariantly constant along the fibers and one can build out of these critical points a metric and a connection over the space-time which are solutions of the Einstein–Yang–Mills system of equations.

Note that our results work partially for e.g. $U(1)$, for which our mechanism fails to imply the compactness of the fibers without extra *ad hoc* hypotheses. Hence either there is a need to improve our theory (for example by taking into account semi-classical or quantum effects), or one may argue that our results could be sufficient in an Grand Unified Theory, where all

structure gauge groups are supposed to arise from a single compact, simply connected one, by a symmetry breaking.

1.2. The main result

To introduce our model let us first remind the higher dimension generalization of the so-called *Palatini* (see [6]) formulation of gravity: Let $N \geq 2$ be an integer and E be an oriented N -dimensional real vector space endowed with a non degenerate bilinear form \mathfrak{h} (in most cases the Minkowski scalar product) and let $so(E, \mathfrak{h})$ be the Lie algebra of the group of isometries of (E, \mathfrak{h}) . We identify $so(E, \mathfrak{h})$ with $\Lambda^2 E = E \wedge E$ (with a Lie bracket denoted by $[\cdot, \cdot]_2$, see the next section for details). The N -dimensional generalization of the Palatini action on an oriented N -dimensional manifold \mathcal{Y} is a functional defined on pairs (θ, φ) where θ is a (soldering) 1-form on \mathcal{Y} with coefficient in E and φ is a (connection) 1-form on \mathcal{Y} with coefficient in $so(E, \mathfrak{h}) \simeq \Lambda^2 E$. This functional reads

$$\mathcal{A}_P[\theta, \varphi] = \int_{\mathcal{Y}} \star\theta^{(N-2)} \wedge \left(d\varphi + \frac{1}{2}[\varphi \wedge \varphi]_2 \right),$$

or $\mathcal{A}_P[\theta, \varphi] = \int_{\mathcal{Y}} \star\theta^{(N-2)} \wedge \Phi$ by denoting $\Phi := d\varphi + \frac{1}{2}[\varphi \wedge \varphi]_2$. Here $\star\theta^{(N-2)}$ is the $(N - 2)$ -form with coefficient in $so(E, \mathfrak{h})^* \simeq \Lambda^2 E^*$, with components $\theta_{A_1 A_2}^{(N-2)} = \frac{1}{(N-2)!} \epsilon_{A_1 \dots A_N} \theta^{A_3} \wedge \dots \wedge \theta^{A_N}$, where $\epsilon_{A_1 \dots A_N}$ is the completely antisymmetric tensor such that $\epsilon_{1 \dots N} = 1$ and, in the product $\star\theta^{(N-2)} \wedge \Phi$, the duality pairing between $\Lambda^2 E^*$ and $\Lambda^2 E$ is implicitly assumed so that $\star\theta^{(N-2)} \wedge \Phi = \frac{1}{2} \theta_{AB}^{(N-2)} \wedge \Phi^{AB}$ (see the next section for more details).

Then, as it is well-known, the critical points (θ, φ) of \mathcal{A}_P such that the rank of θ is equal to N everywhere correspond to solutions of the Einstein equations of gravity in vacuum (with a metric $\theta^*\mathfrak{h}$ on \mathcal{Y}).

Our model can be seen as a deformation of the previous one: we assume that E is itself endowed with a Lie bracket $[\cdot, \cdot]_1$ and we denote by $\hat{\mathfrak{g}} := (E, [\cdot, \cdot]_1)$ the resulting Lie algebra. We assume further that:

- (i) $\hat{\mathfrak{g}} = \mathfrak{s} \oplus \mathfrak{g}$, where \mathfrak{s} is contained in the center of $\hat{\mathfrak{g}}$ and \mathfrak{g} is a Lie subalgebra;
- (ii) the Lie bracket $[\cdot, \cdot]_1 : \hat{\mathfrak{g}} \times \hat{\mathfrak{g}} \longrightarrow \hat{\mathfrak{g}}$ preserves the metric \mathfrak{h} ;
- (iii) \mathfrak{s} is orthogonal to \mathfrak{g} for the bilinear form \mathfrak{h} .

We set $n = \dim \mathfrak{s}$ and $r = \dim \mathfrak{g}$ so that $N = n + r$. Note that (i) implies that \mathfrak{s} is a *trivial* Lie subalgebra and (ii) means that $\forall \xi \in \hat{\mathfrak{g}}, \text{ad}_\xi \in \text{so}(\hat{\mathfrak{g}}, \mathfrak{h})$. We consider the following space of fields:

$$\mathcal{E} := \{ (\theta, \varphi, \pi); \quad \theta \in \hat{\mathfrak{g}} \otimes \Omega^1(\mathcal{Y}), \varphi \in \text{so}(\hat{\mathfrak{g}}, \mathfrak{h}) \otimes \Omega^1(\mathcal{Y}), \\ \pi \in \hat{\mathfrak{g}}^* \otimes \Omega^{N-2}(\mathcal{Y}) \}$$

and define on it the action functional \mathcal{A} by:

$$(1) \quad \mathcal{A}[\theta, \varphi, \pi] := \int_{\mathcal{Y}} \pi \wedge \left(d\theta + \frac{1}{2}[\theta \wedge \theta]_1 \right) + \star \theta^{(N-2)} \wedge \left(d\varphi + \frac{1}{2}[\varphi \wedge \varphi]_2 \right)$$

where the duality pairing between, respectively, $\hat{\mathfrak{g}}^*$ and $\hat{\mathfrak{g}}$ and $\text{so}(\hat{\mathfrak{g}}, \mathfrak{h})^*$ and $\text{so}(\hat{\mathfrak{g}}, \mathfrak{h})$ is implicitly used.

We decompose $\theta = \theta^{\mathfrak{s}} + \theta^{\mathfrak{g}}$ according to the splitting $\hat{\mathfrak{g}} = \mathfrak{s} \oplus \mathfrak{g}$ and we impose the constraint

$$(2) \quad \theta^{\mathfrak{s}} \wedge \theta^{\mathfrak{s}} \wedge \pi = 0$$

(see the next section for more details) leading hence us to define the constrained subset:

$$\mathcal{C} := \{ (\theta, \varphi, \pi) \in \mathcal{E}; \quad \theta^{\mathfrak{s}} \wedge \theta^{\mathfrak{s}} \wedge \pi = 0 \}.$$

Theorem 1.1. *Assume Hypotheses (i), (ii), (iii). Let \mathcal{Y} be a connected, oriented N -dimensional manifold. Let $(\theta, \varphi, \pi) \in \mathcal{C}$ be a smooth critical point of the restriction of \mathcal{A} on \mathcal{C} . Let $\mathfrak{h} := \theta^* \mathfrak{h}$, a pseudo Riemannian metric on \mathcal{Y} . Assume that:*

- (iv) \mathfrak{g} is the Lie algebra of a **compact and simply connected** Lie group \mathfrak{G} ;
- (v) the rank of θ is equal to N everywhere;
- (vi) $\mathfrak{h} := \theta^* \mathfrak{h}$ is vertically complete (see §1.2.1).

Then

- 1) the manifold \mathcal{Y} is the total space of a principal bundle over an n -dimensional manifold \mathcal{X} ;
- 2) the structure group of this bundle is a group \mathfrak{G}_0 , the universal cover of which is \mathfrak{G} ;
- 3) we can construct explicitly out of θ a pseudo Riemannian metric \mathfrak{g} and a \mathfrak{g} -valued connection ∇ on \mathcal{X} ;

- 4) \mathbf{g} and ∇ are solution of the Einstein–Yang–Mills system with cosmological constant equal to $\Lambda = \frac{1}{8}(K, h^*)$, where K is the Killing form on $\hat{\mathfrak{g}}$, h^* is the metric on $\hat{\mathfrak{g}}^*$ and (\cdot, \cdot) is the natural pairing between both tensors.

1.2.1. About Hypothesis (vi). The pseudo Riemannian metric $\mathbf{h} := \theta^*\mathbf{h}$ is *vertically complete* if, for any continuous map v from $[0, 1]$ to $\mathfrak{g} \subset \hat{\mathfrak{g}}$ and, for any point $\mathbf{y} \in \mathcal{Y}$, there exists an unique \mathcal{C}^1 map $\gamma : [0, 1] \rightarrow \mathcal{Y}$, which is a solution of $(\gamma^*\theta)_t = v(t)dt, \forall t \in [0, 1]$, with the initial condition $\gamma(0) = \mathbf{y}$. Such curves γ can be interpreted *a posteriori* as being *vertical* curves, i.e. contained in a fiber of the principal bundle over a point in the space-time. This allows thus singular space-times with black holes.

1.2.2. Remark. Our action may alternatively be written as follows. We endow the direct sum $\hat{\mathfrak{g}} \oplus so(\hat{\mathfrak{g}}, \mathbf{h})$ with the product Lie bracket $[\cdot, \cdot]$ of, respectively, $(\hat{\mathfrak{g}}, [\cdot, \cdot]_1)$ and $(so(\hat{\mathfrak{g}}, \mathbf{h}), [\cdot, \cdot]_2)$. We consider the space of fields

$$\tilde{\mathcal{E}} := \{ (\theta + \varphi, \pi + \psi); \quad \theta \in \hat{\mathfrak{g}} \otimes \Omega^1(\mathcal{Y}), \quad \varphi \in so(\hat{\mathfrak{g}}, \mathbf{h}) \otimes \Omega^1(\mathcal{Y}), \\ \pi \in \hat{\mathfrak{g}}^* \otimes \Omega^{N-2}(\mathcal{Y}), \quad \psi \in so(\hat{\mathfrak{g}}, \mathbf{h})^* \otimes \Omega^{N-2}(\mathcal{Y}) \}$$

and we define

$$\tilde{\mathcal{A}}[\theta + \varphi, \pi + \psi] := \int_{\mathcal{Y}} (\pi + \psi) \wedge \left(d(\theta + \varphi) + \frac{1}{2}[\theta + \varphi \wedge \theta + \varphi] \right).$$

We observe that, if the constraint

$$(3) \quad \psi = \star\theta^{(N-2)}$$

is satisfied, then $\tilde{\mathcal{A}}[\theta + \varphi, \pi + \psi] = \mathcal{A}[\theta, \varphi, \pi]$. Hence the study of critical points of \mathcal{A} on \mathcal{C} is equivalent to the study of critical points of $\tilde{\mathcal{A}}$ on:

$$\tilde{\mathcal{C}} := \{ (\theta + \varphi, \pi + \psi) \in \tilde{\mathcal{E}}; \quad \psi = \star\theta^{(N-2)} \text{ and } \theta^s \wedge \theta^s \wedge \pi = 0 \}.$$

1.3. Outline of the proof

The action $\mathcal{A}[\theta, \varphi, \pi]$ is the sum of the generalized Palatini action $\int_{\mathcal{Y}} \star\theta^{(N-2)} \wedge (d\varphi + \frac{1}{2}[\varphi \wedge \varphi]_2)$ and of the extra term $\int_{\mathcal{Y}} \pi \wedge (d\theta + \frac{1}{2}[\theta \wedge \theta]_1)$.

In the latter term the coefficients of the $(N - 2)$ -form π (constrained by $\theta^s \wedge \theta^s \wedge \pi = 0$) play the role of Lagrange multipliers and, for a critical point, it forces $d\theta + \frac{1}{2}[\theta \wedge \theta]_1$ to be a linear combination of components of $\theta^s \wedge \theta^s$. One can thus use repeatedly Frobenius theorem: first to the Pfaffian

system $\theta^s|_f = 0$, where f is an r -dimensional submanifold of \mathcal{Y} , to obtain a local foliation of \mathcal{Y} , the leaves f that we show are actually the fibers of a fibration $\mathcal{Y} \rightarrow \mathcal{X}$ thanks to the hypotheses; second by using the fact that $d\theta^g + \frac{1}{2}[\theta^g \wedge \theta^g]_1$ is a linear combination of components of $\theta^s \wedge \theta^s$ to deduce that the geometric data associated with θ are covariantly constant along the fibers.

On the other hand one uses the fact that the first variation of \mathcal{A} with respect to φ vanishes to show that the connection on $T\mathcal{Y}$ associated to φ and θ is the Levi-Civita connection for the metric $\mathbf{h} := \theta^*h$. Note that this step is the same as in the standard derivation of the Palatini Euler–Lagrange equation since φ is only present in the integral $\int_{\mathcal{Y}} \star\theta^{(N-2)} \wedge (d\varphi + \frac{1}{2}[\varphi \wedge \varphi]_2)$.

Lastly one exploits the fact that the first variation of \mathcal{A} with respect to θ vanishes. If the action would only be equal to $\int_{\mathcal{Y}} \star\theta^{(N-2)} \wedge (d\varphi + \frac{1}{2}[\varphi \wedge \varphi]_2)$ one would find that the metric \mathbf{h} on \mathcal{Y} is a solution of the Einstein equation in vacuum and consequently the equivariance of the metric along the fibers derived previously would then give us a solution of an Einstein–Yang–Mills system of equations on \mathcal{X} . However the coupling of θ with π in the second term $\int_{\mathcal{Y}} \pi \wedge (d\theta + \frac{1}{2}[\theta \wedge \theta]_1)$ creates extra source terms in the Einstein–Yang–Mills system which contains an *a priori* high degree of arbitrariness and which could hence ruin our efforts.

A miraculous cancellation: however, apart from a cosmological constant, the extra sources just cancel! This cancellation is due to the fact that each of the source terms is covariantly constant along each fiber and hence is equal to its average value on the fiber, which is compact. But it turns out that this average value is proportional to the integral of an *exact* r -form on the fiber and hence vanishes. This phenomenon is similar to the one discovered in [7] and [8].

2. Notations and description of the obtained equations

2.1. Intrinsic setting

Since our action and the resulting Euler–Lagrange equations mix forms with coefficients in $\hat{\mathfrak{g}}$, $so(\hat{\mathfrak{g}}, \mathfrak{h})$ and their dual spaces it will be convenient to identify $so(\hat{\mathfrak{g}}, \mathfrak{h})$ with $\hat{\mathfrak{g}} \wedge \hat{\mathfrak{g}}$ as follows.

For any finite dimensional real vector space E and any $k \in \mathbb{N}$ we let $E^{\otimes k}$ be the k -th tensorial power of E and $\Lambda^k E := E \wedge \cdots \wedge E$ be the subspace

of $E^{\otimes k}$ of skewsymmetric tensors. If $v_1, \dots, v_k \in E$ we set

$$v_1 \wedge \dots \wedge v_k := \sum_{\sigma \in \mathfrak{S}(k)} (-1)^{|\sigma|} v_{\sigma(1)} \otimes \dots \otimes v_{\sigma(k)} \in \Lambda^k E$$

and, for $p \in \mathbb{N}$ greater than or equal to k and $\lambda \in \Lambda^p E^*$, we define the *interior product*¹ $v_1 \wedge \dots \wedge v_k \lrcorner \lambda$ to be the $(p - k)$ -form in $\Lambda^{p-k} E^*$ such that:

$$\begin{aligned} & (v_1 \wedge \dots \wedge v_k \lrcorner \lambda)(w_{k+1}, \dots, w_p) \\ &= \lambda(v_1, \dots, v_k, w_{k+1}, \dots, w_p), \quad \forall w_{k+1}, \dots, w_p \in E. \end{aligned}$$

To any $\xi \otimes \alpha$ in $E \otimes E^*$ we associate the linear map from E to itself defined by $[\eta \mapsto \xi \alpha(\eta)]$. By extending linearly this map, we get a linear isomorphism which allows us to identify $E \otimes E^*$ with $End(E)$. If furthermore E is endowed with a non degenerate symmetric bilinear form \mathfrak{h} , it induces a vector space isomorphism $\zeta \mapsto \zeta \lrcorner \mathfrak{h} := \mathfrak{h}(\zeta, \cdot)$ from E to E^* . We hence get an unique linear map $\mathcal{L} : E \otimes E \rightarrow E \otimes E^* \simeq End(E)$ such that, for any $\xi, \zeta, \eta \in E$,

$$\mathcal{L}(\xi \otimes \zeta) = \xi \otimes (\zeta \lrcorner \mathfrak{h}) \simeq [E \ni \eta \mapsto \xi \mathfrak{h}(\zeta, \eta) \in E].$$

Then \mathcal{L} is an isomorphism. We endow $E \otimes E$ with the unique product law $*$ such that $\mathcal{L}(\alpha * \beta) = \mathcal{L}(\alpha) \circ \mathcal{L}(\beta)$, $\forall \alpha, \beta \in E \otimes E$. We also get a Lie algebra bracket $[\cdot, \cdot]_2$ on $E \otimes E$ defined by $[\alpha, \beta]_2 = \alpha * \beta - \beta * \alpha$.

The subspace $\Lambda^2 E = E \wedge E \subset E \otimes E$ is then a Lie subalgebra of $(E \otimes E, [\cdot, \cdot]_2)$ which coincides with the inverse image by \mathcal{L} of the Lie subalgebra $so(E, \mathfrak{h})$. This allows us to identify $so(E, \mathfrak{h})$ with $\Lambda^2 E$ endowed with the bracket $[\cdot, \cdot]_2$.

2.2. Introducing a basis of $\hat{\mathfrak{g}}$ and using indices

We let $(\mathbf{t}_A)_{1 \leq A \leq N}$ be a basis of $\hat{\mathfrak{g}}$ such that $(\mathbf{t}_a)_{1 \leq a \leq n}$ is a basis of \mathfrak{s} and $(\mathbf{t}_\alpha)_{n+1 \leq \alpha \leq N}$ is a basis of \mathfrak{g} . We will systematically use the following conventions for the indices: $1 \leq A, B, C, \dots \leq N$ and $1 \leq a, b, c, \dots \leq n < \alpha, \beta, \gamma, \dots \leq N$.

We denote by \mathfrak{b} the restriction of \mathfrak{h} to \mathfrak{s} and \mathfrak{k} the restriction of \mathfrak{h} to \mathfrak{t} and we set $\mathfrak{h}_{AB} := \mathfrak{h}(\mathbf{t}_A, \mathbf{t}_B)$, $\mathfrak{b}_{ab} := \mathfrak{b}(\mathbf{t}_a, \mathbf{t}_b)$ and $\mathfrak{k}_{\alpha\beta} := \mathfrak{k}(\mathbf{t}_\alpha, \mathbf{t}_\beta)$, so that

¹Note that, if we view $v_1 \wedge \dots \wedge v_k$ and λ as elements of, respectively, $E^{\otimes k}$ and $(E^*)^{\otimes p}$, then $v_1 \wedge \dots \wedge v_k \lrcorner \lambda$ is $1/k!$ times the contraction of $v_1 \wedge \dots \wedge v_k$ with λ .

Hypothesis (iii) translates as

$$(\mathbf{h}_{AB}) = \begin{pmatrix} \mathbf{h}_{ab} & \mathbf{h}_{a\beta} \\ \mathbf{h}_{\alpha b} & \mathbf{h}_{\alpha\beta} \end{pmatrix} = \begin{pmatrix} \mathbf{b}_{ab} & 0 \\ 0 & \mathbf{k}_{\alpha\beta} \end{pmatrix}.$$

We denote by c_{BC}^A the structure constants of $\hat{\mathfrak{g}}$ in the basis $(\mathbf{t}_A)_{1 \leq A \leq N}$, defined by $[\mathbf{t}_B, \mathbf{t}_C]_1 = \mathbf{t}_A c_{BC}^A$. We observe that, due to Hypothesis (i),

$$(c_{BC}^A) = \begin{pmatrix} c_{bc}^a & c_{b\gamma}^a & c_{\beta\gamma}^a \\ c_{bc}^\alpha & c_{b\gamma}^\alpha & c_{\beta\gamma}^\alpha \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & c_{\beta\gamma}^\alpha \end{pmatrix}.$$

For any $A, B = 1, \dots, N$, we let $\mathbf{t}_{AB} := \mathbf{t}_A \wedge \mathbf{t}_B$. Then $(\mathbf{t}_{AB})_{1 \leq A < B \leq N}$ is a basis of $\Lambda^2 \hat{\mathfrak{g}} = \hat{\mathfrak{g}} \wedge \hat{\mathfrak{g}}$. Hence using the isomorphism \mathcal{L} defined previously to identify $so(\hat{\mathfrak{g}}, \mathbf{h})$ with $\Lambda^2 \hat{\mathfrak{g}}$ we can view $(\mathbf{t}_{AB})_{1 \leq A < B \leq N}$ as a basis of $so(\hat{\mathfrak{g}}, \mathbf{h})$ as well. Through this identification we have $\mathbf{t}_{AB}(\mathbf{t}_C) = \mathbf{t}_A \mathbf{h}_{BC} - \mathbf{t}_B \mathbf{h}_{AC}$. Moreover

$$[\mathbf{t}_{A_1 B_1}, \mathbf{t}_{A_2 B_2}]_2 = \mathbf{t}_{A_1 B_2} \mathbf{h}_{B_1 A_2} - \mathbf{t}_{A_1 A_2} \mathbf{h}_{B_1 B_2} - \mathbf{t}_{B_1 B_2} \mathbf{h}_{A_1 A_2} + \mathbf{t}_{B_1 A_2} \mathbf{h}_{A_1 B_2}.$$

We denote by $(\mathbf{t}^A)_{1 \leq A \leq N}$ the basis of $\hat{\mathfrak{g}}^*$ which is dual to $(\mathbf{t}_A)_{1 \leq A \leq N}$ and by $(\mathbf{t}^{AB})_{1 \leq A < B \leq N}$ the basis of $\Lambda^2 \hat{\mathfrak{g}}^* \simeq (\Lambda^2 \hat{\mathfrak{g}})^*$ which is dual to $(\mathbf{t}_{AB})_{1 \leq A < B \leq N}$.

If Φ is a form with coefficients in $so(\hat{\mathfrak{g}}, \mathbf{h})$ with coordinates $(\Phi^{AB})_{1 \leq A < B \leq N}$ we set $\Phi^{BA} := -\Phi^{AB}$, for $A \geq B$, so that

$$\Phi = \sum_{1 \leq A < B \leq N} \mathbf{t}_{AB} \Phi^{AB} = \frac{1}{2} \sum_{A, B=1}^N \mathbf{t}_{AB} \Phi^{AB} = \frac{1}{2} \mathbf{t}_{AB} \Phi^{AB}$$

and we will systematically use the last writing $\Phi = \frac{1}{2} \mathbf{t}_{AB} \Phi^{AB}$, where the summation over $1 \leq A, B \leq N$ is implicitly assumed. Similarly if ψ is a $\Lambda^2 \hat{\mathfrak{g}}^*$ -valued form, we will use the same convention $\psi = \frac{1}{2} \psi_{AB} \mathbf{t}^{AB}$ for its decomposition in the basis $(\mathbf{t}^{AB})_{1 \leq A < B \leq N}$. The duality pairing between a $\Lambda^2 \hat{\mathfrak{g}}$ -valued form Φ and a $\Lambda^2 \hat{\mathfrak{g}}^*$ -valued form ψ then reads $\psi \wedge \Phi = \frac{1}{2} \psi_{AB} \wedge \Phi^{AB}$.

Lastly we use \mathbf{h}_{AB} and \mathbf{h}^{AB} to raise and lower the indices: $\varphi^A{}_B = \mathbf{h}_{BB'} \varphi^{AB'}$, $\varphi^{AB} = \varphi^A{}_{B'} \mathbf{h}^{B'B}$, etc.

With these conventions, if $\theta \in \hat{\mathfrak{g}} \otimes \Omega^1(\mathcal{Y})$ we write $\theta = \mathbf{t}_A \theta^A$ and $[\theta \wedge \theta]_1 = \mathbf{t}_A [\theta \wedge \theta]_1^A$ with $[\theta \wedge \theta]_1^A := c_{BC}^A \theta^B \wedge \theta^C$ and hence

$$d\theta^A + \frac{1}{2} [\theta \wedge \theta]_1^A = d\theta^A + \frac{1}{2} c_{BC}^A \theta^B \wedge \theta^C$$

If $\varphi \in so(\hat{\mathfrak{g}}, \mathfrak{h}) \otimes \Omega^1(\mathcal{Y}) \simeq \Lambda^2 \hat{\mathfrak{g}} \otimes \Omega^1(\mathcal{Y})$ we write $\varphi = \frac{1}{2} \mathbf{t}_{AB} \varphi^{AB}$ and $[\varphi \wedge \varphi]_2 = \frac{1}{2} \mathbf{t}_{AB} [\varphi \wedge \varphi]_2^{AB}$ with $[\varphi \wedge \varphi]_2^{AB} := 2\mathbf{h}_{A'B'} \varphi^{AA'} \wedge \varphi^{B'B} = 2\varphi^A_{A'} \wedge \varphi^{A'B}$ and hence

$$d\varphi^{AB} + \frac{1}{2} [\varphi \wedge \varphi]_2^{AB} = d\varphi^{AB} + \varphi^A_{A'} \wedge \varphi^{A'B}.$$

Constraint (2) then reads $\theta^a \wedge \theta^b \wedge \pi = 0, \forall a, b = 1, \dots, n$.

2.3. Useful relations

Assume that the rank of $\theta \in \hat{\mathfrak{g}} \otimes \Omega^1(\mathcal{Y})$ is equal to N everywhere and decompose $\theta = \mathbf{t}_A \theta^A$. Then $(\theta^1, \dots, \theta^N)$ is a coframe on \mathcal{Y} . We denote by $(\frac{\partial}{\partial \theta^1}, \dots, \frac{\partial}{\partial \theta^N})$ its dual frame. We define recursively

$$(4) \quad \begin{aligned} \theta_A^{(N-1)} &:= \frac{\partial}{\partial \theta^A} \lrcorner \theta^{(N)}, & \theta_{AB}^{(N-2)} &:= \frac{\partial}{\partial \theta^B} \lrcorner \theta_A^{(N-1)}, \\ \theta_{ABC}^{(N-3)} &:= \frac{\partial}{\partial \theta^C} \lrcorner \theta_{AB}^{(N-2)}. \end{aligned}$$

Using the fact that $\theta^{(N)} = \frac{1}{N!} \epsilon_{A_1 \dots A_N} \theta^{A_1} \wedge \dots \wedge \theta^{A_N}$ one may prove that

$$(5) \quad \theta_A^{(N-1)} = \frac{1}{(N-1)!} \epsilon_{AA_2 \dots A_N} \theta^{A_2} \wedge \dots \wedge \theta^{A_N},$$

$$(6) \quad \theta_{AB}^{(N-2)} = \frac{1}{(N-2)!} \epsilon_{ABA_3 \dots A_N} \theta^{A_3} \wedge \dots \wedge \theta^{A_N},$$

$$(7) \quad \theta_{ABC}^{(N-3)} = \frac{1}{(N-3)!} \epsilon_{ABCA_4 \dots A_N} \theta^{A_4} \wedge \dots \wedge \theta^{A_N}, \text{ etc.}$$

Moreover we have the following

$$(8) \quad \theta^A \wedge \theta_{A'}^{(N-1)} = \delta_{A'}^A \theta^{(N)},$$

$$(9) \quad \theta^A \wedge \theta_{A'B'}^{(N-2)} = \delta_{B'}^A \theta_{A'}^{(N-1)} - \delta_{A'}^A \theta_{B'}^{(N-1)}$$

and

$$(10) \quad \theta^A \wedge \theta_{A'B'C'}^{(N-3)} = \delta_{C'}^A \theta_{A'B'}^{(N-2)} + \delta_{B'}^A \theta_{C'A'}^{(N-2)} + \delta_{A'}^A \theta_{B'C'}^{(N-2)}.$$

Indeed (8) can be proved by developping the relation $0 = \frac{\partial}{\partial \theta^{A'}} \lrcorner 0 = \frac{\partial}{\partial \theta^{A'}} \lrcorner (\theta^A \wedge \theta^{(N)})$. Computing the interior product by $\frac{\partial}{\partial \theta^{B'}}$ to both sides of (8) leads to (9) and computing the interior product by $\frac{\partial}{\partial \theta^{C'}}$ to both sides of (9) leads to (10).

Lastly we have the following formulas

$$(11) \quad d\theta_A^{(N-1)} = d\theta^B \wedge \theta_{AB}^{(N-2)},$$

$$(12) \quad d\theta_{AB}^{(N-2)} = d\theta^C \wedge \theta_{ABC}^{(N-3)},$$

which can be proved, e.g., by using (5), (6) and (7).

As an application, assuming that the rank of $\theta \in \hat{\mathfrak{g}} \otimes \Omega^1(\mathcal{Y})$ is equal to N , we have

$$\star\theta^{(N-2)} = \frac{1}{2}\theta_{AB}^{(N-2)}\mathbf{t}^{AB}.$$

(Thus Condition (3) reads $\psi = \frac{1}{2}\theta_{AB}^{(N-2)}\mathbf{t}^{AB}$ or, equivalently, $\theta^A \wedge \theta^B \wedge \psi = \mathbf{t}^{AB}\theta^{(N)}$, $\forall A, B = 1, \dots, N$.)

2.4. More precisions on the proof

In the proof of the Theorem, once we prove the existence of a fibration of \mathcal{Y} over \mathcal{X} and once a local trivialization of this bundle has been chosen (characterized by a projection map from \mathcal{Y} to \mathcal{X} and a map g from an open subset of \mathcal{Y} to \mathfrak{G}_0), one can write that $\theta^a = e^a$ and $\theta^\alpha = (gAg^{-1} + g^{-1}dg)^\alpha$, where e^a and $A = \mathbf{t}_\alpha A^\alpha$ are pull-back forms of 1-forms on \mathcal{X} . Then a metric \mathbf{g} on \mathcal{X} is defined by $\mathbf{g} = (\theta^s)^*\mathbf{b} = \mathbf{b}_{ab}e^a e^b$ and A is the expression of the connection ∇ in the trivialization. We then set $F := dA + \frac{1}{2}[A \wedge A]$, the curvature 2-form of A . The variation with respect to θ leads to the equation

$$\frac{1}{2}\theta_{ABC}^{(-3)} \wedge (d\varphi^{AB} + \varphi^A{}_D \wedge \varphi^{DB}) = -d\pi_C - c_{CA}^B \theta^A \wedge \pi_B \text{ mod}[\theta_\gamma^{(N-1)}].$$

One can recognize on the left hand side the Einstein tensor of \mathbf{h} on \mathcal{Y} . After a gauge transformation $e^\alpha = S_\beta^\alpha \theta^\beta$ and $\omega^\alpha{}_\beta = S_{\alpha'}^\alpha \varphi^{\alpha'}{}_{\beta'} (S^{-1})_\beta^{\beta'} - dS_{\beta'}^\alpha (S^{-1})_\beta^{\beta'}$, where $S = \text{Ad}_g$ (see Section 5), the previous equation translates as

$$\frac{1}{2}e_{ABC}^{(-3)} \wedge (d\omega^{AB} + \omega^A{}_D \wedge \omega^{DB}) = -dp_C \text{ mod}[e_\gamma^{(-1)}]$$

The key observations are that the left hand side is constant on any fiber, whereas the restriction of the right hand side to any fiber is an exact form. Both observations lead to the conclusion that

$$\frac{1}{2}e_{ABC}^{(-3)} \wedge (d\omega^{AB} + \omega^A{}_C \wedge \omega^{CB}) = 0 \text{ mod}[e_\gamma^{(-1)}],$$

i.e. the two blocks $\text{Ein}(\mathbf{h})^a{}_c$ and $\text{Ein}(\mathbf{h})^a{}_\gamma$ of the Einstein tensor of ω vanish.

The final equations, after a long computation (see Section 6) then read

$$(13) \quad \begin{cases} \text{Ein}(\mathbf{g})^a{}_d + \frac{1}{2} (F_\gamma{}^{ac} F \gamma_{dc} - \frac{1}{4} F_\gamma{}^{bc} F \gamma_{bc}) \delta_d^a + \Lambda \delta_d^a = 0 \\ \nabla_c F_\gamma{}^{ca} - c_{\alpha\gamma}^\beta A_c^\alpha F_\beta{}^{ca} = 0 \end{cases}$$

where $\text{Ein}(\mathbf{g})^a{}_d := \text{Ric}(\mathbf{g})^a{}_d - \frac{1}{2} \mathbf{R}(\mathbf{g}) \delta_d^a$ is the Einstein tensor of \mathbf{g} , $F := dA + \frac{1}{2} [A \wedge A]$ and $\Lambda := -\frac{1}{8} c_{\beta\gamma}^\alpha c_{\alpha\epsilon}^\beta h^{\gamma\epsilon} = -\frac{1}{8} (K, \mathbf{h}^*)$, where K is the Killing form on \mathfrak{g} .

3. The Euler–Lagrange equations

In the following we assume that $(\theta, \varphi, \pi) \in \mathcal{C}$ is a critical point of \mathcal{A} such that $\text{rank}\theta = N$ (Hypothesis (v)). We denote by $\mathbf{h} = \mathbf{b}_{ab} \theta^a \theta^b + \mathbf{k}_{\alpha\beta} \theta^\alpha \theta^\beta$ the induced metric on \mathcal{Y} and we assume that \mathbf{h} is vertically complete (Hypothesis (vi)).

3.1. Variations with respect to coefficients of π

Since $\text{rank}\theta = N$, the family $(\theta^1, \dots, \theta^N)$ is a coframe on \mathcal{Y} , there exists unique coefficients H_{BC}^A such that $d\theta^A + \frac{1}{2} c_{BC}^A \theta^B \wedge \theta^C = \frac{1}{2} H_{BC}^A \theta^B \wedge \theta^C$ and $H_{BC}^A + H_{CB}^A = 0$. We decompose $\pi = \pi_A \mathbf{t}^A$ and each π_A as $\pi_A = \frac{1}{2} \pi_A^{BC} \theta_{BC}^{(N-2)}$, where $\pi_A^{BC} + \pi_A^{CB} = 0$. The constraint (2) then reads $\pi_A^{ab} = 0$ or

$$(14) \quad \pi_A = \pi_A^{b\gamma} \theta_{b\gamma}^{(N-2)} + \frac{1}{2} \pi_A^{\beta\gamma} \theta_{\beta\gamma}^{(N-2)}$$

A first order variation of (θ, φ, π) keeping θ and φ constant and respecting (14) thus induces a variation of π of the form $\delta\pi_A = \chi_A^{b\gamma} \theta_{b\gamma}^{(N-2)} + \frac{1}{2} \chi_A^{\beta\gamma} \theta_{\beta\gamma}^{(N-2)}$. The fact that the action \mathcal{A} is stationary with respect to such variations of π thus reads

$$\begin{aligned} & \int_{\mathcal{Y}} \delta\pi_A \wedge \left(d\theta^A + \frac{1}{2} [\theta \wedge \theta]^A \right) \\ &= \int_{\mathcal{Y}} \left(\chi_A^{b\gamma} H_{b\gamma}^A + \frac{1}{2} \chi_A^{\beta\gamma} H_{\beta\gamma}^A \right) \theta^{(N)} = 0, \quad \forall \chi_A^{b\gamma}, \chi_A^{\beta\gamma} \end{aligned}$$

and lead to the Euler–Lagrange equations $H_{b\gamma}^A = H_{\beta\gamma}^A = 0, \forall A, b, \beta, \gamma$. We thus deduce that

$$(15) \quad \Theta^A := d\theta^A + \frac{1}{2} c_{BC}^A \theta^B \wedge \theta^C = \frac{1}{2} H_{bc}^A \theta^b \wedge \theta^c$$

or equivalently

$$(16) \quad \begin{cases} d\theta^a = \frac{1}{2}H_{bc}^a \theta^b \wedge \theta^c \\ d\theta^\alpha + \frac{1}{2}c_{\beta\gamma}^\alpha \theta^\beta \wedge \theta^\gamma = \frac{1}{2}H_{bc}^\alpha \theta^b \wedge \theta^c \end{cases}$$

3.2. Variations with respect to φ

Keeping θ and π fixed we look at first order variations $\delta\varphi = \lambda$ of φ . This induces the condition that, for all λ ,

$$\begin{aligned} \frac{1}{2} \int_{\mathcal{Y}} d \left(\lambda^{AB} \wedge \theta_{AB}^{(N-2)} \right) \\ + \lambda^{AB} \wedge \left(d\theta_{AB}^{(N-2)} - \varphi^{A'}{}_A \wedge \theta_{A'B}^{(N-2)} - \varphi^{B'}{}_B \wedge \theta_{AB'}^{(N-2)} \right) = 0 \end{aligned}$$

Assuming that λ has compact support and using (10) and (12) we deduce the relation

$$\begin{aligned} \left(d\theta^C + \varphi^C{}_{C'} \wedge \theta^{C'} \right) \wedge \theta_{ABC}^{(N-3)} \\ = d\theta_{AB}^{(N-2)} - \varphi^{A'}{}_A \wedge \theta_{A'B}^{(N-2)} - \varphi^{B'}{}_B \wedge \theta_{AB'}^{(N-2)} = 0 \end{aligned}$$

which implies that the torsion 2-form $d\theta^A + \varphi^A{}_{A'} \wedge \theta^{A'}$ vanishes. Hence the connection on $T\mathcal{Y}$ associated to φ coincides with the Levi-Civita connection of $(\mathcal{Y}, \mathbf{h})$, where $\mathbf{h} = h_{AB}\theta^A\theta^B$.

3.3. Variations with respect to θ

We first observe that, through a variation $\delta\theta = \tau$ of θ keeping φ and the coefficients $\pi_A^{b\gamma}$ and $\pi_A^{\beta\gamma}$ fixed, we have

$$\delta \left(\theta_{AB}^{(N-2)} \right) = \tau^C \wedge \theta_{ABC}^{(N-3)},$$

plus the relation $\delta\Theta^A = d\tau^A + c_{BC}^A \tau^B \wedge \theta^C$ which implies

$$\pi_A \wedge \delta\Theta^A = d(\tau^A \wedge \pi_A) + \tau^A \wedge (d\pi_A + c_{AB}^C \theta^B \wedge \pi_C)$$

and lastly

$$\begin{aligned} \delta\pi_A = \pi_A^{b\gamma} \left(\tau^d \wedge \theta_{b\gamma d}^{(N-3)} + \tau^\delta \wedge \theta_{b\gamma\delta}^{(N-3)} \right) \\ + \frac{1}{2} \pi_A^{\beta\gamma} \left(\tau^d \wedge \theta_{\beta\gamma d}^{(N-3)} + \tau^\delta \wedge \theta_{\beta\gamma\delta}^{(N-3)} \right) \end{aligned}$$

which, thanks to $\Theta^A \wedge \theta_{b\gamma\delta}^{(N-3)} = \Theta^A \wedge \theta_{\beta\gamma d}^{(N-3)} = \Theta^A \wedge \theta_{\beta\gamma\delta}^{(N-3)} = 0$ by (15), leads to

$$(\delta\pi_A) \wedge \Theta^A = -\pi_A^{b\gamma} H_{bd}^A \tau^d \wedge \theta_\gamma^{(N-1)}.$$

In conclusion, by assuming that τ has compact support, we obtain

$$\int_{\mathcal{Y}} \tau^C \wedge \left(\frac{1}{2} \theta_{ABC}^{(N-3)} \wedge \Phi^{AB} - \pi_A^{b\gamma} H_{bC}^A \theta_\gamma^{(N-1)} + d\pi_C - c_{AC}^B \theta^A \wedge \pi_B \right) = 0$$

where we set $\Phi := d\varphi + \frac{1}{2}[\varphi \wedge \varphi]$. Hence we deduce the Euler–Lagrange equation

$$(17) \quad \frac{1}{2} \theta_{ABC}^{(N-3)} \wedge \Phi^{AB} + d\pi_C - c_{AC}^B \theta^A \wedge \pi_B = 0 \text{ mod}[\theta_{\mathfrak{g}}^{(N-1)}]$$

where, for any 3-form λ , $\lambda = 0 \text{ mod}[\theta_{\mathfrak{g}}^{(N-1)}]$ means that there exists coefficients λ^α such that $\lambda = \lambda^\alpha \theta_\alpha^{(N-1)}$.

4. The fibration

From the first equation in (16) we deduce that $d\theta^a = 0 \text{ mod}[\theta^b], \forall a = 1, \dots, n$. Since the rank of $(\theta^1, \dots, \theta^n)$ is equal to n everywhere, Frobenius’ theorem implies that, for any point $y \in \mathcal{Y}$, there exists a neighbourhood of y in which there exists a unique submanifold \mathfrak{f} of dimension r crossing y such that $\theta^a|_{\mathfrak{f}} = 0, \forall a = 1, \dots, n$. Hence \mathcal{Y} is foliated by integral leaves of dimension r .

Consider on the product manifold $\mathcal{Y} \times \mathfrak{G}$ the \mathfrak{g} -valued 1-form $\tau := h^{-1}dh - \theta^{\mathfrak{g}}$, where (y, h) denotes a point in $\mathcal{Y} \times \mathfrak{G}$ and where $\theta^{\mathfrak{g}} := \mathfrak{t}_\alpha \theta^\alpha$. It satisfies the identity $d\tau + d\theta^{\mathfrak{g}} + \frac{1}{2}[\theta^{\mathfrak{g}} \wedge \theta^{\mathfrak{g}}] + [\theta^{\mathfrak{g}} \wedge \tau] + \frac{1}{2}[\tau \wedge \tau] = 0$. However the second equation in (16) implies that, for any integral leaf \mathfrak{f} , $d\theta^{\mathfrak{g}} + \frac{1}{2}[\theta^{\mathfrak{g}} \wedge \theta^{\mathfrak{g}}]|_{\mathfrak{f}} = 0$ and thus $d(\tau|_{\mathfrak{f} \times \mathfrak{G}}) = 0 \text{ mod}[\tau]$. Hence, again by Frobenius’ theorem, for any $(y_0, g_0) \in \mathfrak{f} \times \mathfrak{G}$, there exist a unique r -dimensional submanifold $\Gamma \subset \mathfrak{f} \times \mathfrak{G}$ which is a solution of $\tau|_{\Gamma} = 0$ and which contains (y_0, g_0) . This implies the existence of a unique map g (the graph of which is Γ) from a neighbourhood of y_0 in \mathfrak{f} to \mathfrak{G} such that $g(y_0) = g_0$ and $dg - g\theta^{\mathfrak{g}}|_{\mathfrak{f}} = 0$. Moreover g is clearly invertible.

Consider any smooth path $\gamma : [0, 1] \rightarrow \mathfrak{G}$ such that $\gamma(0) = 1_{\mathfrak{G}}$ and a point $y_0 \in \mathcal{Y}$. By Hypothesis (vi) we can associate to it a unique path $u : [0, 1] \rightarrow \mathfrak{f}$ such that $u(0) = y_0$ and $(u, \gamma)^* \tau = 0$. The image of (u, γ) is contained in some integral submanifold Γ which coincides locally with the graph of an invertible map g as previously. Thus to any path homotopic to γ in \mathfrak{G} with fixed extremities it corresponds a path homotopic to u in \mathfrak{f} with

fixed extremities. Since \mathfrak{G} is simply connected we can thus define a unique map $T : \mathfrak{G} \rightarrow \mathfrak{f}$ such that $T(1_{\mathfrak{G}}) = y_0$ and $(T \times Id)^*\tau = 0$. Hence \mathfrak{G} is a universal cover of \mathfrak{f} and, in particular, since \mathfrak{G} is compact \mathfrak{f} is *compact*.

To any *fixed* $x = (x^1, \dots, x^n) \in \mathbb{R}^n$ we associated the vector field X on \mathcal{Y} defined by $X = x^a \frac{\partial}{\partial \theta^a}$. Let \mathfrak{f}_0 be some integral leaf. Let us assume that x is in the unit ball B^n of \mathbb{R}^n . Since \mathfrak{f}_0 is compact there exists a neighbourhood \mathcal{T} of \mathfrak{f}_0 in \mathcal{Y} and some $\varepsilon > 0$ such that the flow map $(t, y) \mapsto e^{tX}(y)$ is defined on $[-\varepsilon, \varepsilon] \times \mathcal{T}$. We observe that, due to (16), $L_X \theta^a = H_{bc}^a x^b \theta^c, \forall a$. Hence there exists functions M_{bc}^a on \mathcal{Y} (depending on x) such that $(e^{tX})^* \theta^a = M_c^a \theta^c, \forall a$. For any leaf $\mathfrak{f} \subset \mathcal{T}$, let $\iota : \mathfrak{f} \rightarrow \mathcal{Y}$ its embedding map and $\iota_t := e^{tX} \circ \iota$. Note that the image of ι_t is $e^{tX}(\mathfrak{f})$. We have then

$$\iota_t^* \theta^a = (e^{tX} \circ \iota)^* \theta^a = \iota^* (e^{tX})^* \theta^a = \iota^* (M_c^a \theta^c), \quad \forall a.$$

Thus the 1-form $\mathfrak{t}_a \theta^a$ vanishes on $e^{tX}(\mathfrak{f})$ iff it vanishes on \mathfrak{f} , i.e. \mathfrak{f} is an integral leaf iff $e^{tX}(\mathfrak{f})$ is also an integral leaf. As a consequence the map $B^n \times \mathfrak{f}_0 \ni (x, y) \mapsto e^{\varepsilon x^a \frac{\partial}{\partial \theta^a}}(y)$ is a local diffeomorphism onto a neighbourhood of \mathfrak{f}_0 , which provides us with a local trivialization of the set of leaves. Hence the set \mathcal{X} of integral leaves has the structure of an n -dimensional manifold and the quotient map $P : \mathcal{Y} \rightarrow \mathcal{X}$ is a bundle fibration.

Set $e^a := \theta^a$, for $1 \leq a \leq n$. From $\frac{\partial}{\partial \theta^{\beta}} \lrcorner e^a = \frac{\partial}{\partial \theta^{\beta}} \lrcorner de^a = 0$ we deduce that there exists a coframe $(\underline{e}^a)_{1 \leq a \leq n}$ on \mathcal{X} such that $e^a = P^* \underline{e}^a, \forall a$. Thus we can equip \mathcal{X} with the pseudo Riemannian metric $\underline{\mathfrak{g}} := \mathfrak{b}_{ab} \underline{e}^a \underline{e}^b$.

In the following we choose an n -dimensional submanifold $\Sigma \subset \mathcal{Y}$ transverse to the fibration. Without loss of generality (replacing \mathcal{Y} by an open subset of \mathcal{Y} if necessary) we can assume that Σ intersects all fibers of P and we define the map $g : \mathcal{Y} \rightarrow \mathfrak{G}$ which is constant equal to $1_{\mathfrak{G}}$ on Σ and such that $dg - g\theta^{\mathfrak{g}}|_{\mathfrak{f}} = 0$ for any integral leaf \mathfrak{f} . We then define $A := g\theta^{\mathfrak{g}}g^{-1} - dg \cdot g^{-1}$. The relation $dg - g\theta^{\mathfrak{g}}|_{\mathfrak{f}} = 0$ then translates as $A|_{\mathfrak{f}} = 0$ and hence we have the decomposition $A = A_a \theta^a$. Moreover since

$$(18) \quad \theta^{\mathfrak{g}} = g^{-1} A g + g^{-1} dg,$$

we have $d\theta^{\mathfrak{g}} + \frac{1}{2}[\theta \wedge \theta]^{\mathfrak{g}} = g^{-1}(dA + \frac{1}{2}[A \wedge A])g = g^{-1} F g$, where $F := dA + \frac{1}{2}[A \wedge A]$. By using (16) we deduce that $\frac{\partial}{\partial \theta^{\alpha}} \lrcorner dA = 0, \forall \alpha = n + 1, \dots, N$, i.e. the coefficients A_a are constants on the fibers \mathfrak{f} . Moreover we have

$$(19) \quad F^{\alpha} = \frac{1}{2} F_{bc}^{\alpha} e^b \wedge e^c,$$

where the coefficients $F_{bc} = g H_{bc}^{\mathfrak{g}} g^{-1}$ are constant on the fibers.

5. Trivialization of the bundle

Using the map $g : \mathcal{Y} \rightarrow \mathfrak{G}$ defined previously we define the map S from \mathcal{Y} to $\text{End}(\hat{\mathfrak{g}})$ which, to any $y \in \mathcal{Y}$, associates $\text{Ad}_{g(y)}$. In other words, $\forall (v, \xi) \in \mathfrak{s} \times \mathfrak{g}$, $S(v + \xi) := g(v + \xi)g^{-1} = v + g\xi g^{-1}$. We remark that S takes values in $SO(\hat{\mathfrak{g}}, \mathfrak{h})$ because of Hypothesis (ii). Let $(S_B^A)_{1 \leq A, B \leq N}$ be the matrix of S in the basis $(\mathbf{t}_A)_{1 \leq A \leq N}$, i.e. such that $S(\mathbf{t}_A) = \mathbf{t}_B S_B^A$. We define a new coframe $(e^A)_{1 \leq A \leq N}$ by $e^A = S_B^A \theta^B$. Equivalently

$$\begin{cases} e^a := \theta^a & \forall a = 1, \dots, n \\ e^\alpha := S_\beta^\alpha \theta^\beta & \forall \alpha = n + 1, \dots, N \end{cases}$$

Then $e^\alpha = (g\theta^{\mathfrak{g}}g^{-1})^\alpha$ and (18) imply

$$(20) \quad e^\alpha = A^\alpha + (dg g^{-1})^\alpha, \quad \forall \alpha = n + 1, \dots, N.$$

We deduce that

$$\begin{aligned} & de^\alpha - \frac{1}{2}[e \wedge e]^\alpha + [A \wedge e]^\alpha \\ &= de^\alpha - \frac{1}{2}[e \wedge e]^\alpha + [(e - dg g^{-1}) \wedge e]^\alpha \\ &= de^\alpha + \frac{1}{2}[e \wedge e]^\alpha - [dg g^{-1} \wedge e]^\alpha \\ &= (gd\theta g^{-1} + [dgg^{-1} \wedge e])^\alpha + \frac{1}{2}[e \wedge e]^\alpha - [dgg^{-1} \wedge e]^\alpha \\ &= \left(g \left(d\theta + \frac{1}{2}[\theta \wedge \theta] \right) g^{-1} \right)^\alpha \end{aligned}$$

from which we get the useful identity

$$(21) \quad de^\alpha - \frac{1}{2}[e \wedge e]^\alpha + [A \wedge e]^\alpha = F^\alpha := \frac{1}{2}F_{bc}^\alpha e^b \wedge e^c.$$

Let us translate the left hand side of (17) in the new coframe. First we define $e^{(N)} := e^1 \wedge \dots \wedge e^N$ and note that $e^{(N)} = \theta^{(N)}$. Moreover defining $e_A^{(N-1)} := \frac{\partial}{\partial e^A} \lrcorner e^{(N)}$, $e_{AB}^{(N-2)} := \frac{\partial}{\partial e^A} \wedge \frac{\partial}{\partial e^B} \lrcorner e^{(N)}$, we observe that, since $\frac{\partial}{\partial \theta^A} = \frac{\partial}{\partial e^B} S_A^B$, we have $\theta_A^{(N-1)} = e_{A'}^{(N-1)} S_A^{A'}$, $\theta_{AB}^{(N-2)} = e_{A'B'}^{(N-2)} S_A^{A'} S_B^{B'}$ and $\theta_{ABC}^{(N-3)} = e_{A'B'C'}^{(N-3)} S_A^{A'} S_B^{B'} S_C^{C'}$.

Second let ω be the $so(\hat{\mathfrak{g}}, \mathfrak{h})$ -valued connection 1-form in the coframe $(e^A)_{1 \leq A \leq N}$, which is equal to $\omega := S\varphi S^{-1} - dS S^{-1}$. Let $\Omega := d\omega + \frac{1}{2}[\omega \wedge \omega] = S\Phi S^{-1}$, where $\Phi = d\varphi + \frac{1}{2}[\varphi \wedge \varphi]$. Then $\Phi^{AB} = (S^{-1})_A^A (S^{-1})_B^B \Omega^{A'B'}$.

We deduce that $\theta_{ABC}^{(N-3)} \wedge \Phi^{AB} = e_{ABC'}^{(N-3)} \wedge \Omega^{AB} S_C^{C'}$. Hence (17) is equivalent to

$$(22) \quad \frac{1}{2} e_{ABC'}^{(N-3)} \wedge \Omega^{AB} + (d\pi_{C'} - c_{AC'}^B \theta^A \wedge \pi_B) (S^{-1})_C^{C'} = 0 \text{ mod}[e_{\mathfrak{g}}^{(N-1)}],$$

where, for any $(N-1)$ -form λ , we write:

$$\lambda = 0 \text{ mod}[e_{\mathfrak{g}}^{(N-1)}]$$

iff there exists forms λ^α such that $\lambda = \lambda^\alpha e_\alpha^{(N-1)}$.

In the following we use extensively Relations (8), (9), (10), (11) and (12).

Lemma 5.1. *We have*

$$(23) \quad (d\pi_{C'} - c_{AC'}^B \theta^A \wedge \pi_B) (S^{-1})_C^{C'} = d \left(\pi_{C'} (S^{-1})_C^{C'} \right) \text{ mod}[e_{\mathfrak{g}}^{(N-1)}].$$

Proof. From the definition of S we deduce that, $\forall \xi \in \hat{\mathfrak{g}}$,

$$d(S^{-1}(\xi)) = [g^{-1}\xi g, g^{-1}dg] = g^{-1}[\xi, \mathbf{t}_\alpha(e^\alpha - A^\alpha)]g = -S^{-1}([e - A, \xi]),$$

where, in the last equality we used the fact that $[\xi, \mathbf{t}_\alpha e^\alpha] = 0$ because of Hypothesis (i). Thus we can write $d(S^{-1})_C^{C'} = -(S^{-1})_A^{C'} c_{BC}^A (e^B - A^B)$. Hence

$$\begin{aligned} d \left((S^{-1})_C^{C'} \pi_{C'} \right) &= -(S^{-1})_A^{C'} c_{BC}^A (e^B - A^B) \wedge \pi_{C'} + (S^{-1})_C^{C'} (d\pi_{C'}) \\ &= -(S^{-1})_A^{C'} c_{BC}^A S_B^B \theta^{B'} \wedge \pi_{C'} + (S^{-1})_A^{C'} c_{BC}^A A^B \wedge \pi_{C'} \\ &\quad + (S^{-1})_C^{C'} (d\pi_{C'}) \end{aligned}$$

But because of $[\text{Ad}_g(\xi), \text{Ad}_g(\eta)] = \text{Ad}_g([\xi, \eta])$, $\forall \xi, \eta \in \mathfrak{g}$, which is equivalent to $c_{B'C'}^A S_B^{B'} S_C^{C'} = S_A^A c_{BC}^A$, we have $(S^{-1})_A^{C'} c_{BC}^A S_B^{B'} = c_{B'C''}^{C'} (S^{-1})_C^{C''}$. Thus for the first term on the r.h.s.,

$$(S^{-1})_A^{C'} c_{BC}^A S_B^{B'} \theta^{B'} \wedge \pi_{C'} = c_{B'C''}^{C'} (S^{-1})_C^{C''} \theta^{B'} \wedge \pi_{C'} = c_{AC'}^B \theta^A \wedge \pi_B (S^{-1})_C^{C'}$$

and hence

$$d \left((S^{-1})_C^{C'} \pi_{C'} \right) = (d\pi_{C'} - c_{AC'}^B \theta^A \wedge \pi_B) (S^{-1})_C^{C'} + (S^{-1})_A^{C'} c_{BC}^A A^B \wedge \pi_{C'}$$

However it follows from (14) that $\pi_{C'} = S_{\gamma'}^\gamma \pi_{C'}^{b\gamma'} e_{b\gamma}^{(N-2)} + \frac{1}{2} S_{\beta'}^\beta S_{\gamma'}^\gamma \pi_{C'}^{\beta'\gamma'} e_{\beta\gamma}^{(N-2)}$ and, since $A^B = A_c^B e^c$, we get

$$(S^{-1})_A^{C'} c_{BC}^A A^B \wedge \pi_{C'} = -(S^{-1})_A^{C'} c_{BC}^A A_b^B S_{\gamma'}^\gamma \pi_{C'}^{b\gamma'} e_{\gamma}^{(N-1)} = 0 \text{ mod}[e_{\mathfrak{g}}^{(N-1)}].$$

Hence (23) follows. □

Thus if we define $p_C := \pi_{C'}(S^{-1})_C^{C'}$ we deduce from (23) that (22) is equivalent to

$$(24) \quad \frac{1}{2}e_{ABC}^{(N-3)} \wedge \Omega^{AB} + dp_C = 0 \text{ mod}[e_{\mathfrak{g}}^{(N-1)}].$$

We need to compute dp_C . For that purpose we use the *a priori* decomposition $p_C = p_C^{b\gamma} e_{b\gamma}^{(N-2)} + \frac{1}{2}p_C^{\beta\gamma} e_{\beta\gamma}^{(N-2)}$. We first compute using (9), (10), (16) and (21)

$$\begin{aligned} de_{b\gamma}^{(N-2)} &= de^a \wedge e_{b\gamma a}^{(N-3)} + de^\alpha \wedge e_{b\gamma \alpha}^{(N-3)} \\ &= H_{ab}^a e_\gamma^{(N-1)} + c_{\gamma\alpha}^\alpha e_b^{(N-1)} - c_{\beta\gamma}^\alpha (A^\beta)_b e_\gamma^{(N-1)} \\ &= \left(H_{ab}^a - c_{\beta\gamma}^\alpha (A^\beta)_b \right) e_\gamma^{(N-1)} = 0 \text{ mod}[e_{\mathfrak{g}}^{(N-1)}], \end{aligned}$$

where we have used the fact that, since \mathfrak{G} is compact, its Lie algebra \mathfrak{g} is *unimodular*, which reads $c_{\gamma\alpha}^\alpha = 0$. Similarly

$$\begin{aligned} de_{\beta\gamma}^{(N-2)} &= de^a \wedge e_{\beta\gamma a}^{(N-3)} + de^\alpha \wedge e_{\beta\gamma \alpha}^{(N-3)} \\ &= 0 + c_{\gamma\alpha}^\alpha e_\beta^{(N-1)} + c_{\alpha\beta}^\alpha e_\gamma^{(N-1)} + c_{\beta\gamma}^\alpha e_\alpha^{(N-1)} \\ &= 0 \text{ mod}[e_{\mathfrak{g}}^{(N-1)}], \end{aligned}$$

Thus by writing $dp_C^{b\gamma} = p_{C,c}^{b\gamma} e^c + p_{C,\gamma}^{b\gamma} e^\gamma$ and $dp_C^{\beta\gamma} = p_{C,c}^{\beta\gamma} e^c + p_{C,\delta}^{\beta\gamma} e^\delta$, we get

$$\begin{aligned} dp_C &= p_{C,\gamma}^{b\gamma} e_b^{(N-1)} - p_{C,b}^{b\gamma} e_\gamma^{(N-1)} + p_{C,\gamma}^{\beta\gamma} e_\beta^{(N-1)} \text{ mod}[e_{\mathfrak{g}}^{(N-1)}] \\ &= p_{C,\gamma}^{b\gamma} e_b^{(N-1)} \text{ mod}[e_{\mathfrak{g}}^{(N-1)}] \end{aligned}$$

Lastly by decomposing $\Omega^{AB} = \frac{1}{2}\Omega^{AB}_{CD} e^C \wedge e^D$, we find that

$$\frac{1}{2}e_{ABC}^{(N-3)} \wedge \Omega^{AB} = -\text{Ein}(\omega)^A_C e_A^{(N-1)},$$

where $\text{Ein}(\omega)^A_C := \text{Ric}(\omega)^A_C - \frac{1}{2}\text{R}(\omega)\delta^A_C$, $\text{Ric}(\omega)^A_C := \Omega^{AB}_{CB}$ and $\text{R}(\omega) := \text{Ric}(\omega)^A_A$. Obviously $\text{Ric}(\omega)^A_C$ is the Ricci curvature, $\text{R}(\omega)$ the scalar curvature and $\text{Ein}(\omega)^A_C$ the Einstein tensor of \mathfrak{h} in the coframe $(e^A)_{1 \leq A \leq N}$.

Hence we find that (24) is equivalent to

$$\left(\text{Ein}(\omega)^a{}_C - p_{C,\gamma}^{a\gamma} \right) e_a^{(N-1)} = 0 \pmod{[e_{\mathfrak{g}}^{(N-1)}]},$$

or

$$(25) \quad \text{Ein}(\omega)^a{}_C = p_{C,\gamma}^{a\gamma}, \quad \forall a = 1, \dots, n, \quad \forall C = 1, \dots, N.$$

We will come back to this equation later on.

6. Computation of the connection and the curvature forms

We need to compute the connection 1-form ω and its curvature 2-form. As a preliminary we first set $\underline{\gamma}^a{}_c$ to be the connection 1-form on $(\mathcal{X}, \mathfrak{g})$ in the coframe \underline{e}^a , i.e. which satisfies $\underline{\gamma}^{ac} + \underline{\gamma}^{ca} = 0$ and $d\underline{e}^a + \underline{\gamma}^a{}_c \wedge \underline{e}^b = 0$. Then we set $\gamma^a{}_c := P^* \underline{\gamma}^a{}_c$ which satisfies similar relations, which, together with (21), leads to

$$(26) \quad \begin{cases} de^a + \gamma^a{}_c \wedge e^c = 0 \\ de^\alpha - \frac{1}{2} F_{bc}^\alpha e^b \wedge e^c - \frac{1}{2} c_{\beta\gamma}^\alpha (e^\beta - 2A^\beta) \wedge e^\gamma = 0 \end{cases}$$

Now the connexion 1-form ω is uniquely characterized by the condition $\omega^{AB} + \omega^{BA} = 0$ (preservation of the metric) and $de^A + \omega^A{}_C \wedge e^C = 0$ (the torsion vanishes), which can be written

$$(27) \quad \begin{cases} de^a + \omega^a{}_c \wedge e^c + \omega^a{}_\gamma \wedge e^\gamma = 0 \\ de^\alpha + \omega^\alpha{}_c \wedge e^c + \omega^\alpha{}_\gamma \wedge e^\gamma = 0 \end{cases}$$

Comparing with (26) we are tempted to assume that $\omega^a{}_\gamma = -\frac{1}{2} c_{\beta\gamma}^\alpha (e^\beta - 2A^\beta)$, which fulfills the condition $\omega^{\alpha\beta} + \omega^{\beta\alpha} = 0$, since $c_{\beta\gamma'}^\alpha k^{\gamma'\gamma} + c_{\beta\alpha'}^\gamma k^{\alpha'\alpha} = 0$ because the metric k is preserved by the adjoint action of \mathfrak{g} . We also guess that $\omega^\alpha{}_c = -\frac{1}{2} F_{bc}^\alpha e^b$, which forces automatically $\omega^a{}_\gamma = \frac{1}{2} k_{\gamma\gamma'} F_{bc}^{\gamma'} \mathfrak{g}^{c'c} e^b$, in order to satisfy $\omega^{\alpha b} + \omega^{b\alpha} = 0$. Then in order to fulfill the first relation of (27), one needs to assume that $\omega^a{}_c = \gamma^a{}_c - \frac{1}{2} k_{\gamma\gamma'} F_{a'c}^{\gamma'} \mathfrak{b}^{a'a} e^\gamma$. We then check that $\omega^{ac} = \gamma^{ac} - \frac{1}{2} k_{\gamma\gamma'} F_{a'c'}^{\gamma'} \mathfrak{b}^{a'a} \mathfrak{b}^{c'c} e^\gamma$ is skew symmetric in (a, c) . Thus we see that the forms ω^{AC} defined by:

$$\begin{pmatrix} \omega^a{}_c & \omega^a{}_\gamma \\ \omega^\alpha{}_c & \omega^\alpha{}_\gamma \end{pmatrix} = \begin{pmatrix} \gamma^a{}_c - \frac{1}{2} k_{\gamma\gamma'} F_{a'c}^{\gamma'} \mathfrak{b}^{a'a} e^\gamma & \frac{1}{2} k_{\gamma\gamma'} F_{ba'}^{\gamma'} \mathfrak{b}^{a'a} e^b \\ -\frac{1}{2} F_{bc}^\alpha e^b & -\frac{1}{2} c_{\beta\gamma}^\alpha (e^\beta - 2A^\beta) \end{pmatrix}$$

satisfy (27) and $\omega^{AC} + \omega^{CA} = 0$. Hence this is the Levi-Civita connection 1-form of $(\mathcal{Y}, \mathbf{h})$. In the following it will be convenient to set $F^{\gamma}_{bc} := F^{\gamma}_{bc}$, $F^a_{\gamma c} := k_{\gamma\gamma'} F^{\gamma'}_{a'c} b^{a'a}$ and $F^c_{\gamma b} := k_{\gamma\gamma'} F^{\gamma'}_{bc} b^{c'c}$. Then

$$\begin{pmatrix} \omega^a_c & \omega^a_\gamma \\ \omega^\alpha_c & \omega^\alpha_\gamma \end{pmatrix} = \begin{pmatrix} \gamma^a_c - \frac{1}{2} F^a_{\gamma c} e^\gamma & \frac{1}{2} F^a_{\gamma b} e^b \\ -\frac{1}{2} F^\alpha_{bc} e^b & -\frac{1}{2} c^\alpha_{\beta\gamma} (e^\beta - 2A^\beta) \end{pmatrix}$$

We can thus compute the curvature 2-form $\Omega^A_C = d\omega^A_C + \omega^A_B \wedge \omega^B_C$.

$$\begin{aligned} \Omega^a_c &= d\left(\gamma^a_c - \frac{1}{2} F^a_{\gamma c} e^\gamma\right) + \left(\gamma^a_b - \frac{1}{2} F^a_{\beta' b} e^{\beta'}\right) \wedge \left(\gamma^b_c - \frac{1}{2} F^b_{\gamma' c} e^{\gamma'}\right) \\ &\quad - \frac{1}{4} F^a_{\beta b'} F^{\beta'}_{c'e} e^{b'} \wedge e^{c'}, \\ \Omega^a_\gamma &= d\left(F^a_{\gamma b} e^b\right) + \frac{1}{2} \left(\gamma^a_b - \frac{1}{2} F^a_{\beta' b} e^{\beta'}\right) \wedge \left(F^b_{\gamma' c} e^{c'}\right) \\ &\quad + \frac{1}{4} F^a_{\beta b'} c^\beta_{\gamma' c} e^{b'} \wedge (2A^{\beta'} - e^{\beta'}), \\ \Omega^\alpha_c &= -d\left(F^\alpha_{bc} e^b\right) - \frac{1}{2} \left(F^\alpha_{b'b} e^{b'}\right) \wedge \left(\gamma^b_c - \frac{1}{2} F^b_{\gamma' c} e^{\gamma'}\right) \\ &\quad - \frac{1}{4} F^\beta_{bc} c^\alpha_{\beta'\beta} (2A^{\beta'} - e^{\beta'}) \wedge e^b, \\ \Omega^\alpha_\gamma &= \frac{1}{2} d\left(c^\alpha_{\beta\gamma} (2A^\beta - e^\beta)\right) - \frac{1}{4} \left(F^\alpha_{b'b} e^{b'}\right) \wedge \left(F^b_{\gamma' c} e^{c'}\right) \\ &\quad + \frac{1}{4} c^\alpha_{\beta'\beta} c^\beta_{\gamma' c} (2A^{\beta'} - e^{\beta'}) \wedge (2A^{\gamma'} - e^{\gamma'}). \end{aligned}$$

Lastly we obtain the components of the Ricci tensor $\text{Ric}(\omega)$ through a lengthy computation.

$$(28) \quad \text{Ric}(\omega)^a_d = \text{Ric}(\gamma)^a_d - \frac{1}{2} F^{\beta ac} F^{\beta d}$$

where $\text{Ric}(\gamma)^a_d := (d\gamma^a_c + \gamma^a_b \wedge \gamma^b_c)_{de} b^{ce}$ is the Ricci curvature of γ , and using the decompositions $dF_\delta^{ac} = F_{\delta,c}^{ac} e^c$ and $\gamma^a_b = (\gamma^a_b)_c e^c$,

$$(29) \quad \text{Ric}(\omega)^a_\delta = \frac{1}{2} \left(F_{\delta,c}^{ac} + (\gamma^a_b)_c F_\delta^{bc} + (\gamma^c_b)_c F_\delta^{ab} - c_{\alpha\delta}^\gamma A_c^\alpha F_\gamma^{ac} \right)$$

$$(30) \quad \text{Ric}(\omega)^\alpha_\delta = \frac{1}{4} F_\delta^{bc} F_{bc}^\alpha - \frac{1}{4} c_{\beta\gamma}^\alpha c_{\delta\epsilon}^\beta k^{\gamma\epsilon}$$

We deduce the scalar curvature $R(\omega)$ of ω in function of the scalar curvature $R(\gamma) := \text{Ric}(\gamma)^a_a$:

$$(31) \quad R(\omega) = R(\gamma) - \frac{1}{4}F_\alpha^{ab}F^\alpha_{ab} - \frac{1}{4}c_{\beta\gamma}^\alpha c_{\alpha\delta}^\beta k^{\gamma\delta}$$

Hence the Einstein tensor of ω is

$$(32) \quad \text{Ein}(\omega)^a_d = \text{Ein}(\gamma)^a_d - \frac{1}{2} \left(F_\beta^{ac}F^\beta_{dc} - \frac{1}{4}F_\alpha^{bc}F^\alpha_{bc}\delta^a_d \right) + \frac{1}{8}c_{\beta\gamma}^\alpha c_{\alpha\delta}^\beta k^{\gamma\delta}\delta^a_d$$

and $\text{Ein}(\omega)^a_\delta = \text{Ric}(\omega)^a_\delta$ is given by (29).

An important observation is that *the components of $\text{Ein}(\omega)^a_d$ and $\text{Ein}(\omega)^a_\delta$ are constant on the fibers f .*

7. The Einstein–Yang–Mills equations

We conclude by exploiting the fact that the fibers f are compact without boundary. Let $\mu^{(r)} := e^{n+1} \wedge \dots \wedge e^N$ and set $\mu_\alpha^{(r-1)} := \frac{\partial}{\partial e^\alpha} \lrcorner \mu^{(r)}, \forall \alpha$. By integrating both sides of (25) on a fiber f we obtain

$$\int_f \text{Ein}(\omega)^a_C \mu^{(r)} = \int_f p_{C,\gamma}^{a\gamma} \mu^{(r)} = \int_f d \left(p_C^{a\gamma} \mu_\gamma^{(r-1)} \right) = 0.$$

But on the one hand, the components of $\text{Ein}(\omega)^a_C$ are constant on the fiber f , as seen in the previous section. Hence

$$(33) \quad \text{Ein}(\omega)^a_C = \frac{\int_f \text{Ein}(\omega)^a_C \mu^{(r)}}{\int_f \mu^{(r)}} = 0.$$

Thus, using (29) and (32) we deduce that γ and A are solutions of the Einstein–Yang–Mills system

$$\begin{cases} \text{Ein}(\gamma)^a_d - \frac{1}{2} \left(F_\beta^{ac}F^\beta_{dc} - \frac{1}{4}F_\alpha^{bc}F^\alpha_{bc}\delta^a_d \right) + \frac{1}{8}c_{\beta\gamma}^\alpha c_{\alpha\delta}^\beta k^{\gamma\delta}\delta^a_d = 0 \\ F_\delta^{ac},_c + (\gamma^a_b)_c F_\delta^{bc} + (\gamma^c_b)_c F_\delta^{ab} - c_{\alpha\delta}^\gamma A_c^\alpha F_\gamma^{ac} = 0 \end{cases}$$

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