EXPLOITING LOG-CAPACITY IN CONVEX GEOMETRY*

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Abstract. This article is devoted to an exploitation of the log-capacity for convex bodies - especially - its connections to volume-radius, mean-width, Hadamard-type variational formula, Minkowski-type problem, and Yau-type problem.

Key words. Log-capacity, volume-radius, mean-width, Hadamard-type variation, Minkowski-type problem, Yau-type problem.

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1. Introduction.

1.1. Background. Thanks to its role in two-dimensional potential theory that is the study of planar harmonic functions in mathematics and mathematical physics, the logarithmic capacity in the Euclidean plane \mathbb{R}^2 has been studied systemically; see [28, 2, 24, 33, 44, 45, 43, 54] for some relatively recent publications on this topic. However, the higher dimensional extension (i.e., to the Euclidean space \mathbb{R}^n , $n \geq 3$) of the planar logarithmic capacity has received relatively little attention due to a nonlinear nature; see [6, 11, 18, 19, 3, 4, 32] (see also [1, 23, 39] for some function-space-based capacities) only because of the author's limited knowledge of other references.

Fortunately, in their paper [11] Colosanti-Cuoghi were able to utilize an equilibrium potential to introduce a kind of the logarithmic capacity (in short, log-capacity) for $2 \leq n$ -dimensional convex bodies. To be more precise, let \mathscr{C}^n be the class of all non-empty convex compact subsets of \mathbb{R}^n , and denote by \mathscr{K}^n the class of all $K \in \mathscr{C}^n$ with non-empty interior K° . For $K \in \mathscr{K}^n$ let $u = u_K$ be its log-equilibrium potential, i.e., the unique weak solution to the following boundary value problem:

$$\begin{cases} -\operatorname{div}(|\nabla u|^{n-2}\nabla u) = 0 \quad \text{in} \quad \mathbb{R}^n \setminus K; \\ u = 0 \quad \text{on} \quad \partial K; \\ u(x) \sim \log |x| \quad \text{as} \quad |x| \to \infty, \end{cases}$$
(1.1)

where $\log(\cdot)$ is the base-*e* (i.e., natural) logarithm, ~ means that there exists a constant c > 0 such that

$$c^{-1} \le \frac{u(x)}{\log |x|} \le c$$
 as $|x| \to \infty$.

In accordance with Kichenassamy-Veron's [31, Theorem 1.1 and Remarks 1.4-1.5], $u(x) - \log |x|$ tends to a constant depending on K as $|x| \to \infty$, and so the following

$$\operatorname{ncap}(K) = \exp\left(-\lim_{|x| \to \infty} \left(u(x) - \log|x|\right)\right)$$
(1.2)

was employed by Colosanti-Cuoghi in [11] to define the log-capacity of K since the case n = 2 of (1.2) is just the logarithmic capacity on \mathbb{R}^2 .

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According to [11, Remarks 2.2&2.3], the log-capacity ncap(\cdot) enjoys the following basic properties:

- ncap $(\overline{\mathbb{B}^n}) = 1$ provided $\overline{\mathbb{B}^n} = \{x \in \mathbb{R}^n : |x| \le 1\};$
- $\operatorname{ncap}(x_0 + \rho K) = \rho \operatorname{ncap}(K)$ provided $x_0 + \rho K = \{x_0 + \rho x : x \in K\}$ and $(x_0, \rho, K) \in \mathbb{R}^n \times (0, \infty) \times \mathscr{K}^n;$
- $\operatorname{ncap}(K_1) \leq \operatorname{ncap}(K_2)$ provided $K_1, K_2 \in \mathscr{K}^n$ with $K_1 \subseteq K_2$.

Naturally, the log-capacity of an arbitrary $K \in \mathscr{C}^n$ is defined as:

$$\operatorname{ncap}(K) = \inf_{K \subseteq L \in \mathscr{K}^n} \operatorname{ncap}(L).$$

Such a definition induces not only the last two properties for \mathscr{C}^n but also the following downward-monotone-convergence

• $\operatorname{ncap}(\bigcap_{j=1}^{\infty} K_j) = \lim_{j \to \infty} \operatorname{ncap}(K_j)$ provided $K_j \in \mathscr{C}^n$ with $K_j \supseteq K_{j+1}$.

1.2. Overview. In this paper we study five problems which are naturally associated with the above-defined log-capacity. First of all, we discover the optimal relationship among the volume-radius, the log-capacity and the mean-width (cf. Theorem 2.1). Secondly, we find an integral identity and a lower bound estimate for the non-tangential limit of the gradient of the log-equilibrium potential on the boundary of a \mathscr{K}^n -member (cf. Theorems 3.1 & 3.2). Thirdly, we establish Hadamard's variational formula for (1.2) (cf. Theorem 4.4). Fourthly, we handle the existence and uniqueness of Minkowski's problem for the log-capacity (cf. Theorem 5.1). Last of all, we settle the log-capacity analogue of Yau's [56, Problem 59] (the prescribed mean curvature problem) in a weak sense (cf. Theorem 6.1). Here it is perhaps appropriate to point out that since our log-capacity generalization is from the linear case n = 2 (where the classical 2 = n-harmonic functions are often taken into account) to the nonlinear case $n \ge 3$ (where only the nonlinear $3 \le n$ -harmonic functions can be used), in all situations we have to seek an unified way, which turns out to be highly non-trivial, to deal with these issues.

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2. Volume-radius and mean-width via log-capacity.

2.1. Log-capacity breaking iso-mean-width inequality. Given $K \in \mathscr{C}^n$. Following [48, (1.7)], we say that

$$h_K(x) = \sup_{y \in K} x \cdot y \quad \forall \quad x \in \mathbb{R}^n$$

is the support function of K, and

$$\mathbf{b}(K) = \frac{2}{\sigma_{n-1}} \int_{\mathbb{S}^{n-1}} h_K \, d\theta$$

is the mean-width of K whose case n = 2 gives $\pi b(K) = S(K)$, the perimeter of K (cf. [48, p. 318]) – here and henceforth $d\theta$ is the uniform surface area measure on \mathbb{S}^{n-1} , i.e., the n-1 dimensional spherical Lebesgue measure, where $\sigma_{n-1} = n\omega_n$ is the surface area of the unit sphere \mathbb{S}^{n-1} of \mathbb{R}^n . The sharp iso-mean-width (or Uryasohn's) inequality

$$\left(\frac{V(K)}{\omega_n}\right)^{\frac{1}{n}} \le \frac{\mathbf{b}(K)}{2} \tag{2.1}$$

956

is well known for any $K \in \mathscr{C}^n$ (cf. [48, (6.25)]), where the left-hand quantity of (2.1) is called the volume-radius of K and the right-hand quantity of (2.1) is dominated by a half of the diameter diam(K) of K. Surprisingly, the following result indicates that (2.1) can be split by ncap(K), just like the well-known planar case (cf. [44, Theorem 5.3.5] and [7, Example 7.4]).

THEOREM 2.1. Let $K \in \mathscr{C}^n$. Then

$$\left(\frac{V(K)}{\omega_n}\right)^{\frac{1}{n}} \le ncap(K) \le \frac{b(K)}{2}.$$
(2.2)

And, (2.2) is optimal in the sense that if K is either a ball or a singleton then two equalities of (2.2) hold.

Proof. A straightforward computation shows that each equality of (2.2) occurs whenever K is either a ball or or a singleton.

In order to proceed further, let us recall the definition of the conformal capacity ncap(O, K) for a given open set $O \subset \mathbb{R}^n$ containing a compact set K (cf. [23, p.287]):

$$\operatorname{ncap}(O, K) = \inf_{f \in \mathsf{W}(O, K)} \int_{O \setminus K} |\nabla f|^n \, dV_{\mathcal{H}}$$

where dV is the Lebesgue volume element and W(O, K) comprises all $f \in C_0^{\infty}(O)$ (infinitely differentiable functions with compact support in O) enjoying $f \ge 1$ on K - according to [23, p.27], without affecting ncap(O, K) the class W(O, K) can be replaced by

$$W_0(O,K) = \{ f \in W_0^{1,n}(O) \cap C(O) : f \ge 1 \text{ on } K \},\$$

where C(O) consists of all continuous functions in O and $W_0^{1,n}(O)$ is the closure of $C_0^{\infty}(O)$ in the Sobolev (1, n)-space $W^{1,n}(O)$ equipped with the norm

$$||f||_{W^{1,n}(O)} = \left(\int_{O} |f|^{n} dV\right)^{\frac{1}{n}} + \left(\int_{O} |\nabla f|^{n} dV\right)^{\frac{1}{n}}.$$

For an arbitrary subset E of O, the above definition is extended by

$$\operatorname{ncap}(O, E) = \inf_{\substack{E \subseteq \text{open } U \subseteq O \text{ compact } K \subseteq U}} \operatorname{ncap}(O, K).$$

Below are the known facts (cf. [23, Theorem 2.2] and [17, (2.10)]):

- (i) $\operatorname{ncap}(O, K_1) \leq \operatorname{ncap}(O, K_2)$ as $K_1 \subseteq K_2$ are compact;
- (ii) $\operatorname{ncap}(O_1, K) \ge \operatorname{ncap}(O_2, K)$ as $O_1 \subseteq O_2$ are open and K is compact;
- (iii) $\operatorname{ncap}(O, \bigcap_{j=1}^{\infty} K_j) = \lim_{j \to \infty} \operatorname{ncap}(O, K_j)$ as $K_j \supseteq K_{j+1}$ are compact;

(iv)
$$\left(\frac{\operatorname{ncap}(O,K)}{\sigma_{n-1}}\right)^{\frac{1}{1-n}} \le \log\left(\frac{V(O)}{V(K)}\right)^{\frac{1}{n}}$$

Due to the definition of ncap(K) for $K \in \mathscr{C}^n$, it is enough to verify (2.2) under the assumption $K \in \mathscr{K}^n$ in what follows. On the one hand, we check the left-hand inequality of (2.2). To do so, let $r \in (0, \infty)$ be large enough such that $K \subseteq r\mathbb{B}^n = \{x \in \mathbb{R}^n : |x| < r\}$ and set u_r be the unique solution to

$$\begin{cases} -\operatorname{div}(|\nabla u_r|^{n-2}\nabla u_r) = 0 \quad \text{in} \quad r\mathbb{B}^n \setminus K; \\ u_r = 0 \quad \text{on} \quad \partial K \quad \& \quad u_r(x) = \log r \quad \text{as} \quad |x| = r, \end{cases}$$

According to the argument for [11, Theorem 2.2], $\{u_r\}$ has a subsequence, still denoted by $\{u_r\}$, convergent to u which is the unique weak solution of (1.1) and makes that

 $\alpha = \lim_{|x| \to \infty} \left(u(x) - \log |x| \right)$

is finite. According to [31], we have that if $|x| \to \infty$ then

$$u(x) = \log |x| + \alpha + o(1)$$
 & $|\nabla u(x)| = |x|^{-1} + o(|x|^{-1}).$

Consequently, by the maximum principle we get

$$0 \le u(x) \le \max_{|y|=r} u(y) \quad \forall \quad x \in \overline{r\mathbb{B}^n} = \{y \in \mathbb{R}^n : |y| \le r\}.$$

 \mathbf{If}

$$v_r(x) = \frac{u(x)}{\max_{|y|=r} u(y)} \quad \forall \quad x \in \overline{r\mathbb{B}^n},$$

then for $r \to \infty$ and $0 < t \to 1$ we have

$$v_r(x) = t \Leftrightarrow \log |x| + \alpha + o(1) = t \big(\log r + \alpha + o(1) \big)$$
$$\Leftrightarrow |x| = r^t \exp \big((t-1) \big(\alpha + o(1) \big) \big) \equiv r_*.$$

Note that

$$\begin{cases} -\operatorname{div}(|\nabla v_r|^{n-2}\nabla v_r) = 0 \quad \text{in} \quad r\mathbb{B}^n \setminus K; \\ v_r = 0 \quad \text{on} \quad \partial K; \\ 0 \le v_r(x) \le 1 \quad \text{as} \quad x \in \overline{r\mathbb{B}^n}. \end{cases}$$

So, using (ii), the definition of ncap (\cdot, K) , the test function $v_{r,t} := 1 - t^{-1}v_r$ which belongs to the class $W_0(\{\{v_r(x) < t\}, K\})$ via setting $v_r(x) = 0$ as $x \in K$, the divergence theorem and an integration-by-part, we get

$$\begin{split} \operatorname{ncap}(r\mathbb{B}^{n}, K) &\leq \operatorname{ncap}\left(\{v_{r}(x) < t\}, K\right) \\ &\leq \int_{\{v_{r}(x) < t\}} |\nabla v_{r,t}|^{n} \, dV \\ &\leq \int_{\{v_{r}(x) = t\}} |\nabla v_{r,t}|^{n-1} \, dS \\ &= t^{1-n} \int_{\{v_{r}(x) = t\}} \left(\frac{|\nabla u|}{\max_{|y| = r} u(y)}\right)^{n-1} \, dS \\ &= t^{1-n} \int_{|x| = r_{*}} \left(\frac{1 + o(1)}{r_{*}(\log r + \alpha + o(1))}\right)^{n-1} \, dS \\ &= t^{1-n} \sigma_{n-1} \left(\frac{1 + o(1)}{\log r + \alpha + o(1)}\right)^{n-1}. \end{split}$$

That is to say,

$$\left(\frac{\operatorname{ncap}(r\mathbb{B}^n, K)}{t^{1-n}\sigma_{n-1}}\right)^{\frac{1}{n-1}} \le \frac{1+o(1)}{\log r + \alpha + o(1)}$$

Now, an application of (iv) derives

$$\frac{\log r + \alpha + o(1)}{t^{-1}(1 + o(1))} \le \log \frac{r}{\left(\frac{V(K)}{\omega_n}\right)^{\frac{1}{n}}} = \log r - \log \left(\frac{V(K)}{\omega_n}\right)^{\frac{1}{n}}$$

thereby finding (thanks to: $t \to 1$; $r \to \infty$; $o(1) \to 0$)

$$\left(\frac{V(K)}{\omega_n}\right)^{\frac{1}{n}} \le e^{-\alpha} = \operatorname{ncap}(K).$$

On the other hand, we demonstrate the right-hand inequality of (2.2). For $x \in \mathbb{R}^n$, we have

$$\frac{|x|\mathbf{b}(K)|}{2} = \frac{1}{\sigma_{n-1}} \int_{\mathbb{S}^{n-1}} h_K(|x|\theta) \, d\theta.$$
(2.3)

The right side of (2.3) can be approximated by $\sum_{k=1}^{m} h_K(|x|\theta_k)\lambda_k$ – the support function of $\sum_{k=1}^{m} \lambda_k T_k K$, where $\lambda_k \in (0,1)$, $\sum_{k=1}^{m} \lambda_k = 1$, and $T_k K$ is a rotation of K generated by θ_k . Meanwhile, according to Colesanti-Cuoghi's [11, Theorem 3.1], we have

$$\operatorname{ncap}\left(\sum_{k=1}^{m} \lambda_k T_k K\right) \ge \sum_{k=1}^{m} \lambda_k \operatorname{ncap}(T_k K) = \operatorname{ncap}(K)$$
(2.4)

due to the easily-checked rotation-invariance of ncap(·). Note also that the left side of (2.3) is the support function of a ball of radius $2^{-1}\mathbf{b}(K)$. So, the above approximation, the correspondence between a support function and an element of \mathscr{C}^n , and (2.4) yield the desired inequality. \square

2.2. Another look at volume-radius and log-capacity. Here, we can say more about volume-radius and log-capacity through the solution u_K of (1.1).

REMARK 2.2. For $K \in \mathscr{K}^n$, let $(\nabla u_K)|_{\partial K}$ be the non-tangential limit of ∇u_K at ∂K (cf. [35, Theorem 3] and [34, Theorem 4.3]). If $|\nabla u_K|$ equals a positive constant c on ∂K , then $c^{-1} = (V(K)/\omega_n)^{\frac{1}{n}}$ is the volume-radius of K and hence $|\nabla u_K|$ exists as a kind of weak mean curvature on the level surfaces of $u = u_K$. In fact,

$$-\operatorname{div}(|\nabla u|^{n-2}\nabla u) = 0$$
 in $\mathbb{R}^n \setminus K$ & $|\nabla u|_{\partial K} = c$

implies that if

$$X = n(x \cdot \nabla u) |\nabla u|^{n-2} \nabla u - |\nabla u|^n x$$

 ν stands for the outer unit normal vector, and $r \to \infty$, then

$$(n-1)nc^{n}V(K) = (1-n)\int_{\partial K} x \cdot \nabla u |\nabla u|^{n-1} dS$$
$$= \left(\frac{n-1}{n}\right)\int_{\partial (r\mathbb{B}^{n})} X \cdot \nu \, dS$$
$$= (n-1)\sigma_{n-1} + o(1),$$

Thus, $c = \left(\omega_n / V(K)\right)^{\frac{1}{n}}$, as desired.

Moreover, if U is n-harmonic, i.e., $\operatorname{div}(|\nabla U|^{n-2}\nabla U) = 0$, in $\mathbb{R}^n \setminus K$, U is continuous on ∂K , and U(x) has a finite limit $U(\infty)$ as $x \to \infty$, then the divergence theorem is utilized to produce

$$U(\infty) = \frac{1}{\sigma_{n-1}} \left(\int_{\partial K} U |\nabla u_K|^{n-1} \, dS + \int_{\mathbb{R}^n \setminus K} \frac{\nabla u_K \cdot \nabla U}{\left(|\nabla u_K|^{n-2} - |\nabla U|^{n-2} \right)^{-1}} \, dV \right).$$

In particular, if n = 2 then this formula reduces to [28, (6.3)], and consequently, if $U(x) = u_K(x) - \log |x|$ (which is 2 = n-harmonic in $\mathbb{R}^n \setminus K$) then

$$\operatorname{ncap}(K) = \exp\left(\sigma_{n-1}^{-1} \int_{\partial K} (\log |x|) |\nabla u_K(x)|^{n-1} \, dS(x)\right) \quad \text{for} \quad n = 2$$

It is our conjecture that this last formula is still valid for $n \geq 3$.

3. Boundary estimation of log-equilibrium.

3.1. An identity for the unit sphere area through log-equilibrium. In the above and below, by a convex body in \mathbb{R}^n we mean an element of \mathscr{K}^n . For $K \in \mathscr{K}^n$, the Gauss map $g : \partial K \to \mathbb{S}^{n-1}$ is defined almost everywhere with respect to the surface measure dS and determined by $g(x) = \nu$, the outer unit normal at $x \in \partial K$. In the process of finding a representation of the log-capacity ncap(K) in terms of the integral of $|\nabla u_K|^n$ of the log-equilibrium potential u_K on ∂K , we get the following result whose case n = 2 is essentially known; see also [28].

THEOREM 3.1. If $K \in \mathscr{K}^n$, then

$$\int_{\partial K} h_K(g) |\nabla u_K|^n \, dS = \sigma_{n-1}. \tag{3.1}$$

In other words, if $g_*(|\nabla u_K|^n dS)$ is defined by

$$\int_{g^{-1}(E)} |\nabla u_K|^n \, dS \quad \forall \quad Borel \ set \ E \subset \mathbb{S}^{n-1},$$

then

$$\int_{\mathbb{S}^{n-1}} h_K g_*(|\nabla u_K|^n \, dS) = \sigma_{n-1}.$$

Consequently,

$$\int_{\mathbb{S}^{n-1}} \xi g_*(|\nabla u_K|^n \, dS)(\xi) = 0. \tag{3.2}$$

Proof. For $K \in \mathscr{K}^n$, let $u = u_K$. Suppose that ν is the outer unit normal. Two cases are in order.

Case 1. K is of class $C^{2,+}$ - namely - ∂K is of class C^2 and its Gauss curvature G(K, x) is positive at any $x \in \partial K$. Then

$$|\nabla u| = -\frac{\partial u}{\partial \nu} \quad \text{on} \quad \partial K; \tag{3.3}$$

see also [46].

Observe that if

$$X = n(x \cdot \nabla u) |\nabla u|^{n-2} \nabla u - |\nabla u|^n x$$

then $\operatorname{div} X = 0$ in $\mathbb{R}^n \setminus K$ and hence by an integration-by-part,

$$\int_{\partial K} X \cdot \nu \, dS = \int_{\partial (r \mathbb{B}^n)} X \cdot \nu \, dS \quad \text{as} \quad r \to \infty.$$

However, the right side of the last formula tends to σ_{n-1} as $r \to \infty$ thanks to the expansion of u at infinity. So, from (3.3) it follows that

$$(n-1)\int_{\partial K} (x \cdot \nabla u) \left(-\frac{\partial u}{\partial \nu}\right)^{n-1} dS = \left(\frac{1-n}{n}\right) \int_{\partial K} X \cdot \nu \, dS = (n-1)\sigma_{n-1}.$$

Consequently, (3.1) follows from

$$\int_{\partial K} h_K(g) |\nabla u|^n \, dS = \int_{\partial K} (x \cdot \nabla u) \left(-\frac{\partial u}{\partial \nu} \right)^{n-1} \, dS = \sigma_{n-1}.$$

To reach (3.2), note that σ_{n-1} is a dimensional constant and the support function of $L = K + x_0$ is

$$h_L(\xi) = h_K(\xi) + x_0 \cdot \xi \quad \text{for} \quad \xi \in \mathbb{S}^{n-1},$$

where $x_0 \in \mathbb{R}^n$ is arbitrarily given. So, an application of (3.1) to L yields

$$\int_{\partial K} x_0 \cdot g(x) |\nabla u_K(x)|^n \, dS(x) = 0$$

and consequently, the following vector equation

$$\int_{\partial K} g(x) |\nabla u_K(x)|^n \, dS(x) = 0$$

holds. This gives (3.2).

Case 2. K just belongs to \mathscr{K}^n . To prove (3.1) under this general situation, recall first that the Hausdorff metric d_H on \mathscr{C}^n is determined by

$$d_H(K_1,K_2) = \sup_{x\in K_1} d(x,K_1) + \sup_{x\in K_2} d(x,K_2) \quad \forall \quad K_1,K_2\in \mathscr{C}^n,$$

where d(x, E) stands for the distance from the point x to the set E.

Of course, the interior of the above K is a Lipschitz domain. According to Lewis-Nyström's [35, Theorem 3] (cf. [15] and [29] for harmonic functions), we see that ∇u_K has non-tangential limit, still denoted by ∇u_K , almost everywhere on ∂K with respect to dS. Moreover, $|\nabla u_K|$ is *n*-integrable on ∂K under dS, i.e.,

$$\int_{\partial K} |\nabla u_K|^n \, dS < \infty. \tag{3.4}$$

For 0 < t < 1 let

$$L_t = \{ x \in \mathbb{R}^n \setminus K : u_K(x) > t \} \quad \& \quad K_t = \mathbb{R}^n \setminus L_t.$$

Then $K_t \in \mathscr{K}^n$ is of class $C^{2,+}$ (cf. [11, Theorem 2.2]). Note that $u_K - t$ is equal to the log-equilibrium potential u_{K_t} of K_t , and note that continuity of u_K on ∂K yields $\lim_{t\to 0} d_H(K_t, K) = 0$. So,

$$\sigma_{n-1} = \int_{\partial K_t} (x \cdot \nabla u_K(x)) |\nabla u_K(x)|^{n-1} \, dS(x).$$

This, plus (3.4) and the dominated convergence theorem, derives

$$\sigma_{n-1} = \lim_{t \to 0} \int_{\partial K_t} (x \cdot \nabla u_K(x)) |\nabla u_K(x)|^{n-1} \, dS(x)$$
$$= \int_{\partial K} (x \cdot \nabla u_K(x)) |\nabla u_K(x)|^{n-1} \, dS(x),$$

whence yielding (3.1) and its consequence (3.2).

3.2. A lower bound for the gradient of log-equilibrium. Being motivated by [13, Lemma 2.18] we find the following lower bound estimate for the gradient of the equilibrium potential of (1.1) on the boundary of a convex body.

THEOREM 3.2. For $K \in \mathscr{K}^n$ let u_K be its equilibrium potential. If $K \subset r\mathbb{B}^n$, then there exists a constant c > 0 depending only on r and n such that $|\nabla u_K| \ge c$ almost everywhere on ∂K with respect to dS.

Proof. Suppose that $u = u_K$ and $t_0 \in (0, 1)$ obey

$$K_t = \{ x \in \mathbb{R}^n \setminus K : u(x) \le t \} \subset r \mathbb{B}^n \quad \forall \quad t \in (0, t_0).$$

Note that K_t is of class $C^{2,+}$ and the existence of t_0 is ensured by the continuity of u in $\mathbb{R}^n \setminus K$ (cf. [11, Theorem 2.2]). Now, for $t \in (0, t_0)$ let

$$\check{u}_t(x) = u(x) - t \quad \forall \quad x \in \mathbb{R}^n \setminus K_t.$$

Then \check{u}_t is the solution of (1.1) for K_t , and in $C^2(\mathbb{R}^n \setminus K_t)$. For $\tau \in [0,1)$ let

$$\check{K}_{\tau} = \{ x \in \mathbb{R}^n \setminus K_t : \check{u}_t(x) \le \tau \}$$

and $h(\cdot, \tau)$ be its support function $h_{\check{K}_{\tau}}$. Since $\check{K}_0 = K_t \subset r\mathbb{B}^n$, \check{u}_t is controlled, via the maximum principle, by the log-equilibrium potential of $r\mathbb{B}^n$. Consequently, there is a constant $c_0 > 0$ depending on n and r such that

$$\operatorname{diam}(\check{K}_{2^{-1}}) = \operatorname{diam}(\{x \in \mathbb{R}^n : 2^{-1} < u(x) \le 1\}) \le c_0.$$

Moreover, we have

$$0 \le \inf_{x \in \mathbb{S}^{n-1}} h(x, 2^{-1}) \le \sup_{x \in \mathbb{S}^{n-1}} h(x, 2^{-1}) \le c_0,$$

whence deriving

$$h(x,0) = h(x,2^{-1}) - \int_0^{2^{-1}} \frac{\partial h}{\partial \tau}(x,\tau) \, d\tau \quad \forall \quad x \in \mathbb{S}^{n-1}.$$

From [11, Theorem A.2] it follows that $s \mapsto \frac{\partial h}{\partial \tau}(x,\tau)$ is a non-decreasing function on [0,1). This monotonicity and the mean-value theorem for derivatives yield

$$\frac{\partial h}{\partial \tau}(x,\tau)\Big|_{\tau=0} \le 2\big(h(x,2^{-1}) - h(x,0)\big) \le 2h(x,2^{-1}) \le 2c_0 \quad \forall \ x \in \mathbb{S}^{n-1}.$$

Meanwhile, an application of [11, Theorem A.1] gives

$$\frac{\partial h}{\partial \tau}(x,\tau)|_{\tau=0} = |\nabla \check{u}_t(x)|^{-1}$$

where $x \in \partial K_t$ satisfies

$$x = (\nabla \check{u}_t(x)) |\nabla \check{u}_t(x)|^{-1} \& \check{u}_t(x) = 0.$$

As a result, we get

$$\inf_{x \in \partial K_t} |\nabla u(x)| = \inf_{x \in \partial K_t} |\nabla \check{u}_t(x)| \ge (2c_0)^{-1}$$

The desired assertion follows by letting $t \to 0$ and using the existence of the non-tangential maximal function of $|\nabla u|$ on ∂K .

4. Hadamard's variation for log-capacity.

4.1. Hadamard's variation: smooth case. For $K_1, K_2 \in \mathscr{K}^n$ and $0 \le t_1, t_2$ define

$$t_1K_1 + t_2K_2 = \{x = t_1x_1 + t_2x_2 : x_j \in K_j\}.$$

In accordance with Colesant-Cuoghi's [11, Theorem 3.1] (cf. Borell [7] for n = 2), we have the following Brunn-Minkowski inequality for $t \in [0, 1]$ and $K_1, K_2 \in \mathscr{K}^n$:

$$ncap(tK_1 + (1-t)K_2) \ge tncap(K_1) + (1-t)ncap(K_2)$$
(4.1)

with equality if and only if K_1 is a translate and a dilate of K_2 .

Notice that (4.1) implies that

$$\frac{d^2}{dt^2} \operatorname{ncap}(tK_1 + (1-t)K_2)\big|_{t=0} \le 0.$$

So, we get the following assertion extending the smooth two-dimensional Hadamard's variation formula (cf. [47]).

THEOREM 4.1. If $K_0, K_1 \in \mathscr{K}^n$ are of class $C^{2,+}$, then

$$\frac{d}{dt}\log ncap(K_0 + tK_1)\big|_{t=0} = \sigma_{n-1}^{-1} \int_{\partial K_0} h_{K_1}(g) |\nabla u_{K_0}|^n \, dS, \tag{4.2}$$

equivalently,

$$\frac{d}{dt}\log ncap((1-t)K_0 + tK_1)\big|_{t=0} = \sigma_{n-1}^{-1} \int_{\partial K_0} \frac{|\nabla u_{K_0}|^n}{\left(h_{K_1}(g) - h_{K_0}(g)\right)^{-1}} \, dS.$$
(4.3)

Consequently,

$$\frac{\sigma_{n-1}}{ncap(K_0)} \le \int_{\partial K_0} |\nabla u_{K_0}|^n \, dS \tag{4.4}$$

with equality if K_0 is a ball.

Proof. To derive (4.2), note again that

$$u(x) = u_K(x) = \log |x| - \log \operatorname{ncap}(K) + o(1) \quad \forall \ x \in \mathbb{R}^n \setminus K.$$

Proving (4.2) is equivalent to establishing the first variation of u. To do so, for an arbitrary small number $\epsilon > 0$ let K_{ϵ} be such a convex body that its boundary ∂K_{ϵ} is obtained by shifting ∂K an infinitesimal distance $\delta \nu = \epsilon \rho(s)$ along its outer unit normal ν , where ρ is a smooth function on ∂K :

$$\partial K_{\epsilon} = \{ x + \epsilon \rho(x) \nu(x) : x \in \partial K \},\$$

and denote by $u_{\epsilon} = u_{K_{\epsilon}}$.

For convenience, set

$$K^c = \mathbb{R}^n \setminus K \& K^c_{\epsilon} = \mathbb{R}^n \setminus K_{\epsilon},$$

and define

$$u(x) = 0 \ \forall \ x \in K \ \& \ u_{\epsilon}(x) = 0 \ \forall \ x \in K_{\epsilon}.$$

Consider the following difference

$$\operatorname{Dif}(\epsilon) = \int_{K^c} |\nabla u|^{n-2} \nabla u \cdot \nabla u_{\epsilon} \, dV - \int_{K^c_{\epsilon}} |\nabla u_{\epsilon}|^{n-2} \nabla u_{\epsilon} \cdot \nabla u \, dV. \tag{4.5}$$

On the one hand,

$$\operatorname{Dif}(\epsilon) = \int_{K^c \setminus K^c_{\epsilon}} |\nabla u|^{n-2} \nabla u \cdot \nabla u_{\epsilon} \, dV + \int_{K^c_{\epsilon}} (|\nabla u|^{n-2} - |\nabla u_{\epsilon}|^{n-2}) \nabla u_{\epsilon} \cdot \nabla u \, dV$$
$$= \epsilon \int_{\partial K^c} |\nabla u|^{n-1} \Big(\frac{\partial u_{\epsilon}}{\partial \nu}\Big) \rho \, dS + \int_{K^c_{\epsilon}} (|\nabla u|^{n-2} - |\nabla u_{\epsilon}|^{n-2}) \nabla u_{\epsilon} \cdot \nabla u \, dV.$$

This yields

$$\lim_{\epsilon \to 0} \frac{\operatorname{Dif}(\epsilon)}{\epsilon} = -\int_{\partial K} |\nabla u|^{n-1} \left(\frac{\partial u}{\partial \nu}\right) \rho \, dS.$$

On the other hand, note that

.

$$\begin{cases} -\operatorname{div}(|\nabla u_{\epsilon}|^{n-2}\nabla u_{\epsilon}=0 & \text{in } K_{\epsilon}^{c}; \\ -\operatorname{div}(|\nabla u_{\epsilon}|^{n-2}\nabla u_{\epsilon}=0 & \text{in } K^{c}, \end{cases}$$

and

$$\begin{cases} \operatorname{div}(u|\nabla u_{\epsilon}|^{n-2}\nabla u_{\epsilon}) = u\operatorname{div}(|\nabla u_{\epsilon}|^{n-2}\nabla u_{\epsilon}) + |\nabla u_{\epsilon}|^{n-2}\nabla u_{\epsilon} \cdot \nabla u;\\ \operatorname{div}(u_{\epsilon}|\nabla u|^{n-2}\nabla u) = u_{\epsilon}\operatorname{div}(|\nabla u|^{n-2}\nabla u) + |\nabla u|^{n-2}\nabla u \cdot \nabla u_{\epsilon}.\end{cases}$$

964

So, an application of the divergence theorem gives

$$\begin{split} &\int_{K^c} |\nabla u|^{n-2} \nabla u \cdot \nabla u_{\epsilon} \, dV \\ &= \int_{K^c} \operatorname{div}(u_{\epsilon} |\nabla u|^{n-2} \nabla u) \, dV \\ &= \lim_{r \to \infty} \int_{K^c \setminus (r\mathbb{B}^n)^c} \operatorname{div}(u_{\epsilon} |\nabla u|^{n-2} \nabla u) \, dV \\ &= \int_{\partial K^c} u_{\epsilon} |\nabla u|^{n-2} \nabla u \cdot \nu \, dS - \lim_{r \to \infty} \int_{\partial (r\mathbb{B}^n)^c} u_{\epsilon} |\nabla u|^{n-2} \nabla u \cdot \nu \, dS \\ &= -\lim_{r \to \infty} \int_{\partial (r\mathbb{B}^n)^c} u_{\epsilon} |\nabla u|^{n-2} \nabla u \cdot \nu \, dS. \end{split}$$

Similarly, we have

$$\int_{K_{\epsilon}^{c}} |\nabla u_{\epsilon}|^{n-2} \nabla u_{\epsilon} \cdot \nabla u \, dV = -\lim_{r \to \infty} \int_{\partial (r\mathbb{B}^{n})^{c}} u |\nabla u_{\epsilon}|^{n-2} \nabla u_{\epsilon} \cdot \nu \, dS.$$

Consequently,

 $\operatorname{Dif}(\epsilon)$

$$= -\lim_{r \to \infty} \left(\int_{\partial (r\mathbb{B}^n)^c} u_{\epsilon} |\nabla u|^{n-2} \nabla u \cdot \nu \, dS - \int_{\partial (r\mathbb{B}^n)^c} u |\nabla u_{\epsilon}|^{n-2} \nabla u_{\epsilon} \cdot \nu \, dS \right)$$

$$= \lim_{r \to \infty} \int_{\partial (r\mathbb{B}^n)^c} \nu \cdot \left(\frac{\nabla u_{\epsilon}}{|\nabla u_{\epsilon}|^{2-n}} - \frac{\nabla u}{|\nabla u|^{2-n}} \right) u \, dS - \lim_{r \to \infty} \int_{\partial (r\mathbb{B}^n)^c} \frac{(u_{\epsilon} - u) \nabla u}{|\nabla u|^{2-n}} \cdot \nu \, dS.$$

This derives via (3.1)

$$\begin{split} \lim_{\epsilon \to 0} \frac{\operatorname{Dif}(\epsilon)}{\epsilon} &= \lim_{\epsilon \to 0} \left(\frac{\log \operatorname{ncap}(K_{\epsilon}) - \log \operatorname{ncap}(K)}{\epsilon} \right) \lim_{r \to \infty} \int_{\partial (r\mathbb{B}^n)^c} \frac{\nabla u \cdot \nu}{|\nabla u|^{2-n}} \, dS \\ &= -\sigma_{n-1} \lim_{\epsilon \to 0} \frac{\log \operatorname{ncap}(K_{\epsilon}) - \log \operatorname{ncap}(K)}{\epsilon}. \end{split}$$

The above two formulas for $\lim_{\epsilon \to 0} \epsilon^{-1} \text{Dif}(\epsilon)$ derive

$$\lim_{\epsilon \to 0} \frac{\log \operatorname{ncap}(K_{\epsilon}) - \log \operatorname{ncap}(K)}{\epsilon} = \int_{\partial K} |\nabla u|^n \rho \, \frac{dS}{\sigma_{n-1}},$$

and thereby verifying (4.2) through letting $K = K_0$ and $\rho = h_{K_1} \circ g$.

Through the chain rule and the homogeneous property of the support function, (4.2) immediately derives (4.3) and vice visa. Now, because $t \mapsto \operatorname{ncap}((1-t)K_0+tK_1)$ is concave on [0, 1]; see also [11], if $K_1 = \overline{r\mathbb{B}^n}$ and $r = \operatorname{ncap}(K_0)$ then an application of (4.3) gives

$$0 \leq \frac{d}{dt} \log \operatorname{ncap}((1-t)K_0 + tK_1)\big|_{t=0}$$

= $\left(\frac{1}{\operatorname{ncap}(K_0)}\right) \frac{d}{dt} \operatorname{ncap}((1-t)K_0 + tK_1)\big|_{t=0}$
= $\int_{\partial K_0} \left(h_{K_1}(g) - h_{K_0}(g)\right) |\nabla u_{K_0}|^n \frac{dS}{\sigma_{n-1}}$
= $\int_{\partial K_0} \left(r - h_{K_0}(g)\right) |\nabla u_{K_0}|^n \frac{dS}{\sigma_{n-1}},$

whence reaching (4.4) via (3.1).

4.2. Hadamard's variation: non-smooth case. To generalize Theorem 4.1, without loss of generality we may assume that the origin is an interior point of $K, K_j \in \mathscr{K}^n$, write $\varrho_K : \mathbb{S}^{n-1} \to \partial K$ and $\varrho_{K_j} : \mathbb{S}^{n-1} \to \partial K_j$ for the radial projections

$$\mathbb{S}^{n-1} \ni \theta \mapsto \varrho_K(\theta) = r_K(\theta)\theta \in \partial K$$

and

$$\mathbb{S}^{n-1} \ni \theta \mapsto \varrho_{K_i}(\theta) = r_{K_i}(\theta)\theta \in \partial K_j$$

respectively, where $r_K(\theta)$ and r_{K_j} are the unique positive numbers ensuring $r_K(\theta)\theta \in \partial K$ and $r_{K_j}(\theta)\theta \in \partial K_j$ respectively, and set

$$D(\theta) = |\nabla u_K(\varrho_K(\theta))| r_K(\theta) (h_K(g(\varrho_K(\theta))))^{-\frac{1}{n}}$$

and

$$D_j(\theta) = |\nabla u_{K_j}(\varrho_{K_j}(\theta))| r_{K_j}(\theta)(h_{K_j}(g(\varrho_{K_j}(\theta))))^{-\frac{1}{n}}$$

respectively.

In the sequel, we will use the fact that $dS(x) = |x|^n (x \cdot g(x))^{-1} d\theta$ holds for $\theta = x/|x|$.

THEOREM 4.2. For $\{K, K_1, K_2, ...\} \subseteq \mathscr{K}^n$, $\epsilon > 0$ and $\alpha > 0$, there exist $s_0 > 0$, $\eta > 0$ and a family of balls \mathcal{B} on \mathbb{S}^{n-1} such that:

- (i) every member in \mathcal{B} has radius s_0 ;
- (ii) there is a constant N > 0 depending only on the inner and outer radii of K, such that any point of Sⁿ⁻¹ belongs to at most N balls of B;
- (iii) $S(\mathbb{S}^{n-1} \setminus F) < \epsilon$ where $F = \bigcup_{B \in \mathcal{B}} B$;
- (iv) if $d_H(K_j, K) < \eta$, then for any $B \in \mathcal{B}$ we have

$$s_0^{1-n} \left(\int_B \left| \left(\frac{D_j(\theta)}{D(\theta)} \right)^{n-1} - 1 \right|^\alpha d\theta + \int_B \left| \left(\frac{D(\theta)}{D_j(\theta)} \right)^{n-1} - 1 \right|^\alpha d\theta \right) < \epsilon;$$

(v)

$$\lim_{j \to \infty} \int_{\mathbb{S}^{n-1}} \left| D_i^n(\theta) - D^n(\theta) \right| d\theta = 0$$

Proof. The following argument comes from an appropriate modification of the argument for Lemmas 4.4-4.5-4.6 in [13]. According to Jerison's [27, Lemma 3.3], we have that for any $\epsilon > 0$ there exists $\eta > 0$ and a finite disjoint collection of open balls $B_{r_k}(z_k)$ (centered at z_k with radius r_k) such that $z_k \in \partial K$ and for any convex body $L \in \mathscr{K}^n$ for which $d_H(L, K) < \eta$:

- (a) $S(\partial L \setminus \bigcup_k B_{r_k}(z_k)) < \epsilon;$
- (b) after a suitable rotation and translation depending on k, we have that ∂K and ∂L are given on $B_{r_k}(z_k)$ by the graphs of functions ϕ and ψ respectively, enjoying

$$\sup\left\{|\nabla\phi(x)| + |\nabla\psi(x)| : |x| < \epsilon^{-1}r_k, \ \phi \& \ \psi \text{ differentiable at } x\right\} \le \epsilon.$$

Now, given $\epsilon > 0$. Following the beginning part of the proof of Jerison's [27, Lemma 3.7] we choose a sufficiently small number $s_0 < \min\{r_k\}$ such that the Jacobians of the change of variables ρ_{K_k} and ρ_K vary by at most ϵ as θ varies by the distance s > 0 and $\rho_K(\theta)$ is contained in $\cup_k B_{r_k}(z_k)$. As a consequence, we can select \mathcal{B} obeying (i)-(ii) described as above.

Meanwhile, from Lewis-Nyström's [36, Theorem 2] it follows that for each $s \in (0, s_0)$ and each ball B of radius s in the concentric ϵ^{-1} multiple of any element in \mathcal{B} , there is a constant c_B such that

$$s^{1-n} \int_{B} |\log D(\theta) - c_B| \, d\theta < \epsilon.$$
(4.6)

Furthermore, using the previously-stated (a)-(b) we can take $\delta > 0$ small enough to obtain

$$s^{1-n} \int_{B} \left| \log D_{j}(\theta) - c_{B} \right| d\theta < \epsilon \quad \forall \quad s \in (0, \delta).$$

$$(4.7)$$

A combination of (4.6) and (4.7) gives

$$s^{1-n} \int_{B} \left| \log \frac{D_{j}(\theta)}{D(\theta)} \right| d\theta < 2\epsilon$$

Applying John-Nirenberg's exponential inequality (cf. [30]) for a BMO-function to (4.6), we obtain that given $\alpha > 0$ and for arbitrarily small $\epsilon' > 0$ one can take $\eta' > 0$ and s_0 so small that for each $B \in \mathcal{B}$ there is a constant c'_B ensuring

$$s_0^{1-n} \int_B \left| c'_B \left(\frac{D_j(\theta)}{D(\theta)} \right)^{n-1} - 1 \right|^{\alpha} d\theta < \epsilon'.$$

$$\tag{4.8}$$

Note that η' and s_0 can be chosen small enough to ensure that for each $B \in \mathcal{B}$ we have

$$\frac{\int_B D_j^{n-1}(\theta) \, d\theta}{\int_B D^{n-1}(\theta) \, d\theta} = \left(1 + \mathcal{O}(\epsilon')\right) \frac{\int_{\varrho_{\Omega_j}(B)} |\nabla u_{K_j}|^{n-1} \, dS}{\int_{\varrho_{\Omega}(B)} |\nabla u_K|^{n-1} \, dS},\tag{4.9}$$

where $\mathcal{O}(\epsilon')$ is a positive big-oh function of ϵ' .

Next, we are about to show that c'_B in (4.8) is equal to 1. To this end, let us fix s_0 and allow η to rely on s_0 . Note that the quotient on the right side of (4.9) is the ratio of the *n*-harmonic measures (cf. [38]) of the sets $\varrho_j(B)$ and $\varrho(B)$. So, employing the maximum principle to compare *n*-harmonic functions in $\mathbb{R}^n \setminus K_j$ to *n*-harmonic functions in $\mathbb{R}^n \setminus \rho K$ (where ρK means a ρ -dilation of K), we can take $\eta > 0$ smaller still, relying on s_0 such that

$$\left| \frac{\int_B D_j^{n-1}(\theta) \, d\theta}{\int_B D^{n-1}(\theta) \, d\theta} - 1 \right| \lesssim \epsilon' \tag{4.10}$$

holds for any $B \in \mathcal{B}$. In the above and below, $U \leq V$ stands for $U \leq c_n V$ for a dimensional constant $c_n > 0$.

Using the q > n-harmonic setting of Lewis-Nyström's [35, Theorem 3] and the Hölder inequality we find that

$$\left(\frac{1}{S(\varrho_{\Omega}(B))}\int_{\varrho_{\Omega}(B)}|\nabla u_{K}|^{n}\,dS\right)^{\frac{n-1}{n}} \lesssim \frac{1}{S(\varrho_{K}(B))}\int_{\varrho_{K}(B)}|\nabla u_{K}|^{n-1}\,dS \qquad (4.11)$$

is valid for any ball centered at ∂K . Clearly, a similar estimate is valid for each ∂K_j . Thus,

$$\left(s_0^{1-n} \int_B D^n(\theta) \, d\theta\right)^{\frac{n-1}{n}} \lesssim s_0^{1-n} \int_B D^{n-1}(\theta) \, d\theta \tag{4.12}$$

and similarly for D_j . Now, using Hölder's inequality plus (4.12), (4.8) and (4.11), we get that for each $B \in \mathcal{B}$,

$$\begin{split} \frac{\int_{B} c'_{B} D_{j}^{n-1}(\theta) \, d\theta}{\int_{B} D^{n-1}(\theta) \, d\theta} - 1 &= \frac{\int_{B} c'_{B} \left(\left(\frac{D_{j}(\theta)}{D(\theta)}\right)^{n-1} - 1 \right) D^{n-1}(\theta) \, d\theta}{\int_{B} D^{n-1}(\theta) \, d\theta} \\ &\lesssim \left(\int_{B} \left(c'_{B} \left(\frac{D_{j}(\theta)}{D(\theta)} \right)^{n-1} - 1 \right)^{n} d\theta \right)^{\frac{1}{n}} \left(\frac{\left(\int_{B} D^{n}(\theta) \, d\theta \right)^{\frac{n-1}{n}}}{\int_{B} D^{n-1}(\theta) \, d\theta} \right) \\ &\lesssim \left(s_{0}^{1-n} \int_{B} \left(c'_{B} \left(\frac{D_{j}(\theta)}{D(\theta)} \right)^{n-1} - 1 \right)^{n} d\theta \right)^{\frac{1}{n}} \\ &\lesssim \epsilon'. \end{split}$$

In a similar manner, we replace $c_B^\prime D_j/D$ by $(D/c_B^\prime)D_j$ in the above estimates to obtain

$$\frac{\int_B D^{n-1}(\theta) \, d\theta}{\int_B c'_B D_j^{n-1}(\theta) \, d\theta} - 1 \lesssim \epsilon'.$$

Since (4.10) yields

$$\left|\frac{\int_B D_j^{n-1}(\theta) \, d\theta}{\int_B D^{n-1}(\theta) \, d\theta} - 1\right| \lesssim \epsilon',$$

we must have $|c'_B - 1| \lesssim \epsilon'$, whence getting $c'_B = 1$. As a consequence of this and (4.8), we find

$$s_0^{1-n} \int_B \left| \left(\frac{D_j(\theta)}{D(\theta)} \right)^{n-1} - 1 \right|^\alpha d\theta \lesssim \epsilon' \quad \& \quad s_0^{1-n} \int_B \left| \left(\frac{D(\theta)}{D_j(\theta)} \right)^{n-1} - 1 \right|^\alpha d\theta \lesssim \epsilon',$$

whence completing the proof of (iv).

Although the idea of verifying (v) is motivated by the argument for [27, Proposition 4.3], we still need more effort to adapt it to our nontrivial situation. Because of q > n in [35, Theorem 3], it is possible to find $\beta \in (1, \infty)$ such that $n\beta/(\beta - 1) = q$. Given $\epsilon > 0$, take $\eta > 0$ and F in accordance with (i)-(iv). Using the inequality

$$|a^n - b^n| \le \frac{(a+b)|a^{n-1} - b^{n-1}|}{n^{-1}(n-1)} \quad \forall \ a, b \ge 0 \,,$$

the Hölder inequality and (3.1), we achieve

$$\begin{split} &\int_{F} |D_{j}^{n}(\theta) - D^{n}(\theta)| \, d\theta \\ &\leq \left(\frac{n}{n-1}\right) \int_{F} \left|D_{j}^{n-1}(\theta) - D^{n-1}(\theta)\right| \left(D_{j}(\theta) + D(\theta)\right) \, d\theta \\ &\lesssim \left(\int_{F} \left|D_{j}^{n-1}(\theta) - D^{n-1}(\theta)\right|^{\frac{n}{n-1}} \, d\theta \right)^{\frac{n-1}{n}} \left(\int_{F} \left(D_{j}(\theta) + D(\theta)\right)^{n} \, d\theta \right)^{\frac{1}{n}} \\ &\lesssim \left(2\sigma_{n-1}\right)^{\frac{1}{n}} \left(\int_{F} \left|\left(\frac{D_{j}(\theta)}{D(\theta)}\right)^{n-1} - 1\right|^{\frac{n}{n-1}} D^{n}(\theta) \, dS(\theta)\right)^{\frac{n-1}{n}} \\ &\lesssim \left(\int_{F} \left|\left(\frac{D_{j}(\theta)}{D(\theta)}\right)^{n-1} - 1\right|^{\frac{n\beta}{n-1}} \, dS(\theta)\right)^{\frac{n-1}{n\beta}} \left(\int_{F} D^{q}(\theta) \, d\theta\right)^{\frac{n-1}{q}}, \end{split}$$

thereby deducing

$$\int_{F} \left| D_{j}^{n}(\theta) - D^{n}(\theta) \right| d\theta \lesssim \epsilon \quad \text{as} \quad j \to \infty,$$
(4.13)

via (iv) with $\alpha = q$ as well as [35, Theorem 3] insuring $\int_{\mathbb{S}^{n-1}} D^q(\theta) d\theta < \infty$. On the other hand, by the Hölder inequality with q > n we derive

$$\begin{split} \int_{\mathbb{S}^{n-1}\setminus F} |D_j^n(\theta) - D^n(\theta)| \, d\theta &\leq \int_{\mathbb{S}^{n-1}\setminus F} \left(D_j^n(\theta) + D^n(\theta) \right) d\theta \\ &\lesssim \left(S(\mathbb{S}^{n-1}\setminus F) \right)^{\frac{q}{q-n}} \left(\int_{\mathbb{S}^{n-1}\setminus F} \left(D_j^q(\theta) + D^q(\theta) \right) d\theta \right)^{\frac{n}{q}}, \end{split}$$

whence getting (v) through (iii), (4.13) and [35, Theorem 3] which especially guarantees

$$\sup_{j} \int_{\mathbb{S}^{n-1} \setminus F} \left(D_{j}^{q}(\theta) + D^{q}(\theta) \right) d\theta < \infty.$$

With the help of Theorem 4.2, we can establish the following weak convergence result for the measure induced by Theorem 3.1.

THEOREM 4.3. Let $K, K_j \in \mathscr{K}^n$ and $\lim_{j\to\infty} d_H(K_j, K) = 0$. If u, u_j are the log-equilibrium potentials of K, K_j respectively, then $d\mu_j = (g_j)_*(|\nabla u_j|^n dS)$ converges weakly to $d\mu = g_*(|\nabla u|^n dS)$, i.e.,

$$\lim_{j \to \infty} \int_{\mathbb{S}^{n-1}} f \, d\mu_j = \int_{\mathbb{S}^{n-1}} f \, d\mu \quad \forall \quad f \in C(\mathbb{S}^{n-1}).$$

Proof. The following argument is analogous to [9, Section 5] (cf. [27, the proof of Theorem 3.1] and [13, the proof of Lemma 4.3]). Recall that the push-forward measures $d\mu \& d\mu_i$ on \mathbb{S}^{n-1} are determined respectively by

$$\mu(E) = \int_{g^{-1}(E)} |\nabla u|^n \, dS \quad \& \quad \mu_j(E) = \int_{g_j^{-1}(E)} |\nabla u_j|^n \, dS \,\,\forall \quad \text{Borel set} \quad E \subset \mathbb{S}^{n-1},$$

where g and g_j are the Gauss maps attached to K and K_j respectively. It remains to verify that μ is the weak limit of μ_j as $j \to \infty$.

An application of Theorem 4.2(v) yields

$$\lim_{j \to \infty} \left(\mu(\mathbb{S}^{n-1}) - \mu_j(\mathbb{S}^{n-1}) \right) = \lim_{j \to \infty} \int_{\mathbb{S}^{n-1}} \left(D^n(\theta) - D^n_j(\theta) \right) d\theta = 0.$$
(4.14)

Note that $g^{-1}(E) \subseteq \partial K$ and $g_j^{-1}(E) \subseteq \partial K_j$ are closed (cf. [9] and [26, 27]) for any Borel set $E \subseteq \mathbb{S}^{n-1}$, and that if $\xi_j \in g_j(x_j)$ approaches ξ and if $x_j \to x$ then $\xi \in g(x)$ and $x \in \partial K$. So, for any open neighborhood U in ∂K of the closed set $g^{-1}(E)$ we have that $\varrho_{K_j}^{-1}(g_j^{-1}(E)) \subseteq \varrho_K^{-1}(U)$ as $j \to \infty$, whence finding

$$\limsup_{j \to \infty} \mu_j(E) \le \lim_{j \to \infty} \int_{\varrho_K^{-1}(U)} D_j^n(\theta) \, d\theta \le \int_{\varrho_K^{-1}(U)} D^n(\theta) \, d\theta.$$

When the infimum is over all $U \supseteq g^{-1}(E)$, we get $\limsup_{j\to\infty} \mu_j(E) \leq \mu(E)$. This last inequality and (4.14) imply that for any open subset O of \mathbb{S}^{n-1} ,

$$\liminf_{j \to \infty} \mu_j(O) = \liminf_{j \to \infty} \left(\mu_j(O) - \mu_j(\mathbb{S}^{n-1} \setminus O) \right)$$
$$\geq \liminf_{j \to \infty} \mu_j(\mathbb{S}^{n-1}) - \mu(\mathbb{S}^{n-1} \setminus O)$$
$$= \mu(\mathbb{S}^{n-1}) - \mu(\mathbb{S}^{n-1} \setminus O) = \mu(O).$$

If $\tilde{\mu}$ is any weak limit of a subsequence of μ_j , then the above inequalities on $\limsup_{j\to\infty}$ and $\liminf_{j\to\infty}$ deduce that $\tilde{\mu}(C) \leq \mu(C)$ and $\mu(O) \leq \tilde{\mu}(O)$ hold for any closed $C \subseteq \mathbb{S}^{n-1}$ and any open $O \subseteq \mathbb{S}^{n-1}$. Consequently, for any closed $C \subseteq \mathbb{S}^{n-1}$ we have

$$\mu(C) \ge \tilde{\mu}(C) = \inf\{\tilde{\mu}(O) : \text{open } O \supseteq C\} \ge \inf\{\mu(O) : \text{ open } O \supseteq C\} = \mu(C),$$

and hence $\tilde{\mu} = \mu$.

The following is the general variational result.

THEOREM 4.4. (4.2)-(4.3)-(4.4) are valid for $K_0, K_1 \in \mathscr{K}^n$.

Proof. Given $K_0, K_1 \in \mathscr{K}^n$. There are two $C^{2,+}$ -sequences $\{K_{0,j}\}, \{K_{1,j}\}$ in \mathscr{K}^n such that

$$\lim_{j \to \infty} d_H(K_{0,j}, K_0) = 0 = \lim_{j \to \infty} d_H(K_{1,j}, K_1).$$

Now, for $t \in (0, 1)$ and j = 1, 2, ... set

$$\begin{cases} K_t = (1-t)K_0 + tK_1, & K_{t,j} = (1-t)K_{0,j} + tK_{1,j}; \\ \Phi(t) = \operatorname{ncap}(K_0 + tK_1), & \Phi_j(t) = \operatorname{ncap}(K_{0,j} + tK_{1,j}); \\ \Psi(t) = \operatorname{ncap}(K_t), & \Psi_j(t) = \operatorname{ncap}(K_{t,j}). \end{cases}$$

Note that

$$t \mapsto \Psi_j(t) = (1-t)\Phi_j\left(\frac{t}{1-t}\right)$$

is a concave function on (0, 1). So,

$$\Psi'_{j}(t) \le \frac{\Psi_{j}(t) - \Psi_{j}(0)}{t} \le \Psi'_{j}(0) \quad \forall \quad t \in (0, 1).$$
(4.15)

A simple computation gives

$$\Psi'_{j}(t) = -\Phi_{j}\left(\frac{t}{1-t}\right) + (1-t)^{-1}\Phi'_{j}\left(\frac{t}{1-t}\right)$$

and

$$\begin{split} \Psi'_{j}(0) &= -\Phi_{j}(0) + \Phi'_{j}(0) \\ &= \frac{\operatorname{ncap}(K_{0,j})}{\sigma_{n-1}} \left(-\sigma_{n-1} + \int_{\partial K_{0,j}} h_{K_{1,j}}(g) |\nabla u_{K_{0,j}}|^{n} \, dS \right) \\ &= \frac{\operatorname{ncap}(K_{0,j})}{\sigma_{n-1}} \int_{\partial K_{0,j}} \left(h_{K_{1,j}}(g) - h_{K_{0,j}}(g) \right) |\nabla u_{K_{0,j}}|^{n} \, dS \end{split}$$

owing to (3.1) and (4.3). Upon letting $j \to \infty$ and $t \to 0$ in (4.15), we use Theorem 4.3 to obtain

$$\Psi'(0) = \frac{\operatorname{ncap}(K_0)}{\sigma_{n-1}} \int_{\partial K_0} \left(h_{K_1}(g) - h_{K_0}(g) \right) |\nabla u_{K_0}|^n \, dS,$$

whence establishing (4.3), equivalently, (4.2), and thus (4.4).

5. Minkowski's problem for log-capacity.

5.1. Prescribing volume variation. Given $K \in \mathscr{K}^n$. From the Gauss map $g: \partial K \to \mathbb{S}^{n-1}$ one can introduce the area set function $\mathcal{H}^{n-1}_{\partial K}$ of ∂K via setting

 $\mathcal{H}^{n-1}_{\partial K}(E) = S\big(\{x\in \partial K: \ g(x)\cap E\neq \emptyset\}) \quad \forall \quad \text{Borel subset } E\subset \mathbb{S}^{n-1}.$

This measure $d\mathcal{H}_{\partial K}^{n-1}$ is treated as the push-forward measure $g_*(dS)$ on \mathbb{S}^{n-1} of the n-1 dimensional surface measure dS on ∂K through the inverse map g^{-1} of g. Obviously, $\mathcal{H}_{\partial K}^{n-1}(\mathbb{S}^{n-1}) = S(K)$, i.e., the surface area of K. Two more special facts on this measure are worth recalling. The first is that if ∂K is polyhedron then $d\mathcal{H}_{\partial K}^{n-1} = \sum_k c_k \delta_{\nu_k}$, where δ_{ν_k} is the unit point mass at ν_k and c_k is the (n-1) dimensional measure of the face of ∂K with outward unit normal being ν_k . The second is that if $K \in \mathscr{H}^n$ is of class $C^{2,+}$ then $d\mathcal{H}_{\partial K}^{n-1}$ is absolutely continuous with respect to $d\theta$ and so decided by the reciprocal of the Gauss curvature $G(K, \cdot)$ of ∂K .

The classical Minkowski problem is to ask under what conditions on a given nonnegative Borel measure on \mathbb{S}^{n-1} one can get a convex body $K \in \mathscr{K}^n$ such that $d\mathcal{H}^{n-1}_{\partial K} = d\mu$. As is well-known in convex geometry, this problem is solvable if and only if the support of μ is not contained in any equator (the intersection of \mathbb{S}^{n-1} with any hype-plane through the origin) and μ has centroid at the origin. Moreover, the above K is unique up to translation – this follows from the equality case of the well-known Brunn-Minkowski inequality for $V(\cdot)$:

$$V(K_0 + tK_1)^{\frac{1}{n}} \ge V(K_0)^{\frac{1}{n}} + tV(K_1)^{\frac{1}{n}} \quad \forall \quad K_0, K_1 \in \mathscr{K}^n \quad \& \quad t \in [0, 1].$$

The foregoing inequality and the following Hadamard's variation formula:

$$\frac{d}{dt}V(K_0+tK_1)\big|_{t=0} = \int_{\partial K_0} h_{K_1}(g) \, dS = \int_{\mathbb{S}^{n-1}} h_{K_1} \, d\mathcal{H}^{n-1}_{\partial K_0} \quad \forall \quad K_0, K_1 \in \mathscr{K}^n$$

give

$$\int_{\mathbb{S}^{n-1}} h_{K_1} \, d\mathcal{H}_{\partial K_0}^{n-1} \ge nV(K_0)^{1-\frac{1}{n}} V(K_1)^{\frac{1}{n}},$$

whence ensuring that if K_0 is fixed and K_1 varies with $V(K_1) \geq 1$ then $\int_{\mathbb{S}^{n-1}} h_{K_1} d\mathcal{H}_{\partial K_0}^{n-1}$ reaches its minimum whenever $K_1 = V(K_0)^{-\frac{1}{n}} K_0$. So, the just-described Minkowski problem is equivalent to the problem prescribing the first variation of volume, i.e., the following minimum problem

$$\inf\left\{\int_{\mathbb{S}^{n-1}} h_K \, d\mu: \ K \in \mathscr{K}^n \ \& \ V(K) \ge 1\right\}$$

for a given nonnegative Borel measure μ on \mathbb{S}^{n-1} ; see e.g.[10, 12, 42, 41].

5.2. Prescribing log-capacity variation. As $V(\cdot)$ is replaced by ncap (\cdot) , we empoy Theorem 4.1 and (4.1) to obtain that

$$\int_{\partial K_0} h_{K_1}(g) |\nabla u_{K_0}|^n \, dS = \left(\frac{\sigma_{n-1}}{\operatorname{ncap}(K_0)}\right) \frac{d}{dt} \operatorname{ncap}(K_0 + tK_1) \Big|_{t=0} \ge \frac{\sigma_{n-1}\operatorname{ncap}(K_1)}{\operatorname{ncap}(K_0)}$$

holds for all $K_0, K_1 \in \mathscr{K}^n$. Clearly, if $K_0 \in \mathscr{K}^n$ is fixed and $K_1 \in \mathscr{K}^n$ changes under $\operatorname{ncap}(K_1) \geq 1$, then

$$\int_{\mathbb{S}^{n-1}} h_{K_1} g_*(|\nabla u_{K_0}|^n \, dS) = \int_{\partial K_0} h_{K_1}(g) |\nabla u_{K_0}|^n \, dS \ge \frac{\sigma_{n-1}}{\operatorname{ncap}(K_0)}$$

with equality (i.e., the most right quantity exists as the infimum of the most left integral) if $K_1 = K_0/\operatorname{ncap}(K_0)$. This implication plus the review about the problem of prescribing the first variation of volume as well as [28, Corollaries 2.7 & 6.6] leads to a consideration of the Minkowski-type problem for the first variation of the log-capacity. Below is our result.

THEOREM 5.1. Let μ be a nonnegative Borel measure on \mathbb{S}^{n-1} . (i) If

$$\inf_{\zeta \in \mathbb{S}^{n-1}} \int_{\mathbb{S}^{n-1}} |\zeta \cdot \eta| \, d\mu(\eta) > 0 = \int_{\mathbb{S}^{n-1}} \theta \cdot \eta \, d\mu(\eta) \quad \forall \quad \theta \in \mathbb{S}^{n-1}, \tag{5.1}$$

then

$$\mathcal{M}_{ncap} = \inf\left\{\int_{\mathbb{S}^{n-1}} h_K d\mu : K \in \mathscr{C}^n \& ncap(K) \ge 1\right\} > 0,$$

and hence there is a $K \in \mathscr{C}^n$ with $ncap(K) \ge 1$ such that

$$\mathcal{M}ncap = \int_{\mathbb{S}^{n-1}} h_K \, d\mu$$

(ii) Conversely, if $K \in \mathscr{K}^n$ with ncap(K) = 1 is a minimizer for \mathcal{M}_{ncap} , then it satisfies

$$g_*(|\nabla u_K|^n \, dS) = \sigma_{n-1} \, d\mu, \tag{5.2}$$

and hence (5.1) holds.

(iii) The minimizer in (ii) is unique up to translation.

Proof. (i) For convenience, let

$$\mathbb{S}^{n-1} \ni \xi \mapsto \mathcal{P}_{\mu}(\xi) = \int_{\mathbb{S}^{n-1}} \max\{0, \xi \cdot \eta\} \, d\mu(\eta)$$

be the projection body function. Then (5.1) amounts to

$$0 < \min_{\mathbb{S}^{n-1}} \mathcal{P}_{\mu} \le \max_{\mathbb{S}^{n-1}} \mathcal{P}_{\mu} < \infty \quad \& \quad P_{\mu}(\xi) = P_{\mu}(-\xi) \quad \forall \quad \xi \in \mathbb{S}^{n-1}.$$

In order to prove $\mathcal{M}_{ncap} > 0$, observe that the equation in (5.1) ensures that $\int_{\mathbb{S}^{n-1}} h_K d\mu$ is translation invariant. So, we may assume that the origin is at the midpoint of a diameter of $K \in \mathscr{C}^n$ with $ncap(K) \ge 1$. Let 2R = diam(K). According to Theorem 2.1, we have:

$$\operatorname{ncap}(K) \ge 1 \Rightarrow 2R \ge \operatorname{b}(K) \ge 2\operatorname{ncap}(K) \ge 2.$$

If **e** is a unit vector with $\pm R\mathbf{e} \in \partial K$, then $h_K(\xi) \geq R|\mathbf{e} \cdot \xi|$ holds for all $\xi \in \mathbb{S}^{n-1}$, and hence

$$0 < 2\min_{\mathbb{S}^{n-1}} \mathcal{P}_{\mu} \le 2R\mathcal{P}_{\mu}(\mathbf{e}) \le \int_{\mathbb{S}^{n-1}} R|\mathbf{e} \cdot \xi| \, d\mu(\xi) \le \int_{\mathbb{S}^{n-1}} h_K \, d\mu.$$

This, along with the definition of \mathcal{M}_{ncap} , yields $\mathcal{M}_{ncap} > 0$. Furthermore, when $K \in \mathscr{C}^n$ satisfies

$$\operatorname{ncap}(K) \ge 1 \quad \& \quad \int_{\mathbb{S}^{n-1}} h_K \, d\mu \le 2\mathcal{M}_{\operatorname{ncap}},$$

we have

$$0 < \operatorname{diam}(K) \min_{\mathbb{S}^{n-1}} \mathcal{P}_{\mu} = 2R \min_{\mathbb{S}^{n-1}} \mathcal{P}_{\mu} \le 2\mathcal{M}_{\operatorname{ncap}}.$$

Now, suppose that $\{K_j\}_{j=1}^{\infty}$ is a sequence in \mathscr{C}^n which satisfies

$$\mathcal{M}_{\mathrm{ncap}} = \lim_{j \to \infty} \int_{\mathbb{S}^n} h_{K_j} d\mu \quad \& \quad \mathrm{ncap}(K_j) \ge 1.$$

Then

$$2 \leq 2\operatorname{ncap}(K_j) \leq \operatorname{diam}(K_j) \leq \frac{2\mathcal{M}\operatorname{ncap}}{\min_{\mathbb{S}^{n-1}} \mathcal{P}_{\mu}} \text{ as } j \to \infty.$$

In accordance with the Blaschke selection principle (see e.g. [48, Theorem 1.8.6]), $\{K_j\}_{j=1}^{\infty}$ has a subsequence, still denoted by $\{K_j\}_{j=1}^{\infty}$, that converges to a $K \in \mathscr{C}^n$ with respect to the Hausdorff distance $d_H(\cdot, \cdot)$. Consequently, $h_{K_j} \to h_K$. Now, if $\operatorname{ncap}(K) < 1$, then from the definition of $\operatorname{ncap}(K)$ it follows that there is an $L \in \mathscr{K}^n$ enjoying

$$K \subset L$$
 & $\operatorname{ncap}(L) < 1$.

But, as j is sufficiently large we have $K_j \subset L$, and consequently by the monotonicity of ncap (\cdot) ,

$$1 \le \operatorname{ncap}(K_j) \le \operatorname{ncap}(L) < 1,$$

a contradiction. Therefore, one must have $ncap(K) \ge 1$.

(ii) Suppose that $K \in \mathcal{K}^n$ with $\operatorname{ncap}(K) = 1$ is a minimizer for $\mathcal{M}_{\operatorname{ncap}}$. For $(t, L) \in (0, 1) \times \mathcal{K}^n$ one has $K + tL \in \mathcal{K}^n$ and $h_{K+tL} = h_K + th_L$. Consequently, K is a critical point of the functional

$$\mathcal{D}(K+tL) = \int_{\mathbb{S}^{n-1}} h_{K+tL} \, d\mu - \operatorname{ncap}(K+tL).$$

This, along with (4.2) in Theorem 4.4 and ncap(K) = 1, gives

$$0 = \frac{d}{dt} \mathcal{D}(K+tL) \Big|_{t=0}$$

= $\int_{\mathbb{S}^{n-1}} h_L d\mu - \sigma_{n-1}^{-1} \int_{\partial K} h_L(g) |\nabla u_K|^n dS$
= $\int_{\mathbb{S}^{n-1}} h_L d\mu - \sigma_{n-1}^{-1} \int_{\mathbb{S}^{n-1}} h_L g_* (|\nabla u_K|^n dS).$

An application of [48, Lemmas 1.7.9 & 1.8.10] implies

$$\sigma_{n-1} \int_{\mathbb{S}^{n-1}} \phi \, d\mu = \int_{\mathbb{S}^{n-1}} \phi \, g_* \left(|\nabla u_K|^n \, dS \right) \quad \forall \quad \phi \in C(\mathbb{S}^{n-1})$$

thereby producing (5.2). Accordingly, a combination of both (3.2) and (5.2) derives

$$0 = \int_{\mathbb{S}^{n-1}} \theta \cdot \xi \, g_*(|\nabla u_K|^n \, dS)(\xi) = \sigma_{n-1} \int_{\mathbb{S}^{n-1}} \theta \cdot \xi \, d\mu(\xi) \quad \forall \quad \theta \in \mathbb{S}^{n-1}.$$

Therefore, the equality in (5.1) holds. Meanwhile, an application of (5.2) (for $K \in \mathscr{K}^n$ with $\operatorname{ncap}(K) = 1$) and Theorem 3.2 (with a positive constant c) deduces

$$\begin{split} \inf_{\theta \in \mathbb{S}^{n-1}} \int_{\mathbb{S}^{n-1}} |\theta \cdot \eta| \, d\mu(\eta) &= \sigma_{n-1}^{-1} \inf_{\theta \in \mathbb{S}^{n-1}} \int_{\mathbb{S}^{n-1}} |\theta \cdot \eta| \, g_*(|\nabla u_K|^n \, dS)(\eta) \\ &= \sigma_{n-1}^{-1} \inf_{\theta \in \mathbb{S}^{n-1}} \int_{\partial K} |\theta \cdot g(x)| |\nabla u_K(x)|^n \, dS(x) \\ &\geq c^n \sigma_{n-1}^{-1} \inf_{\theta \in \mathbb{S}^{n-1}} \int_{\partial K} |\theta \cdot g(x)| \, dS(x) \\ &= c^n \sigma_{n-1}^{-1} \inf_{\theta \in \mathbb{S}^{n-1}} \int_{\mathbb{S}^{n-1}} |\theta \cdot \eta| \, d\mathcal{H}_{\partial K}^{n-1}(\eta) \\ &> 0. \end{split}$$

Thus, the inequality in (5.1) is true.

(iii) Our argument for the uniqueness is inspirited by [8, Section 5]. Now, assume that $K_0, K_1 \in \mathscr{K}^n$ are two minimizers of \mathcal{M}_{ncap} in (ii). Then

$$\begin{cases} g_*(|\nabla u_{K_0}|^n \, dS) = g_*(|\nabla u_{K_1}|^n \, dS); \\ ncap(K_0) = 1 = ncap(K_1). \end{cases}$$

 \mathbf{If}

$$\psi(t) = \operatorname{ncap}((1-t)K_0 + tK_1),$$

then Theorems 4.4 & 3.1 yield

$$\psi'(0) = \frac{\operatorname{ncap}(K_0)}{\sigma_{n-1}} \int_{\partial K_0} \left(h_{K_1}(g) - h_{K_0}(g) \right) |\nabla u_{K_0}|^n \, dS$$

$$= \sigma_{n-1}^{-1} \left(\int_{\partial K_0} h_{K_1}(g) |\nabla u_{K_0}|^n \, dS - \sigma_{n-1} \right)$$

$$= \sigma_{n-1}^{-1} \left(\int_{\mathbb{S}^{n-1}} h_{K_1} \, g_*(|\nabla u_{K_0}|^n \, dS) - \sigma_{n-1} \right)$$

$$= \sigma_{n-1}^{-1} \left(\int_{\mathbb{S}^{n-1}} h_{K_1} \, g_*(|\nabla u_{K_1}|^n \, dS) - \sigma_{n-1} \right)$$

$$= \sigma_{n-1}^{-1} \left(\sigma_{n-1} - \sigma_{n-1} \right)$$

$$= 0.$$

Note that $t \mapsto \psi(t)$ is concave on [0, 1]. So this function is constant, in particular, we have

$$ncap(K_1) = \psi(1) = \psi(0) = ncap(K_0).$$
(5.3)

Since the equality of (4.1) holds, K_1 is a translate and a dilate of K_0 . But (5.3) is valid, so K_1 is only a translate of K_0 thanks to the uniqueness of the Brunn-Minkowski inequality for ncap(·) over \mathscr{K}^n proved in [11].

6. Yau's problem for log-capacity.

6.1. Prescribing mean curvature. On [56, p. 683], Yau posed the following problem:

"Let h be a real-valued function on \mathbb{R}^3 . Find (reasonable) conditions on h to insure that one can find a closed surface with prescribed genus in \mathbb{R}^3 whose mean curvature (or curvature) is given by h. F. Almgren made the following comments: For "suitable" h one can obtain a compact smooth submanifold ∂A in \mathbb{R}^3 having mean curvature h by maximizing over bounded open sets $A \subset \mathbb{R}^3$ the quantity

$$F(A) = \int_{A} h \, d\mathcal{L}^{3} - Area(\partial A).$$

A function h would be suitable, for example, in case it were continuous, bounded, and \mathcal{L}^3 summable, and sup F > 0. However, the relation between h and the genus of the resulting extreme ∂A is not clear."

Although not yet completely solved, this problem for mean curvature or Gaussian curvature has a solution at least for the closed surface of genus zero, see [50, 5, 25] or [51, 52]. The following, essentially contained in [55, Corollary 1.2], may be regarded as a resolution of Yau's problem in a special form - if $I \in L^1(\mathbb{R}^n)$ is positive and continuous, k is nonnegative integer, $\alpha \in (0, 1)$, and

$$\mathcal{I}(K) = S(K) - \int_{K} I \, dV,$$

then:

• There is $K_0 \in \mathscr{C}^n$ such that $\mathcal{I}(K_0) = \inf_{K \in \mathscr{C}^n} \mathcal{I}(K) \leq 0$ if and only if there is $L_0 \in \mathscr{C}^n$ such that $\mathcal{I}(L_0) \leq 0$.

- Suppose that $K \in \mathscr{K}^n$ is a minimizer for $\mathcal{I}(\cdot)$. Then there exists a measure μ_K on \mathbb{S}^{n-1} such that the weak mean curvature equation $d\mu_K = g_*(I|_{\partial K} dS)$. Moreover, if K is of class $C^{2,+}$ then the mean curvature H(K, x) (i.e., the arithmetic mean of n-1 principal curvatures at $x \in \partial K$) equals $(n-1)^{-1}I(x)$.
- If I is of $C^{k,\alpha}(\mathbb{R}^n)$ and $K \in \mathscr{K}^n$, being of class $C^{2,+}$, is a minimizer for $\mathcal{I}(\cdot)$, then K is of $C^{k+2,\alpha}$.

6.2. Prescribing log-capacitary curvature. Thanks to the relationship between the mean-width and the log-capacity explored in Section 2, as well as the discussion on the Minkowski-type problem above, it seems interesting to consider the log-capacity analogue of Yau's problem. More precisely, using the log-capacity in place of the surface area we study the functional

$$\mathcal{J}(K) = \operatorname{ncap}(K) - \int_{K} J \, dV,$$

thereby obtaining the following result.

THEOREM 6.1. Let J be positive and continuous function on \mathbb{R}^n with

$$\|J\|_{L^1(\mathbb{R}^n)} = \int_{\mathbb{R}^n} J \, dV < \infty,$$

 $(k+1, \alpha, \beta) \in \mathbb{N} \times (0, 1) \times (0, \infty)$, and \mathscr{K}_{β}^{n} comprise all $K \in \mathscr{K}^{n}$ whose inradii $r_{in}(K)$ are not less than β .

- (i) There exists $K_0 \in \mathscr{K}^n_\beta$ such that $\mathcal{J}(K_0) = \inf_{K \in \mathscr{K}^n_\beta} \mathcal{J}(K)$. Moreover, $\inf_{K \in \mathscr{K}^n_\beta} \mathcal{J}(K) \leq 0$ if and only if there exists $L_0 \in \mathscr{K}^n_\beta$ such that $\mathcal{J}(L_0) \leq 0$.
- (ii) Suppose that $K \in \mathscr{K}^n_\beta$ is a minimizer for $\mathcal{J}(\cdot)$. Then such a K satisfies the weak log-capacitary curvature equation

$$ncap(K)\sigma_{n-1}^{-1}g_*(|\nabla u_K|^n \, dS) = g_*(J|_{\partial K} \, dS).$$
(6.1)

Moreover, if K is of class $C^{2,+}$, then we have the log-capacitary curvature equation

$$ncap(K)\sigma_{n-1}^{-1}|\nabla u_K(x)|^n = J(x) \quad \forall \quad x \in \partial K.$$
(6.2)

(iii) If J is of $C^{k,\alpha}(\mathbb{R}^n)$ and $K \in \mathscr{K}^n_\beta$, being of class $C^{2,+}$, is a minimizer for $\mathcal{J}(\cdot)$, then K is of $C^{k+1,\alpha}$.

Proof. (i) Since

$$\mathcal{J}(K) \ge \operatorname{ncap}(K) - \|J\|_{L^1(\mathbb{R}^n)} \ge -\|J\|_{L^1(\mathbb{R}^n)} \quad \forall \quad K \in \mathscr{K}^n_\beta,$$

it follows that $\inf_{K \in \mathscr{K}_{\beta}^{n}} \mathcal{J}(K)$ is finite. Consequently, there is a sequence $\{K_{j}\}$ from \mathscr{K}_{β}^{n} such that

$$\lim_{j \to \infty} \mathcal{J}(K_j) = \inf_{K \in \mathscr{K}_{\beta}^n} \mathcal{J}(K).$$

Using the linear structure of ncap(·), Theorem 2.1 and $r_{K_j} \ge \beta > 0$, we get

$$0 < 2\beta \le 2\mathbf{r}_{K_j} = 2\mathrm{ncap}(\mathbf{r}_{K_j}\mathbb{B}^n) \le 2\mathrm{ncap}(K_j) \le \mathbf{b}(K_j) \le \mathrm{diam}(K_j).$$
(6.3)

An application of (2.2) implies

$$\mathcal{J}(K_j) \ge \operatorname{ncap}(K_j) - \|J\|_{L^1(\mathbb{R}^n)} \ge \left(\frac{V(K_j)}{\omega_n}\right)^{\frac{1}{n}} - \|J\|_{L^1(\mathbb{R}^n)}.$$

So, if $\{\operatorname{diam}(K_j)\}$ is unbounded, then (6.3) is used to ensure that $\{V(K_j)\}$ is unbounded, and hence $\{\mathcal{J}(K_j)\}$ has a subsequence $\{\mathcal{J}(K_{j_k})\}$ which tends to ∞ as $k \to \infty$. But, $\lim_{k\to\infty} \mathcal{J}(K_{j_k})$ exists as a finite value. Therefore, $\{\operatorname{diam}(K_j)\}$ has a uniform upper bound. Now, taking into account of the above-mentioned Blaschke selection principle, we can get a subsequence of $\{K_j\}$ which is convergent to an element $K_0 \in \mathscr{K}_{\beta}^n$ due to $K_j \in \mathscr{K}_{\beta}^n$. Note that $\mathcal{J}(\cdot)$ is continuous. Thus, K_0 is a minimizer of $\mathcal{J}(\cdot)$ over \mathscr{K}_{β}^n , i.e., $\mathcal{J}(K_0) = \inf_{K \in \mathscr{K}_{\beta}^n} \mathcal{J}(K)$, as desired.

Furthermore, if $\inf_{K \in \mathscr{K}_{\beta}^{n}} \mathcal{J}(K) \leq 0$, then the previously-found minimizer $K_{0} \in \mathscr{K}_{\beta}^{n}$ satisfies $\mathcal{J}(K_{0}) \leq 0$. Conversely, if there is $L_{0} \in \mathscr{K}_{\beta}^{n}$ such that $\mathcal{J}(L_{0}) \leq 0$, then $\inf_{K \in \mathscr{K}_{\beta}^{n}} \mathcal{J}(K) \leq \mathcal{J}(L_{0}) \leq 0$.

(ii) For $K \in \mathscr{K}^n$, t > 0 and $\phi \in C(\mathbb{S}^{n-1})$ let

$$K_t = \left\{ x \in \mathbb{R}^n : x \cdot \theta \le h_K(\theta) + t\phi(\theta) \quad \forall \quad \theta \in \mathbb{S}^{n-1} \right\}$$

Then $K_t \in \mathscr{K}^n$ and $h_{K_t} = h_K + t\phi$. Using Theorem 4.4 (plus the ideas presented in [28, Sections 3-4]) as well as Tso's variation formula [52, (4)], we produce

$$\frac{d}{dt}\mathcal{J}(K_t)\Big|_{t=0} = \left(\frac{\operatorname{ncap}(K)}{\sigma_{n-1}}\right)\int_{\partial K}\phi(g)|\nabla u_K|^n\,dS - \int_{\partial K}\phi(g)J\,dS.$$
(6.4)

Obviously, if K is a minimizer of $\mathcal{J}(\cdot)$, then it is a critical point of $\mathcal{J}(K_t)$ and hence $\frac{d}{dt}\mathcal{J}(K_t)\Big|_{t=0} = 0$. This last equation, along with (6.4), gives

$$\left(\frac{\operatorname{ncap}(K)}{\sigma_{n-1}}\right) \int_{\mathbb{S}^{n-1}} \phi g_*(|\nabla u_K|^n \, dS) = \left(\frac{\operatorname{ncap}(K)}{\sigma_{n-1}}\right) \int_{\partial K} \phi(g) |\nabla u_K|^n \, dS$$
$$= \int_{\partial K} \phi(g) J \, dS$$
$$= \int_{\mathbb{S}^{n-1}} \phi g_*(J \, dS).$$

Owing to the fact that $\phi \in C(\mathbb{S}^{n-1})$ is arbitrary, we arrive at (6.1). Furthermore, if K is of class $C^{2,+}$, then $g: \partial K \to \mathbb{S}^{n-1}$ is a diffeomorphism (cf. [14, 22]), and hence

$$\left(\frac{\operatorname{ncap}(K)}{\sigma_{n-1}}\right)|\nabla u_K(x)|^n = J(x) \quad \forall \quad x \in \partial K$$

validates (6.2).

(iii) Suppose $J \in C^{k,\alpha}(\mathbb{R}^n)$ with k being a nonnegative integer. Since K is of class $C^{2,+}$, an application of [37, Theorem 1] and [40, Theorem 4.1] (cf. [20, 16, 49, 53, 21]) yields that $u_K \in C^{1,\hat{\alpha}}(\partial K)$ holds for some $\hat{\alpha} \in (0, 1)$, and more importantly, the Gauss map from ∂K to \mathbb{S}^{n-1} is a diffeomorphism. Therefore, (6.2) is true. Using (6.2) and $J \in C^{k,\alpha}(\mathbb{R}^n)$ with $\alpha \in (0, 1)$, we obtain that $|\nabla u_K|$ belongs to $C^{k,\alpha}(\partial K)$. Note again that K is of class $C^{2,+}$. So, it follows that K is of $C^{k+1,\alpha}$ from the fact that $|\nabla u_K||_{\partial K}$ is bounded above and below by two positive constants (cf. (6.2) and Theorem 3.2). \square

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